Math 455: Analysis IV Summary Midterm Date: 12 March 2020 18.00 - 20.00 Key Results, Theorems, Definitions, etc. Shereen Elaidi

Abstract

This document contains a summary of all the key definitions, results, and theorems from class. There are probably typos, and so I would be grateful if you brought those to my attention :-).

Syllabus: L^p space, duality, weak convergence, Young, Holder, and Minkowski inequalities, point-set topology, topological space, dense sets, completeness, compactness, connectedness, path-connectedness, separability, Tychnoff theorem, Stone-Weierstrass Theorem, Arzela-Ascoli, Baire category theorem, open mapping theorem, closed graph theorem, uniform boudnedness principle, Hahn Banch theorem.

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COMPLETENESS AND APPROXIMATION

NORMED VECTOR SPACES

Definition 1 (ℓ^p space). Let $(a_1, a_n, ...)$ be a sequence. Then, the ℓ^p -space is:

$$\ell^p := \left\{ (a_1, a_2, \dots) \mid \sum_{n=1}^{\infty} |a_n|^p < +\infty \right\}$$
 (1)

Theorem 1 (Riesz-Fisher). $L^p(X)$ is complete.

Definition 2 (L^p space). Let E be a measurable set and let $1 \le p < \infty$. Then, $L^p(E)$ is the collection of measurable functions f for which $|f|^p$ is Lebesgue integrable over E.

Definition 3 (Equivalent Functions). Let \mathcal{F} be the collection of all measurable extended real-valued functions on E that are finite a.e. on E. Define two functions f and g to be equivalent, and write $f \sim g$ if g(x) = f(x) a.e. on E.

Definition 4 (Essentially Bounded). We call a function $f \in \mathcal{F}$ to be **essentially bounded** if there exists some $M \geq 0$, called the **essential upper bound** for f, for which

$$|f(x)| \le M$$

for almost every $x \in E$. $L^{\infty}(E)$ is the collection of equivalence classes [f] for which f is essentially bounded.

Definition 5 (Norm). Let X be a linear space. A real-valued functional $||\cdot||$ on X is called a **norm** provided that for each f and g in X and each real number α ,

(i) (The Triangle Inequality).

$$||f + g|| \le ||f|| + ||g||$$

(ii) (Positive Homogeneity).

$$||\alpha f|| = |\alpha|||f||$$

(iii) (Non-Negativity).

$$||f|| \ge 0$$
 and $||f|| = 0$ if and only if $f = 0$

Definition 6 (Normed Linear Space). X is said to be a **normed linear space** if X is equipped with a norm.

Definition 7 (Essential Supremum). Let $f \in L^{\infty}(E)$. $||f||_{\infty}$ is called the **essential supremum** and is defined as:

$$||f||_{\infty} := \{M \mid M \text{ is an essential upper bound for } f\}$$

Theorem: $||\cdot||_{\infty}$ is a norm on $L^{\infty}(E)$.

1.2. The Inequalities of Young, Hölder, and Minkowski

Definition 8 (p-norm). Let E be a measurable set, $1 , and let <math>f \in L^p(E)$. Then, define the **p-norm** to be:

$$||f||_p := \left[\int_E |f|^p \right]^{\frac{1}{p}} \tag{2}$$

Definition 9 (Conjugate). The **conjugate** of a number $p \in]1, \infty[$ is the number q = p/(p-1), which is the unique number $q \in]1, \infty[$ for which

$$\frac{1}{p} + \frac{1}{q} = 1\tag{3}$$

The conjugate of 1 is defined to be ∞ and the conjugate of ∞ is defined to be 1.

Definition 10 (Young's Inequality). For 1 , q the conjugate of p, and any two positive numbers a and b, we have:

$$ab \le \frac{a^p}{p} + \frac{b^q}{q} \tag{4}$$

Theorem 2 (Hölder's Inequality). Let $E \subseteq \mathbb{R}$ be measurable, $1 \le p < \infty$, and q the conjugate of p. If f belongs to $L^p(E)$, and g belongs to $L^q(E)$, then their product $f \cdot g$ is integrable over E and:

$$\int_{E} |f \cdot g| \le ||f||_{p} \cdot ||g||_{q}. \tag{5}$$

Moreover, if $f \neq 0$, then the function defined as:

$$f^* := ||f||_p^{1-p} \cdot \operatorname{sgn}(f) \cdot |f|^{p-1} \tag{6}$$

belongs to $L^q(E)$,

$$\int_{E} f \cdot f^* = ||f||_p \text{ and } ||f^*||_q = 1$$

We call f^* defined as above to be called the **conjugate function** of f.

Theorem 3 (Minkowski's Inequality). Let E be a measurable set and $1 \le p \le \infty$. If the functions f and g belong to $L^p(E)$, then so does their sum f + g. Moreover,

$$||f+g||_p \le ||f||_p + ||g||_p \tag{7}$$

Theorem 4 (Cauchy-Schwarz Inequality). Let E be a measurable set and let f and g be measurable functions over E for which f^2 and g^2 are integrable over E. Then, $f \cdot g$ is integrable over E and

$$\int_{E} |f \cdot g| \le \sqrt{\int_{E} f^{2}} \cdot \sqrt{\int_{E} g^{2}} \tag{8}$$

Corollary 1. Let E be a measurable set and $1 . Suppose <math>\mathcal{F}$ is a family of functions in $L^p(E)$ that is bounded in $L^p(E)$ in the sense that there is a constant M for which

$$||f||_p \leq M$$
 for all $f \in \mathcal{F}$

Then, the family \mathcal{F} is uniformly integrable over E.

Corollary 2. Let E be a measurable set of finite measure and $1 \le p_1 < p_2 \le \infty$. Then, $L^{p_2}(E) \subseteq L^{p_1}(E)$. Furthermore,

$$||f||_{p_1} \leq c||f||_{p_2}$$

for all f in $L^{p_2}(E)$, where $c = [m(E)]^{\frac{p_2 - p_1}{q_1 p_2}}$ if $p_2 < \infty$ and $c = [m(E)]^{\frac{1}{p_1}}$ if $p_2 = \infty$.

1.3. L^p is complete: the Reisz-Fischer Theorem

Definition 11 (Converge). A sequence $\{f_n\}$ in a linear space X normed by $||\cdot||$ is said to converge to f in X provided:

$$\lim_{n \to \infty} ||f - f_n|| = 0$$

Definition 12 (Cauchy). A sequence $\{f_n\}$ in a linear space X that is normed by $||\cdot||$ is said to be Cauchy in X provided for each $\varepsilon > 0$, there exists a $N \in \mathbb{N}$ such that

$$||f_n - f_m|| < \varepsilon \ \forall \ m, n \ge N \tag{9}$$

Definition 13 (Complete). A normed linear space X is called **complete** if every Cauchy sequence in X converges to a function in X. A complete normed linear space is called a **Banach space**.

Proposition 1. Let X be a normed linear space. Then, every convergent sequence in X is Cauchy. Moreover, a Cauchy sequence in X converges if it has a convergent subsequence.

Definition 14. Let X be a linear space normed by $||\cdot||$. A sequence $\{f_n\}$ in X is said to be **rapidly** Cauchy if there is a convergent series of positive numbers $\sum_{k=1}^{\infty} \varepsilon_k$ for which

$$||f_{k+1} - f_k|| \le \varepsilon_k^2$$
 for all k

Proposition 2. Let X be a normed linear space. Then, every rapidly Cauchy sequence in X is Cauchy. Furthermore, every Cauchy sequence has a rapidly Cauchy subsequence.

Proposition 3. Let E be a measurable set and $1 \le p \le \infty$. Then, every rapidly Cauchy sequence in $L^p(E)$ converges with respect to the $L^p(E)$ norm and pointwise a.e. on E to a function in $L^p(E)$.

Theorem 5 (Riesz-Fischer Theorem). Let E be a measurable set and $1 \le p \le \infty$. Then $L^p(E)$ is a Banach space. Moreover, if $\{f_n\} \to f$ in $L^p(E)$, a subsequence of $\{f_n\}$ converges pointwise a.e. on E to f.

Theorem 6. Let E be a measurable set and $1 \le p < \infty$. Suppose $\{f_n\}$ is a sequence in $L^p(E)$ that converges pointwise a.e. on E to the function f which belongs to $L^p(E)$. Then:

$$\{f_n\} \to f \text{ in } L^p(E) \iff \lim_{n \to \infty} \int_E |f_n|^p = \int_E |f|^p$$

Definition 15 (Tight). A family \mathcal{F} of measurable functions on E is said to be **tight** over E provided that for each $\varepsilon > 0$, there exists a subset E_0 of E of finite measure for which

$$\int_{E \setminus E_0} |f| < \varepsilon \text{ for all } f \in \mathcal{F}$$

Theorem 7. Let E be a measurable set and let $1 \le p < \infty$. Suppose $\{f_n\}$ is a sequence in $L^p(E)$ that converges pointwise a.e. on E to the function f which belongs to $L^p(E)$. Then, $\{f_n\} \to f$ in $L^p(E) \iff \{|f_n|^p\}$ is uniformly integrable and tight over E.

1.4. Approximation and Separability

Definition 16 (Dense). Let X be a normed linear space with norm $||\cdot||$. Given two subsets \mathcal{F} and \mathcal{G} of X with $\mathcal{F} \subseteq \mathcal{G}$, we say that \mathcal{F} is **dense** in \mathcal{G} provided for each function g in \mathcal{G} and $\varepsilon > 0$, there is a function $f \in \mathcal{F}$ for which $||f - g|| < \varepsilon$.

Proposition 4. Let E be a measurable set and let $1 \le p \le \infty$. Then, the subspace of simple functions in $L^p(E)$ is dense in $L^p(E)$.

Proposition 5. Let [a, b] be a closed, bounded interval and $1 \le p < \infty$. Then, the subspace of step functions on [a, b] is dense in $L^p[a, b]$.

Definition 17 (Separable). A normed linear space X is said to be **separable** provided there is a countable subset that is dense in X.

Theorem 8. Let E be a measurable set and $1 \leq p < \infty$. Then, the normed linear space $L^p(E)$ is separable.

Theorem 9. Suppose E is measurable and let $1 \leq p < \infty$. Then, $C_c(E)$ (the set of all continuous functions with compact support on E) is dense in $L^p(E)$.

2. L^p Spaces: Duality and Weak Convergence

2.1. Riesz Representation Theorem for the Dual of L^p , $1 \le p < \infty$

Definition 18 (Linear Functional). A linear functional on a linear space X is a real-valued function T on T such that for g and g in X and α and β real numbers,

$$T(\alpha \cdot g + \beta \cdot h) = \alpha \cdot T(g) + \beta \cdot T(h) \tag{10}$$

Definition 19 (Bounded). For a normed linear space X, a linear functional T on X is said to be bounded provided there is an $M \ge 0$ for which

$$|T(f)| \le M \cdot ||f|| \text{ for all } f \in X$$
 (11)

The infimum of all such M is called the **norm** of T and is denoted by $||T||_*$.

Proposition 6 (Continuity Property of a Bounded Linear Functional). Let T be a bounded linear functional on the normed space X. Then, if $\{f_n\} \to f$ in X, then $\{T(f_n)\} \to \{T(f)\}$.

Proposition 7. Let X be a normed vector space. Then, the collection of bounded linear functionals on X is a linear space which is normed by $||\cdot||_*$. This normed vector space is called the **dual space** of X, and is denoted by X^* .

Proposition 8. Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$, q the conjugate of $p, g \in L^q(E)$. Define the functional T on $L^p(E)$ by:

$$T(f) := \int_{E} g \cdot f \,\,\forall f \in L^{p}(E) \tag{12}$$

Then, T is a bounded linear functional on $L^p(E)$ and $||T||_* = ||g||_q$.

Proposition 9. Let T, S be bounded linear functionals on the normed vector space X. If T = S on a dense subset X_0 of X, then T = S.

Lemma 10. Let $E \subseteq \mathbb{R}$ be measurable, $1 \le p < \infty$. Suppose that g is integrable over E and there exists a $M \ge 0$ for which

$$\left| \int_{E} g \cdot f \right| \leq M ||f||_{p} \,\, \forall f \in L^{p}(E), \,\, f \,\, \text{simple}$$

Then, $g \in L^q(E)$, where q is the conjugate of p. Moreover, $||g||_q \leq M$.

Theorem 11. Let [a,b] be a closed, bounded interval, and $1 \le p < \infty$. Suppose that T is a bounded linear functional on $L^p[a,b]$. Then, there is a functional $g \in L^q[a,b]$, where q is the conjugate of p, for which:

$$T(f) = \int_{a}^{b} g \cdot f \,\,\forall f \in L^{p}[a, b] \tag{13}$$

Theorem 12 (Riesz-Representation Theorem for the Dual of $L^p(E)$). Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$, and q the conjugate of p. For all $g \in L^q(E)$, define the bounded linear functional \mathcal{R}_q on $L^p(E)$ by:

$$\mathcal{R}_g := \int_E g \cdot f \ \forall f \in L^p(E) \tag{14}$$

Then, for each bounded linear functional T on $L^p(E)$, there exists a unique $g \in L^q(E)$ for which

- (i) $\mathcal{R}_g = T$ and
- (ii) $||T||_* = ||g||_q$

2.2. Weak Sequential Convergence in L^p

Definition 20 (Converge Weakly). Let X be a normed vector space. A sequence $\{f_n\}$ in X is said to converge weakly in X to f provided that

$$\lim_{n \to \infty} T(f_n) = T(f) \ \forall T \in X^*$$
 (15)

we write

$$\{f_n\} \rightharpoonup f$$

to mean that f and each f_n belong to X and $\{f_n\}$ converges weakly in X to f.

Definition 21. Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$, q the conjugate of p. Then, $\{f_n\} \rightharpoonup f$ in $L^p(E)$ \iff

$$\lim_{n \to \infty} \int_{E} g \cdot f_n = \int_{E} g \cdot f \,\,\forall g \in L^q(E) \tag{16}$$

Theorem 13. Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$. Suppose that $\{f_n\} \rightharpoonup f$ in $L^p(E)$. Then:

$$\{f_n\}$$
 is bounded and $||f||_p \leq \liminf ||f_n||_p$

Corollary 3. Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$, q the conjugate of p. Suppose $\{f_n\}$ converges weakly to f in $L^p(E)$ and $\{g_n\}$ converges strongly to $g \in L^q(E)$. Then:

$$\lim_{n \to \infty} \int_{E} g_n \cdot f_n = \int_{E} g \cdot f \tag{17}$$

Definition 22 (Linear Span). Let X be a normed vector space, and let $S \subseteq X$. Then, the linear span of S is the vector space consisting of all linear functionals of the form:

$$f = \sum_{k=1}^{n} \alpha_k \cdot f_k \tag{18}$$

where each $\alpha_k \in \mathbb{R}$ and $f_k \in S$. It is the set of all *finite linear combinations of elements in S*. We care about this since L^p is an infinite dimensional space, so we want to find a way to approximate it with finitely many elements.

Proposition 10 (Characterisation of Weak Convergence in $L^p(E)$). Let $E \subseteq \mathbb{R}$ be measurable, $1 \leq p < \infty$, q the conjugate of P. Assume that $\mathcal{F} \subseteq L^q(E)$ whose linear span is dense in $L^q(E)$. Let $\{f_n\}$ be a bounded sequence in $L^p(E)$, and let $f \in L^p(E)$. Then, $\{f_n\} \rightharpoonup f$ in $L^p(E) \iff$

$$\lim_{n \to \infty} \int_{E} f_n \cdot g = \int_{E} f \cdot g \,\,\forall g \in \mathcal{F} \tag{19}$$

Theorem 14. Let $E \subseteq \mathbb{R}$ be measurable, $1 \le p < \infty$. Suppose that $\{f_n\}$ is a bounded sequence in $L^p(E)$ and f belongs to $L^p(E)$. Then, $\{f_n\} \to f$ in $L^p(E) \iff \forall$ measurable sets $A \subseteq E$:

$$\lim_{n \to \infty} \int_{A} f_n = \int_{A} f \tag{20}$$

if p > 1, then it is sufficient to consider sets A of finite measure.

Theorem 15. Let [a,b] be a closed and bounded interval, $1 . Suppose that <math>\{f_n\}$ is a bounded sequence in $L^p[a,b]$ and $f \in L^p[a,b]$. Then, $\{f_n\} \rightharpoonup f$ in $L^p[a,b]$ in $L^p[a,b]$ \iff

$$\lim_{n \to \infty} \left[\int_{a}^{x} f_{n} \right] = \int_{a}^{x} f \, \forall x \in [a, b]$$
 (21)

Lemma 16 (Riemann-Lebesgue Lemma; used in Fourier Series :-)). Let $I = [-\pi, \pi], 1 \le p < \infty$. $\forall n \in \mathbb{N}$, define $f_n(x) := \sin(nx)$ for $x \in I$. Then, $\{f_n\}$ converges weakly in $L^p(I)$ to $f \equiv 0$.

Theorem 17. Let $E \subseteq \mathbb{R}$ be measurable, $1 . Suppose that <math>\{f_n\}$ is a bounded sequence in $L^p(E)$ that converges pointwise a.e. on E to f. Then, $\{f_n\} \rightharpoonup f$ in $L^p(E)$.

This theorem was used in the proof but was not covered in Analysis 3:

Theorem 18 (Vitali Convergence Theorem). Let $E \subseteq \mathbb{R}$ be measurable and of finite measure. Suppose that the sequence of functions $\{f_n\}$ is uniformly integrable over E. Then, if $\{f_n\} \to f$ pointwise a.e. on E, then f is integrable over E and $\lim_{n\to\infty} \int_E f_n = f$.

Theorem 19 (Radon-Riesz Theorem). Let $E \subseteq \mathbb{R}$ be measurable, $1 . Suppose that <math>\{f_n\} \rightharpoonup f$ in $L^p(E)$. Then:

$$\{f_n\} \to f \text{ in } L^p(E) \iff \lim_{n \to \infty} ||f_n||_p = ||f||_p$$
 (22)

Corollary 4. (Not Covered in Class): Let $E \subseteq \mathbb{R}$ be measurable and $1 . Suppose that <math>\{f_n\} \to f$ in $L^p(E)$. Then, a subsequence of $\{f_n\}$ converges strongly to $f \iff ||f||_p = \liminf ||f_n||_p$.

2.3. Weak Sequential Compactness ("Compactness Found!")

Theorem 20. Let $E \subseteq \mathbb{R}$ be measurable, $1 . Then, every bounded sequence in <math>L^p(E)$ has a subsequence that converges weakly in $L^p(E)$ to a function in $L^p(E)$.

Theorem 21 (Helly's Theorem). Let X be a SEPARABLE normed vector space and $\{T_n\}$ a sequence in its dual space X^* that is bounded; that is, \exists a M > 0 for which

$$|T_n(f)| \le M \cdot ||f|| \ \forall f \in X, \ \forall n \in \mathbb{N}$$

Then, there is a subsequence $\{T_{n_k}\}$ of $\{T_n\}$ and $T \in X^*$ for which

$$\lim_{k \to \infty} T_{n_k}(f) = T(f) \ \forall f \in X$$
 (23)

Definition 23 (Weakly Sequentially Compact (Compact in the "weak topology"). Let X be a normed vector space. Then, a subset $K \subseteq X$ is **weakly sequentially compact** in X provided that every sequence $\{f_n\}$ in K has a subsequence that converges weakly to $f \in K$.

Theorem 22 (The Unit Ball is Weakly Sequentially Compact). Let $E \subseteq \mathbb{R}$ be measurable, 1 . Define:

$$B_1 := \{ f \in L^p(E) \mid ||f||_p \le 1 \}. \tag{24}$$

 B_1 is weakly sequentially compact in $L^p(E)$.

3. Metric Spaces

This section was not covered in class, but since we have homework on this chapter I figured having this as a review from analysis 2 might be helpful. Also, there are a few terms/results that I don't think we covered in analysis 2.

3.1. Examples of Metric Spaces

Definition 24 (Metric Space). Let X be a non-empty set. A function $\rho: X \times X \to \mathbb{R}$ is called a **metric** if $\forall x, y \in X$:

- (i) $\rho(x,y) \geq 0$
- (ii) $\rho(x,y) = 0 \iff x = y$
- (iii) $\rho(x,y) = \rho(y,x)$
- (iv) $\rho(x,z) \leq \rho(x,y) + \rho(y,z)$ (Triangle Inequality).

A non-empty set together with a metric, denoted (X, ρ) is called a **metric space**.

Definition 25 (Discrete Metric). For any non-empty set X, the **discrete metric** ρ is defined by setting $\rho(x,y)=0$ if x=y and $\rho(x,y)=1$ if $x\neq y$.

Definition 26 (Metric Subspace). For any metric space (X, ρ) , let $Y \subseteq X$ be non-empty. Then, the restriction of ρ to $Y \times Y$ defines a metric on Y. We define this induced metric space as a **metric subspace**.

Example 3.1 (Examples of metric spaces). The following are examples of metric spaces:

- (i) Every non-empty subset of a Euclidean space.
- (ii) $L^p(E)$, where $E \subseteq \mathbb{R}$ is a measurable set.
- (iii) C[a,b].

Definition 27 (Product Metric). For metric spaces (X_1, ρ_1) and (X_2, ρ_2) , we define the **product metric** τ on the cartesian product $X_1 \times X_2$ by setting, for (x_1, x_2) and (y_1, y_2) in $X_1 \times X_2$:

$$\tau((x_1, x_2), (y_1, y_2)) := \{ [\rho_1(x_1, x_2)]^2 + [\rho_2(y_1, y_2)]^2 \}^{1/2}$$
(25)

Definition 28. Two metrics ρ and σ on a set X are said to be equivalent if there are positive numbers c_1 and c_2 such that $\forall x_1, x_2 \in X$,

$$c_1\sigma(x_1, x_2) \le \rho(x_1, x_2) \le c_2\sigma(x_1, x_2)$$

Definition 29 (Isometry). A mapping $f:(X,\rho)\to (Y,\sigma)$ between two metric spaces is called an **isometry** provided that f is surjective and $\forall x_1,x_2\in X$:

$$\sigma(f(x_1), f(x_2)) = \rho(x_1, x_2) \tag{26}$$

We say that two metric spaces are **isometric** if there is an isometry from one to another.

3.2. OPEN SETS, CLOSED SETS, AND CONVERGENT SEQUENCES

Definition 30 (Open Ball). Let (X, ρ) be a metric space. For a point $x \in X$ and r > 0, the set:

$$B(x,r) := \{ x' \in X \mid \rho(x',x) < r \}$$
(27)

is called the **open ball** centred at x of radius r. A subset $\mathcal{O} \subseteq X$ is said to be **open** if $\forall x \in \mathcal{O}$, there exists an open ball centred at x and contained in \mathcal{O} . For a point $x \in X$, an open set containing x is called a **neighbourhood** of x.

Proposition 11. Let X be a metric space. The whole set X and the empty set \emptyset are open. The intersection of any two open sets is open. The union of any collection of open sets is open.

Proposition 12. Let X be a subspace of a metric space Y and $E \subseteq X$. Then, E is **open in** $X \iff E = X \cap \mathcal{O}$, where \mathcal{O} is open in Y.

Definition 31 (Closure). For a subset $E \subseteq X$, a point $x \in X$ is called a **point of closure** of E provided that every neighbourhood of x contains a point in E. The collection of the points of closure of E is called the **closure** of E and is denoted by \overline{E} .

Proposition 13. For $E \subseteq X$, where X is a metric space, its closure \overline{E} is closed. Moreover, \overline{E} is the smallest closed subset of X containing E in the sense that if F is closed and if $E \subseteq F$, then $\overline{E} \subseteq F$.

Definition 32 (Converge). A sequence $\{x_n\}$ in a metric space (X, ρ) is said to **converge** to the point $x \in x$ provided that:

$$\lim_{n \to \infty} \rho(x_n, x) = 0$$

that is, $\forall \varepsilon > 0$, \exists an index N such that $\forall n \geq N$, $\rho(x_n, x) < \varepsilon$.

Proposition 14. Let ρ and σ be equivalent metrics on a non-empty set X. Then, a subset X is open in a metric space $(X, \rho) \iff$ it is open in (X, σ) .

3.3. Continuous Mappings Between Metric Spaces

Definition 33 (Continuous). A mapping f from a metric space X to a metric space Y is continuous at the point $x \in X$ if $\{x_n\} \in X$, if $\{x_n\} \to x$, then $\{f(x_n)\} \to f(x)$. f is said to be **continuous** if it is continuous at every point in X.

Proposition 15 (ε - δ criteria for continuity). A mapping from a metric space (X, ρ) to a metric (Y, σ) is continuous at the point $x \in X \iff \forall \varepsilon > 0, \exists \delta > 0$ such that if $\rho(x, x') < \delta$, then $\sigma(f(x), f(x')) < \varepsilon$. That is:

$$f(B(x,\delta)) \subseteq B(f(x),\varepsilon)$$
 (28)

Proposition 16. A mapping f from a metric space X to a metric space Y is continuous \iff \forall open subsets $\mathcal{O} \subseteq Y$, the inverse image under f of \mathcal{O} , $f^{-1}(\mathcal{O})$, is an open subset of X.

Proposition 17. The composition of continuous mappings between metric spaces, when defined, is continuous.

Definition 34 (Uniformly Continuous). A mapping from a metric space (X, ρ) to a metric space (Y, σ) is said to be **uniformly continuous** if $\forall \varepsilon > 0$, $\exists \delta > 0$ such that $\forall u, v \in X$, if $\rho(u, v) < \delta$, $\sigma(f(u), f(v)) < \varepsilon$.

Definition 35 (Lipschitz). A mapping $f:(X,\rho)\to (Y,\sigma)$ is said to be **Lipschitz** if \exists a $c\geq 0$ such that \forall $u,v\in X$:

$$\sigma(f(u), f(v)) \le c\rho(u, v)$$

3.4. Complete Metric Spaces

Definition 36 (Cauchy). A sequence $\{x_n\}$ in a metric space (X, ρ) is said to be a Cauchy sequence if $\forall \varepsilon > 0$, there exists a $N \in \mathbb{N}$ such that if $m, n \geq N$, then $\rho(x_n, x_m) < \varepsilon$.

Definition 37 (Complete). A metric space X is said to be **complete** if every Cauchy sequence in X converges to a point in X.

Proposition 18. Let [a, b] be a closed and bounded interval of real numbers. Then, C[a, b] with the metric induced by the max norm is complete.

Proposition 19 (Characterisation of Complete Subspaces of Metric Spaces). Let $E \subseteq X$, where X is a complete metric space. Then, the metric subspace E is complete $\iff E$ is a closed subset of X.

Theorem 23. The following are complete metric spaces:

- (i) Every non-empty closed subset of \mathbb{R}^n .
- (ii) $E \subseteq \mathbb{R}$ measurable, $1 \le p \le \infty$, each non-empty closed subset of $L^p(E)$.
- (iii) Each non-empty closed subset of C[a, b].

Definition 38 (Diameter). Let E be a non-empty subset of a metric space (X, ρ) . We define the **diameter** of E, denoted by diam(E), by:

$$\operatorname{diam}(E) := \sup \left\{ \rho(x, y) \mid x, y \in E \right\} \tag{29}$$

We say that E is **bounded** if it has finite diameter.

Definition 39 (Contracting Sequence). A decreasing sequence $\{E_n\}$ of non-empty subsets of X is called a contracting sequence if:

$$\lim_{n \to \infty} \operatorname{diam}(E_n) = 0 \tag{30}$$

Theorem 24 (Cantor Intersection Theorem). Let X be a metric space. Then, X is complete \iff whenever $\{F_n\}$ is a contracting sequence of non-empty closed subsets of X, there is a point $x \in X$ for which:

$$\bigcap_{n=1}^{\infty} F_n = \{x\} \tag{31}$$

Theorem 25. Let (X, ρ) be a metric space. Then, there is a complete metric space $(\widetilde{X}, \widetilde{\rho})$ for which X is a dense subset of \widetilde{X} and

$$\rho(u,v) = \tilde{\rho}(u,v) \ \forall \ u,v \in X \tag{32}$$

we call such a space the **completion** of (X, ρ) .

3.5. Compact Metric Spaces

Definition 40 (Compact Metric Space). A metric space X is called **compact** if every open cover of X has a finite sub-cover. A subset $K \subseteq X$ is compact if K, considered as a metric subspace of X, is compact.

Formulation of compactness in terms of closed sets: Let \mathcal{T} be a collection of open subsets of a metric space X. Define \mathcal{F} to be the collection of the complements of elements in \mathcal{T} . Since the elements of \mathcal{T} are open, the elements of \mathcal{F} are closed. Thus, \mathcal{T} is a cover \iff the elements of \mathcal{F} have *empty intersection*. By deMorgan's law, we can formulate compactness in terms of closed sets as:

A metric space X is compact \iff every collection of closed sets with empty intersection has a finite sub-collection whose intersection is non-empty.

This property is called the **finite intersection property**.

Definition 41 (Finite Intersection Property). A collection of sets \mathcal{F} is said to have the finite intersection property if any finite sub-collection of \mathcal{F} has a non-empty intersection.

Proposition 20 (Compactness in terms of closed sets). A metric space X is compact \iff every collection \mathcal{F} of closed subsets of X with the finite intersection property has a non-empty intersection.

Definition 42 (Totally Bounded). A metric space X is **totally bounded** if $\forall \varepsilon > 0$, the space X can be covered by a finite number of open balls of radius ε . A subset $E \subseteq X$ is said to be **totally bounded** if E, as a subspace of the metric space X, is totally bounded.

Definition 43 (ε -net). Let E be a subset of a metric space X. A ε -net for R is a finite collection of open balls $\{B(x_k, \varepsilon)\}_{k=1}^n$ with centres $x_k \in X$ whose union covers E.

Proposition 21. A metric space E is totally bounded $\iff \forall \varepsilon > 0$, there is a finite ε -net for E.

Proposition 22. A subset of Euclidean space \mathbb{R}^n is bounded \iff it is totally bounded.

Definition 44 (Sequentially Compact). A metric space X is sequentially compact if every sequence in X has a subsequence that converges to a point in X.

Theorem 26 (Characterisation of Compactness for a metric space). Let X be a metric space. Then, TFAE:

- (i) X is complete and totally bounded.
- (ii) X is compact.
- (iii) X is sequentially compact.

The following three propositions of this chapter are just breaking down these equivalences, so I will not write them.

Theorem 27. Let $K \subseteq \mathbb{R}^n$. Then, TFAE:

- (i) K is closed and bounded.
- (ii) K is compact.
- (iii) K is sequentially compact.

Observe: The equivalence $(1) \iff (2)$ is the Heine-Borel theorem. The equivalence $(2) \iff (3)$ is the Bolzano-Weierstrass theorem.

Proposition 23. Let f be a continuous mapping from a compact metric space X to a compact metric space Y. Then, its image f(X) is compact.

Theorem 28 (Extreme Value Theorem). Let X be a metric space. Then, X is compact \iff every continuous real-valued function on X attains a minimum and maximum value.

Definition 45 (Lebesgue Number). Let X be a metric space, and let $\{\mathcal{O}_{\lambda}\}_{{\lambda}\in\Lambda}$ be an open cover of X. Thus, each $x\in X$ is contained in a member of the cover, \mathcal{O}_{λ} . Since \mathcal{O}_{λ} is open, $\exists \ \varepsilon > 0$ such that:

$$B(x,\varepsilon) \subset \mathcal{O}_{\lambda}$$

In general, ε on X, but for compact metric spaces we can get *uniform control*. This ε that uniformly works is called the **Lebesgue number** for the cover $\{\mathcal{O}_{\lambda}\}_{{\lambda}\in\Lambda}$.

Lemma 29. Let $\{\mathcal{O}_{\lambda}\}_{\lambda in\Lambda}$ be an open cover of a compact metric space X. Then, there is a number $\varepsilon > 0$ such that for each $x \in X$, the open ball $B(x, \varepsilon)$ is contained in some member of the cover.

Proposition 24. A continuous mapping from a compact space (X, ρ) to a metric space (Y, σ) is uniformly continuous.

3.6. Separable Metric Spaces

Definition 46 (Dense & Separable). A subset D of a metric space X is **dense** in X if every non-empty subset of X contains a point of D. A metric space is **separable** if there is a countable subset of X that is dense in X.

The Weierstrass Approximation Theorem states that polynomials are dense in C[a, b]. So, C[a, b] is separable, with the countable dense set being the set of polynomials with rational coefficients.

Proposition 25. A compact metric space is separable.

Proposition 26. A metric space X is separable \iff there is a countable collection of $\{\mathcal{O}_n\}$ of open subsets of X such that any open subset of X is the union of a sub-collection of $\{\mathcal{O}_n\}$.

Proposition 27. Every subspace of a separable metric space is separable.

Theorem 30. Each of the following are separable metric spaces:

- (i) Every non-empty subset of Euclidean space \mathbb{R}^n .
- (ii) $1 \le p < \infty$, $L^p(E)$ and all non-empty subsets of $L^p(E)$.
- (iii) Each non-empty subset of C[a, b].
- 4. Topological Spaces
- 4.1. Open Sets, Closed Sets, Bases, and Sub-bases

Definition 47 (Open Sets). Let X be a non-empty set. A **topology** \mathcal{T} for X is a collection of subsets of X, called **open sets**, possessing the following properties:

- (i) The entire set X and the empty set \emptyset are open.
- (ii) The finite intersection of open sets are open.
- (iii) The union of any collection of open sets is open.

A non-empty set X, together with a topology on X, is called a **topological space**. For a point $x \in X$, an open set that contains x is called a **neighbourhood** of x.

Proposition 28. A subset $E \subseteq X$ is open \iff for each $x \in E$, there exists a neighbourhood of x that is contained in E.

Example 1 (Metric Topology). Let (X, ρ) be a metric space. Let $\mathcal{O} \subseteq X$ be open if for all $x \in \mathcal{O}$, \exists an open ball at x that is contained in \mathcal{O} . This collection of open sets forms a topology; we call this the **metric topology** induced by ρ .

Example 2 (Discrete Topology). This topology is "too much." Let X be a non-empty subset. Let $\mathcal{T} := \mathcal{P}(X)$. Then, every set containing a point is a neighbourhood of that point. This is induced by the discrete metric.

Example 3 (Trivial Topology). Let X be non-empty. Define $\mathcal{T} := \{X, \emptyset\}$. The only neighbourhood of any point is the whole set X.

Definition 48 (Topological Subspaces). Let (X, \mathcal{T}) be a topological space and let E be a non-empty subset of X. The inherited topology \mathcal{S} for E is the set of all sets of the form $E \cap \mathcal{T}$, where $\mathcal{O} \in \mathcal{T}$. The topological space (E, \mathcal{S}) is called a **subspace** of (X, \mathcal{T}) .

Definition 49 (Base for the Topology). The building blocks of a topology is called a base. Let (X, \mathcal{T}) be a topological space. For a point $x \in X$, a collection of neighbourhoods of x, B_x , is called a base for the topology at X if \forall neighbourhoods \mathcal{U} of x, there exists a set B in the collection B_x for which $B \subseteq \mathcal{U}$.

A collection of open sets \mathcal{B} is called a **base for the topology** \mathcal{T} provided it contains a base for the topology at each point.

A base for a topology completely determines a topology, alongside \emptyset and X.

Proposition 29. For a non-empty set X, let \mathcal{B} be a collection of subsets of X. Then, \mathcal{B} is a base for a topology for $X \iff$:

(i) \mathcal{B} covers X. That is:

$$X = \bigcup_{B \in \mathcal{B}} B \tag{33}$$

(ii) If $B_1, B_2 \in \mathcal{B}$, and $x \in B_1 \cap B_2$, then there is a set $B_3 \in \mathcal{B}$ for which $x \in B_3 \subseteq B_1 \cap B_2$.

The unique topology that has \mathcal{B} as its base consists of \emptyset and unions of sub-collections of \mathcal{B} .

Definition 50 (Product Topology). Let (X, \mathcal{T}) and (Y, \mathcal{S}) be two topological spaces. In the cartesian product $X \times Y$, consider the collection of sets \mathcal{B} containing the products $\mathcal{O}_1 \times \mathcal{O}_2$, where \mathcal{O}_1 is open in X and \mathcal{O}_2 is open in Y. Then, \mathcal{B} is a base for a topology on $X \times Y$, which we call the **product topology**.

Definition 51 (Sub-base). Let (X, \mathcal{T}) be a topological space. The collection of \mathcal{S} of \mathcal{T} that covers X is called a sub-base for the topology \mathcal{T} provided intersections of finite collections of \mathcal{S} are a base for \mathcal{T} .

Definition 52 (Closure). Let $E \subseteq X$ be a subset of a topological space. A point $x \in E$ is called a **point** of closure of E if every neighbourhood of x contains a point in E. The collection of the points of closure of E is called the closure of E, denoted \overline{E} .

Proposition 30. Let X be a topological space, $E \subseteq X$. Then, \overline{E} is closed. Moreover, \overline{E} is the smallest closed subset of X containing E in the sense that if F is closed and $E \subseteq F$, then $\overline{E} \subseteq F$.

Proposition 31. A subset of a topological space X is open \iff its complement is closed.

Proposition 32. Let X be a topological space. Then, (a) \emptyset and X are closed, (b) the union of a finite collection of closed sets is closed, (c) the intersection of any collection of closed sets in X is closed.

4.2. Separation Properties

Motivation: Separation properties for a topology allow us to discriminate between which topologies discriminate between certain disjoint pairs of sets, which will then allow us to study a robust collection of cts real-valued functions on X.

Definition 53 (Neighbourhood). A neighbourhood of K for a subset $K \subseteq X$ is an open set that contains K.

Definition 54 (Separated by Neighbourhoods). We say that two disjoint sets A and B in X can be separated by disjoint neighbourhoods provided that there exists neighbourhoods of A and B, respectively, that are disjoint.

Definition 55 (Separation Properties of Topological Spaces). In the order of most general to least general, they are:

(i) Tychonoff Separation Property: For each two points $u, v \in X$, there exists a neighbourhood of u that does not contain v and a neighbourhood of v that does not contain u.

- (ii) **Hausdorff Separation Property**: Each two points in X can be separated by disjoint neighbourhoods.
- (iii) Regular Separation Property: Tychonoff + each closed set and a point not in the set can be separated by disjoint neighbourhoods.
- (iv) Normal Separation Property: Tychonoff + each two disjoint closed sets can be separated by disjoint neighbourhoods.

Proposition 33. A topological space is Tychonoff \iff every set containing a single point, $\{x\}$, is closed.

Proposition 34. Every metric space is normal.

Lemma 31. F is closed \iff dist $(x, F) > 0 \ \forall \ x \notin F$.

Proposition 35. Let X be a Tychonoff topological space. Then, X is normal \iff whenever \mathcal{U} is a neighbourhood of a closed subset of F of X, there is another neighbourhood of F whose closure is contained in \mathcal{U} . that is, there is an open set \mathcal{O} for which:

$$F \subseteq \mathcal{O} \subseteq \overline{\mathcal{O}} \subseteq \mathcal{U} \tag{34}$$

4.3. Countability and Separability

Definition 56 (Converge, Limit). A sequence $\{x_n\}$ in a topological space X is said to **converge** to the point $x \in X$ if for each neighbourhood \mathcal{U} of x, there exists an index $N \in \mathbb{N}$ such that if $n \geq N$, then x_n belongs to \mathcal{U} . This point is called a **limit** of the sequence.

Definition 57 (First and Second Countable). A topological space X is first countable if there is a countable base at each point. A space X is said to be **second countable** if there is a countable base for the topology.

Example 4. Every metric space is first countable.

Proposition 36. Let X be a first countable topological space. For a subset $E \subseteq X$, a point $x \in X$ is called a point of closure of E \iff it is a limit of a sequence in E. Thus, a subset E of X is closed \iff whenever a sequence in E converges to $x \in X$, we have that $x \in E$.

Definition 58 (Dense/Separable). A subset $E \subseteq X$ is **dense** in X if every open set in X contains a point of E. We call X separable if it has a countable dense subset.

Definition 59 (Metrisable). A topological space X is said to be **metrisable** if the topology is induced by the metric.

Theorem 32. Let X be a second countable topological space. Then, X is metrisable \iff it is normal.

4.4. Continuous Mappings between Topological Spaces

Definition 60 (Continuous). For topological spaces (X, \mathcal{T}) , (Y, \mathcal{S}) , a mapping $f: X \to Y$ is said to be **continuous** at the point x_0 in X if, for every neighbourhood \mathcal{O} if $f(x_0)$, there is a neighbourhood \mathcal{U} of x_0 for which $f(\mathcal{U}) \subseteq \mathcal{O}$. We say that f is continuous provided it is continuous at each point in X.

Proposition 37. A mapping $f: X \to Y$ between topological spaces X and Y is continuous \iff for any open subset \mathcal{O} in Y, its inverse image under f, $f^{-1}(\mathcal{O})$, is an open subset of X.

Proposition 38. The composition of continuous mappings between topological spaces, when defined, is continuous.

Definition 61 (Stronger). Given two topologies \mathcal{T}_1 and \mathcal{T}_2 for a set X, if $\mathcal{T}_2 \subseteq \mathcal{T}_1$, then we say that \mathcal{T}_2 is weaker than \mathcal{T}_1 , and that \mathcal{T}_1 is stronger than \mathcal{T}_2 .

Proposition 39. Let X be a non-empty set and let S be a collection of subsets of X that covers X. The collection of subsets of X consisting of intersections of finite collections of S is a base for a topology T of X. It is the weakest topology containing S in the sense that if T' is any other topology for X containing S, then $T \subseteq T'$.

Definition 62 (Weak Topology). Let X be a non-empty set and $\mathcal{F} := \{f_{\alpha} \mid X \to X_{\alpha}\}_{\alpha \in \Lambda}$ a collection of mappings, where each X_{α} is a topological space. The weakest topology for X that contains the collection of sets

$$\{f_{\alpha}^{-1}(\mathcal{O}_{\alpha}) \mid f_{\alpha} \in \mathcal{F}, \ \mathcal{O}_{\alpha} \text{ open in } X_{\alpha}\}$$
 (35)

is called the weak topology for X induced by \mathcal{F} .

Proposition 40. Let X be a non-empty set, $\mathcal{F} := \{f_{\lambda} \mid X \to X_{\lambda}\}_{{\lambda} \in \Lambda}$ a collection of mappings where each X_{λ} is a topological space. The weak topology for X induced by \mathcal{F} is the topology on X that has the fewest number of sets covering the topologies on X for which each mapping $f_{\lambda} : X \to X_{\lambda}$ is continuous.

Definition 63 (Homeomorphism). A mapping from a topological space $X \to Y$ is said to be a **homeomorphism** if it is bijective and has a continuous inverse $f^{-1}: Y \to X$. Two topological spaces are said to be **homeomorphic** if there exists a homeomorphism between them. The notion of homeomorphism induces a notion of an equivalence relation between spaces.

4.5. Compact Topological Spaces

Definition 64 (Cover). A collection of sets $\{E_{\lambda}\}_{{\lambda}\in\Lambda}$ is said to be a **cover** of a set E if $E\subseteq\bigcup_{{\lambda}\in\Lambda}E_{\lambda}$.

Definition 65 (Compact). A topological space X is said to be **compact** if every open cover of X has a finite sub-cover. A subset $K \subseteq X$ is compact if K, considered as a topological space with the subspace topology inherited from X, is compact.

Proposition 41. A topological space X is compact \iff every collection of closed subsets of X that possesses the finite intersection property has non-empty intersection.

Proposition 42. A closed subset K of a compact topological space is compact.

Proposition 43. A compact subspace K of a Hausdorff topological space is a closed subset of X.

Definition 66 (Sequentially Compact). A topological space X is said to be sequentially compact if every sequence in X has a subsequence that converges to a point in X.

Proposition 44. Let X be a second countable topological space. Then, X is compact \iff it is sequentially compact.

Theorem 33. A compact Hausdorff space is normal.

Proposition 45. A continuous one-to-one mapping f of a compact space X onto a Hausdorff space Y is a homeomorphism.

Proposition 46. The continuous image of a compact topological space is compact.

Corollary 5. A continuous real-valued function on a compact topological space takes on a minimum and maximum functional value.

Definition 67 (Countably Compact). A topological space is **countably compact** if every countable open cover has a finite subcover.

4.6. Connected Topological Space

Definition 68 (Separated). Two non-empty subsets of a topological space **separate** X if they are disjoint and their union is X.

Definition 69 (Connected). A topological space which cannot be separated by open sets is said to be **connected**. A subset $E \subseteq X$ is **connected** if there do NOT exist open subsets \mathcal{O}_1 , \mathcal{O}_2 of X for which:

$$\mathcal{O}_1 \cap E \neq \emptyset$$

$$\mathcal{O}_2 \cap E \neq \emptyset$$

$$E \subseteq \mathcal{O}_1 \cup \mathcal{O}_2,$$

$$E \cap \mathcal{O}_1 \cap \mathcal{O}_2 = \emptyset$$

Proposition 47. Let f be a continuous mapping of a connected space X to a topological space Y. Then, its image f(X) is connected.

Proposition 48. For A set $C \in \mathbb{R}$, the following are equivalent.

- (i) C is an interval.
- (ii) C is convex.
- (iii) C is connected.

Definition 70 (Intermediate Value Property). A topological space X has the intermediate value property if the image of any continuous real-valued function on X is an interval.

Proposition 49. A topological space has the intermediate value property \iff it is connected.

Definition 71 (Arcwise connected). A topological space X is arcwise connected if, for each pair $u, v \in X$, there exists a continuous map $f : [0, 1] \to X$ for which f(0) = u and f(1) = v. Note:

- (i) Connected \iff arcwise connected in \mathbb{R}^n .
- (ii) Arcwise connected \Rightarrow connected (in general)
- (iii) There exist connected but non-arcwise connected spaces (in general).