Project 1: Optimizing the Performance of a Pipelined Processor

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1 Introduction

Part A

In part A, we write three simple assembly programs to mimic three functions in example.c. Based on ensuring correctnessiijŇwe especially focus on the functional equivalence with the example C functions. By selecting and placing labels in the assembly code appropriately, the code is also very readable.

Part B

In part B, we modify the HCL file of the SEQ to add a new instruction — iaddl. The following is the roadmap to finish this part:

- Clarify the computation process of iadd and write it down at the beginning in seq-full.hcl.
- Add any dependence relations of iaddl to all boosigs.
- Design the datapath for iaddl (generate control signals for src and dst)

Part C

We achieve full scores in the benchmark testing **in just 2 hours**, but we **spent 2 more days** researching all the potential methods to optimize the performance even further. The following is our roadmap:

- Change the order of the instruction sequence to avoid data hazard and structure hazards, which leaves CPI = 12.96.
- ullet Beyond the changes on instructions order, we use loop unrolling to reduce the number of conditional check and registers updating, which leaves CPI=9.83
- \bullet Use a binary search tree to find the precise remaining number of loops after several rounds of unrolling to achieve complete unrolling, which leaves CPI=8.95
- Modify the HCL file to achieve 100% accuracy in branch prediction for certain code pattern, which brings *CPI* down to 7.78.

Contribution

Ziqi Zhao : Part A (coding) & Part B (coding) & Part C (coding & designing)

Yimin Zhao: Part A (reviewing) & Part B (reviewing) & Part C (designing) & project

report

2 Experiments

2.1 Part A

2.1.1 Analysis

In this part, we are asked to implement and simulate three y86 programs. From a macro point of viewïijŇthis part is relatively easy. But there are plenty of optimizations worth exploring in terms of code readability and elegance.

Difficult Point

- Always pull the correct element from the stack.
- Be careful to protect the callee-save register.
- Implement function recursion smartly.

Core Techniques

- Mimicking C functions, division of functional areas with enough and clear label.
- Get the fastest completion speed by coding line by line referring to C language functions
- Always draw a picture of the stack to ensure the correctness of fetching a variable.

2.1.2 Code

sum.ys

```
# 518030910211 ZiqiZhao
2
    # 518030910188 YiminZhao
3
4
    # Set up stack
5
            .pos
                    0
6
            irmovl
                    stack,
                             %esp
7
            rrmovl %esp,
                             %ebp
8
            pushl
                    %edx
                                     # save %edx
9
            irmovl ele1,
                             %eax
10
            pushl
                    %eax
11
            call
                    sum_list
12
            popl
                    %edx
                                     # flatten the stack for ele1
```

```
13
            popl
                                     # restore %edx
                    %edx
14
            halt
15
   # Sample linked list
16
17
    .align 4
18
    ele1:
19
            .long
                    0x00a
20
            .long
                    ele2
21
    ele2:
22
                    0x0b0
            .long
23
            .long
                    ele3
24
   ele3:
25
                    0xc00
            .long
26
            .long
                    0
27
28
    # sum_list func
29
    sum_list:
30
            pushl
                                     # enter
                    %ebp
31
                                     # save %ecx
            pushl
                    %ecx
32
            rrmovl %esp,
                             %ebp
33
            xorl
                                     # clear %eax
                    %eax,
                             %eax
34
            mrmovl 12(%ebp),%edx
                                     # get ls
35
                    test
            jmp
36
    loop:
37
            mrmovl (%edx), %ecx
38
            addl
                    %ecx,
                            %eax
39
            mrmovl 4(%edx),%edx
40
    test:
41
            andl
                    %edx,
                             %edx
42
                                     # %edx != 0
            jne
                    loop
43
    return:
44
            rrmovl %ebp,
                             %esp
                                     # leave
45
            popl
                    %ecx
46
            popl
                    %ebp
47
            ret
48
49
    # Stack
50
                    0x400
             .pos
51
    stack:
```

rsum.ys

```
# 518030910211 ZiqiZhao
 1
 2
    # 518030910188 YiminZhao
 3
 4
    # Set up stack
 5
        .pos
 6
        irmovl stack, %esp
 7
        rrmovl %esp, %ebp
 8
        pushl
                %edx
 9
        irmovl ele1, %eax
10
        pushl
                %eax
11
                rsum_list
        call
12
        popl
                %edx
                                # eat ele1
13
        popl
                %edx
                                # restore %edx
14
        halt
15
16
    # Sample linked list
17
    .align 4
18
    ele1:
19
        .long
                0x00a
20
        .long
                ele2
21
    ele2:
22
        .long
                0x0b0
23
        .long
                ele3
24
    ele3:
25
        .long
                0xc00
26
        .long
27
28
    # rsum_list func
29
    rsum_list:
30
        pushl
                %ebp
                                 # enter
31
        rrmovl %esp, %ebp
32
        xorl
                %eax, %eax
33
        mrmovl 8(%ebp), %edx
                                 # get ls
34
        andl
                %edx, %edx
35
        jе
                 return
                                 # ls == NULL
36
    do:
37
        pushl
                %ebx
                                 # save %ebx
38
        mrmovl (%edx), %ebx
                                 # mov ls->val to %ebx
39
        mrmovl 4(%edx), %eax
40
                                 # push ls->next
        pushl
                %eax
41
        call
                rsum_list
42
        addl
                %ebx, %eax
                                 # ret = val + ret
43
        popl
                %edx
                                 # eat para
44
        popl
                %ebx
                                 # restore %ebx
```

```
45
    return:
46
        rrmovl
                %ebp, %esp
                                 # leave
47
        popl
                 %ebp
48
        ret
49
50
51
    # Stack
52
         .pos
                 0x400
53
    stack:
```

copy.ys

```
# 518030910211 ZiqiZhao
 1
 2
    # 518030910188 Yimin Zhao
 3
 4
    # Set up stack
 5
        .pos
 6
        irmovl stack, %esp
 7
        rrmovl
                %esp, %ebp
 8
        irmovl $3, %eax
 9
        pushl
                %eax
10
        irmovl src, %eax
11
        pushl
                %eax
12
        irmovl dest, %eax
13
        pushl
                %eax
14
        call
                copy_block
15
        halt
    .align 4
16
17
    # Source block
18
    src:
19
        .long 0x00a
20
        .long 0x0b0
21
        .long 0xc00
22
23
    # Destination block
24
    dest:
25
        .long 0x111
26
        .long 0x222
27
        .long 0x333
28
29
    copy_block:
30
        pushl
                %ebp
31
        rrmovl %esp, %ebp
32
        pushl
                %ecx
33
        pushl
                %edx
```

```
34
        pushl
                %edi
35
        irmovl $0, %eax
                                 # %eax = result = 0
36
        mrmovl 16(%ebp), %ecx
                                 # %ecx = len
37
        mrmovl 12(%ebp), %edx
                                 # %edx = src
38
        mrmovl 8(%ebp), %edi
                                 # %edi = dest
39
        jmp
                while_loop
40
41
    while_loop:
42
        andl
                %ecx, %ecx
                                 # check if %ecx == 0?
43
        jle
                return
                                 # if so, jump to "return"
44
        mrmovl (%edx), %esi
                                 # %esi = val = *src
45
                                 \# %ebx = 4
        irmovl $4, %ebx
46
                %ebx, %edx
                                 # src++
        addl
47
        rmmovl %esi, (%edi)
                                 # *dest = val
                                 # dest++
48
                %ebx, %edi
        addl
49
                %esi, %eax
        xorl
50
        irmovl $-1, %ebx
51
                                 # len--
        addl
                %ebx, %ecx
52
        jmp
                while_loop
53
54
    return:
55
        popl
                %edi
56
                %edx
        popl
57
        popl
                %ecx
58
        rrmovl
                %ebp, %esp
59
        popl
                %ebp
60
        ret
61
    # Stack
62
        .pos
                0x400
63
    stack:
```

2.1.3 Evaluation

sum.ys

```
./yas sum.ys
../yis sum.yo
Stopped in 36 steps at PC = 0x1b. Status 'HLT', CC Z=1 S=0 0=0
Changes to registers:
%eax: 0x00000000
                       0x00000cba
                       0x00000400
      0x00000000
%esp:
                       0x00000400
      0x00000000
Changes to memory:
0x03f0: 0x00000000
                       0x00000400
0x03f4: 0x00000000
                       0x00000017
0x03f8: 0x00000000
                       0x0000001c
```

Figure 1: partA-sum.ys

- The %eax register has the correct value which is the return value of the function—0xcba.
- The memory is not corrupted since all the modifications locate at the stack whose starting addresss is set to be 0x400.

rsum.ys

```
../yas rsum.ys
../yis rsum.yo
Stopped in 69 steps at PC = 0x1b. Status 'HLT', CC Z=0 S=0 0=0
Changes to registers:
%eax: 0x00000000
                      0x00000cba
%esp: 0x00000000
                    0x00000400
%ebp: 0x00000000
                      0x00000400
Changes to memory:
0x03c0: 0x00000000
                      0x000003d0
0x03c4: 0x00000000 0x0000005c
0x03cc: 0x00000000 0x000000b0
0x03d0: 0x00000000 0x000003e0
0x03d4: 0x00000000 0x0000005c
0x03d8: 0x00000000 0x0000002c
0x03e0: 0x00000000 0x000003f0
0x03e4: 0x00000000
                      0x0000005c
0x03e8: 0x00000000
                      0x00000024
0x03f0: 0x00000000
                      0x00000400
0x03f4: 0x00000000
                      0x00000017
0x03f8: 0x00000000
                     0x0000001c
```

Figure 2: partA-rsum.ys

- The %eax register has the correct value which is the return value of the function—0xcba.
- The memory is not corrupted since all the modifications locate at the stack whose starting addresss is set to be 0x400.

copy.ys

```
./yas copy.ys
../yis copy.yo
Stopped in 61 steps at PC = 0x25. Status 'HLT', CC Z=1 S=0 0=0
Changes to registers:
%eax: 0x00000000
                      0x00000cba
      0x00000000
                      0xffffffff
%ebx:
%esp:
      0x00000000
                      0x000003f4
      0x00000000
                      0x00000400
%ebp:
      0x00000000
                      0x00000c00
%esi:
Changes to memory:
0x0034: 0x00000111
                      0x0000000a
0x0038: 0x00000222
                      0x000000b0
0x003c: 0x00000333
                      0x00000c00
0x03ec: 0x00000000
                      0x00000400
0x03f0: 0x00000000
                      0x00000025
0x03f4: 0x00000000
                      0x00000034
0x03f8: 0x00000000
                      0x00000028
0x03fc: 0x00000000
                      0x00000003
```

Figure 3: partA-copy.ys

- The %eax register has the correct value which is the return value of the function—0xcba.
- Values are written into the memory correctly as shown in the first three rows in the "Changes to memory" part in Figure 3
- The memory is not corrupted since all the modifications other than 3 source values locate at the stack whose starting addresss is set to be 0x400.

2.2 Part B

2.2.1 Analysis

In part B, we are asked to extend the SEQ processor to support instruction "iaddl" by modifying SEQ-full.hcl. Once we understand the processing logic and HCL syntax of the y86 seq processor, the problem becomes very simple. We can do it in five minutes because all we need to do is change the followings in the HCL

 Add "IIADDL" in the choices region of (bool) instr_valid since iaddl is a valid instruction.

- Add "IIADDL" in the choices region of (bool) need_regid since iaddl operation involves one register.
- Add "IIADDL" in the choices region of (bool) need_valC since iaddl operation involves one constend(represented by valC in the circuit of y86 SEQ).
- Add "IIADDL" in the choices region of (bool) set_cc since iaddl operation involves ALU operation which will set flags.
- When icode is IIADDL, alufun will be ALUADD since the operation is "adding" the constand to rB.
- When icode is IIADDL, srcB is from rB since the second operand of iaddl is a register.
- When icode is IIADDL, dstE (where the result from ALU is passed towards) is rB since "iaddl constant, rB" means rB += constant (rB is updated).
- When icode is IIADDL, aluA (the first op) is valC (the constant in the instruction) since "iaddl constant, rB" means the first op is the constant (valC).
- When icode is IIADDL, aluB (the second op) is valB (the value of the second register that is read) for the same reason above.

[In this part, you should give an overall analysis for the task, like difficult point, core technique and so on.]

2.2.2 Code

Modifications in SEQ-full.hcl

```
1
 2
   |bool instr_valid = icode in
3
   { INOP, IHALT, IRRMOVL, IIRMOVL, IRMMOVL, IMRMOVL,
4
         IOPL, IJXX, ICALL, IRET, IPUSHL, IPOPL, IIADDL };
5
6
   # Does fetched instruction require a regid byte?
7
   bool need_regids =
8
           icode in { IRRMOVL, IOPL, IPUSHL, IPOPL,
9
                  IIRMOVL, IRMMOVL, IMRMOVL, IIADDL };
10
   |-----
11
   # Does fetched instruction require a constant word?
12
   bool need_valC =
13
           icode in { IIRMOVL, IRMMOVL, IMRMOVL, IJXX, ICALL, IIADDL };
14
15
   ## What register should be used as the B source?
16
   int srcB = [
17
           icode in { IOPL, IRMMOVL, IMRMOVL, IIADDL } : rB;
```

```
18
         icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
19
         1 : RNONE; # Don't need register
20 | ];
21
  |-----
  ## What register should be used as the E destination?
23
   int dstE = [
24
         icode in { IRRMOVL } && Cnd : rB;
25
         icode in { IIRMOVL, IOPL, IIADDL } : rB;
26
         icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
27
         1 : RNONE; # Don't write any register
28
  ];
29
30
   ## Select input A to ALU
31
  int aluA = [
32
         icode in { IRRMOVL, IOPL } : valA;
33
         icode in { IIRMOVL, IRMMOVL, IMRMOVL, IIADDL } : valC;
34
         icode in { ICALL, IPUSHL } : -4;
35
         icode in { IRET, IPOPL } : 4;
36
         # Other instructions don't need ALU
37
  ];
38
   ______
39
   ## Select input B to ALU
40
  int aluB = [
41
         icode in { IRMMOVL, IMRMOVL, IOPL, ICALL,
42
               IPUSHL, IRET, IPOPL, IIADDL } : valB;
43
         icode in { IRRMOVL, IIRMOVL } : 0;
44
         # Other instructions don't need ALU
45
  ];
46
   -----
  ## Set the ALU function
47
  int alufun = [
49
         icode == IOPL : ifun;
50
         icode == IIADDL : ALUADD;
51
         1 : ALUADD;
52 ];
53
   ______
  ## Should the condition codes be updated?
55 | bool set_cc = icode in { IOPL, IIADDL };
   ______
```

2.2.3 Evaluation

```
* eng tit (master) # of __/y86_-code && make testssim
./deg(sis = t_asum_y > asum_seq
./deg(sis = t_jrcy > ) asum_seq
./deg(sis = t_jrcy > ) asum_seq
./deg(sis = t_jrcy > ) - cc.seq
./deg(sis = t_jrcy > ) - cc.seq
./deg(sis = t_pushtesty > y progl.seq
./deg(sis = t_pushtesty > y progl.seq
./deg(sis = t_progl.y > ) - progl.seq
./deg(sis = t_pr
```

Figure 4: part B benchmark test

```
→ ptest git:(master) x make SIM=../seq/ssim
./optest.pl -s ../seq/ssim
Simulating with ../seq/ssim
All 49 ISA Checks Succeed
./jtest.pl -s ../seq/ssim
Simulating with ../seq/ssim
All 64 ISA Checks Succeed
./ctest.pl -s ../seq/ssim
Simulating with ../seq/ssim
All 22 ISA Checks Succeed
./htest.pl -s ../seq/ssim
Simulating with ../seq/ssim
Simulating with ../seq/ssim
All 600 ISA Checks Succeed
→ ptest git:(master) x
```

Figure 5: part B regression test

```
→ ptest git:(master) X cd .../ptest && make SIM=../seq/ssim TFLAGS=-i
./optest.pl -s ../seq/ssim
-i
Simulating with ../seq/ssim
All 58 ISA Checks Succeed
./jtest.pl -s ../seq/ssim
All 96 ISA Checks Succeed
./ctest.pl -s ../seq/ssim
-i
Simulating with ../seq/ssim
All 22 ISA Checks Succeed
./htest.pl -s ../seq/ssim
-i
Simulating with ../seq/ssim
All 756 ISA Checks Succeed
-> ptest git:(master) X
```

Figure 6: part B iaddl test

2.3 Part C

2.3.1 Analysis

In this part, we were asked to speed up the program ncopy.ys as much as possible by modifying the ncopy.ys and HCL. The following is our roadmap:

Avoid Load and Use: $CPI \rightarrow 12.96$

For the pipeline design in CS:APP 2e, "load and use" or "mrmovl" then "rmmovl" will cause penalty, which must be avoided to improve the performance. On the one hand, we rearranged the order of instructions to avoid stalling as much as possible. On the other hand, we use two registers to store the variable "val", loading them separately and ahead of time.

10-way Loop Unrolling: CPI \rightarrow 9.83

There's much overhead in testing and updating procedure of loops, and one way to minimize it is to perform a technique named "loop unrolling". That is, we do multiple loops and update the relevant data at once, to reduce the number of times we execute the 'add' and 'jxx' instructions.

Search Tree for Remaining Elements: $CPI \rightarrow 8.95$

For large inputs, the more ways we unroll the loops, the better the program performs. However, for small inputs, it is important to choose a good method to process the remaining elements. The simplest way is to write another loop for them, but a much better way is to totally unroll the code, that is, jump to different position for different number of remaining ones. Since Y86 does not support relative jump instruction, we designed a search tree to get the correct jump destination for each possibility.

The above optimization took us two hours, so far we have reached full marks But **can** it be even faster? We spent another two days poring over the implementation logic and HCL and other files of the y86 pipeline. And it finally gets us here:

Optimized for Our Branch Prediction Design: $CPI \rightarrow 7.78$

For this program, a significant performance factor is the branch prediction failure for count++. In "pipe-zzcc.hcl", we made a special optimization for the situation like this:

Instruction:	any instruction	non-alu instruction	jxx
Stages:	EX	ID	IF

Note that in this case, we can forward the conditions from EX stage to IF and predict the branch with 100% accuracy. Thus, we optimized the program to ensure that there were as many of these patterns as possible and took much advantage of it, which leads to an average CPE of 7.78.

2.3.2 Code

——10-Way Loop Unrolling——

```
1
    # Entry
 2
            iaddl $-9, %edx
                                     # len -= 9, i.e., initial_len <= 9?
 3
            irmovl $0, %eax
                                     \# count = 0
 4
            jle Remaining
                                     # if so, goto Remaining
 5
 6
    # Loop unrolling part
7
    Loop0:
 8
            mrmovl (%ebx), %esi
                                     \# valA = src[0]
 9
            mrmovl 4(%ebx), %edi
                                     \# valB = src[1]
10
            andl %esi, %esi
                                     # valA <= 0?
11
                                     \# dst[0] = valA
            rmmovl %esi, (%ecx)
12
            jle Loop1
                                     # if so, goto next loop
13
            iaddl $1, %eax
                                     # count++
14
    Loop1:
15
            mrmovl 8(%ebx), %esi
                                     \# valA = src[2]
16
            andl %edi, %edi
                                     # valB <= 0?
17
            rmmovl %edi, 4(%ecx)
                                     \# dst[1] = valB
18
            jle Loop2
                                     # if so, goto next loop
19
            iaddl $1, %eax
                                     # count++
20
    Loop2:
21
            mrmovl 12(%ebx), %edi
                                     \# valB = src[3]
22
            andl %esi, %esi
                                     # valA <= 0?
23
            rmmovl %esi, 8(%ecx)
                                     \# dst[2] = valA
24
            jle Loop3
                                     # if so, goto next loop
25
            iaddl $1, %eax
                                     # count++
26
    Loop3:
27
            mrmovl 16(%ebx), %esi
                                     \# valA = src[4]
28
            andl %edi, %edi
                                     # valB <= 0?
29
                                     \# dst[3] = valB
            rmmovl %edi, 12(%ecx)
30
            jle Loop4
                                     # if so, goto next loop
                                     # count++
31
            iaddl $1, %eax
32
    Loop4:
33
            mrmovl 20(%ebx), %edi
                                     \# valB = src[5]
34
                                     # valA <= 0?
            andl %esi, %esi
35
            rmmovl %esi, 16(%ecx)
                                     \# dst[4] = valA
36
            jle Loop5
                                     # if so, goto next loop
            iaddl $1, %eax
37
                                     # count++
38
    Loop5:
39
            mrmovl 24(%ebx), %esi
                                     \# valA = src[6]
40
            andl %edi, %edi
                                     # valB <= 0?
41
            rmmovl %edi, 20(%ecx)
                                     \# dst[5] = valB
42
            jle Loop6
                                     # if so, goto next loop
43
            iaddl $1, %eax
                                     # count++
44
    Loop6:
45
            mrmovl 28(%ebx), %edi # valB = src[7]
```

```
46
                                     # valA <= 0?
            andl %esi, %esi
47
                                   # dst[6] = valA
            rmmovl %esi, 24(%ecx)
48
            ile Loop7
                                     # if so, goto next loop
49
            iaddl $1, %eax
                                     # count++
50
    Loop7:
51
                                    \# valA = src[8]
            mrmovl 32(%ebx), %esi
52
            andl %edi, %edi
                                     # valB <= 0?
53
                                     \# dst[7] = valB
            rmmovl %edi, 28(%ecx)
54
                                     # if so, goto next loop
            jle Loop8
55
            iaddl $1, %eax
                                     # count++
56
    Loop8:
57
            mrmovl 36(%ebx), %edi # valB = src[9]
58
            andl %esi, %esi
                                     # valA <= 0?
59
                                    \# dst[8] = valA
            rmmovl %esi, 32(%ecx)
60
            jle Loop9
                                     # if so, goto next loop
61
            iaddl $1, %eax
                                     # count++
62
    Loop9:
63
                                     # valB <= 0?
            andl %edi, %edi
64
            rmmovl %edi, 36(%ecx)
                                    \# dst[9] = valB
65
            ile LoopEnd
                                     # if so, goto loop end
66
            iaddl $1, %eax
67
    LoopEnd:
68
            iaddl $40, %ecx
                                     \# dst += 10 * 4
69
            iaddl $40, %ebx
                                     \# src += 10 * 4
70
                                     # len -= 10
            iaddl $-10, %edx
71
            jg Loop0
                                     # if so, goto Loop0
72
                                     # else, goto process remaining elements
```

—Binary Search Tree for Finding the Number of Remaining Loops—

```
# The following block is a binary search tree to
   # find the number of remaining loops
   # (which must be less than 10) at minimal cost
4
   Remaining:
5
            iaddl $6, %edx
                                    # [-9,0] -> [-3,6]
                                                             (+3)
    RemTest:
7
            irmovl $0, %esi
8
            jg RemTestR
9
            je Rem3
10
    RemTestL:
11
            iaddl $2, %edx
                                    # [-3,-1] -> [-1,1]
                                                             (+1)
12
            je Rem1
13
            jg Rem2
14
                                     # -1 + 1 = 0
            jmp Done
15 | RemTestR:
```

```
16
                                     # [1,6] -> [-2,3]
            iaddl $-3, %edx
                                                               (+6)
17
            jg RemTestRR
18
            ie Rem6
19
    RemTestRL:
20
            iaddl $1, %edx
                                      # [-2,-1] -> [-1,0]
                                                               (+5)
21
            jl Rem4
22
            je Rem5
23
    RemTestRR:
24
                                      # [1,3] -> [-1,1]
                                                               (+8)
            iaddl $-2, %edx
25
            jl Rem7
26
            je Rem8
```

--- Unrolling of Remaining Loops---

```
1
    Rem9:
 2
            mrmovl 32(%ebx), %esi
                                   \# valA = src[8]
 3
            rmmovl %esi, 32(%ecx)
                                    # dst[8] = valA
 4
            # Note that %esi == 0, directly jumping here
    Rem8:
 5
            # implies that RemXb will performs correctly.
 6
            andl %esi, %esi
                                     # valA <= 0?
 7
            mrmovl 28(%ebx), %esi # valA = src[7]
 8
                                     # if so, goto Rem8b
            jle Rem8b
 9
                                     # count++
            iaddl $1, %eax
10
    Rem8b:
            rmmovl %esi, 28(%ecx)
                                    \# dst[7] = valA
11
    Rem7:
12
                                     # valA <= 0?
            andl %esi, %esi
13
                                     \# valA = src[6]
            mrmovl 24(%ebx), %esi
14
            jle Rem7b
                                     # if so, goto Rem7b
15
            iaddl $1, %eax
                                     # count++
16
    Rem7b:
            rmmovl %esi, 24(%ecx)
                                     \# dst[6] = valA
17
    Rem6:
18
            andl %esi, %esi
                                     # valA <= 0?
19
            mrmovl 20(%ebx), %esi
                                     \# valA = src[5]
20
            jle Rem6b
                                     # if so, goto Rem6b
21
            iaddl $1, %eax
                                     # count++
22
    Rem6b:
            rmmovl %esi, 20(%ecx)
                                     \# dst[5] = valA
23
    Rem5:
24
            andl %esi, %esi
                                     # valA <= 0?
25
            mrmovl 16(%ebx), %esi
                                     \# valA = src[4]
26
                                     # if so, goto Rem5b
            jle Rem5b
27
            iaddl $1, %eax
                                     # count++
28
    Rem5b:
            rmmovl %esi, 16(%ecx)
                                     \# dst[4] = valA
29
    Rem4:
30
                                     # valA <= 0?
            andl %esi, %esi
31
            mrmovl 12(%ebx), %esi
                                     \# valA = src[3]
```

```
32
            jle Rem4b
                                     # if so, goto Rem4b
33
            iaddl $1, %eax
                                     # count++
34
    Rem4b:
            rmmovl %esi, 12(%ecx)
                                     \# dst[3] = valA
35
    Rem3:
36
            andl %esi, %esi
                                     # valA <= 0?
37
            mrmovl 8(%ebx), %esi
                                     \# valA = src[2]
38
            jle Rem3b
                                     # if so, goto Rem3b
39
            iaddl $1, %eax
                                     # count++
40
            rmmovl %esi, 8(%ecx)
                                     \# dst[2] = valA
    Rem3b:
41
    Rem2:
42
                                     # valA <= 0?
            andl %esi, %esi
43
                                     \# valA = src[1]
            mrmovl 4(%ebx), %esi
44
            jle Rem2b
                                     # if so, goto Rem2b
45
            iaddl $1, %eax
                                     # count++
46
    Rem2b:
            rmmovl %esi, 4(%ecx)
                                     \# dst[1] = valA
47
    Rem1:
48
            andl %esi, %esi
                                     # valA <= 0?
49
            mrmovl (%ebx), %esi
                                     \# valA = src[0]
50
                                     # if so, goto Rem1b
            jle Rem1b
51
            iaddl $1, %eax
                                     # count++
52
    Rem1b:
53
            andl %esi, %esi
                                     # valA <= 0?
54
                                     \# dst[0] = valA
            rmmovl %esi, (%ecx)
55
            jle Done
                                     # if so, goto Done
56
            iaddl $1, %eax
                                     # count++
```

---Modification to hcl (all in pipe-zzcc.hcl)----

```
1
   -----add following definition-----
   quote 'int gen_aluA();'
                                      # Declaration of gen_aluA
3
   quote 'int gen_aluB();'
                                      # Declaration of gen_aluB
4
   # For JXX in ID and ALU in EX, check the cc generated by ALU
   # Note that the simulator do not generate 'cc_in' correctly
7
   boolsig f_cnd_alu
8
          'cond_holds(compute_cc(id_ex_curr->ifun,
9
                        gen_aluA(), gen_aluB()),
10
                        if_id_next->ifun)'
11
   # For JXX in ID and non-ALU in EX, check the cc register
  boolsig f_cnd_other 'cond_holds(cc, if_id_next->ifun)'
13
   -----modify f_predPC-----
15
   # Predict next value of PC
16
  17
          f_icode == ICALL : f_valC;
```

```
18
            f_icode == IJXX && f_ifun == UNCOND : f_valC;
19
20
            # Decode stage is ALU and will set CC -> always taken by
                → default
21
            f_icode == IJXX && (D_icode in {IOPL, IIADDL}): f_valC;
22
23
            # Decode stage is not ALU
24
             # Execute stage is ALU -> compute CC
25
            f_icode == IJXX && (E_icode in {IOPL, IIADDL}) &&
26
            !f_cnd_alu : f_valP;
27
28
            # Execute stage is not ALU -> check cc -> ZF SF OF
29
            f_icode == IJXX && !(E_icode in {IOPL, IIADDL}) &&
30
            !f_cnd_other : f_valP;
31
            # Other JXX
32
            f_icode == IJXX : f_valC;
33
34
            # Otherwise
35
            1 : f_valP;
36
   ];
37
    -----add conditions to D_Bubble & E_BUbble-----
38
    bool D_bubble =
39
            # Mispredicted branch taken
40
            (E_icode == IJXX && E_ifun != UNCOND &&
41
            (M_icode in {IOPL, IIADDL}) && !e_Cnd) ||
42
            # Stalling at fetch while ret passes through pipeline
43
            # but not condition for a load/use hazard
44
            !(E_icode in { IMRMOVL, IPOPL }
45
            && E_dstM in { d_srcA, d_srcB })
46
            && IRET in { D_icode, E_icode, M_icode };
47
48
    # Should I stall or inject a bubble into Pipeline Register E?
   # At most one of these can be true.
50
   bool E_stall = 0;
51
   |bool E_bubble =
52
            # Mispredicted branch taken
53
            (E_icode == IJXX && E_ifun != UNCOND &&
54
            (M_icode in {IOPL, IIADDL}) && !e_Cnd) ||
55
            # Conditions for a load/use hazard
            E_icode in { IMRMOVL, IPOPL } &&
56
57
             E_dstM in { d_srcA, d_srcB};
```

2.3.3 Evaluation

3 Conclusion

3.1 Problems

[In this part you can list the obstacles you met during the project, and better add how you overcome them if you have made it.]

3.2 Achievements

[In this part you can list the strength of your project solution, like the performance improvement, coding readability, partner cooperation and so on. You can also write what you have learned if you like.]