

# MATH 567: FUNCTIONAL ANALYSIS (FALL 2020 SEMESTER)

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This class is about linear functional analysis. This has a lot in common with linear algebra in infinite-dimensional spaces. We can think of this as infinite-dimensional linear algebra. There are two main applications of this: (a) geometry and topology in infinite dimensions and (b) solving PDEs. Recall that in regular linear algebra, we used those tools to solve linear systems. The infinite-dimensional equivalent to this is a PDE. In this class, we'll focus on the second application of functional analysis.

## 1. BASIC FUNCTIONAL ANALYSIS

This corresponds to Chapters 4 and 5 of the textbook.

**1.1. Banach Spaces and General Topology.** Let  $X$  be a vector space. Recall that this means that it is closed under addition and scalar multiplication.

**Definition 1.1** (Norm). A **norm** on a vector space  $X$ ,  $\|\cdot\| : X \rightarrow [0, \infty[$ , satisfies the following three properties:

- (1)  $\|x\| = 0 \iff x = 0$ .
- (2) **(Homogeneity)**:  $\|\lambda x\| = |\lambda| \|x\|$  for each  $x \in X$ ,  $\lambda \in \mathbb{R}$ .
- (3) **(Triangle Inequality)**:  $\|x + y\| \leq \|x\| + \|y\|$ .

**Definition 1.2** (Completeness / Banach Space).  $X$  is **complete** if every Cauchy sequence converges.  $(X, \|\cdot\|)$  is a **Banach space** if it is a complete normed vector space.

**Definition 1.3** (Dense Subset).  $Y \subseteq X$  is **dense** if

- (1)  $\overline{Y} = X$  (one thing we need to note:  $\overline{Y}$  is the closure, but we need to ask ourselves “in which topology”?).

This is equivalent to:

$$\forall \varepsilon > 0, \forall x \in X, \exists y \in Y \text{ s.t. } \|x - y\| < \varepsilon.$$

And also equivalent to,

$$\forall x \in X, \exists \{y_n\} \subseteq Y \text{ s.t. } y_n \rightarrow x.$$

**Definition 1.4** (Strong Topology). The **strong topology** is the topology induced by the norm,  $\|\cdot\|$  (the open sets are characterized by the balls,  $B_r := \{x \mid \|x\| < r\}$ ). In this topology, the definitions of density given above are equivalent.

**Definition 1.5** (Separable).  $X$  is **separable** if  $\exists$  a countable dense subset.

We have the following equivalent definitions of compactness.

**Definition 1.6** (Compactness 1).  $E \subseteq X$  is **compact** if every open cover of  $E$  admits a finite subcover.

**Definition 1.7** (Compactness 2). Every sequence has a convergent sub-sequence.

**Definition 1.8** (Compactness 3). For any sequence  $\{x_n\} \subseteq E$ , there exists  $\{x_{n_k}\}$  and  $x^* \in E$  such that  $x_{n_k} \rightarrow x^* \in E$ .

**Definition 1.9** (Pre-Compact).  $E \subseteq X$  is **pre-compact** if  $\overline{E}$  is compact.

**1.2. Euclidean Space  $\mathbb{R}^n$ .** Let  $x \in \mathbb{R}^n$ . This is denoted by  $(x_1, \dots, x_n)$ . Then, recall,

$$\|x\| = \|x\|_{\ell^2} = \left( \sum_{j=1}^n x_j^2 \right)^{1/2}.$$

We also have these other typical norms on Euclidean space:

$$\begin{aligned} \|x\|_{\ell^1} &= \sum_{j=1}^n |x_j| \\ \|x\|_{\ell^p} &= \left( \sum_{j=1}^n |x_j|^p \right)^{1/p} \\ \|x\|_{\ell^\infty} &= \max_{1 \leq j \leq n} |x_j|. \end{aligned}$$

**Definition 1.10** (Equivalent Norms). We say that two norms,  $|\cdot|$  and  $\|\cdot\|$ , are equivalent if and only if there exist two constants  $a$  and  $b$  such that

$$(1.11) \quad \boxed{a\|x\| \leq |x| \leq b\|x\| \quad \forall x \in X.}$$

In words, this is saying that you can't be big on one norm but small in another. These norms are comparable; they are bounded by constants on either side.

**Theorem 1.12.** All norms on  $\mathbb{R}^n$  are equivalent (all norms in finite dimensions are equivalent).

*Proof.* Let  $\|\cdot\|$  be the Euclidean norm, and let  $|\cdot|$  be another norm. Let  $\{e_i\}_{i=1}^n$  be the standard basis of  $\mathbb{R}^n$ ; recall that this is  $e_i = (0, \dots, 1, \dots, 0)$  where the 1 is in the  $i$ th slot. Since this is a basis, for  $x \in X$ :

$$x = \sum_{i=1}^n x_i e_i.$$

By the reverse triangle inequality,

$$\begin{aligned} \|x\| - \|y\| &\leq \|x - y\| \\ &= \left\| \sum_{i=1}^n (x_i - y_i) e_i \right\| \\ &\leq \sum_{i=1}^n |x_i - y_i| \|e_i\| \\ &\leq \underbrace{\left( \sum_{i=1}^n \|e_i\|^2 \right)^{1/2}}_{:=C} \left( \sum_{i=1}^n |x_i - y_i|^2 \right)^{1/2} \quad (\text{Cauchy-Schwarz}) \\ &\leq C\|x - y\| \quad (*), \end{aligned}$$

where  $C$  is some number. Norms are continuous;  $x \mapsto \|x\|$  is continuous  $S = \{x \mid \|x\| = 1\}$  (the unit ball). By (\*),  $x \mapsto |x|$  is continuous on  $S$ .  $S$  is closed and bounded on  $\mathbb{R}^n$  which means that  $S$  is compact. By the extreme value theorem, this means that there exist two constants  $a, b \in \mathbb{R}$  such that

$$(1.13) \quad a \leq |x| \leq b \quad \forall x \in S.$$

Observe that  $|x| = 0 \iff x = 0$ , which implies that  $a > 0$ . For any  $y \in \mathbb{R}^n$ , let  $x := \frac{y}{\|y\|} \in S$ . Then,

$$a \leq \left| \frac{y}{\|y\|} \right| \leq b \iff a \leq \frac{1}{\|y\|} |y| \leq b \iff a\|y\| \leq |y| \leq b\|y\| \quad \forall y \in \mathbb{R}^n \setminus \{0\}.$$

The case of  $y = 0$  is straightforward. This proves that any norm in a finite-dimensional vector space are equivalent. Note that this proof rests on the fact that we have a basis.  $\square$

*Remark 1.14.*  $\mathbb{R}^n$  is separable in any norm. The typical countable dense subset of  $\mathbb{R}^n$  is  $\mathbb{Q}^n$ . We will see in infinite-dimensions that all norms are not equivalent.

### 1.3. The Spaces of $C^r$ , $C^{r,\gamma}$ of Continuous Functions.

**Definition 1.15** ( $C^0$ ). Let  $\Omega \subseteq \mathbb{R}^n$  be open. Then,

$$\begin{aligned} C^0(\Omega) &:= \{f \mid \Omega \rightarrow \mathbb{R} \text{ s.t. } f \text{ is continuous on } \Omega\} \\ C^0(\overline{\Omega}) &:= \{f \mid \overline{\Omega} \rightarrow \mathbb{R} \text{ s.t. } f \text{ is continuous on } \overline{\Omega}\}. \end{aligned}$$

This implies that  $f \in C^0(\overline{\Omega})$  is bounded and uniformly continuous.

**Definition 1.16** ( $\|\cdot\|_\infty$ ). The standard norm on  $C^0(\Omega)$  is

$$(1.17) \quad \|u\|_\infty := \sup_{x \in \Omega} |u(x)| \leftrightarrow \text{uniform convergence.}$$

**Proposition 1.18.** (1)  $(C^0(\Omega), \|\cdot\|_\infty)$  is a Banach space.

(2) If  $\Omega \subseteq \mathbb{R}^n$  is bounded, then  $C^0(\overline{\Omega})$  is separable.

We will only give a sketch of the proof.

*Proof.* (1) The uniform limit of continuous functions is continuous.

(2) Follows from the Weierstrass approximation theorem: polynomials are dense in  $C^0(\overline{\Omega})$ ; then, consider the polynomials with rational coefficients. □

1.3.1. *Higher-Order Derivatives.* Recall some notation from advanced calculus:

$$(1.19) \quad Du = \nabla u = \text{gradient of } u = \begin{bmatrix} \partial_1 u \\ \vdots \\ \partial_n u \end{bmatrix}.$$

We consider the **multi-index**  $\alpha = (\alpha_1, \dots, \alpha_n)$ , where  $|\alpha| := \alpha_1 + \dots + \alpha_n$ , and  $\forall k \in \mathbb{R}^n$ , define  $k^\alpha := k_1^{\alpha_1} \dots k_n^{\alpha_n}$ . Then, in this notation,

$$\begin{aligned} D^\alpha u &= \partial_1^{\alpha_1} \dots \partial_n^{\alpha_n} u \\ &= \frac{\partial^{|\alpha|} u}{\partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}} \quad (\text{partial derivative}). \end{aligned}$$

**Definition 1.20** ( $C^r(\Omega)$ ).

$$(1.21) \quad C^r(\Omega) := \{f \mid D^\alpha f \in C^0(\Omega) \forall |\alpha| \leq r\}$$

In words, this means that all partial derivatives less than or equal to  $r$  are continuous. Then, we can define the following space:

$$(1.22) \quad C^\infty(\Omega) := \bigcap_{r=1}^{\infty} C^r(\Omega).$$

**Definition 1.23** (Support of  $f$ ). The **support** of  $f$  is defined as the smallest closed set such that  $f \equiv 0$  on  $\mathbb{R}^n \setminus \text{supp}(f)$ .

$$(1.24) \quad \text{supp}(f) := \overline{\{x \mid f(x) \neq 0\}}.$$

**Definition 1.25** (Compactly Contained). A set  $K \subset \subset \Omega$  means that  $K \subseteq \Omega$  is compact. We say that  $K$  is **compactly contained** in  $\Omega$  if  $K \subset \subset \Omega$ ,  $\Omega$  is bounded, and that there exists an  $\varepsilon > 0$  such that  $B(x, \varepsilon) \subseteq \Omega$  for all  $x \in K$ . This is equivalent to for all  $x \in K$ ,

$$(1.26) \quad \exists \varepsilon > 0 \text{ s.t. } d(x, \partial\Omega) := \inf_{y \in \partial\Omega} |x - y| > \varepsilon.$$

**Definition 1.27** ( $C_c^r(\Omega)$ ).

$$(1.28) \quad C_c^r(\Omega) := \{f \mid f \in C^r(\Omega), \text{supp}(f) \subset \subset \Omega\}.$$

**Definition 1.29** (Norm on  $C^r(\overline{\Omega})$ ). Let  $\Omega$  be bounded. Then,

$$(1.30) \quad \|f\|_{C^r} := \sum_{|\alpha| \leq r} \sup_{x \in \Omega} |D^\alpha f(x)|.$$

**Proposition 1.31.** Let  $\Omega \subseteq \mathbb{R}^n$  be bounded. Then,  $C^r(\Omega)$  is a separable Banach space (in fact, all you need for separable is that it is bounded) for all  $r < \infty$ .

*Remarks 1.32.*  $C_c^r(\Omega)$  is not complete.  $C^\infty(\Omega)$  is not complete. However, subspaces of  $C^\infty$  is still complete with some norm.

We also introduce,

**Definition 1.33** (Hölder Continuous  $C^{0,\gamma}(\Omega)$ ).  $f : \Omega \rightarrow \mathbb{R}$  is **Hölder Continuous** with exponent  $\gamma \in [0, 1[$  if there exists a  $C$  such that

$$(1.34) \quad |f(x) - f(y)| \leq C \|x - y\|^\gamma.$$

If  $\gamma = 1 \Rightarrow f$  is **Lipschitz Continuous**.

Also,

$$[f]_{C^{0,\gamma}(\Omega)} := \sup_{x,y \in \Omega} \frac{|f(x) - f(y)|}{\|x - y\|^\gamma}$$

is called the **Hölder seminorm**. This is not a norm, but we can make it a norm:

**Definition 1.35** ( $\|\cdot\|_{C^{0,\gamma}}$ ).

$$(1.36) \quad \|f\|_{C^{0,\gamma}(\Omega)} := \|f\|_\infty + [f]_{C^{0,\gamma}(\Omega)}.$$

On the homework, you'll show that

$$(C^{0,\gamma}(\Omega), \|f\|_{C^{0,\gamma}(\Omega)})$$

is complete.

**Definition 1.37** ( $C^{r,\gamma}$ ).

$$(1.38) \quad C^{r,\gamma}(\Omega) := \{f \mid f \in C^r(\Omega) \text{ and } |D^\alpha f(x) - D^\alpha f(y)| \leq C \|x - y\|^\gamma \forall |\alpha| = r\}.$$

The norm of this space is given by,

$$(1.39) \quad \|f\|_{C^{r,\gamma}} := \|f\|_{C^r} + \sup_{|\alpha|=r} [D^\alpha f]_{C^{0,\gamma}}.$$

*Remark 1.40.* If  $f \in C^{0,\gamma}(\Omega)$ ,  $\Omega$  bounded, then  $f \in C^{0,\alpha}(\Omega)$  for all  $0 < \alpha \leq \gamma$

*Remark 1.41. (Rademacher's Theorem).* If  $f \in C^{0,1}$ , then  $f$  is differentiable a.e.

#### 1.4. Integration Theorems.

**Theorem 1.42** (Monotone Convergence Theorem). If  $f_n \uparrow f$  pointwise for almost every  $x$ , then

$$(1.43) \quad \lim_{n \rightarrow \infty} \int_{\Omega} f_n(x) dx = \int_{\Omega} f(x) dx.$$

**Theorem 1.44** (Fatou's Lemma). Let  $\{f_n\}$  be a sequence of measurable functions that are all positive. Then,

$$(1.45) \quad \int_{\Omega} \liminf_{n \rightarrow \infty} f_n(x) \leq \liminf_{n \rightarrow \infty} \int_{\Omega} f_n(x) dx$$

**Theorem 1.46** (Dominated Convergence Theorem). Assume that  $\{f_n\}$  are measurable,  $f_n \rightarrow f$  pointwise a.e. Then, if  $|f_n(x)| \leq g(x)$  for all  $n \in \mathbb{N}$  for almost every  $x$ , where  $g \in L^1(\Omega)$ , then

$$(1.47) \quad \lim_{n \rightarrow \infty} \int_{\Omega} f_n(x) dx = \int_{\Omega} f(x) dx$$

This is the theorem that you use when you want to differentiate under integrals.

**Theorem 1.48.** The space  $C_c^0(\mathbb{R}^n)$  is dense in  $L^1(\mathbb{R}^n)$ .

**Theorem 1.49** (Fubini-Tonelli). *For all  $f : X \times Y \rightarrow \mathbb{R}^n$ ,*

$$(1.50) \quad \boxed{\int_X \int_Y |f(x, y)| dy dx = \int_Y \int_X |f(x, y)| dx dy = \int_{X \times Y} |f(x, y)| d(x, y).}$$

*If, moreover,  $f \in L^1(X \times Y)$ ,*

$$(1.51) \quad \int_X \int_Y f(x, y) dy dx = \int_Y \int_X f(x, y) dx dy = \int_{X \times Y} f(x, y) d(x, y)$$

### 1.5. Elementary $L^p$ Spaces.

**Definition 1.52** ( $L^p$ ). Fix  $1 \leq p < \infty$ , let  $\Omega \subseteq \mathbb{R}^n$ . Then, we define the  $L^p$  space to be

$$(1.53) \quad \boxed{L^p(\Omega) := \{f : \Omega \rightarrow \mathbb{R} \mid f \text{ measurable } |f|^p \in L^1(\Omega)\}}$$

with the following norm,

$$(1.54) \quad \|f\|_{L^p} := \left[ \int_{\Omega} |f(x)|^p \right]^{1/p}.$$

**Definition 1.55** ( $L^\infty$ ). We define  $L^\infty$  to be:

$$(1.56) \quad L^\infty(\Omega) := \{f : \Omega \rightarrow \mathbb{R} \mid f \text{ measurable }, \exists C \text{ s.t. } |f(x)| \leq C \text{ a.e. } \},$$

with the following norm,

$$(1.57) \quad \|f\|_{L^\infty} = \|f\|_\infty = \inf\{c \mid |f(x)| \leq c \text{ a.e.}\}$$

This definition implies that  $f(x) \leq \|f\|_\infty$  almost everywhere. Below are some fundamental tools that we'll be using

**Theorem 1.58** (Hölder's Inequality). *Let  $1 \leq p, p' \leq \infty$ . If  $f \in L^p(\Omega)$ ,  $g \in L^{p'}(\Omega)$  and  $1/p + 1/p' = 1$ , then  $fg \in L^1$  and*

$$(1.59) \quad \boxed{\int |fg| dx \leq \|f\|_p \|g\|_{p'}}$$

**Theorem 1.60** (Minkowski's Inequality). *For all  $p \in [1, \infty]$ ,*

$$(1.61) \quad \boxed{\|f + g\|_p \leq \|f\|_p + \|g\|_p.}$$

As a consequence of [Minkowski's Inequality,  $L^p$  is a vector space.