# SOSELETO: A Unified Approach to Transfer Learning and Training with Noisy Labels

Or Litany

Facebook Al Research

Joint work with Daniel Freedman (Google)

Or Litany SOSELETO May 6th, 2019 1/19

## Background

• Deep Learning is data hungry



#### Background

- Deep Learning is data hungry
- What about data-poor regimes?





#### Transfer learning

Pass knowledge gleaned from a *source* (data-rich regime) to the *target* (data-poor regime)

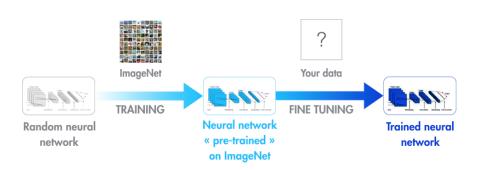


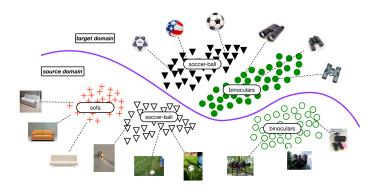
Image credit: Medium.com

3/19

#### Selective Transfer Learning

#### Observation

Some source examples are more informative than others for the target classification problem.



#### Core idea

#### Problem

We do not know a priori which source examples will be important.



#### Core idea

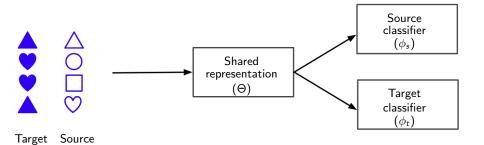
#### Problem

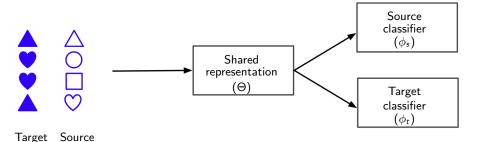
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#### Proposal

What if we let the target decide?

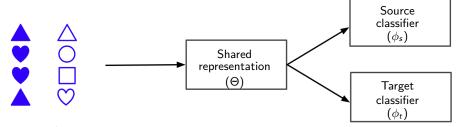




$$\theta^*, \phi^{s*} = \operatorname*{arg\,min}_{\theta,\phi^s} \mathit{L}_s(\theta,\phi^s)$$

$$\phi^{t*} = \operatorname*{arg\,min}_{\phi^t} L_t(\theta^*, \phi^t)$$

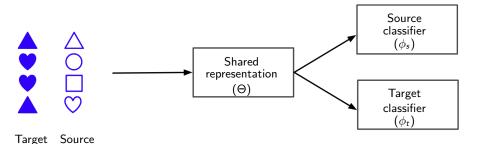
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Target Source

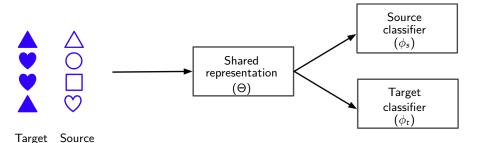
$$egin{aligned} heta^*, \phi^{s*} &= rg \min_{ heta, \phi^s} rac{1}{n^s} \sum_{j=1}^{n^s} \ell(y^s_j, F(x^s_j; heta, \phi^s)) \ \phi^{t*} &= rg \min_{\phi^t} L_t( heta^*, \phi^t) \end{aligned}$$

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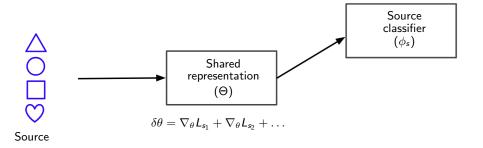
$$\theta^*(\alpha), \phi^{s*}(\alpha) = \arg\min_{\theta, \phi^s} \frac{1}{n^s} \sum_{i=1}^{n^s} \alpha_i \ell(y_j^s, F(x_j^s; \theta, \phi^s))$$

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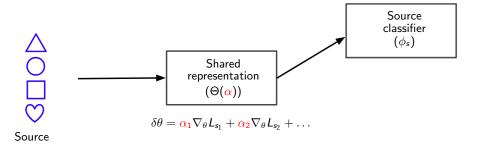
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6/19



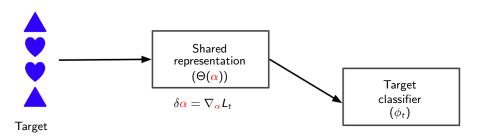
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Interior level:

$$\theta^*(\alpha), \phi^{s*}(\alpha) = \underset{\theta, \phi^s}{\arg\min} L_s(\theta, \phi^s, \alpha)$$

Exterior level:

$$\min_{\alpha,\phi^t} L_t(\theta^*(\alpha),\phi^t)$$

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 8 / 19

Interior level:

$$\theta^*(\alpha), \phi^{s*}(\alpha) = \underset{\theta, \phi^s}{\arg\min} L_s(\theta, \phi^s, \alpha)$$

$$\theta_{m+1} = \theta_m - \lambda_p \frac{\partial L_s}{\partial \theta} (\theta_m, \phi_m^s, \alpha_m)$$

$$= \theta_m - \lambda_p Q(\theta_m, \phi_m^s) \alpha_m$$
(1)

Exterior level:

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Exterior level:

$$\min_{\alpha,\phi^t} L_t(\theta_m - \lambda_p Q \alpha, \phi^t)$$

$$\alpha_{m+1} \approx \alpha_m + \lambda_\alpha \lambda_\rho Q^T \frac{\partial L_t}{\partial \theta} (\theta_m)$$
 (2)

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Exterior level:

$$\min_{\alpha,\phi^t} L_t(\theta_m - \lambda_p Q \alpha, \phi^t)$$

$$\alpha_{m+1} = \mathsf{CLIP}_{[0,1]} \left( \alpha_m + \lambda_\alpha \lambda_p Q^\mathsf{T} \frac{\partial L_t}{\partial \theta} (\theta_m) \right) \tag{2}$$

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- Weigh source instances.
- Train a shared representation, as a bi-level optimization:
  - Interior level: minimize source loss wrt representation parameters.
  - Exterior level: minimize target loss wrt source weights.

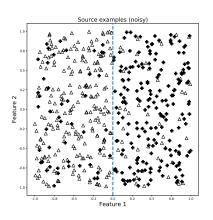
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#### Intuition

- The target set "chooses" source samples which are informative for its own classification task.
- bi-level optimization mitigates overfitting: target samples do not control the representation parameter directly.

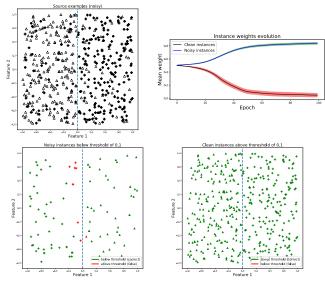
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#### Noisy Labels: synthetic experiment



- Source: 500 points with 20% noisy labels.
- Target: 50 points with clean labels

#### Noisy Labels: synthetic experiment



#### Results: Noisy labels (CIFAR-10)

- 60,000 images of 10 categories (airplane, automobile, bird, etc.)
- Noise was added uniformly (unstructured)

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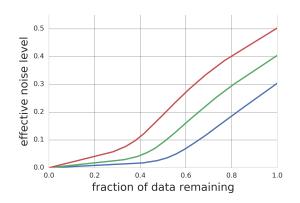
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Noise Level	CIFAR-10 Quick	Sukhbaatar <i>et al.</i> 10K clean examples	Xiao <i>et al.</i> 10K clean examples	Ours 5K clean examples
30%	65.57	69.73	69.81	72.41
40%	62.38	66.66	66.76	69.98
50%	57.36	63.39	63.00	66.33

## Results: Noisy labels (CIFAR-10)

#### A denoising effect:



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#### $\overline{\text{SVHN}}$ 0-4 $\rightarrow$ MNIST 5-9



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#### SVHN 0-4 $\rightarrow$ MNIST 5-9

Uses Unlabelled Data?	Method	$n^{t} = 20$	$n^t = 25$
No	Target only	80.1	84.0
No	Fine-tuning	80.2	83.0
No	SOSELETO	83.2	87.9
Yes	Matching Nets <sup>1</sup>	56.6	51.3
Yes	Fine-tuned Matching Nets	79.3	82.7
Yes	Fine-tune domain adversarial <sup>2</sup>	80.4	83.1
Yes	Label Efficient <sup>2</sup>	94.2	95.0

<sup>&</sup>lt;sup>1</sup>Vinyals et al., 2016

<sup>&</sup>lt;sup>2</sup>Luo *et al.*, 2017

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 $\bullet$  Leveraging unlabeled MNIST:  $\approx 92\%$ 

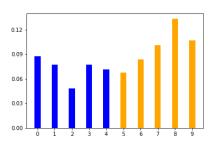
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Boosts performance to above 90%

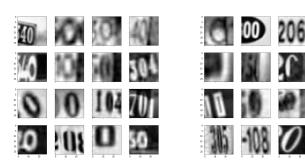
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- Boosts performance to above 90%
- Distribution across classes: does not correlate with labels



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- Noisy lable detector



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#### Summary

- Datasets and tasks share information (don't reinvent the mechanical turk)
- SOSELETO: Simple to implement, can be used with any architecture



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- Limitations:
  - Requires more memory (and adds variables)
  - Updates a sample once per epoch



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- SOSELETO: Simple to implement, can be used with any architecture
- Limitations:
  - Requires more memory (and adds variables)
  - Updates a sample once per epoch
- Follow ups:
  - Group weighting
  - Domain adaptation
  - Task weighting

## Thanks!

github.com/orlitany

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