

An introduction to optimality

Statistical Consultary

SHENDUO ZHANG

Institute of Mathematics
Xi'an Jiaotong University

November 8, 2020

Summary

1 Minimavity

2 Admissibility

Minimaxity

Classical Linear Model

Linear model:

$$Y = X\beta + \xi, \xi \sim N(0, \sigma^2 I_V)$$

W, V linear space, $\beta \in W$, $X : W \mapsto V$, $Y, \xi \in V$, σ is known.



Gaussian shift model:

$$Y = \mu + \xi, \xi \sim N(0, \sigma^2 I_V)$$

$\mu = X\beta$, $\mu \in L = \text{Im}(X) \subset V$, σ is known.

Classical Linear Model

Linear model:

$$Y = X\beta + \xi, \xi \sim N(0, \sigma^2 I_V)$$

W, V linear space, $\beta \in W$, $X : W \mapsto V$, $Y, \xi \in V$, σ is known.



Gaussian shift model:

$$Y = \mu + \xi, \xi \sim N(0, \sigma^2 I_V)$$

$\mu = X\beta$, $\mu \in L = \text{Im}(X) \subset V$, σ is known.

Least square estimator

$$\hat{\beta} = \arg \min_{\beta \in W} \|Y - X\beta\|^2$$



$$\hat{\mu} = P_L Y = X\hat{\beta}$$



$$X^* X \hat{\beta} = X^* Y$$



$$\hat{\beta} \in X^+ Y + \ker(X)$$

where X^+ is the MP inverse.

Least square estimator

$$\hat{\beta} = \arg \min_{\beta \in W} \|Y - X\beta\|^2$$

$$\Downarrow$$

$$\hat{\mu} = P_L Y = X\hat{\beta}$$

$$\Downarrow$$

$$X^* X \hat{\beta} = X^* Y$$

$$\Downarrow$$

$$\hat{\beta} \in X^+ Y + \ker(X)$$

where X^+ is the MP inverse.

Least square estimator

$$\hat{\beta} = \arg \min_{\beta \in W} \|Y - X\beta\|^2$$

$$\Downarrow$$

$$\hat{\mu} = P_L Y = X\hat{\beta}$$

$$\Downarrow$$

$$X^* X \hat{\beta} = X^* Y$$

$$\Downarrow$$

$$\hat{\beta} \in X^+ Y + \ker(X)$$

where X^+ is the MP inverse.

Least square estimator

$$\hat{\beta} = \arg \min_{\beta \in W} \|Y - X\beta\|^2$$

$$\Downarrow$$

$$\hat{\mu} = P_L Y = X\hat{\beta}$$

$$\Downarrow$$

$$X^* X \hat{\beta} = X^* Y$$

$$\Downarrow$$

$$\hat{\beta} \in X^+ Y + \ker(X)$$

where X^+ is the MP inverse.

$\hat{\mu}$ is a good estimator

Theorem (Gauss-Markov)

Suppose $\langle Y, d \rangle$ for some $d \in V$ is a linear unbiased for linear functional $\langle \mu, c \rangle$, $\mu \in L$. Then,

$$\mathbf{Var}(\langle Y, d \rangle) \geq \mathbf{Var}(\langle \hat{\mu}, c \rangle), \mu \in L \quad (1)$$

and more over, $\langle \hat{\mu}, c \rangle$ is the unique linear unbiased estimator with the smallest possible variance.

General statistical framework

- 1 $(\mathcal{X}, \mathcal{F}, \mathbb{P}_\theta)$ where the data was drawn. \mathbb{P} is index by θ .
- 2 $\theta \in \Theta$ where θ is the estimation target, Θ is the candidate family.
- 3 $d(\cdot, \cdot) : \Theta \times \Theta \mapsto [0, \infty)$ is a semi-distance to judge the performance of estimation.

Risk of $\hat{\mu}$

Definition (Risk)

$$R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta}).$$

Definition (Maximum Risk)

$$r(\theta; \hat{\theta}) = \sup_{\theta \in \Theta} R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta})^2.$$

Risk is not accessible, maximum risk is with enough regulation.

$$R(\mu; \hat{\mu}) = r(\mu; \hat{\mu}) = \mathbb{E}_{\theta} \|\mu - \hat{\mu}\|^2 = \sigma^2 \dim(L). \quad (2)$$

Risk of $\hat{\mu}$

Definition (Risk)

$$R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta}).$$

Definition (Maximum Risk)

$$r(\theta; \hat{\theta}) = \sup_{\theta \in \Theta} R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta})^2.$$

Risk is not accessible, maximum risk is with enough regulation.

$$R(\mu; \hat{\mu}) = r(\mu; \hat{\mu}) = \mathbb{E}_{\theta} \|\mu - \hat{\mu}\|^2 = \sigma^2 \dim(L). \quad (2)$$

Risk of $\hat{\mu}$

Definition (Risk)

$$R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta}).$$

Definition (Maximum Risk)

$$r(\theta; \hat{\theta}) = \sup_{\theta \in \Theta} R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta})^2.$$

Risk is not accessible, maximum risk is with enough regulation.

$$R(\mu; \hat{\mu}) = r(\mu; \hat{\mu}) = \mathbb{E}_{\theta} \|\mu - \hat{\mu}\|^2 = \sigma^2 \dim(L). \quad (2)$$

Risk of $\hat{\mu}$

Definition (Risk)

$$R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta}).$$

Definition (Maximum Risk)

$$r(\theta; \hat{\theta}) = \sup_{\theta \in \Theta} R(\theta; \hat{\theta}) = \mathbb{E}_{\theta} d(\theta - \hat{\theta})^2.$$

Risk is not accessible, maximum risk is with enough regulation.

$$R(\mu; \hat{\mu}) = r(\mu; \hat{\mu}) = \mathbb{E}_{\theta} \|\mu - \hat{\mu}\|^2 = \sigma^2 \dim(L). \quad (2)$$

$\hat{\mu}$ is the best estimator

Theorem (Minimaxity of projection estimator)

\forall estimator $T(Y)$ of μ ,

$$\sup_{\mu \in L} \mathbb{E}_{\mu} \|T(Y) - \mu\|^2 \geq \sup_{\mu \in L} \mathbb{E}_{\mu} \|\hat{\mu} - \mu\|^2 = \sigma^2 \dim L. \quad (3)$$

In another words,

$$\sup_{\mu \in L} R(\mu; \hat{\mu}) = \inf_T \sup_{\mu \in L} R(\mu; T). \quad (4)$$

Definition (Minimax estimator)

An estimator T^* is called minimax estimator if

$$\sup_{\theta \in \Theta} R(\theta, T^*) = \inf_T \sup_{\theta \in \Theta} R(\theta, T) \quad (5)$$

$\hat{\mu}$ is the best estimator

Theorem (Minimaxity of projection estimator)

\forall estimator $T(Y)$ of μ ,

$$\sup_{\mu \in L} \mathbb{E}_{\mu} \|T(Y) - \mu\|^2 \geq \sup_{\mu \in L} \mathbb{E}_{\mu} \|\hat{\mu} - \mu\|^2 = \sigma^2 \dim L. \quad (3)$$

In another words,

$$\sup_{\mu \in L} R(\mu; \hat{\mu}) = \inf_T \sup_{\mu \in L} R(\mu; T). \quad (4)$$

Definition (Minimax estimator)

An estimator T^* is called minimax estimator if

$$\sup_{\theta \in \Theta} R(\theta, T^*) = \inf_T \sup_{\theta \in \Theta} R(\theta, T) \quad (5)$$

Reduction to finding Bayes estimator

Definition (Bayes risk)

Let T be an estimator of θ , $R(\theta; T)$ be the risk of T ,

$$R_{\Pi}(T) = \int_{\Theta} R(\theta; T) \Pi(d\theta) = \int_{\Theta} R(\theta; T) \pi(\theta) d\theta \quad (6)$$

is called the average risk with respect to prior Π .

Definition (Bayes estimator)

The estimator T_{Π} is Bayes estimator with respect to Π if and only if $\forall T$, estimator of θ , one has

$$R_{\Pi}(T) \geq R_{\Pi}(T_{\Pi}) \quad (7)$$

Reduction to finding Bayes estimator

Definition (Bayes risk)

Let T be an estimator of θ , $R(\theta; T)$ be the risk of T ,

$$R_{\Pi}(T) = \int_{\Theta} R(\theta; T) \Pi(d\theta) = \int_{\Theta} R(\theta; T) \pi(\theta) d\theta \quad (6)$$

is called the average risk with respect to prior Π .

Definition (Bayes estimator)

The estimator T_{Π} is Bayes estimator with respect to Π if and only if $\forall T$, estimator of θ , one has

$$R_{\Pi}(T) \geq R_{\Pi}(T_{\Pi}) \quad (7)$$

Definition (Bayes estimator)

The estimator T_{Π} is Bayes estimator with respect to Π if and only if $\forall T$, estimator of θ , let P_i be a probability distribution on Θ , one has

$$R_{\Pi}(T) \geq R_{\Pi}(T_{\Pi}) \quad (8)$$

Theorem

Suppose exists an estimator $T(\mathbf{X})$ and a sequence of prior distribution $\{\Pi_k\}$ such that

$$R_{\Pi_k}(T_{\Pi_k}) \rightarrow \sup_{\theta \in \Theta} R(\theta; T) \quad (k \rightarrow \infty) \quad (9)$$

Then T is a minimax estimator.

Reduction to finding Bayes estimator

Theorem

Suppose exists an estimator $T(\mathbf{X})$ and a sequence of prior distribution $\{\Pi_k\}$ such that

$$R_{\Pi_k}(T_{\Pi_k}) \rightarrow \sup_{\theta \in \Theta} R(\theta; T) \quad (k \rightarrow \infty) \quad (10)$$

Then T is a minimax estimator.

Proof.

\forall estimator \tilde{T} ,

$$\sup_{\theta \in \Theta} R(\theta; \tilde{T}) \geq R_{\Pi_k}(\tilde{T}) \geq R_{\Pi_k}(T_{\Pi_k}) \rightarrow \sup_{\theta \in \Theta} R(\theta; T) \quad (11)$$



Explicit construction of prior

$$\Pi_k \sim N(0, \tau_k^2 I_L), \tau_k^2 \rightarrow \infty \quad (12)$$

$$T_{\Pi_k}(Y) = \frac{\tau_k^2}{\sigma^2 + \tau_k^2} \hat{\mu} \quad (13)$$

$$R_{\Pi_k}(\mu; T_{\Pi_k}) = \frac{\tau_k^2}{\sigma^2 + \tau_k^2} \sigma^2 d + \left(\frac{\sigma^2}{\sigma^2 + \tau_k^2} \right)^2 \tau_k^2 d \rightarrow \sigma^2 d \quad (14)$$

$\hat{\mu}$ is not the best estimator

Theorem (James-Stein)

When $\dim L \geq 3$, there \exists an estimator $T(Y)$ of μ such that $\forall \mu \in L$,

$$\mathbb{E}_{\mu} \|T(Y) - \mu\|^2 < \mathbb{E}_{\mu} \|\hat{\mu} - \mu\|^2 = \sigma^2 \dim L \quad (15)$$

Admissibility

Admissible estimator

Definition (Admissible estimator)

An estimator $\hat{\theta}$ is called inadmissible if there $\exists T(Y)$ of θ such that

$$\mathbb{E}_{\theta} \|T(Y) - \theta\|^2 \leq \mathbb{E}_{\mu} \|\hat{\theta} - \theta\|^2 \quad (16)$$

with the strict inequality for some $\theta \in \Theta$. Otherwise, it's called admissible.

In another word, projection estimator $\hat{\mu}$ is an inadmissible estimator of linear model when $\dim L \geq 3$.

Admissible estimator

Definition (Admissible estimator)

An estimator $\hat{\theta}$ is called inadmissible if there $\exists T(Y)$ of θ such that

$$\mathbb{E}_{\theta} \|T(Y) - \theta\|^2 \leq \mathbb{E}_{\mu} \|\hat{\theta} - \theta\|^2 \quad (16)$$

with the strict inequality for some $\theta \in \Theta$. Otherwise, it's called admissible.

In another word, projection estimator $\hat{\mu}$ is an inadmissible estimator of linear model when $\dim L \geq 3$.

James-Stein

$$T(Y) = \hat{\mu} + \sigma^2 g(\hat{\mu}) \quad (17)$$

where $g : \mathbb{R}^d \mapsto \mathbb{R}^d$ is a smooth function.

Check its risk,

$$\begin{aligned} \mathbb{E}_{\mu} \|T(Y) - \mu\|^2 &= \mathbb{E}_{\mu} \|\hat{\mu} + \sigma^2 g(\hat{\mu}) - \mu\|^2 \\ &= \mathbb{E}_{\mu} \left(\|\mu - \hat{\mu}\|^2 + \sigma^4 \|g(\hat{\mu})\|^2 + 2\sigma^2 \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \right) \\ &= \mathbb{E}_{\mu} \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_{\mu} \|g(\hat{\mu})\|^2 + 2\sigma^2 \mathbb{E}_{\mu} \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \end{aligned}$$

James-Stein

$$T(Y) = \hat{\mu} + \sigma^2 g(\hat{\mu}) \quad (17)$$

where $g : \mathbb{R}^d \mapsto \mathbb{R}^d$ is a smooth function.

Check its risk,

$$\begin{aligned} \mathbb{E}_\mu \|T(Y) - \mu\|^2 &= \mathbb{E}_\mu \|\hat{\mu} + \sigma^2 g(\hat{\mu}) - \mu\|^2 \\ &= \mathbb{E}_\mu \left(\|\mu - \hat{\mu}\|^2 + \sigma^4 \|g(\hat{\mu})\|^2 + 2\sigma^2 \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \right) \\ &= \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^2 \mathbb{E}_\mu \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \end{aligned}$$

Stein lemma

Theorem (Stein identity)

Let $X \sim N(\theta, \sigma^2 I_d)$, let g be a differentiable function satisfying $\mathbb{E}|\nabla g(X)| < \infty$. Then

$$\mathbb{E}\langle g(X), X - \theta \rangle = \sigma^2 \mathbb{E} \nabla \cdot g(X) \quad (18)$$

Stein lemma

Proof.

In the case when $d = 1$,

$$\mathbb{E}g(X)(X - \theta) = \frac{1}{\sqrt{2\pi}\sigma} \int_{-\infty}^{\infty} g(x)(x - \theta)e^{-(x-\theta)^2/(2\sigma^2)} dx$$

Integration by parts,

$$\begin{aligned} \mathbb{E}g(X)(X - \theta) &= \frac{1}{\sqrt{2\pi}\sigma^2} \left[-\sigma^2 g(x) e^{-(x-\theta)^2/(2\sigma^2)} \right] \Big|_{-\infty}^{\infty} \\ &\quad + \sigma^2 \int_{-\infty}^{\infty} g'(x) e^{-(x-\theta)^2/(2\sigma^2)} dx \end{aligned}$$

The first term is 0 by writing g as integral of g' and apply bounded convergence theorem, and the second term is $\sigma^2 \mathbb{E}g'(X)$. □

James-Stein

$$T(Y) = \hat{\mu} + \sigma^2 g(\hat{\mu}) \quad (19)$$

$$R(\mu, T) = \mathbb{E}_{\mu} \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_{\mu} \|g(\hat{\mu})\|^2 \\ + 2\sigma^2 \mathbb{E}_{\mu} \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \quad (20)$$

$$\mathbb{E} \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle = \sigma^2 \mathbb{E} \nabla \cdot g(X) \quad (21)$$

$$\Downarrow$$

$$R(\mu, T) = \mathbb{E}_{\mu} \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_{\mu} \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (22)$$

James-Stein

$$T(Y) = \hat{\mu} + \sigma^2 g(\hat{\mu}) \quad (19)$$

$$R(\mu, T) = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 \\ + 2\sigma^2 \mathbb{E}_\mu \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle \quad (20)$$

$$\mathbb{E} \langle \mu - \hat{\mu}, g(\hat{\mu}) \rangle = \sigma^2 \mathbb{E} \nabla \cdot g(X) \quad (21)$$

$$\Downarrow$$

$$R(\mu, T) = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (22)$$

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (23)$$

$$g = \nabla \log \psi \quad (24)$$

ψ is a smooth, non-constant, positive function $\psi : \mathbb{R}^d \mapsto \mathbb{R}$.

We have the following equation

$$g(x) = \frac{\nabla \psi(x)}{\psi(x)} \quad (25)$$

$$\nabla \cdot g(x) = \frac{\Delta \psi(x) \psi(x) - \|\nabla \psi\|^2}{\psi^2(x)} = \frac{\Delta \psi(x)}{\psi(x)} - \|g(x)\|^2 \quad (26)$$

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta \psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (27)$$

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (23)$$

$$g = \nabla \log \psi \quad (24)$$

ψ is a smooth, non-constant, positive function $\psi : \mathbb{R}^d \mapsto \mathbb{R}$.

We have the following equation

$$g(x) = \frac{\nabla \psi(x)}{\psi(x)} \quad (25)$$

$$\nabla \cdot g(x) = \frac{\Delta \psi(x) \psi(x) - \|\nabla \psi\|^2}{\psi^2(x)} = \frac{\Delta \psi(x)}{\psi(x)} - \|g(x)\|^2 \quad (26)$$

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta \psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (27)$$

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (23)$$

$$g = \nabla \log \psi \quad (24)$$

ψ is a smooth, non-constant, positive function $\psi : \mathbb{R}^d \mapsto \mathbb{R}$.

We have the following equation

$$g(x) = \frac{\nabla \psi(x)}{\psi(x)} \quad (25)$$

$$\nabla \cdot g(x) = \frac{\Delta \psi(x) \psi(x) - \|\nabla \psi\|^2}{\psi^2(x)} = \frac{\Delta \psi(x)}{\psi(x)} - \|g(x)\|^2 \quad (26)$$

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta \psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (27)$$

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 + \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E} \nabla \cdot g(\hat{\mu}) \quad (23)$$

$$g = \nabla \log \psi \quad (24)$$

ψ is a smooth, non-constant, positive function $\psi : \mathbb{R}^d \mapsto \mathbb{R}$.

We have the following equation

$$g(x) = \frac{\nabla \psi(x)}{\psi(x)} \quad (25)$$

$$\nabla \cdot g(x) = \frac{\Delta \psi(x) \psi(x) - \|\nabla \psi\|^2}{\psi^2(x)} = \frac{\Delta \psi(x)}{\psi(x)} - \|g(x)\|^2 \quad (26)$$

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta \psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (27)$$

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta\psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (28)$$

- 1 $\sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 > 0$
- 2 $\psi : \mathbb{R}^d \mapsto \mathbb{R}$ that is smooth, positive
- 3 $\Delta\psi = 0$

In another words, we are interested to find a smooth harmonic function $\psi \neq \text{constant}$ and is positive.

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta\psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (28)$$

- 1 $\sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 > 0$
- 2 $\psi : \mathbb{R}^d \mapsto \mathbb{R}$ that is smooth, positive
- 3 $\Delta\psi = 0$

In another words, we are interested to find a smooth harmonic function $\psi \neq \text{constant}$ and is positive.

Choice of g

$$\mathbb{E}_\mu \|T(Y) - \mu\|^2 = \mathbb{E}_\mu \|\mu - \hat{\mu}\|^2 - \sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 + 2\sigma^4 \mathbb{E}_\mu \frac{\Delta\psi(\hat{\mu})}{\psi(\hat{\mu})} \quad (28)$$

- 1 $\sigma^4 \mathbb{E}_\mu \|g(\hat{\mu})\|^2 > 0$
- 2 $\psi : \mathbb{R}^d \mapsto \mathbb{R}$ that is smooth, positive
- 3 $\Delta\psi = 0$

In another words, we are interested to find a smooth harmonic function $\psi \neq \text{constant}$ and is positive.

Choice of g

When $d \geq 3$, such function ψ exists and satisfies for some $\mu \in \mathbb{R}^d$,

$$\mathbb{E}_\mu \|g(\hat{\mu})\| > 0. \quad (29)$$

Explicit form of JS-estimator

$$\psi(x) = \|x\|^{-(d-2)}. \quad (30)$$

$$T_{JS}(Y) = \hat{\mu} - (d-2) \frac{\sigma^2 \hat{\mu}}{\|\hat{\mu}\|} = \hat{\mu} \left(1 - \frac{\sigma^2 (d-2)}{\|\hat{\mu}\|^2} \right) \quad (31)$$

for $d > 2$.

Explicit form of JS-estimator

$$\psi(x) = \|x\|^{-(d-2)}. \quad (30)$$

$$T_{JS}(Y) = \hat{\mu} - (d-2) \frac{\sigma^2 \hat{\mu}}{\|\hat{\mu}\|} = \hat{\mu} \left(1 - \frac{\sigma^2 (d-2)}{\|\hat{\mu}\|^2} \right) \quad (31)$$

for $d > 2$.

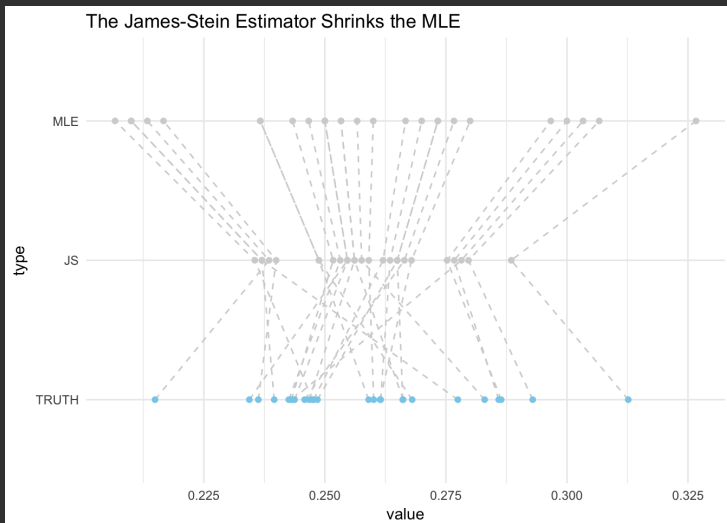
Risk of Jame-Stein

$$\mathbb{E}_{\mu} \|T_{JS} - \mu\|^2 = \sigma^2 d - \sigma^2 (d-2)^2 \mathbb{E} \frac{1}{\chi_{d, \frac{\|\mu\|}{\sigma}}^2} \quad (32)$$

where $\chi_{d, \frac{\|\mu\|}{\sigma}}^2$ is the non-central Chi-square distribution.

Projection estimator is indeed the best estimator.

Simulation



Reference



Stein, C. Inadmissibility of the usual estimator for the mean of a multivariate distribution. (1956).



Tsybakov, A. *Introduction to non-parametric estimation*. (Springer, 2003).



Wichura, M. J. *The coordinate-free approach to linear models*. (Cambridge Press, 2006).

The End