

6.2. Orthogonal Sets

Example 1

Compute the dot product between all the vectors in this set:

$$S = \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 1 \\ 2 \end{bmatrix} \right\}$$

$$A = \begin{bmatrix} 1 & 1 & 3 & -1 \\ 1 & 2 & 1 & -1 \\ -1 & 3 & 1 & 1 \\ -1 & 4 & 3 & 2 \end{bmatrix}$$

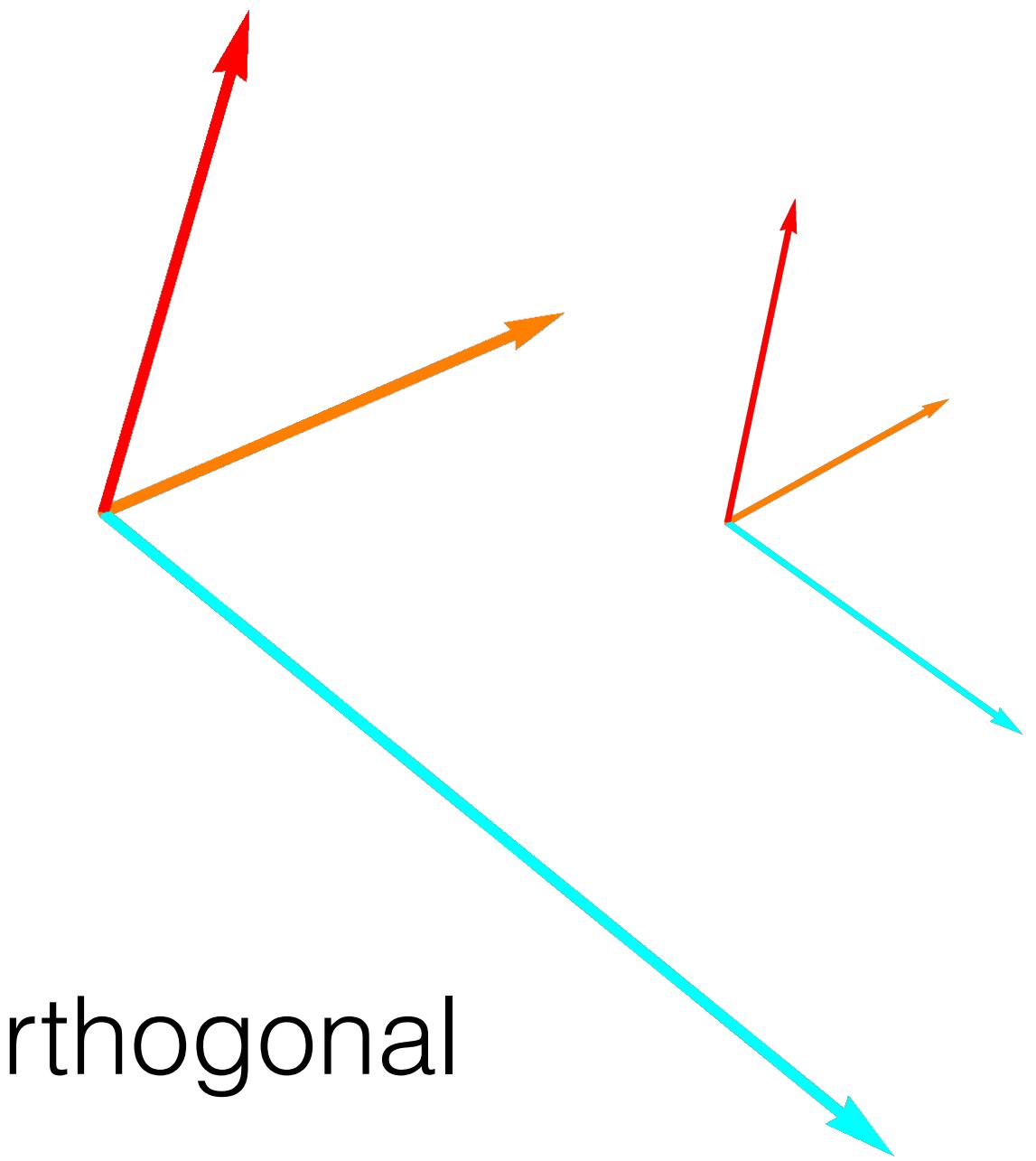
$$A^T A = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 1 & 1 & 3 \\ -1 & -1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 & -4 & 0 & -5 \\ -4 & 30 & 20 & 8 \\ 0 & 20 & 20 & 3 \\ -5 & 8 & 3 & 7 \end{bmatrix}$$

Example 2

Compute the dot product between all the vectors in this set:

$$\mathcal{S} = \left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

$$A^T A = \begin{bmatrix} 0 & -2 & 1 \\ -2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & -2 & 1 \\ 1 & -1 & -1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad \text{Mutually orthogonal}$$



$$\begin{bmatrix} 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ -2/\sqrt{6} & -1/\sqrt{6} & 1/\sqrt{6} \\ 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} 0 & -2/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & -1/\sqrt{3} \\ 1/\sqrt{2} & 1/\sqrt{6} & 1/\sqrt{3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{array}{l} \text{orthonormal} \\ AA^T = I \\ A^{-1} = A^T \end{array}$$

Orthogonal Sets

If $A = \begin{bmatrix} v_1 & v_2 & \dots & v_k \\ | & | & & | \end{bmatrix}$ Then

$$A^T A = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_k \end{bmatrix} \begin{bmatrix} v_1 & v_2 & \dots & v_k \\ | & | & & | \end{bmatrix} = \begin{bmatrix} v_i \cdot v_j \end{bmatrix}_{i,j}$$

Matrix of all
dot products
 $v_i \cdot v_j$

Orthogonal Sets

Def. A set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is **orthogonal** if $\mathbf{v}_i \cdot \mathbf{v}_j = 0$ for all $i \neq j$

The set is **orthonormal** if also $\mathbf{v}_i \cdot \mathbf{v}_i = 1$ for all i . That is, $\|\mathbf{v}_i\| = 1$.

- If the columns of $n \times n$ matrix \mathbf{A} are orthogonal, then $\mathbf{A}^T \mathbf{A} = \text{diagonal}$
- If the columns of $n \times n$ matrix \mathbf{A} are orthonormal, then $\mathbf{A}^T \mathbf{A} = \mathbf{I}$

Def. An $n \times n$ matrix with orthonormal columns is an **orthogonal matrix**

Orthogonal Sets are Nice

#1 They are linearly independent

- given an orthogonal set $\{v_1, v_2, \dots, v_k\}$
- suppose you have a dependence relation
- dot both sides with v_i
- do this for all i

$$\vec{o} = c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 + c_5 v_5$$

$$0 = v_4 \cdot \vec{o} = \underbrace{c_1(v_4 \cdot v_1)}_0 + \underbrace{c_2(v_4 \cdot v_2)}_0 + \underbrace{c_3(v_4 \cdot v_3)}_0 + \underbrace{c_4(v_4 \cdot v_4)}_{\|v_4\|^2} + \underbrace{c_5(v_4 \cdot v_5)}_0$$

$$0 = c_4 \|v_4\|^2$$

$$\Rightarrow c_4 = 0$$

Orthogonal Sets are Nice

- to find the coordinates c_1, c_2, \dots, c_n
- dot both sides with v_i
- do this for all i

#2 Nice way to find coordinates of vectors in the span.

$$w = c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 + c_5 v_5$$

$$v_4 \cdot w = \underbrace{c_1(v_4 \cdot v_1)}_0 + \underbrace{c_2(v_4 \cdot v_2)}_0 + \underbrace{c_3(v_4 \cdot v_3)}_0 + \underbrace{c_4(v_4 \cdot v_4)}_{\|v_4\|^2} + \underbrace{c_5(v_4 \cdot v_5)}_0$$

$$v_4 \cdot w = c_4 v_4 \cdot v_4$$

$$\Rightarrow c_4 = \frac{v_4 \cdot w}{v_4 \cdot v_4}$$

Coordinates in an orthogonal basis



Theorem

Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ be an **orthogonal basis** for \mathbb{R}^n . For any $\vec{w} \in \mathbb{R}^n$, we have

$$\vec{w} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \cdots + c_n \vec{v}_n$$

where

$$c_i = \frac{\vec{w} \cdot \vec{v}_i}{\vec{v}_i \cdot \vec{v}_i} = \frac{\vec{w} \cdot \vec{v}_i}{\|\vec{v}_i\|^2}.$$

Note: this formula for c_i only works when we have an **orthogonal basis!**

An **orthogonal basis** satisfies $\vec{v}_i \cdot \vec{v}_j = 0$ when $i \neq j$

When you do not have an orthogonal basis you: augment and row reduce

Example

- (a) Show that vectors below form an orthogonal basis of \mathbb{R}^n
 (b) Express the vector w as a linear combination of the basis vectors

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

$$\vec{w} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \frac{\vec{w} \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{\vec{w} \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} + \frac{\vec{w} \cdot \vec{v}_3}{\vec{v}_3 \cdot \vec{v}_3} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} + \frac{\vec{w} \cdot \vec{v}_4}{\vec{v}_4 \cdot \vec{v}_4} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}$$

$$= \frac{10}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{-2}{4} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} + \frac{-4}{4} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} + \frac{0}{4} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = \frac{5}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{-1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

You Try

One of the sets below is an orthogonal basis of \mathbb{R}^3

- (a) Figure out which one it is
- (b) And write w as a linear combination of the basis vectors

$$\mathcal{A} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\} \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix} \right\}$$

$$\vec{w} = \begin{bmatrix} -3 \\ 1 \\ -13 \end{bmatrix}$$