

Shengjun(Daniel) Zhang

RESEARCH ASSISTANT · STATISTICAL LEARNING

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Shengjun(Daniel) Zhang

"There is nothing more practical than a good theory."

Education

UNT (University of North Texas)

Ph.D. Major in Electrical Engineering

· Minor in Business Management

NYU (New York University)

M.S. IN ELECTRICAL ENGINEERING

• Robotic Control

CAU (China Agricultural University)

B.S. IN AUTOMATION OF HONORS PROGRAM

· Control Theory

Denton, Texas, U.S.A

Jan. 2018 - present

New York, New York, U.S.A

Jan. 2015 - Jan. 2017

Beijing, China

Sep. 2010 - Jul. 2014

Research Interests

Artificial Intelligence Statistical Learning, Machine Learning, Reinforcement Learning

Optimization Convex Optimization, Non-convex Optimization, Distributed Optimization

Power System DERs with Transactive Approaches

Professional Experience

University of North Texas.

RESEARCH/TEACHING ASSISTANT

Denton, Texas, U.S.A

Jan. 2018 - present

- Cyber-Physical Energy System Laboratory, Department of Electrical Engineering.
- · Supervisor: Dr. Colleen Bailey & Dr. Tao Yang.

Huazhong University of Science and Technology.

Wuhan, China

VISITING RESEARCHER May 2018 - Jul. 2018

- Key Laboratory of Image Processing and Intelligent Control of Education Ministry, School of Artificial Intelligence and Automation.
- Supervisor: Dr. Ye Yuan.

Zhejiang University.

Hangzhou, China

VISITING RESEARCHER

Jul. 2018 - Jul. 2018

- Group of Networked Sensing and Control, College of Control Science and Engineering.
- · Supervisor: Dr. Junfeng Wu.

Supervisor. Dr. Sumerig vva.

New York University.
RESEARCH ASSISTANT

New York, New York, U.S.A

Jan. 2016 - Jul. 2016

- Control/Robotics Research Laboratory, Tandon School of Engineering.
- Supervisor: Dr. Farshad Khorrami.

Research & Projects

Robust Optimization with Event Triggered Communication. UNT RESEARCH PROJECT Feb. 2019 - present Minimize a global cost function formed by a sum of local convex cost functions in a distributed way. • Develop a robust algorithm over an undirected and connected network. • The proposed algorithm is arbitrarily initialized unlike the exsiting algorithms. • The proposed algorithm is arbitrarily initialized unlike the exsiting algorithms. • This work has been submitted to the 58th IEEE Conference on Decision and Control. Analyzing Distributed Optimization Algorithms via IQC. LINT RESEARCH PROJECT Sep. 2018 - present Investigate the convergence rate of distributed push-pull based optimization algorithms in directed graph networks. Present a unified framework based on integral quadratic constaints (IQCs) from robust control theory. • Formulate convergence analysis problems into a semidefinite program (SDP). This work has been accepted by the 15th IEEE International Conference, and is in Best Student Paper Shorten List. Nonlinear System Identification via Sparse Bayesian Learning. UNT Course Project Oct. 2018 - Dec. 2018 • Reimplement Sparse Bayesian Learning Algorithm, proposed in A Sparse Bayesian Approach to The Identification of Nonlinear State-space Systems. • Apply such an algorithm to identify a pendulum model. Applying Q-Learning to a 4 \times 4 Tic-Tac-Toe. UNT Course Project Mar. 2018 - May 2018 • Implement Q-learning algorithm to a 4×4 Tic-Tac-Toe game. **UGV Integrated Mobile Platform.** NYU RESEARCH PROJECT Jan. 2016 - Jul. 2016 • Modele the UGV integrated mobile platform and simulated it via V-rep. • Implemente SLAM and control algorithms on the integrated mobile platform. Honors & Awards_ IEEE Outstanding Graduate Student, IEEE local event 2019 Denton, Texas, U.S.A 2019 College of Engeering Dean Tuition Scholarship, UNT Denton, Texas, U.S.A 2019 Toulouse Graduate School Scholarship, UNT Denton, Texas, U.S.A 2018 College of Engeering Dean Tuition Scholarship, UNT Denton, Texas, U.S.A 2018 Toulouse Graduate School Scholarship, UNT Denton, Texas, U.S.A 2nd prize, Physics Experiment Competition of colleges 2012 Beijing, China **Certifications** Stanford University Machine Learning, Instructor: Andrew Ng, license: NNBCAXYFA2HK. on Coursera Supervision Experiences _____ **Kelvin Darden** UNT M.S. STUDENT 2018 · Project on load shedding in Smart Grid. • First placement: engineer, Electric Reliability Council of Texas (ERCOT), Texas. **Teaching Experiences** Spring '19 EENG 2620 Signals and Systems, Teaching Assistant UNT Fall '18 **EENG 2620 Signals and Systems**, Teaching Assistant UNT Fall '18 **EENG 5940 Control and Optimization for Power Systems**, Teaching Assistant UNT

Professional Activities

Member IEEE Studnet Member, IEEE Young Professionals

Journal Reviewer IET Control Theory and Applications

Neurocomputing

Conference Reviewer IEEE Conference on Decision and Control (CDC)

IEEE International Conference on Control and Automation (ICCA)

Chinese Control Conference (CCC)

Publications

JOURNAL ARTICLES [1]

A Magnetic Nanoparticle Based Nucleic Acid Isolation And Purification Instrument for DNA Extraction of Escherichia coli O157: H7 Yahui Chen, Jianhan Lin, Qin Jiang, Qi Chen, Shengjun Zhang, Li Li

Journal of nanoscience and nanotechnology 16.3 (2016) pp. 2296–2300. American Scientific Publishers

2016

CONFERENCE PROCEEDINGS [2]

Distributed Online Convex Optimization with Long Term Coupled Constraints Xinlei Yi, Shengjun Zhang, Tao Yang, Junfeng Wu, Karl Henrik Johansson 38th Chinese Control Conference (CCC)

Guangzhou, China 2019

 $Computation all Convergence\ Analysis\ of\ Distributed\ Optimization\ Algorithms\ for\ Directed\ Graphs$

Shengjun Zhang, Xinlei Yi, Jemin George, Tao Yang 15th IEEE International Conference on Control and Automation (ICCA)

Edinburgh, Scotland

PRESENTED (UNPUBLISHED) [2]

Distributed Proportional-Integral Optimization Algorithms with Event-triggered Communication Wen Du, Xinlei Yi, Shengjun Zhang, Jemin George, Tao Yang

58th IEEE Conference on Decision and Control (CDC)

Under Review

2019

Event-Triggered Control for Consensus of Multi-Agent Systems with Nonlinear Output and Directed Topologies

Xinlei Yi, Shengjun Zhang, Tao Yang, Junfeng Wu, Karl Henrik Johansson

CoRR abs/1904.07022 (2019)

.URL: http://arxiv.org/abs/1904.07022

JULY 1, 2019