

Daily vocabulary: parametric form of solution to $Ax = \vec{b}$. Comparing the solutions to $Ax = \vec{0}$, $Ax = \vec{b}$, $Ax = \vec{c}$.

Warm Up

dot product

$$(-1)(1) + (2)(0) + (2)(-1) + (-1)(2) + (1)(1) = -4$$

1. Fill in the missing entry

$$\begin{bmatrix} 2 & -2 & -3 & 2 & -3 \\ 2 & -3 & 2 & 1 & -3 \\ -1 & 2 & 2 & -1 & 1 \\ -3 & -2 & -2 & 1 & -3 \\ 3 & 2 & -1 & 3 & 1 \\ -2 & 0 & 2 & -3 & -3 \\ -1 & -3 & 2 & -3 & -3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ -1 \\ -4 \\ 0 \\ 3 \\ -5 \\ -6 \end{bmatrix}$$

compute using dot product

2. "Compute" the product:

$$\begin{bmatrix} | & | & | & | \\ v_1 & v_2 & v_3 & v_4 \\ | & | & | & | \end{bmatrix} \begin{bmatrix} 3 \\ -1 \\ 5 \\ 2 \end{bmatrix} = \text{interpret as linear comb of columns of } A$$

$$= 3v_1 + (-1)v_2 + 5v_3 + 2v_4$$

3. If $A\vec{v} = \vec{b}$ and $A\vec{w} = \vec{d}$ then what are the following matrix-vector products?

$$A(2\vec{v}) = 2A\vec{v}$$

$$A(\vec{v} + \vec{w}) = A\vec{v} + A\vec{w}$$

$$A(5\vec{v} + 3\vec{w}) = 5A\vec{v} + 3A\vec{w}$$

$$A(c\vec{v}) = cA\vec{v}$$

4. A system equations of the form $Ax = \vec{0}$ is a *homogeneous* system of equation (when the right-hand side is 0). Otherwise, it is called a nonhomogeneous system of equations. Here are two homogeneous systems of equations and their row reductions. Describe the solution to each of them.

$$(a) \begin{bmatrix} 1 & 2 & 1 \\ 4 & 5 & 1 \\ 7 & 8 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} &\left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 4 & 5 & 1 & 0 \\ 7 & 8 & -1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & -3 & -3 & 0 \\ 0 & -6 & -8 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 3 & 4 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \\ &\rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \\ &\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$(b) \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 0 & -3 & -6 & 0 \\ 0 & -6 & -12 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{aligned} x_1 - x_3 &= 0 \\ x_2 + 2x_3 &= 0 \\ x_3 &\text{ free} \end{aligned}$$

$$\begin{aligned} x_1 &= x_3 = t \\ x_2 &= -2x_3 = -2t \\ x_3 &= \text{free} = t \end{aligned}$$

(c) Discuss: What can you say, in general, about homogeneous systems of equations? Eg., how many solutions can they have? What can you say about the corresponding vector equation?

parametriz: $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, t \in \mathbb{R}$

Parametric Solutions

5. Here is a matrix problem $Ax = \vec{b}$. Write out the corresponding system of equations and the corresponding vector problem.

$$\begin{bmatrix} 1 & 1 & -1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & -1 & 0 & 2 \\ 0 & 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 12 \\ 2 \\ 15 \\ 3 \end{bmatrix}$$

- (a) All three problems are solved by "augmenting and row reducing". Use the row reduction to write down the parametric solution to $Ax = \vec{b}$.

$$\left[\begin{array}{ccccc|c} 1 & 1 & -1 & 1 & 1 & 12 \\ 1 & 0 & 1 & 1 & 0 & 2 \\ 1 & 1 & -1 & 0 & 2 & 15 \\ 0 & 0 & 0 & -1 & 1 & 3 \end{array} \right] \rightarrow \left[\begin{array}{ccccc|c} 1 & 0 & 1 & 0 & 1 & 5 \\ 0 & 1 & -2 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 & -1 & -3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$x_1 = 5 - x_3 - x_5$$

$$x_2 = 10 + 2x_3 - x_5$$

$$x_3 = \text{free} = s$$

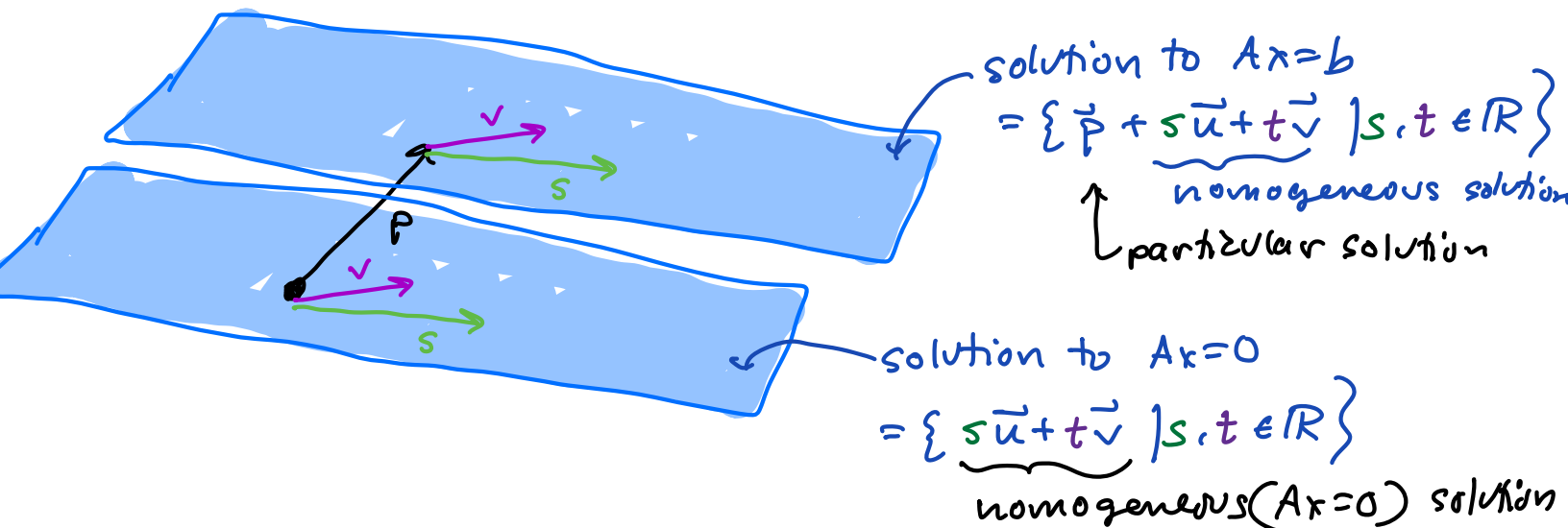
$$x_4 = -3 + x_5$$

$$x_5 = \text{free} = t$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 0 \\ -3 \\ 0 \end{bmatrix} + \begin{bmatrix} -s \\ 2s \\ s \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -t \\ -t \\ 0 \\ t \\ t \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 0 \\ -3 \\ 0 \end{bmatrix} + s \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad s, t \in \mathbb{R}$$

$\vec{p} \quad \vec{u} \quad \vec{v}$

- (b) Draw a picture of the geometry of this solution: It is a subset of \mathbb{R}^5 . Is it the empty set, a point, a line, a plane, a circle, a 3-dimensional space, a sphere, or something else?



- (c) Write down the parametric solution to $Ax = \vec{0}$ (the corresponding homogeneous equations).

$$s \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad s, t \in \mathbb{R}$$

$\vec{u} \quad \vec{v}$

- (d) Discuss the relation between your answers to part (a) and part (c).

parallel planes
in \mathbb{R}^5

6. True-False. Continued with the same problem.

$$A = \begin{bmatrix} 1 & 1 & -1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & -1 & 0 & 2 \\ 0 & 0 & 0 & -1 & 1 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 12 \\ 2 \\ 15 \\ 3 \end{bmatrix}, \quad \left[\begin{array}{ccccc|c} 1 & 1 & -1 & 1 & 1 & 12 \\ 1 & 0 & 1 & 1 & 0 & 2 \\ 1 & 1 & -1 & 0 & 2 & 15 \\ 0 & 0 & 0 & -1 & 1 & 3 \end{array} \right] \rightarrow \left[\begin{array}{ccccc|c} 1 & 0 & 1 & 0 & 1 & 5 \\ 0 & 1 & -2 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 & -1 & -3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Here are some true and false questions to discuss. See if you can also agree on *why* they are T or F.

(a) T **(F)** $Ax = \vec{d}$ has a solution for all right-hand sides $\vec{d} \in \mathbb{R}^4$

it might not have a solution

(b) **(T)** F If $Ax = \vec{d}$ has a solution, then it has infinitely many solutions.

has 2 free variables, so it consistent then ∞ solutions

(c) **(T)** F If \vec{p} and \vec{q} are both solutions to $Ax = \vec{b}$, then $\vec{p} - \vec{q}$ is a solution to $Ax = \vec{0}$.

$$A(\vec{p} - \vec{q}) = A\vec{p} - A\vec{q} = \vec{b} - \vec{b} = \vec{0} \quad \checkmark$$

(d) **(T)** F If \vec{p} and \vec{q} are both solutions to $Ax = \vec{b}$, then $\frac{1}{2}\vec{p} + \frac{1}{2}\vec{q}$ is a solution to $Ax = \vec{b}$.

$$A\left(\frac{1}{2}\vec{p} + \frac{1}{2}\vec{q}\right) = \frac{1}{2}A\vec{p} + \frac{1}{2}A\vec{q} = \frac{1}{2}\vec{b} + \frac{1}{2}\vec{b} = \vec{b} \quad \checkmark$$

7. Consider the matrix equation $Ax = \vec{b}$:

$$A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 0 & 3 & -1 \\ -1 & 1 & -5 & 1 \\ 1 & 2 & -1 & 1 \end{bmatrix}, \quad \text{and} \quad \vec{b} = \begin{bmatrix} 2 \\ 4 \\ -6 \\ 4 \end{bmatrix}$$

Create an R markdown file R to do the row-reduction. Here are R commands for defining A and \vec{b} and the augmented matrix:

```
A = cbind(c(1,1,-1,1),c(1,0,1,2),c(1,3,-5,-1),c(-1,-1,1,1))
```

```
b = c(2,4,-6,4)
```

```
Ab = cbind(A,b)
```

```
A
```

```
Ab
```

Remember that you need to include pracma to get rref:

```
require('pracma')
```

(a) Row reduce the matrix using rref. Write out the solution to $Ax = \vec{b}$ in parametric form.

(b) Find *two* specific, and different, solutions to $Ax = b$. Call them x_1 and x_2 . Name them x1 and x2 in R. Show that they are solutions to $Ax = \vec{b}$ by multiplying by A. The matrix-vector product in R is funny. You use the following syntax to do it.

```
A %*% x1
```

(c) Show, with a matrix-vector product, that $x_h = x_1 - x_2$ is a solution to the homogeneous equation $Ax = \vec{0}$.

(d) Are any of these vectors solutions to $Ax = \vec{b}$? Confirm with a matrix vector product:

i. $x_1 + x_2$

ii. $2x_1$

iii. $\frac{1}{2}x_1 + \frac{1}{2}x_2$

iv. $x_1 + 2021x_h$