

# SHENGJUN(DANIEL) ZHANG

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B241, Department of Electrical Engineering, University of North Texas, Denton, TX 76207

## EDUCATION

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### **Doctor of Philosophy in Electrical Engineering (Minor in Business Management)**

January 2018 - Current

Department of Electrical Engineering, College of Engineering  
University of North Texas, GPA: 4.0/4.0

### **Master of Science in Electrical Engineering**

January 2015 - January 2017

Tandon School of Engineering  
New York University, GPA: 3.71/4.0

### **Bachelor of Science in *Automation of Honors Program***

September 2010 - June 2014

College of Information and Electrical Engineering  
China Agricultural University, GPA: 3.53/4.0

## SKILLS AND INTERESTS

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<b>Interests</b>	Control Theory, Non-linear Control, Robotics, Modeling and Simulation, Machine Learning, Deep Reinforcement Learning, Distributed Optimization, Connected Autonomous Vehicles.
<b>Design Software</b>	MATLAB, Python, TensorFlow, PyTorch, Java, C++, Embedded C, Linux, Assembly Language, Robot Operating System, V-Rep

## PROJECTS

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### **Applying Q-Learning to a $4 \times 4$ Tic-Tac-Toe**

March 2018 - April 2018

*Major Project as a part of curriculum*

- Reinforcement learning is essential for applications where there is no single correct way to solve a problem. In this project, I show that reinforcement learning is very effective at learning how to play the game Tic-Tac-Toe, despite the high-dimensional state. The agent is not given information about what the blocks or grids look like - it must learn these representations and directly use the reward and Q-values to develop an optimal strategy. The Q-agent uses basic Q-Learning algorithm, and shows that it is able to achieve super-human performance.

### **Mathematical Modeling and Analysis of a Hydro-pneumatic Suspension Column of a Car**

July 2015 - October 2015

*Minor Project as a part of curriculum*

- Modeled a 2-DOF system considering sprung and unsprung mass of the vehicle
- Performed sensitivity analysis to minimize the displacement of sprung and unsprung mass caused by vehicle hitting a bump using Transfer Function approach
- The settling time and displacement of the system were decreased using Hydro-pneumatic suspension system

### **Design and Thermal analysis of Disk Brake Rotor using ANSYS**

March 2016

*GT Motorsports, a Formula Student Team of GTU*

- Applied Energy Equation to calculate theoretical data for the input of simulation
- Devised boundary conditions for modeling the system by calculating including Heat power and Heat flux
- A Static thermal analysis in ANSYS Workbench using real time boundary conditions to obtain temperature distribution of Brake Rotor

### **Design, Development and Analysis of Exhaust System and Muffler assembly**

Sept 2015 - Jan 2016

*GT Motorsports, a Formula Student Team of GTU*

- Design and Development of complete muffler assembly for the reduction of noise under 110 dBC as per the rulebook
- Modeling and Acoustics analysis of muffler assembly in ANSYS to determine the Transmission Loss
- A CFD analysis of Exhaust Manifold using ANSYS Fluent to optimize the exhaust gas flow

## RESEARCH PUBLICATION

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Junfeng Wu, **Shengjun Zhang**, Tao Yang, Ling Shi, Hong Wang, “*Distributed Economic Dispatch over Networks with Markovian Communication Losses*”, the 37th Chinese Control Conference(CCC) **Accepted**. April 2018

## INTERNSHIP/TRAININGS

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<b>Automotive Industry Simulation Internship,</b> Expertshub,Sinhgad Institute of Engineering, Pune	June 2015
<b>Machining and Quality Control of Forged Connecting Rods,</b> Amul Group of Industries, Rajkot	February 2015

## POSITION OF RESPONSIBILITY

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<b>CAE and Powertrain Lead, Formula SAE</b> <i>GT Motorsports,a Formula Student Team of GTU</i>	August 2015 - Present
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- Devised the design objectives and validation of designs through simulations and testings
- Concentrated on real time simulation of Exhaust System and the noise reduction of Exhaust system
- Part of core Design group in the team helping with various design decisions
- Performed numerous simulations of various components of the car in the area of FEA and CFD segments with documentations

<b>Head coordinator of Mechanical section at Robotics club</b> <i>Sanjaybhai Rajguru College of Engineering</i>	July 2015 - May 2016
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- A college level Robotics club established by students with the aim of learning and professional skill development among students and peers
- Lead in Mechanical work of Robotics club, working mostly with CAD and Hardware systems
- Team leader and active member working to develop various robots of different concepts and configurations

## EXTRA-CIRRICULAR

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| • STTP on <b>Life Long Research</b> under TEQIP-II, SVNIT, Surat   | February 2016  |
| • Participated in <b>Formula Student India</b> , An International FSAE competition,<br>Secured 9th rank overall & 4th in Endurance | January 2016   |
| • Seminar on <b>Introduction to Robotics and Arduino Programming</b> , SRCOE,Rajkot  | July 2015      |
| • <b>Junkyard</b> , BRIZINGER'15, a National Level Techfest, GEC, Rajkot   | March-2015     |
| • Seminar on <b>Rapid Prototyping</b> , COGNIZANCE 2K14, a National Level Technical Festival,<br>CSPIT, Charotar                   | September-2014 |
| • <b>Rise of Machine</b> , PRAKARSH 9.0, a National Level Technical Symposium, SVIT, Vasad   | March-2014     |

## DECLARATION

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I hereby declare that all the details furnished above are true to the best of my knowledge and belief.