SHEN ZHENG

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Personal Webpage
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EDUCATION

Carnegie Mellon University

Aug. 2024 — Dec. 2027 (Expected)

PhD in Robotics | Advisor: Dr. Srinivasa Narasimhan

Carnegie Mellon University

Aug. 2022 — Dec. 2023

Master of Science in Computer Vision (MSCV) | GPA: 4.07/4.33 | Advisor: Dr. Srinivasa Narasimhan

Pittsburgh, PA

· Coursework (A+): Learning-based Image Synthesis, Visual Learning and Recognition, Computer Vision, MultiModal Machine Learning, etc.

Wenzhou-Kean University

Sep. 2017 - Jun. 2021

Bachelor of Arts in Mathematical Sciences | Major GPA: 3.94/4.00 | Advisor: Dr. Gauray Gupta

Wenzhou, China

Pittsburgh, PA

• Honors: Dean's List (Top 3%); Zhejiang Provincial Government Scholarship (Top 3%); Outstanding Graduate (Top 10%).

PROFESSIONAL EXPERIENCES

Waymo May. 2025 – Aug. 2025

• (WIP) Perception software engineer intern focused on Online HD Map Construction with long- and short-term memory fusion.

Lucid Motors Feb. 2024 – Jul. 2024

- Full-time perception software engineer in the ADAS perception team responsible for auto-parking, traffic light detection, and blockage detection.
- Improved BEVFormer for auto-parking (reverse & parallel) by using extrinsic calibration to interpolate and smooth edges to enhance curb detection.
- $\bullet \ \ Trained\ YOLO6\ on\ traffic\ light\ images\ and\ finetuned\ arrow\ types,\ confidence,\ IoU,\ and\ area\ thresholds,\ improving\ 42+\%\ mAP\ for\ night\ images.$
- Developed a binary segmentation model based on CenterNet to detect blockages (ice, snow, mud, blur, raindrops, sun glares), achieving 93%+ IoU.

SELECTED PUBLICATIONS

- · Anurag Ghosh, Shen Zheng, et al., ROADWork Dataset: Learning to Recognize, Observe, Analyze and Drive Through Work Zones. ICCV 2025.
- Shen Zheng, et al., Instance-Warp: Saliency Guided Image Warping for Unsupervised Domain Adaptation. WACV 2025.
- Shen Zheng, et al., TPSeNCE: Towards Artifact-Free Realistic Rain Generation for Deraining and Object Detection in Rain. WACV 2024.
- Shen Zheng, et al., PointNorm: Dual Normalization is All You Need for Point Cloud Analysis. IJCNN 2023 (Oral).
- Changjie Lu, Shen Zheng, et al., AS-IntroVAE: Adversarial Similarity Distance Makes Robust IntroVAE. ACML 2022.
- Shen Zheng and Gaurav Gupta, Semantic-Guided Zero-Shot Learning for Low-Light Image/Video Enhancement. WACV 2022.

RESEARCH EXPERIENCES

ROADWork Dataset: Learning to Recognize, Observe, Analyze and Drive Through Work Zones [Webpage] Feb. 2024 – May. 2024

- · Proposed ROADWork, the largest open-source work zone dataset, to enhance baseline and foundation models in understanding work zones.
- Achieved +12.8× work zone discovery, +26.2% mAP for object detection, +36.7 SPICE for image captioning, and -21.3% error for path prediction.

Instance-Warp: Saliency Guided Image Warping for Unsupervised Domain Adaptation [Webpage] May. 2023 – Jan. 2024

- Propose an instance-level image warping to oversample objects, enhancing object feature learning amidst dominant and highly varied backgrounds.
- Integrate image warping and feature unwarping into unsupervised domain adaptation in a task-agnostic way without test-time warping.
- Achieved +6.1% mAP50 for BDD100K Clear → DENSE Foggy object detection and +6.3% mIoU for Cityscapes → ACDC semantic segmentation.

TPSeNCE: Towards Artifact-Free Realistic Rain Generation for Deraining and Object Detection in Rain [Webpage] Dec. 2022 – Apr. 2023

- Introduce a Triangular Probability Similarity (TPS) loss based on GAN discriminator to minimize the artifacts and distortions during rain generation.
- Propose a Semantic Noise Contrastive Estimation (SeNCE) strategy based on patch similarity and semantic similarity to optimize the rain amount.
- Obtained the best results for rain generation (KID=72.19), rain removal (MUSIQ=61.853), and object detection (mAP50=52.6%) on BDD100K.

PointNorm: Dual Normalization is All You Need for Point Cloud Analysis [Webpage]

Jun. 2022 – Aug. 2022

- · Introduced PointNorm, a point cloud analysis network leveraging local mean and global standard deviation to boost loss and gradient stability.
- · Proposed a plug-and-play DualNorm that normalize sampled and grouped points to each other to optimize the point cloud density.
- Achieved superior results on shape classification at ScanObjectNN (OA = 86.8%), part segmentation at ShapeNetPart (Inst. mIoU = 86.2%).

AS-IntroVAE: Adversarial Similarity Distance Makes Robust IntroVAE [Slides]

Mar. 2022 - May. 2022

- $\bullet \ \ Introduced \ Adversarial \ Similarity \ Distance \ IntroVAE \ (AS-IntroVAE) \ to \ address \ posterior \ collapse \ and \ vanishing \ gradient \ in \ image \ generation.$
- Proposed Adversarial Similarity Distance (AS-Distance) using 2-Wasserstein distance, kernel trick, and batch-wise prior matching.
- Delivered superb results on image generation (FID=129.61) and reconstruction (PSNR=23.156) at CelebA with fast convergence (<20 epochs).

Semantic-Guided Zero-Shot Learning for Low-Light Image/Video Enhancement [Webpage]

Apr. 2021 - Jun. 2021

- · Proposed a semantic-guided, zero-shot, low-light image enhancement network that consolidates high-level semantics into low-level enhancement.
- Constructed a recurrent image enhancement network that only demands an enhancement factor map with five non-reference loss functions.
- Attained the state-of-the-art UNIQUE/BRISQUE (0.805/27.01), mIOU/mPA (65.87%/74.50%) and inference time (0.001s).

ACADEMIC ACTIVITIES

- Reviewer: AAAI 2022, IJCNN (2023-2025), ECCV 2024, WACV (2023-2025), CVPR 2025, ICCV 2025, TNNLS, IJCV.
- Co-Instructor, MATH 3291/3292: Computer Vision, Wenzhou-Kean University, Summer 2023 [Slides] [Recordings].
- Guest Speaker: Image Processing with Machine Learning, Fudan University, Spring 2021 [Slides].
- LeetCode Content Creator: Created 90+ LeetCode tutorial videos on YouTube, garnering over 40,000 views [Link].

SKILLS

- Languages: Python, C++, Java, R, Matlab, Shell, HTML, LaTeX, Markdown
- Frameworks & Tools: PyTorch, TensorFlow, Keras, MMCV, Docker, Git, ONNX, CUDA, Jupyter, Ubuntu
- Libraries: Scikit-Learn, NumPy, OpenCV, SciPy, Pandas, Matplotlib, Seaborn
- DL Models: CNN, RNN, GAN, VAE, Diffusion, Transformer