# Math 455: Analysis IV Summary Midterm Date: 12 March 2020 18.00 - 20.00 Key Results, Theorems, Definitions, etc. Shereen Elaidi

#### Abstract

This document contains a summary of all the key definitions, results, and theorems from class. There are probably typos, and so I would be grateful if you brought those to my attention :-).

Syllabus:  $L^p$  space, duality, weak convergence, Young, Holder, and Minkowski inequalities, point-set topology, topological space, dense sets, completeness, compactness, connectedness, path-connectedness, separability, Tychnoff theorem, Stone-Weierstrass Theorem, Arzela-Ascoli, Baire category theorem, open mapping theorem, closed graph theorem, uniform boundedness principle, Hahn Banch theorem.

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## 1. $L^p$ Spaces: Completeness and Approximation

## 1.1. NORMED VECTOR SPACES

Definition 1 ( $\ell^p$  space). Let  $(a_1, a_n, ...)$  be a sequence. Then, the  $\ell^p$ -space is:

$$\ell^p := \left\{ (a_1, a_2, \dots) \mid \sum_{n=1}^{\infty} |a_n|^p < +\infty \right\}$$
 (1)

**Theorem 1** (Riesz-Fisher).  $L^p(X)$  is complete.

Definition 2 ( $L^p$  space). Let E be a measurable set and let  $1 \le p < \infty$ . Then,  $L^p(E)$  is the collection of measurable functions f for which  $|f|^p$  is Lebesgue integrable over E.

Definition 3 (Equivalent Functions). Let  $\mathcal{F}$  be the collection of all measurable extended real-valued functions on E that are finite a.e. on E. Define two functions f and g to be equivalent, and write  $f \sim g$  if g(x) = f(x) a.e. on E.

Definition 4 (Essentially Bounded). We call a function  $f \in \mathcal{F}$  to be **essentially bounded** if there exists some  $M \geq 0$ , called the **essential upper bound** for f, for which

$$|f(x)| \le M$$

for almost every  $x \in E$ .  $L^{\infty}(E)$  is the collection of equivalence classes [f] for which f is essentially bounded.

Definition 5 (Norm). Let X be a linear space. A real-valued functional  $||\cdot||$  on X is called a **norm** provided that for each f and g in X and each real number  $\alpha$ ,

(1) (The Triangle Inequality).

$$||f + g|| \le ||f|| + ||g||$$

(2) (Positive Homogeneity).

$$||\alpha f|| = |\alpha|||f||$$

(3) (Non-Negativity).

$$||f|| \ge 0$$
 and  $||f|| = 0$  if and only if  $f = 0$ 

Definition 6 (Normed Linear Space). X is said to be a **normed linear space** if X is equipped with a norm.

Definition 7 (Essential Supremum). Let  $f \in L^{\infty}(E)$ .  $||f||_{\infty}$  is called the **essential supremum** and is defined as:

$$||f||_{\infty} := \{M \mid M \text{ is an essential upper bound for } f\}$$

**Theorem:**  $||\cdot||_{\infty}$  is a norm on  $L^{\infty}(E)$ .

## 1.2. The Inequalities of Young, Hölder, and Minkowski

**Definition 8** (p-norm). Let E be a measurable set,  $1 , and let <math>f \in L^p(E)$ . Then, define the **p-norm** to be:

$$||f||_p := \left[ \int_E |f|^p \right]^{\frac{1}{p}} \tag{2}$$

Definition 9 (Conjugate). The **conjugate** of a number  $p \in ]1, \infty[$  is the number q = p/(p-1), which is the unique number  $q \in ]1, \infty[$  for which

$$\frac{1}{p} + \frac{1}{q} = 1\tag{3}$$

The conjugate of 1 is defined to be  $\infty$  and the conjugate of  $\infty$  is defined to be 1.

Definition 10 (Young's Inequality). For 1 , q the conjugate of p, and any two positive numbers a and b, we have:

$$ab \le \frac{a^p}{p} + \frac{b^q}{q} \tag{4}$$

**Theorem 2** (Hölder's Inequality). Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \le p < \infty$ , and q the conjugate of p. If f belongs to  $L^p(E)$ , and g belongs to  $L^q(E)$ , then their product  $f \cdot g$  is integrable over E and:

$$\int_{E} |f \cdot g| \le ||f||_p \cdot ||g||_q. \tag{5}$$

Moreover, if  $f \neq 0$ , then the function defined as:

$$f^* := ||f||_p^{1-p} \cdot \operatorname{sgn}(f) \cdot |f|^{p-1} \tag{6}$$

belongs to  $L^q(E)$ ,

$$\int_{E} f \cdot f^* = ||f||_{p} \text{ and } ||f^*||_{q} = 1$$

We call  $f^*$  defined as above to be called the **conjugate function** of f.

**Theorem 3** (Minkowski's Inequality). Let E be a measurable set and  $1 \le p \le \infty$ . If the functions f and g belong to  $L^p(E)$ , then so does their sum f + g. Moreover,

$$||f+g||_p \le ||f||_p + ||g||_p \tag{7}$$

**Theorem 4** (Cauchy-Schwarz Inequality). Let E be a measurable set and let f and g be measurable functions over E for which  $f^2$  and  $g^2$  are integrable over E. Then,  $f \cdot g$  is integrable over E and

$$\int_{E} |f \cdot g| \le \sqrt{\int_{E} f^{2}} \cdot \sqrt{\int_{E} g^{2}} \tag{8}$$

Corollary 1. Let E be a measurable set and  $1 . Suppose <math>\mathcal{F}$  is a family of functions in  $L^p(E)$  that is bounded in  $L^p(E)$  in the sense that there is a constant M for which

$$||f||_p \leq M$$
 for all  $f \in \mathcal{F}$ 

Then, the family  $\mathcal{F}$  is uniformly integrable over E.

Corollary 2. Let E be a measurable set of finite measure and  $1 \le p_1 < p_2 \le \infty$ . Then,  $L^{p_2}(E) \subseteq L^{p_1}(E)$ . Furthermore,

$$||f||_{p_1} \le c||f||_{p_2}$$

for all f in  $L^{p_2}(E)$ , where  $c = [m(E)]^{\frac{p_2 - p_1}{q_1 p_2}}$  if  $p_2 < \infty$  and  $c = [m(E)]^{\frac{1}{p_1}}$  if  $p_2 = \infty$ .

## 1.3. $L^p$ is complete: the Reisz-Fischer Theorem

Definition 11 (Converge). A sequence  $\{f_n\}$  in a linear space X normed by  $||\cdot||$  is said to converge to f in X provided:

$$\lim_{n \to \infty} ||f - f_n|| = 0$$

Definition 12 (Cauchy). A sequence  $\{f_n\}$  in a linear space X that is normed by  $||\cdot||$  is said to be Cauchy in X provided for each  $\varepsilon > 0$ , there exists a  $N \in \mathbb{N}$  such that

$$||f_n - f_m|| < \varepsilon \ \forall \ m, n \ge N \tag{9}$$

Definition 13 (Complete). A normed linear space X is called **complete** if every Cauchy sequence in X converges to a function in X. A complete normed linear space is called a **Banach space**.

**Proposition 1.** Let X be a normed linear space. Then, every convergent sequence in X is Cauchy. Moreover, a Cauchy sequence in X converges if it has a convergent subsequence.

Definition 14. Let X be a linear space normed by  $||\cdot||$ . A sequence  $\{f_n\}$  in X is said to be **rapidly** Cauchy if there is a convergent series of positive numbers  $\sum_{k=1}^{\infty} \varepsilon_k$  for which

$$||f_{k+1} - f_k|| \le \varepsilon_k^2$$
 for all  $k$ 

**Proposition 2.** Let X be a normed linear space. Then, every rapidly Cauchy sequence in X is Cauchy. Furthermore, every Cauchy sequence has a rapidly Cauchy subsequence.

**Proposition 3.** Let E be a measurable set and  $1 \le p \le \infty$ . Then, every rapidly Cauchy sequence in  $L^p(E)$  converges with respect to the  $L^p(E)$  norm and pointwise a.e. on E to a function in  $L^p(E)$ .

**Theorem 5** (Riesz-Fischer Theorem). Let E be a measurable set and  $1 \le p \le \infty$ . Then  $L^p(E)$  is a Banach space. Moreover, if  $\{f_n\} \to f$  in  $L^p(E)$ , a subsequence of  $\{f_n\}$  converges pointwise a.e. on E to f.

**Theorem 6.** Let E be a measurable set and  $1 \le p < \infty$ . Suppose  $\{f_n\}$  is a sequence in  $L^p(E)$  that converges pointwise a.e. on E to the function f which belongs to  $L^p(E)$ . Then:

$$\{f_n\} \to f \text{ in } L^p(E) \iff \lim_{n \to \infty} \int_E |f_n|^p = \int_E |f|^p$$

Definition 15 (Tight). A family  $\mathcal{F}$  of measurable functions on E is said to be **tight** over E provided that for each  $\varepsilon > 0$ , there exists a subset  $E_0$  of E of finite measure for which

$$\int_{E \setminus E_0} |f| < \varepsilon \text{ for all } f \in \mathcal{F}$$

**Theorem 7.** Let E be a measurable set and let  $1 \le p < \infty$ . Suppose  $\{f_n\}$  is a sequence in  $L^p(E)$  that converges pointwise a.e. on E to the function f which belongs to  $L^p(E)$ . Then,  $\{f_n\} \to f$  in  $L^p(E) \iff \{|f_n|^p\}$  is uniformly integrable and tight over E.

#### 1.4. Approximation and Separability

Definition 16 (Dense). Let X be a normed linear space with norm  $||\cdot||$ . Given two subsets  $\mathcal{F}$  and  $\mathcal{G}$  of X with  $\mathcal{F} \subseteq \mathcal{G}$ , we say that  $\mathcal{F}$  is **dense** in  $\mathcal{G}$  provided for each function g in  $\mathcal{G}$  and  $\varepsilon > 0$ , there is a function  $f \in \mathcal{F}$  for which  $||f - g|| < \varepsilon$ .

**Proposition 4.** Let E be a measurable set and let  $1 \le p \le \infty$ . Then, the subspace of simple functions in  $L^p(E)$  is dense in  $L^p(E)$ .

**Proposition 5.** Let [a,b] be a closed, bounded interval and  $1 \le p < \infty$ . Then, the subspace of step functions on [a,b] is dense in  $L^p[a,b]$ .

**Definition 17** (Separable). A normed linear space X is said to be **separable** provided there is a countable subset that is dense in X.

**Theorem 8.** Let E be a measurable set and  $1 \leq p < \infty$ . Then, the normed linear space  $L^p(E)$  is separable.

**Theorem 9.** Suppose E is measurable and let  $1 \leq p < \infty$ . Then,  $C_c(E)$  (the set of all continuous functions with compact support on E) is dense in  $L^p(E)$ .

## 1.5. Results from the Homework

(1) (When Hölder's inequality  $\rightarrow$  equality): There is equality in Hölder's Inequality  $\iff$  there exists constants  $\alpha$ ,  $\beta$ , both of which non-zero, for which:

$$\alpha |f|^p = \beta |g|^q$$

a.e. on E.

(2) (Extension of Hölder's Inequality for 3 functions): Let  $E \subseteq \mathbb{R}$  be measurable, let  $1 \leq p < \infty$ ,  $1 \leq q < \infty$ ,  $1 \leq r < \infty$  such that:

$$\frac{1}{p} + \frac{1}{q} + \frac{1}{r} = 1$$

If  $f \in L^p(E)$ ,  $q \in L^q(E)$ , and  $h \in L^r(E)$ , then  $fgh \in L^(E)$  and:

$$\int_{E} |fgh| \le ||f||_{p} ||g||_{q} ||h||_{r}$$

(3) For  $1 \le p \le \infty$ , q conjugate of  $p, f \in L^p(E)$ :

$$||f||_p = \max_{g \in L^q(E), ||g||_q \le 1} \int_E fg$$

- (4) ( $L^p$  dominated convergence theorem): Let  $\{f_n\}$  be a sequence of measurable functions that converge pointwise a.e. on E to f. For  $1 \leq p < \infty$ , suppose  $\exists$  a function  $g \in L^p(E)$  such that  $\forall n \in \mathbb{N}$ ,  $|f_n| \leq g$  a.e. on E. Then,  $\{f_n\} \to f$  in  $L^p(E)$ .
- (5) Assume  $1 \le p < \infty$ , if  $E \subseteq \mathbb{R}$  has finite measure,  $1 \le p < \infty$ , and  $\{f_n\}$  is a sequence of measurable functions which converge pointwise a.e. on E to f, then  $\{f_n\} \to f$  in  $L^p(E)$  if  $\exists$  a  $\theta > 0$  such that  $\{f_n\}$  belongs to and is bounded as a subset of  $L^{p+\theta}(E)$ .
- (6) The space c of all convergent sequences of real numbers and the space  $c_0$  of all sequences which converge to zero are Banach spaces with respect to the  $\ell^{\infty}$  norm.
- (7) Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p \leq \infty$ , q the conjugate of p, and S a dense subset of  $L^q(E)$ . If  $g \in L^p(E)$  and  $\int_E g \cdot g = 0$  for all  $g \in S$ , then g = 0.
- (8) (Separability of  $\ell^p$ ): For  $1 \leq p < \infty$ ,  $\ell^p$  is separable.  $\ell^\infty$  is not separable.

- 2.  $L^p$  Spaces: Duality and Weak Convergence
- 2.1. Riesz Representation Theorem for the Dual of  $L^p$ ,  $1 \le p < \infty$

Definition 18 (Linear Functional). A linear functional on a linear space X is a real-valued function T on X such that for f and g in X and  $\alpha$  and  $\beta$  real numbers,

$$T(\alpha \cdot g + \beta \cdot h) = \alpha \cdot T(g) + \beta \cdot T(h) \tag{10}$$

Definition 19 (Bounded). For a normed linear space X, a linear functional T on X is said to be bounded provided there is an  $M \geq 0$  for which

$$|T(f)| \le M \cdot ||f|| \text{ for all } f \in X$$
 (11)

The infimum of all such M is called the **norm** of T and is denoted by  $||T||_*$ .

**Proposition 6** (Continuity Property of a Bounded Linear Functional). Let T be a bounded linear functional on the normed space X. Then, if  $\{f_n\} \to f$  in X, then  $\{T(f_n)\} \to \{T(f)\}$ .

**Proposition 7.** Let X be a normed vector space. Then, the collection of bounded linear functionals on X is a linear space which is normed by  $||\cdot||_*$ . This normed vector space is called the **dual space** of X, and is denoted by  $X^*$ .

**Proposition 8.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ , q the conjugate of  $p, g \in L^q(E)$ . Define the functional T on  $L^p(E)$  by:

$$T(f) := \int_{E} g \cdot f \,\,\forall f \in L^{p}(E) \tag{12}$$

Then, T is a bounded linear functional on  $L^p(E)$  and  $||T||_* = ||g||_q$ .

**Proposition 9.** Let T, S be bounded linear functionals on the normed vector space X. If T = S on a dense subset  $X_0$  of X, then T = S.

**Lemma 10.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \le p < \infty$ . Suppose that g is integrable over E and there exists a  $M \ge 0$  for which

$$\left| \int_{E} g \cdot f \right| \leq M ||f||_{p} \, \forall f \in L^{p}(E), \, f \text{ simple}$$

Then,  $g \in L^q(E)$ , where q is the conjugate of p. Moreover,  $||g||_q \leq M$ .

**Theorem 11.** Let [a,b] be a closed, bounded interval, and  $1 \le p < \infty$ . Suppose that T is a bounded linear functional on  $L^p[a,b]$ . Then, there is a functional  $g \in L^q[a,b]$ , where q is the conjugate of p, for which:

$$T(f) = \int_{a}^{b} g \cdot f \,\,\forall f \in L^{p}[a, b] \tag{13}$$

**Theorem 12** (Riesz-Representation Theorem for the Dual of  $L^p(E)$ ). Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ , and q the conjugate of p. For all  $g \in L^q(E)$ , define the bounded linear functional  $\mathcal{R}_g$  on  $L^p(E)$  by:

$$\mathcal{R}_g := \int_E g \cdot f \ \forall f \in L^p(E) \tag{14}$$

Then, for each bounded linear functional T on  $L^p(E)$ , there exists a unique  $g \in L^q(E)$  for which

- (1)  $\mathcal{R}_g = T$  and
- (2)  $||T||_* = ||g||_q$

# 2.2. Weak Sequential Convergence in $L^p$

Definition 20 (Converge Weakly). Let X be a normed vector space. A sequence  $\{f_n\}$  in X is said to converge weakly in X to f provided that

$$\lim_{n \to \infty} T(f_n) = T(f) \ \forall T \in X^*$$
 (15)

we write

$$\{f_n\} \rightharpoonup f$$

to mean that f and each  $f_n$  belong to X and  $\{f_n\}$  converges weakly in X to f.

Definition 21. Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ , q the conjugate of p. Then,  $\{f_n\} \rightharpoonup f$  in  $L^p(E)$   $\iff$ 

$$\lim_{n \to \infty} \int_{E} g \cdot f_n = \int_{E} g \cdot f \ \forall g \in L^q(E)$$
 (16)

**Theorem 13.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ . Suppose that  $\{f_n\} \rightharpoonup f$  in  $L^p(E)$ . Then:

$$\{f_n\}$$
 is bounded and  $||f||_p \leq \liminf ||f_n||_p$ 

Corollary 3. Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ , q the conjugate of p. Suppose  $\{f_n\}$  converges weakly to f in  $L^p(E)$  and  $\{g_n\}$  converges strongly to  $g \in L^q(E)$ . Then:

$$\lim_{n \to \infty} \int_{E} g_n \cdot f_n = \int_{E} g \cdot f \tag{17}$$

Definition 22 (Linear Span). Let X be a normed vector space, and let  $S \subseteq X$ . Then, the linear span of S is the vector space consisting of all linear functionals of the form:

$$f = \sum_{k=1}^{n} \alpha_k \cdot f_k \tag{18}$$

where each  $\alpha_k \in \mathbb{R}$  and  $f_k \in S$ . It is the set of all *finite linear combinations of elements in S*. We care about this since  $L^p$  is an infinite dimensional space, so we want to find a way to approximate it with finitely many elements.

**Proposition 10** (Characterisation of Weak Convergence in  $L^p(E)$ ). Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ , q the conjugate of P. Assume that  $\mathcal{F} \subseteq L^q(E)$  whose linear span is dense in  $L^q(E)$ . Let  $\{f_n\}$  be a bounded sequence in  $L^p(E)$ , and let  $f \in L^p(E)$ . Then,  $\{f_n\} \rightharpoonup f$  in  $L^p(E) \iff$ 

$$\lim_{n \to \infty} \int_{E} f_n \cdot g = \int_{E} f \cdot g \,\,\forall g \in \mathcal{F} \tag{19}$$

**Theorem 14.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \leq p < \infty$ . Suppose that  $\{f_n\}$  is a bounded sequence in  $L^p(E)$  and f belongs to  $L^p(E)$ . Then,  $\{f_n\} \to f$  in  $L^p(E) \iff \forall$  measurable sets  $A \subseteq E$ :

$$\lim_{n \to \infty} \int_A f_n = \int_A f \tag{20}$$

if p > 1, then it is sufficient to consider sets A of finite measure.

**Theorem 15.** Let [a,b] be a closed and bounded interval,  $1 . Suppose that <math>\{f_n\}$  is a bounded sequence in  $L^p[a,b]$  and  $f \in L^p[a,b]$ . Then,  $\{f_n\} \to f$  in  $L^p(E)$  in  $L^p[a,b] \iff$ 

$$\lim_{n \to \infty} \left[ \int_{a}^{x} f_n \right] = \int_{a}^{x} f \ \forall x \in [a, b]$$
 (21)

**Lemma 16** (Riemann-Lebesgue Lemma; used in Fourier Series :-)). Let  $I = [-\pi, \pi]$ ,  $1 \le p < \infty$ .  $\forall n \in \mathbb{N}$ , define  $f_n(x) := \sin(nx)$  for  $x \in I$ . Then,  $\{f_n\}$  converges weakly in  $L^p(I)$  to  $f \equiv 0$ .

**Theorem 17.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 . Suppose that <math>\{f_n\}$  is a bounded sequence in  $L^p(E)$  that converges pointwise a.e. on E to f. Then,  $\{f_n\} \rightharpoonup f$  in  $L^p(E)$ .

This theorem was used in the proof but was not covered in Analysis 3:

**Theorem 18** (Vitali Convergence Theorem). Let  $E \subseteq \mathbb{R}$  be measurable and of finite measure. Suppose that the sequence of functions  $\{f_n\}$  is uniformly integrable over E. Then, if  $\{f_n\} \to f$  pointwise a.e. on E, then f is integrable over E and  $\lim_{n\to\infty} \int_E f_n = f$ .

**Theorem 19** (Radon-Riesz Theorem). Let  $E \subseteq \mathbb{R}$  be measurable,  $1 . Suppose that <math>\{f_n\} \to f$  in  $L^p(E)$ . Then:

$$\{f_n\} \to f \text{ in } L^p(E) \iff \lim_{n \to \infty} ||f_n||_p = ||f||_p$$
 (22)

Corollary 4. (Not Covered in Class): Let  $E \subseteq \mathbb{R}$  be measurable and  $1 . Suppose that <math>\{f_n\} \rightharpoonup f$  in  $L^p(E)$ . Then, a subsequence of  $\{f_n\}$  converges strongly to  $f \iff ||f||_p = \liminf ||f_n||_p$ .

## 2.3. Weak Sequential Compactness ("Compactness Found!")

**Theorem 20.** Let  $E \subseteq \mathbb{R}$  be measurable,  $1 . Then, every bounded sequence in <math>L^p(E)$  has a subsequence that converges weakly in  $L^p(E)$  to a function in  $L^p(E)$ .

**Theorem 21** (Helly's Theorem). Let X be a SEPARABLE normed vector space and  $\{T_n\}$  a sequence in its dual space  $X^*$  that is bounded; that is,  $\exists$  a M > 0 for which

$$|T_n(f)| \leq M \cdot ||f|| \ \forall f \in X, \ \forall n \in \mathbb{N}$$

Then, there is a subsequence  $\{T_{n_k}\}$  of  $\{T_n\}$  and  $T \in X^*$  for which

$$\lim_{k \to \infty} T_{n_k}(f) = T(f) \ \forall f \in X$$
 (23)

Definition 23 (Weakly Sequentially Compact (Compact in the "weak topology"). Let X be a normed vector space. Then, a subset  $K \subseteq X$  is **weakly sequentially compact** in X provided that every sequence  $\{f_n\}$  in K has a subsequence that converges weakly to  $f \in K$ .

**Theorem 22** (The Unit Ball is Weakly Sequentially Compact). Let  $E \subseteq \mathbb{R}$  be measurable, 1 . Define:

$$B_1 := \{ f \in L^p(E) \mid ||f||_p \le 1 \}. \tag{24}$$

 $B_1$  is weakly sequentially compact in  $L^p(E)$ .

#### 2.4. Results from the Homework

(1) (Reisz-Representation Theorem for the Dual of  $\ell^p$ ): Let  $1 \leq p < \infty$ , q the conjugate of p. Then for all  $\{g_n\} \in \ell^q$ , define the bounded linear functional  $\mathcal{R}_q$  on  $\ell^p$  by:

$$\mathcal{R}_g := T(\{f_n\}) = \sum_{n=1}^{\infty} g_n f_n \tag{25}$$

 $\forall \{f_n\} \in \ell^p$ . Then, for each bounded linear functional T on  $\ell^p$ , there exists a unique  $\{g_n\} \in \ell^q$  for which:

- (1)  $\mathcal{R}_g = T$ (2)  $||T||_* = ||\{g_n\}||_q$
- (2) Let c be the vector space of all real sequences that converge to a real number and let  $c_0$  be the subspace of c comprising of all sequences that converge to zero. Norm each vector space with the  $\ell^{\infty}$  norm. Then,  $c^* = \ell^1$  and  $c_0^* = \ell^1$ .
- (3) Assume that h is a continuous function defined on all of  $\mathbb{R}$  that is periodic with period T and  $\int_0^T h = 0$ . Let [a, b] be a closed + bounded interval. For each  $n \in \mathbb{N}$ , define  $f_n(x) := h(nx)$ . Define  $f \equiv 0$  on [a, b]. Then,  $\{f_n\}$  converges weakly to f in  $L^p[a, b]$ .
- (4) Let  $1 , assume <math>f_0 \in L^p(\mathbb{R})$ . For each  $n \in \mathbb{N}$ , define  $f_n(x) := f_0(x n)$ . Define  $f \equiv 0$  on  $\mathbb{R}$ . Then,  $\{f_n\}$  converges weakly to f in  $L^p(\mathbb{R})$ . Not true for p=1!
- (5) For  $1 \leq p < \infty$ , for each  $n \in \mathbb{N}$ , let  $e_n \in \ell^p$  be the standard basis sequence. If p > 1, then  $\{e_n\}$  converges weakly to zero in  $\ell^p$ , but no subsequence converges strongly to zero.  $\{e_n\}$  does not converge at all in  $\ell^1$ .
- (6) (Uniform Boundedness Principle): Let  $E \subseteq \mathbb{R}$  be measurable,  $1 \le p < \infty$ , and q the conjugate of p. Suppose that  $\{f_n\}$  is a sequence in  $L^p(E)$  for which for each  $g \in L^q(E)$ , the sequence  $\{\int_E g f_n\}$  is bounded. Show that  $\{f_n\}$  is bounded in  $L^p(E)$ .
- (7)  $\{x^n\}$  in C[0,1] fails to have a strongly convergent subsequence. Suitably modify this to work in any C[a,b] by:

$$f_n := \left(\frac{x-a}{b-a}\right)^n$$

- (8) In  $\ell^p$ ,  $1 , every bounded sequence in <math>\ell^p$  has a weakly convergent subsequence.
- (9) Let X be a normed vector space, and let  $\{T_n\}$  be a sequence in  $X^*$  for which there exists an  $M \geq 0$ such that  $||T_n||_* \leq M$  for all  $n \in \mathbb{N}$ . Let  $S \subseteq X$  be a dense subset such that  $\{T_n(g)\}$  is Cauchy for all  $q \in \mathcal{S}$ . Then:
  - (1)  $\{T_n(g)\}\$  is Cauchy for all  $g \in X$ .
  - (2) The limiting functional is linear and bounded.
- (10) Helly's theorem fails when  $X = L^{\infty}[0,1]$ . To see why, consider a sequence of linear functionals induced by the Rademacher functions.

## Metric Spaces

This section was not covered in class, but since we have homework on this chapter I figured having this as a review from analysis 2 might be helpful. Also, there are a few terms/results that I don't think we covered in analysis 2.

Examples of Metric Spaces

Definition 24 (Metric Space). Let X be a non-empty set. A function  $\rho: X \times X \to \mathbb{R}$  is called a metric if  $\forall x, y \in X$ :

- (1)  $\rho(x,y) \geq 0$
- (2)  $\rho(x,y) = 0 \iff x = y$
- (3)  $\rho(x, y) = \rho(y, x)$

(4)  $\rho(x,z) \le \rho(x,y) + \rho(y,z)$  (Triangle Inequality).

A non-empty set together with a metric, denoted  $(X, \rho)$  is called a **metric space**.

Definition 25 (Discrete Metric). For any non-empty set X, the discrete metric  $\rho$  is defined by setting  $\rho(x,y)=0$  if x=y and  $\rho(x,y)=1$  if  $x\neq y$ .

**Definition 26** (Metric Subspace). For any metric space  $(X, \rho)$ , let  $Y \subseteq X$  be non-empty. Then, the restriction of  $\rho$  to  $Y \times Y$  defines a metric on Y. We define this induced metric space as a **metric subspace**.

**Example 3.1** (Examples of metric spaces). The following are examples of metric spaces:

- (1) Every non-empty subset of a Euclidean space.
- (2)  $L^p(E)$ , where  $E \subseteq \mathbb{R}$  is a measurable set.
- (3) C[a, b].

Definition 27 (Product Metric). For metric spaces  $(X_1, \rho_1)$  and  $(X_2, \rho_2)$ , we define the **product metric**  $\tau$  on the cartesian product  $X_1 \times X_2$  by setting, for  $(x_1, x_2)$  and  $(y_1, y_2)$  in  $X_1 \times X_2$ :

$$\tau((x_1, x_2), (y_1, y_2)) := \{ [\rho_1(x_1, x_2)]^2 + [\rho_2(y_1, y_2)]^2 \}^{1/2}$$
(26)

Definition 28. Two metrics  $\rho$  and  $\sigma$  on a set X are said to be equivalent if there are positive numbers  $c_1$  and  $c_2$  such that  $\forall x_1, x_2 \in X$ ,

$$c_1 \sigma(x_1, x_2) \le \rho(x_1, x_2) \le c_2 \sigma(x_1, x_2)$$

Definition 29 (Isometry). A mapping  $f:(X,\rho)\to (Y,\sigma)$  between two metric spaces is called an **isometry** provided that f is surjective and  $\forall x_1,x_2\in X$ :

$$\sigma(f(x_1), f(x_2)) = \rho(x_1, x_2) \tag{27}$$

We say that two metric spaces are **isometric** if there is an isometry from one to another.

3.2. OPEN SETS, CLOSED SETS, AND CONVERGENT SEQUENCES

Definition 30 (Open Ball). Let  $(X, \rho)$  be a metric space. For a point  $x \in X$  and r > 0, the set:

$$B(x,r) := \{ x' \in X \mid \rho(x',x) < r \}$$
 (28)

is called the **open ball** centred at x of radius r. A subset  $\mathcal{O} \subseteq X$  is said to be **open** if  $\forall x \in \mathcal{O}$ , there exists an open ball centred at x and contained in  $\mathcal{O}$ . For a point  $x \in X$ , an open set containing x is called a **neighbourhood** of x.

**Proposition 11.** Let X be a metric space. The whole set X and the empty set  $\emptyset$  are open. The intersection of any two open sets is open. The union of any collection of open sets is open.

**Proposition 12.** Let X be a subspace of a metric space Y and  $E \subseteq X$ . Then, E is **open in**  $X \iff E = X \cap \mathcal{O}$ , where  $\mathcal{O}$  is open in Y.

Definition 31 (Closure). For a subset  $E \subseteq X$ , a point  $x \in X$  is called a **point of closure** of E provided that every neighbourhood of x contains a point in E. The collection of the points of closure of E is called the **closure** of E and is denoted by  $\overline{E}$ .

**Proposition 13.** For  $E \subseteq X$ , where X is a metric space, its closure  $\overline{E}$  is closed. Moreover,  $\overline{E}$  is the smallest closed subset of X containing E in the sense that if F is closed and if  $E \subseteq F$ , then  $\overline{E} \subseteq F$ .

Definition 32 (Converge). A sequence  $\{x_n\}$  in a metric space  $(X, \rho)$  is said to **converge** to the point  $x \in x$  provided that:

$$\lim_{n \to \infty} \rho(x_n, x) = 0$$

that is,  $\forall \varepsilon > 0$ ,  $\exists$  an index N such that  $\forall n \geq N$ ,  $\rho(x_n, x) < \varepsilon$ .

**Proposition 14.** Let  $\rho$  and  $\sigma$  be equivalent metrics on a non-empty set X. Then, a subset X is open in a metric space  $(X, \rho) \iff$  it is open in  $(X, \sigma)$ .

## 3.3. Continuous Mappings Between Metric Spaces

Definition 33 (Continuous). A mapping f from a metric space X to a metric space Y is continuous at the point  $x \in X$  if  $\{x_n\} \in X$ , if  $\{x_n\} \to x$ , then  $\{f(x_n)\} \to f(x)$ . f is said to be **continuous** if it is continuous at every point in X.

**Proposition 15** ( $\varepsilon$ - $\delta$  criteria for continuity). A mapping from a metric space  $(X, \rho)$  to a metric  $(Y, \sigma)$  is continuous at the point  $x \in X \iff \forall \varepsilon > 0, \exists \delta > 0$  such that if  $\rho(x, x') < \delta$ , then  $\sigma(f(x), f(x')) < \varepsilon$ . That is:

$$f(B(x,\delta)) \subseteq B(f(x),\varepsilon)$$
 (29)

**Proposition 16.** A mapping f from a metric space X to a metric space Y is continuous  $\iff \forall$  open subsets  $\mathcal{O} \subseteq Y$ , the inverse image under f of  $\mathcal{O}$ ,  $f^{-1}(\mathcal{O})$ , is an open subset of X.

**Proposition 17.** The composition of continuous mappings between metric spaces, when defined, is continuous.

**Definition 34** (Uniformly Continuous). A mapping from a metric space  $(X, \rho)$  to a metric space  $(Y, \sigma)$  is said to be **uniformly continuous** if  $\forall \varepsilon > 0$ ,  $\exists \delta > 0$  such that  $\forall u, v \in X$ , if  $\rho(u, v) < \delta$ ,  $\sigma(f(u), f(v)) < \varepsilon$ .

**Definition 35** (Lipschitz). A mapping  $f:(X,\rho)\to (Y,\sigma)$  is said to be **Lipschitz** if  $\exists$  a  $c\geq 0$  such that  $\forall$   $u,v\in X$ :

$$\sigma(f(u), f(v)) \le c\rho(u, v)$$

#### 3.4. Complete Metric Spaces

Definition 36 (Cauchy). A sequence  $\{x_n\}$  in a metric space  $(X, \rho)$  is said to be a Cauchy sequence if  $\forall \varepsilon > 0$ , there exists a  $N \in \mathbb{N}$  such that if  $m, n \geq N$ , then  $\rho(x_n, x_m) < \varepsilon$ .

Definition 37 (Complete). A metric space X is said to be **complete** if every Cauchy sequence in X converges to a point in X.

**Proposition 18.** Let [a, b] be a closed and bounded interval of real numbers. Then, C[a, b] with the metric induced by the max norm is complete.

**Proposition 19** (Characterisation of Complete Subspaces of Metric Spaces). Let  $E \subseteq X$ , where X is a complete metric space. Then, the metric subspace E is complete  $\iff E$  is a closed subset of X.

**Theorem 23.** The following are complete metric spaces:

- (1) Every non-empty closed subset of  $\mathbb{R}^n$ .
- (2)  $E \subseteq \mathbb{R}$  measurable,  $1 \le p \le \infty$ , each non-empty closed subset of  $L^p(E)$ .
- (3) Each non-empty closed subset of C[a, b].

Definition 38 (Diameter). Let E be a non-empty subset of a metric space  $(X, \rho)$ . We define the **diameter** of E, denoted by diam(E), by:

$$\operatorname{diam}(E) := \sup \{ \rho(x, y) \mid x, y \in E \}$$
(30)

We say that E is **bounded** if it has finite diameter.

Definition 39 (Contracting Sequence). A decreasing sequence  $\{E_n\}$  of non-empty subsets of X is called a contracting sequence if:

$$\lim_{n \to \infty} \operatorname{diam}(E_n) = 0 \tag{31}$$

**Theorem 24** (Cantor Intersection Theorem). Let X be a metric space. Then, X is complete  $\iff$  whenever  $\{F_n\}$  is a contracting sequence of non-empty closed subsets of X, there is a point  $x \in X$  for which:

$$\bigcap_{n=1}^{\infty} F_n = \{x\} \tag{32}$$

**Theorem 25.** Let  $(X, \rho)$  be a metric space. Then, there is a complete metric space  $(\widetilde{X}, \widetilde{\rho})$  for which X is a dense subset of  $\widetilde{X}$  and

$$\rho(u,v) = \tilde{\rho}(u,v) \ \forall \ u,v \in X \tag{33}$$

we call such a space the **completion** of  $(X, \rho)$ .

#### 3.5. Compact Metric Spaces

**Definition 40** (Compact Metric Space). A metric space X is called **compact** if every open cover of X has a finite sub-cover. A subset  $K \subseteq X$  is compact if K, considered as a metric subspace of X, is compact.

Formulation of compactness in terms of closed sets: Let  $\mathcal{T}$  be a collection of open subsets of a metric space X. Define  $\mathcal{F}$  to be the collection of the complements of elements in  $\mathcal{T}$ . Since the elements of  $\mathcal{T}$  are open, the elements of  $\mathcal{F}$  are closed. Thus,  $\mathcal{T}$  is a cover  $\iff$  the elements of  $\mathcal{F}$  have *empty intersection*. By deMorgan's law, we can formulate compactness in terms of closed sets as:

A metric space X is compact  $\iff$  every collection of closed sets with empty intersection has a finite sub-collection whose intersection is non-empty.

This property is called the **finite intersection property**.

Definition 41 (Finite Intersection Property). A collection of sets  $\mathcal{F}$  is said to have the finite intersection property if any finite sub-collection of  $\mathcal{F}$  has a non-empty intersection.

**Proposition 20** (Compactness in terms of closed sets). A metric space X is compact  $\iff$  every collection  $\mathcal{F}$  of closed subsets of X with the finite intersection property has a non-empty intersection.

Definition 42 (Totally Bounded). A metric space X is **totally bounded** if  $\forall \varepsilon > 0$ , the space X can be covered by a finite number of open balls of radius  $\varepsilon$ . A subset  $E \subseteq X$  is said to be **totally bounded** if E, as a subspace of the metric space X, is totally bounded.

Definition 43 ( $\varepsilon$ -net). Let E be a subset of a metric space X. A  $\varepsilon$ -net for R is a finite collection of open balls  $\{B(x_k, \varepsilon)\}_{k=1}^n$  with centres  $x_k \in X$  whose union covers E.

**Proposition 21.** A metric space E is totally bounded  $\iff \forall \varepsilon > 0$ , there is a finite  $\varepsilon$ -net for E.

**Proposition 22.** A subset of Euclidean space  $\mathbb{R}^n$  is bounded  $\iff$  it is totally bounded.

Definition 44 (Sequentially Compact). A metric space X is sequentially compact if every sequence in X has a subsequence that converges to a point in X.

**Theorem 26** (Characterisation of Compactness for a metric space). Let X be a metric space. Then, TFAE:

- (1) X is complete and totally bounded.
- (2) X is compact.
- (3) X is sequentially compact.

The following three propositions of this chapter are just breaking down these equivalences, so I will not write them.

**Theorem 27.** Let  $K \subseteq \mathbb{R}^n$ . Then, TFAE:

- (1) K is closed and bounded.
- (2) K is compact.
- (3) K is sequentially compact.

**Observe**: The equivalence  $(1) \iff (2)$  is the Heine-Borel theorem. The equivalence  $(2) \iff (3)$  is the Bolzano-Weierstrass theorem.

**Proposition 23.** Let f be a continuous mapping from a compact metric space X to a compact metric space Y. Then, its image f(X) is compact.

**Theorem 28** (Extreme Value Theorem). Let X be a metric space. Then, X is compact  $\iff$  every continuous real-valued function on X attains a minimum and maximum value.

Definition 45 (Lebesgue Number). Let X be a metric space, and let  $\{\mathcal{O}_{\lambda}\}_{{\lambda}\in\Lambda}$  be an open cover of X. Thus, each  $x\in X$  is contained in a member of the cover,  $\mathcal{O}_{\lambda}$ . Since  $\mathcal{O}_{\lambda}$  is open,  $\exists \ \varepsilon > 0$  such that:

$$B(x,\varepsilon)\subseteq\mathcal{O}_{\lambda}$$

In general,  $\varepsilon$  on X, but for compact metric spaces we can get *uniform control*. This  $\varepsilon$  that uniformly works is called the **Lebesgue number** for the cover  $\{\mathcal{O}_{\lambda}\}_{{\lambda}\in\Lambda}$ .

**Lemma 29.** Let  $\{\mathcal{O}_{\lambda}\}_{{\lambda}\in\Lambda}$  be an open cover of a compact metric space X. Then, there is a number  $\varepsilon>0$  such that for each  $x\in X$ , the open ball  $B(x,\varepsilon)$  is contained in some member of the cover.

**Proposition 24.** A continuous mapping from a compact space  $(X, \rho)$  to a metric space  $(Y, \sigma)$  is uniformly continuous.

# 3.6. Separable Metric Spaces

Definition 46 (Dense & Separable). A subset D of a metric space X is **dense** in X if every non-empty subset of X contains a point of D. A metric space is **separable** if there is a countable subset of X that is dense in X.

The Weierstrass Approximation Theorem states that polynomials are dense in C[a, b]. So, C[a, b] is separable, with the countable dense set being the set of polynomials with rational coefficients.

**Proposition 25.** A compact metric space is separable.

**Proposition 26.** A metric space X is separable  $\iff$  there is a countable collection of  $\{\mathcal{O}_n\}$  of open subsets of X such that any open subset of X is the union of a sub-collection of  $\{\mathcal{O}_n\}$ .

**Proposition 27.** Every subspace of a separable metric space is separable.

**Theorem 30.** Each of the following are separable metric spaces:

- (1) Every non-empty subset of Euclidean space  $\mathbb{R}^n$ .
- (2)  $1 \le p < \infty$ ,  $L^p(E)$  and all non-empty subsets of  $L^p(E)$ .
- (3) Each non-empty subset of C[a, b].

#### 3.7. Results from the Homework

(1)  $\{(X_n, \rho_n)\}_{n=1}^{\infty}$  a countable collection of metric spaces. Then, the following is a metric on the Cartesian product:

$$\rho_*(x,y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \cdot \frac{\rho_n(x_n, y_n)}{1 + \rho_n(x_n + y_n)}$$

- (2) A continuous mapping between metric spaces remains continuous if an equivalent metric is imposed on the domain and an equivalent metric is imposed on the domain.
- (3) The distance function (from a point to a set) is continuous.
- $(4) \{x \in X \mid \operatorname{dist}(x, E) = 0\} = \overline{E}.$
- (5) (Sequential Definition of Uniform Continuity): For a mapping f of a metric space  $(X, \rho)$  to the metric space  $(Y, \sigma)$ , f is uniformly continuous  $\iff$  for all sequences  $\{u_n\}$  and  $\{v_n\}$  in X:

if 
$$\lim_{n\to\infty} \rho(u_n, v_n) = 0$$
 then  $\lim_{n\to\infty} \sigma(f(u_n), f(v_n)) = 0$ 

- (6) If X and Y are metric spaces, with Y complete, and f a uniformly continuous mapping from  $E \subseteq X \to Y$ , then f has a uniquely uniformly continuous extension mapping  $\overline{f}$  of  $\overline{E}$  to Y.
- (7) Let  $E \subseteq X$ , X a compact metric space. Then, the metric subspace E is compact  $\iff E$  is a closed subset of X.
- (8)  $E \subseteq X$ , X complete. Then, E is totally bounded  $\iff \overline{E}$  is totally bounded.
- (9) The closed unit ball in  $\ell^2$  is not compact.

## 4. Topological Spaces

4.1. Open Sets, Closed Sets, Bases, and Sub-bases

Definition 47 (Open Sets). Let X be a non-empty set. A **topology**  $\mathcal{T}$  for X is a collection of subsets of X, called **open sets**, possessing the following properties:

- (1) The entire set X and the empty set  $\emptyset$  are open.
- (2) The finite intersection of open sets are open.
- (3) The union of any collection of open sets is open.

A non-empty set X, together with a topology on X, is called a **topological space**. For a point  $x \in X$ , an open set that contains x is called a **neighbourhood** of x.

**Proposition 28.** A subset  $E \subseteq X$  is open  $\iff$  for each  $x \in E$ , there exists a neighbourhood of x that is contained in E.

**Example 1** (Metric Topology). Let  $(X, \rho)$  be a metric space. Let  $\mathcal{O} \subseteq X$  be open if for all  $x \in \mathcal{O}$ ,  $\exists$  an open ball at x that is contained in  $\mathcal{O}$ . This collection of open sets forms a topology; we call this the **metric topology** induced by  $\rho$ .

**Example 2** (Discrete Topology). This topology is "too much." Let X be a non-empty subset. Let  $\mathcal{T} := \mathcal{P}(X)$ . Then, every set containing a point is a neighbourhood of that point. This is induced by the discrete metric.

**Example 3** (Trivial Topology). Let X be non-empty. Define  $\mathcal{T} := \{X, \emptyset\}$ . The only neighbourhood of any point is the whole set X.

Definition 48 (Topological Subspaces). Let  $(X, \mathcal{T})$  be a topological space and let E be a non-empty subset of X. The inherited topology  $\mathcal{S}$  for E is the set of all sets of the form  $E \cap \mathcal{T}$ , where  $\mathcal{O} \in \mathcal{T}$ . The topological space  $(E, \mathcal{S})$  is called a **subspace** of  $(X, \mathcal{T})$ .

**Definition 49** (Base for the Topology). The building blocks of a topology is called a **base**. Let  $(X, \mathcal{T})$  be a topological space. For a point  $x \in X$ , a collection of neighbourhoods of x,  $B_x$ , is called a **base for the topology at** X if  $\forall$  neighbourhoods  $\mathcal{U}$  of x, there exists a set B in the collection  $B_x$  for which  $B \subseteq \mathcal{U}$ .

A collection of open sets  $\mathcal{B}$  is called a base for the topology  $\mathcal{T}$  provided it contains a base for the topology at each point.

A base for a topology completely determines a topology, alongside  $\emptyset$  and X.

**Proposition 29.** For a non-empty set X, let  $\mathcal{B}$  be a collection of subsets of X. Then,  $\mathcal{B}$  is a base for a topology for  $X \iff$ :

(1)  $\mathcal{B}$  covers X. That is:

$$X = \bigcup_{B \in \mathcal{B}} B \tag{34}$$

(2) If  $B_1, B_2 \in \mathcal{B}$ , and  $x \in B_1 \cap B_2$ , then there is a set  $B_3 \in \mathcal{B}$  for which  $x \in B_3 \subseteq B_1 \cap B_2$ .

The unique topology that has  $\mathcal{B}$  as its base consists of  $\emptyset$  and unions of sub-collections of  $\mathcal{B}$ .

Definition 50 (Product Topology). Let  $(X, \mathcal{T})$  and  $(Y, \mathcal{S})$  be two topological spaces. In the cartesian product  $X \times Y$ , consider the collection of sets  $\mathcal{B}$  containing the products  $\mathcal{O}_1 \times \mathcal{O}_2$ , where  $\mathcal{O}_1$  is open in X and  $\mathcal{O}_2$  is open in Y. Then,  $\mathcal{B}$  is a base for a topology on  $X \times Y$ , which we call the **product topology**.

Definition 51 (Sub-base). Let  $(X, \mathcal{T})$  be a topological space. The collection of  $\mathcal{S}$  of  $\mathcal{T}$  that covers X is called a sub-base for the topology  $\mathcal{T}$  provided intersections of finite collections of  $\mathcal{S}$  are a base for  $\mathcal{T}$ .

Definition 52 (Closure). Let  $E \subseteq X$  be a subset of a topological space. A point  $x \in E$  is called a **point** of closure of E if every neighbourhood of x contains a point in E. The collection of the points of closure of E is called the closure of E, denoted  $\overline{E}$ .

**Proposition 30.** Let X be a topological space,  $E \subseteq X$ . Then,  $\overline{E}$  is closed. Moreover,  $\overline{E}$  is the smallest closed subset of X containing E in the sense that if F is closed and  $E \subseteq F$ , then  $\overline{E} \subseteq F$ .

**Proposition 31.** A subset of a topological space X is open  $\iff$  its complement is closed.

**Proposition 32.** Let X be a topological space. Then, (a)  $\emptyset$  and X are closed, (b) the union of a finite collection of closed sets is closed, (c) the intersection of any collection of closed sets in X is closed.

#### 4.2. Separation Properties

**Motivation:** Separation properties for a topology allow us to discriminate between which topologies discriminate between certain disjoint pairs of sets, which will then allow us to study a robust collection of cts real-valued functions on X.

Definition 53 (Neighbourhood). A neighbourhood of K for a subset  $K \subseteq X$  is an open set that contains K.

Definition 54 (Separated by Neighbourhoods). We say that two disjoint sets A and B in X can be separated by disjoint neighbourhoods provided that there exists neighbourhoods of A and B, respectively, that are disjoint.

**Definition 55** (Separation Properties of Topological Spaces). In the order of most general to least general, they are:

- (1) Tychonoff Separation Property: For each two points  $u, v \in X$ , there exists a neighbourhood of u that does not contain v and a neighbourhood of v that does not contain u.
- (2) **Hausdorff Separation Property**: Each two points in X can be separated by disjoint neighbourhoods.
- (3) Regular Separation Property: Tychonoff + each closed set and a point not in the set can be separated by disjoint neighbourhoods.
- (4) Normal Separation Property: Tychonoff + each two disjoint closed sets can be separated by disjoint neighbourhoods.

**Proposition 33.** A topological space is Tychonoff  $\iff$  every set containing a single point,  $\{x\}$ , is closed.

**Proposition 34.** Every metric space is normal.

**Lemma 31.** F is closed  $\iff$  dist $(x, F) > 0 \ \forall \ x \notin F$ .

**Proposition 35.** Let X be a Tychonoff topological space. Then, X is normal  $\iff$  whenever  $\mathcal{U}$  is a neighbourhood of a closed subset of F of X, there is another neighbourhood of F whose closure is contained in  $\mathcal{U}$ . that is, there is an open set  $\mathcal{O}$  for which:

$$F \subseteq \mathcal{O} \subseteq \overline{\mathcal{O}} \subseteq \mathcal{U} \tag{35}$$

## 4.3. Countability and Separability

Definition 56 (Converge, Limit). A sequence  $\{x_n\}$  in a topological space X is said to **converge** to the point  $x \in X$  if for each neighbourhood  $\mathcal{U}$  of x, there exists an index  $N \in \mathbb{N}$  such that if  $n \geq N$ , then  $x_n$  belongs to  $\mathcal{U}$ . This point is called a **limit** of the sequence.

Definition 57 (First and Second Countable). A topological space X is first countable if there is a countable base at each point. A space X is said to be **second countable** if there is a countable base for the topology.

**Example 4.** Every metric space is first countable.

**Proposition 36.** Let X be a first countable topological space. For a subset  $E \subseteq X$ , a point  $x \in X$  is called a point of closure of  $E \iff$  it is a limit of a sequence in E. Thus, a subset E of X is closed  $\iff$  whenever a sequence in E converges to  $x \in X$ , we have that  $x \in E$ .

Definition 58 (Dense/Separable). A subset  $E \subseteq X$  is dense in X if every open set in X contains a point of E. We call X separable if it has a countable dense subset.

**Definition 59** (Metrisable). A topological space X is said to be **metrisable** if the topology is induced by the metric.

**Theorem 32.** Let X be a second countable topological space. Then, X is metrisable  $\iff$  it is normal.

## 4.4. Continuous Mappings between Topological Spaces

Definition 60 (Continuous). For topological spaces  $(X, \mathcal{T})$ ,  $(Y, \mathcal{S})$ , a mapping  $f: X \to Y$  is said to be **continuous** at the point  $x_0$  in X if, for every neighbourhood  $\mathcal{O}$  if  $f(x_0)$ , there is a neighbourhood  $\mathcal{U}$  of  $x_0$  for which  $f(\mathcal{U}) \subseteq \mathcal{O}$ . We say that f is continuous provided it is continuous at each point in X.

**Proposition 37.** A mapping  $f: X \to Y$  between topological spaces X and Y is continuous  $\iff$  for any open subset  $\mathcal{O}$  in Y, its inverse image under f,  $f^{-1}(\mathcal{O})$ , is an open subset of X.

**Proposition 38.** The composition of continuous mappings between topological spaces, when defined, is continuous.

Definition 61 (Stronger). Given two topologies  $\mathcal{T}_1$  and  $\mathcal{T}_2$  for a set X, if  $\mathcal{T}_2 \subseteq \mathcal{T}_1$ , then we say that  $\mathcal{T}_2$  is weaker than  $\mathcal{T}_1$ , and that  $\mathcal{T}_1$  is stronger than  $\mathcal{T}_2$ .

**Proposition 39.** Let X be a non-empty set and let S be a collection of subsets of X that covers X. The collection of subsets of X consisting of intersections of finite collections of S is a base for a topology T of X. It is the weakest topology containing S in the sense that if T' is any other topology for X containing S, then  $T \subseteq T'$ .

Definition 62 (Weak Topology). Let X be a non-empty set and  $\mathcal{F} := \{f_{\alpha} \mid X \to X_{\alpha}\}_{{\alpha} \in \Lambda}$  a collection of mappings, where each  $X_{\alpha}$  is a topological space. The weakest topology for X that contains the collection of sets

$$\{f_{\alpha}^{-1}(\mathcal{O}_{\alpha}) \mid f_{\alpha} \in \mathcal{F}, \ \mathcal{O}_{\alpha} \text{ open in } X_{\alpha}\}$$
 (36)

is called the weak topology for X induced by  $\mathcal{F}$ .

**Proposition 40.** Let X be a non-empty set,  $\mathcal{F} := \{f_{\lambda} \mid X \to X_{\lambda}\}_{{\lambda} \in \Lambda}$  a collection of mappings where each  $X_{\lambda}$  is a topological space. The weak topology for X induced by  $\mathcal{F}$  is the topology on X that has the fewest number of sets covering the topologies on X for which each mapping  $f_{\lambda} : X \to X_{\lambda}$  is continuous.

Definition 63 (Homeomorphism). A mapping from a topological space  $X \to Y$  is said to be a **homeomorphism** if it is bijective and has a continuous inverse  $f^{-1}: Y \to X$ . Two topological spaces are said to be **homeomorphic** if there exists a homeomorphism between them. The notion of homeomorphism induces a notion of an equivalence relation between spaces.

# 4.5. Compact Topological Spaces

Definition 64 (Cover). A collection of sets  $\{E_{\lambda}\}_{{\lambda}\in\Lambda}$  is said to be a **cover** of a set E if  $E\subseteq\bigcup_{{\lambda}\in\Lambda}E_{\lambda}$ .

Definition 65 (Compact). A topological space X is said to be **compact** if every open cover of X has a finite sub-cover. A subset  $K \subseteq X$  is compact if K, considered as a topological space with the subspace topology inherited from X, is compact.

**Proposition 41.** A topological space X is compact  $\iff$  every collection of closed subsets of X that possesses the finite intersection property has non-empty intersection.

**Proposition 42.** A closed subset K of a compact topological space is compact.

**Proposition 43.** A compact subspace K of a Hausdorff topological space is a closed subset of X.

Definition 66 (Sequentially Compact). A topological space X is said to be sequentially compact if every sequence in X has a subsequence that converges to a point in X.

**Proposition 44.** Let X be a second countable topological space. Then, X is compact  $\iff$  it is sequentially compact.

**Theorem 33.** A compact Hausdorff space is normal.

**Proposition 45.** A continuous one-to-one mapping f of a compact space X onto a Hausdorff space Y is a homeomorphism.

**Proposition 46.** The continuous image of a compact topological space is compact.

Corollary 5. A continuous real-valued function on a compact topological space takes on a minimum and maximum functional value.

Definition 67 (Countably Compact). A topological space is **countably compact** if every countable open cover has a finite subcover.

#### 4.6. Connected Topological Space

Definition 68 (Separated). Two non-empty subsets of a topological space separate X if they are disjoint and their union is X.

Definition 69 (Connected). A topological space which cannot be separated by open sets is said to be connected. A subset  $E \subseteq X$  is connected if there do NOT exist open subsets  $\mathcal{O}_1$ ,  $\mathcal{O}_2$  of X for which:

$$\mathcal{O}_1 \cap E \neq \emptyset$$

$$\mathcal{O}_2 \cap E \neq \emptyset$$

$$E \subseteq \mathcal{O}_1 \cup \mathcal{O}_2,$$

$$E \cap \mathcal{O}_1 \cap \mathcal{O}_2 = \emptyset$$

**Proposition 47.** Let f be a continuous mapping of a connected space X to a topological space Y. Then, its image f(X) is connected.

**Proposition 48.** For A set  $C \in \mathbb{R}$ , the following are equivalent.

- (1) C is an interval.
- (2) C is convex.
- (3) C is connected.

Definition 70 (Intermediate Value Property). A topological space X has the intermediate value property if the image of any continuous real-valued function on X is an interval.

**Proposition 49.** A topological space has the intermediate value property  $\iff$  it is connected.

Definition 71 (Arcwise connected). A topological space X is arcwise connected if, for each pair  $u, v \in X$ , there exists a continuous map  $f : [0,1] \to X$  for which f(0) = u and f(1) = v. Note:

- (1) Connected  $\iff$  arcwise connected in  $\mathbb{R}^n$ .
- (2) Arcwise connected  $\Rightarrow$  connected (in general)
- (3) There exist connected but non-arcwise connected spaces (in general).

#### 4.7. Results from Homework

- (1) Let X be a topological space. Then, X is Hausdorff  $\iff$  the diagonal  $D := \{(x_1, x_2) \in X \times X \mid x_1 = x_2\}$  is closed as a subset of  $X \times X$ .
- (2) The Moore plane is separable. The subspace  $\mathbb{R} \times \{0\}$  is not separable. Thus, the Moore plane is not metrisable and not second countable.
- (3) Let X and Y be topological spaces. Then, you can construct a continuous map from a Hausdorff space to a non-Hausdorff space, and you can do the same for a normal space to a non-normal space.

(4) If  $\rho_1$  and  $\rho_2$  are metrics on a set X that induce topologies  $\mathcal{T}_1$  and  $\mathcal{T}_2$ , respectively, then if they generate the same topology  $\mathcal{T}_1 = \mathcal{T}_2$ , then they are <u>NOT</u> necessarily equivalent. A counter example would be:

$$\rho_1 := |x - y|$$

$$\rho_2 := \frac{|x - y|}{1 + |x - y|}$$