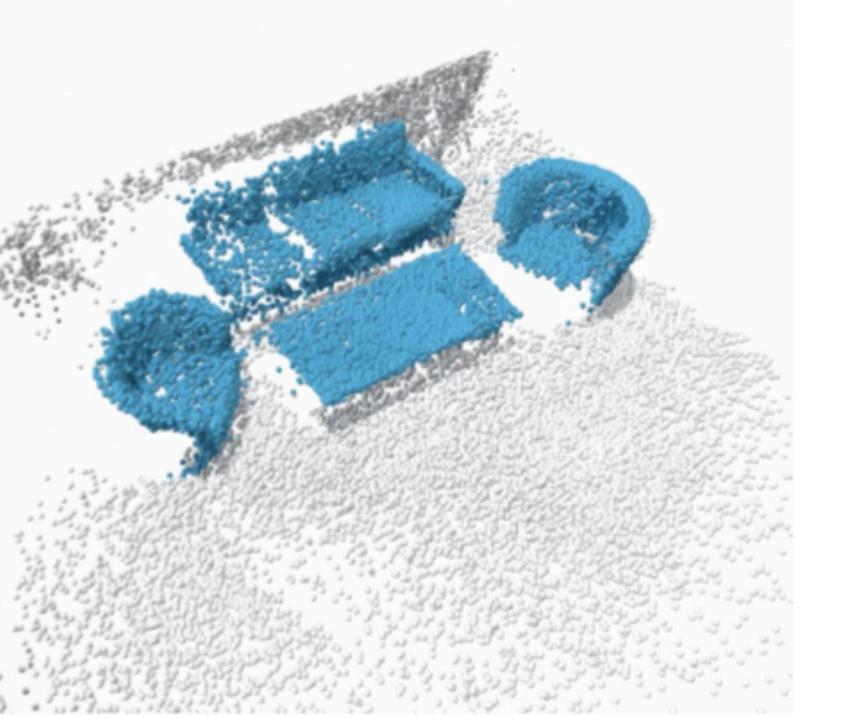
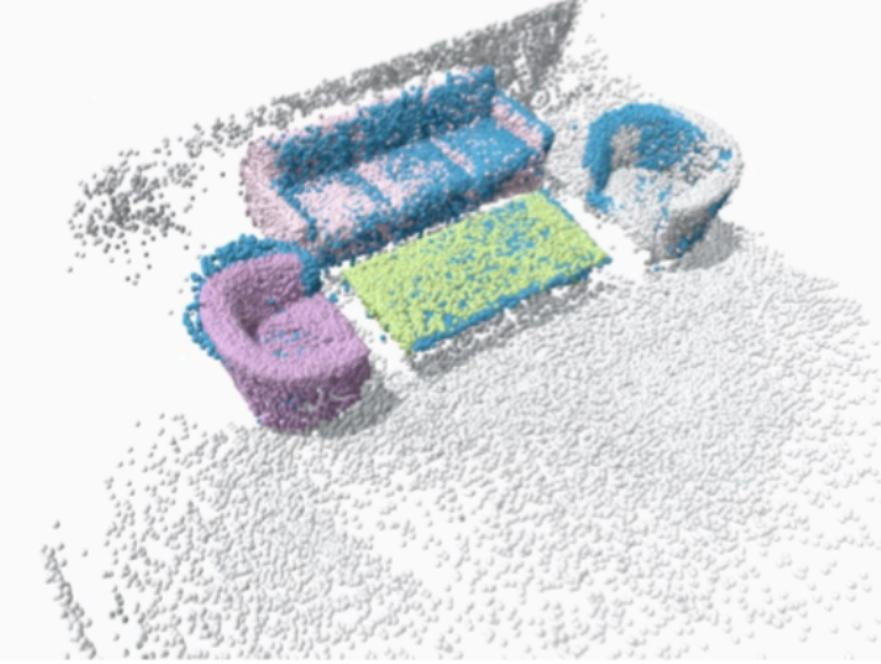


(a) Input point cloud **P** and **Q**



$$\xrightarrow{\{T_i\}}$$



(b) aligned point cloud