1. Below is a subspace of \mathbb{R}^5 . Find a basis for S. And find the dimension of S.

$$S = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} \middle| \begin{array}{c} \mathbf{condition} \\ \mathbf{c} \\ \mathbf{c}$$

The vector $\vec{\mathbf{v}}$ is in S. Give its coordinates with respect to your

pordinates with respect to your basis.

(a)
$$\frac{1}{2}a + \frac{1}{2}b - c = 0$$

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(b) $\frac{1}{2}a + \frac{1}{2}b - c = 0$

(c) $\frac{1}{2}a + \frac{1}{2}b - c = 0$

(d) $\frac{1}{2}a + \frac{1}{2}b - c = 0$

(e) $\frac{1}{2}a + \frac{1}{2}b - c = 0$

(f) $\frac{1}{2}a + \frac{1}{2}b - c = 0$

(g) $\frac{1}{2}a + \frac{1}{2}a + \frac$

2. Below a matrix A is row reduced, and so is its transpose. Compute rank(A), nullity(A) and find bases for

The vectors below are in Col(A) Row(A) Nul(A). There is one vector in each. Which one is in which subspace?

$$\vec{\mathbf{u}} = \begin{bmatrix} 8 \\ -1 \\ -5 \\ -3 \\ 2 \end{bmatrix}, \qquad \vec{\mathbf{v}} = \begin{bmatrix} 13 \\ 26 \\ 0 \\ -15 \\ -33 \end{bmatrix}, \qquad \vec{\mathbf{w}} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}, \text{ Fow}$$

rank (A) = # pivots (A) = 3 = dim ((ol (A)) = dim (Row(A))

nullity (A) = # free vars

$$\mathcal{B}_{NW} = \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \right\}$$

parametriz solution tr=0

$$\mathcal{B}^{m_1} = \left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} -5 \\ -1 \\ 1 \end{bmatrix} \right\}$$

3. If A is 3×3 matrix, are either of the subsets below, subspaces of \mathbb{R}^3 ? Justify your answers.

$$S_1 = \{ ec{\mathsf{v}} \in \mathbb{R}^3 \mid A ec{\mathsf{v}} = - ec{\mathsf{v}} \}$$
 $S_2 = \{ ec{\mathsf{v}} \in \mathbb{R}^3 \mid A ec{\mathsf{v}} = \left[egin{array}{c} 1 \\ 1 \end{array}
ight] \}.$

$$A \left[egin{array}{c} \mathbf{g} \end{bmatrix} = \left[egin{array}{c} \mathbf{g} \end{bmatrix} \right]$$

- O des O if vives then vives O if ves then cues

4. Below is a basis of \mathbb{R}^3 . Let $\mathcal{S} = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ denote the standard basis. Find the missing change of coordinates for one of the examples at the right. For the other, describe two ways of finding the missing entries.

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} \right\}.$$

$$\mathcal{B} = \begin{bmatrix} 2 & -1 \\ 1 & -1 & -1 \end{bmatrix}$$

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$$\mathcal{B} = \begin{bmatrix} 3 \\ 2 \\ 1 & -1 & -1 \end{bmatrix}$$

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$$\mathcal{B} = \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} -3 \\ 2 \\ 1 \\ 2 \end{bmatrix}$$

- 5. See also: E2 review problems.
- 6. See also: PS6 problems.