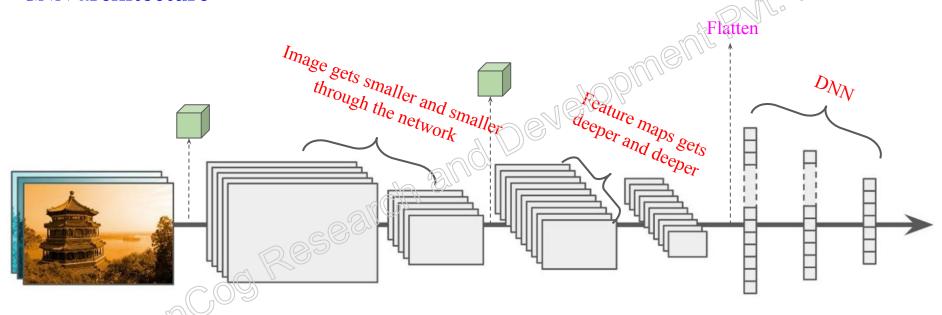


# TRANSFER LEARNING

Dr. Ram Prasad K VisionCog R&D





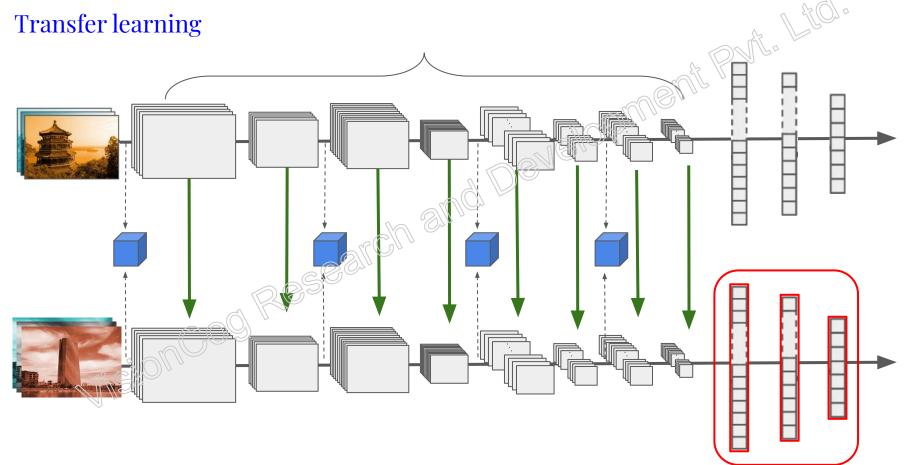


Input Convolution

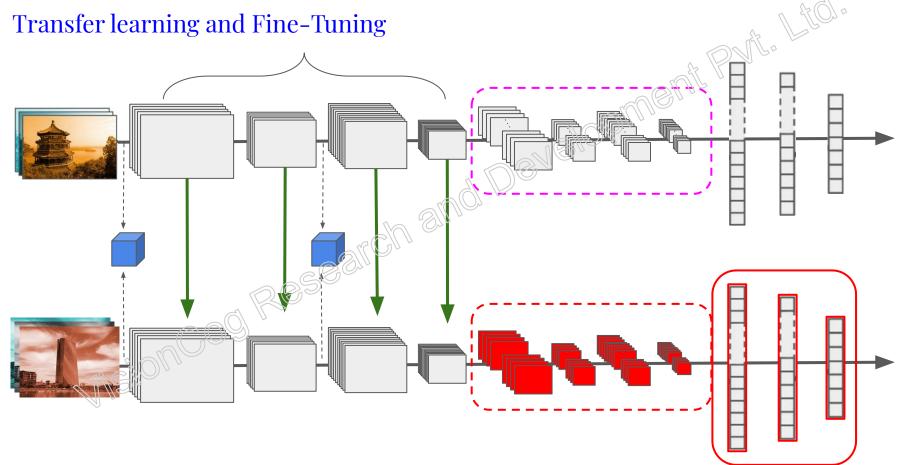
Pooling Convolution Pooling Fully connected

# TRANSFER LEARNING









# [cs.CV]0.02357

### **Xception: Deep Learning with Depthwise Separable Convolutions**

# François Chollet Google, Inc.

fchollet@google.com

### Abstract

We present an interpretation of Inception modules in convolutional neural networks as being an intermediate step in-between regular convolution and the depthwise separable convolution operation (a depthwise convolution followed by a pointwise convolution). In this light, a depthwise separable convolution can be understood as an Inception module with a maximally large number of towers. This observation leads us to propose a novel deep convolutional neural network architecture inspired by Inception, where Inception modules have been replaced with depthwise separable convolutions. We show that this architecture, dubbed Xception, slightly outperforms Inception V3 on the ImageNet dataset (which Inception V3 was designed for), and significantly outperforms Inception V3 on a larger image classification dataset comprising 350 million images and 17,000 classes. Since the Xception architecture has the same number of parameters as Inception V3, the performance gains are not due to increased capacity but rather to a more efficient use of model parameters.

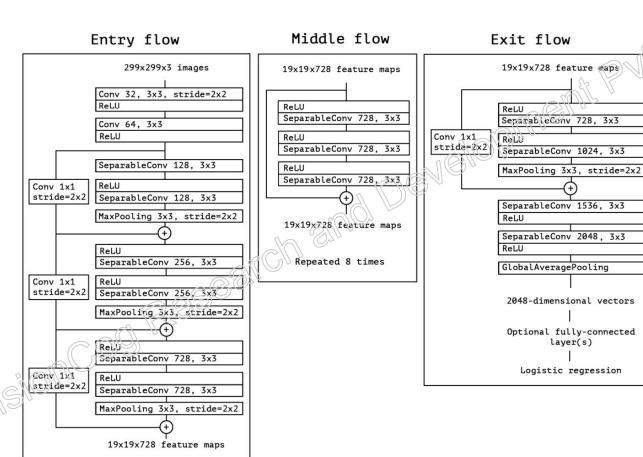
as GoogLeNet (Inception V1), later refined as Inception V2 [7], Inception V3 [21], and most recently Inception-ResNet [19]. Inception itself was inspired by the earlier Network-In-Network architecture [11]. Since its first introduction, Inception has been one of the best performing family of models on the ImageNet dataset [14], as well as internal datasets in use at Google, in particular JFT [5].

The fundamental building block of Inception-style models is the Inception module, of which several different versions exist. In figure 1 we show the canonical form of an Inception module, as found in the Inception V3 architecture. An Inception model can be understood as a stack of such modules. This is a departure from earlier VGG-style networks which were stacks of simple convolution layers.

While Inception modules are conceptually similar to convolutions (they are convolutional feature extractors), they empirically appear to be capable of learning richer representations with less parameters. How do they work, and how do they differ from regular convolutions? What design strategies come after Inception?

### 1.1. The Inception hypothesis







# FLOWER CLASSIFICATION



### **Flower Classification**

daisy









### **Flower Classification**

dandelion









### **Flower Classification**

rose









### **Flower Classification**

sunflower









# **Flower Classification**

tulip









http://download.tensorflow.org/example images/flower photos.tgz (3,670)

### Tiny version

https://www.visioncog.com/rpk/tiny FR.zip (500)

# Flower Classification (100 each, size of image varies)

- daisy
- dandelion
- rose
- sunflower
- tulip











!unzip tiny FR.zip



```
# Original dataset
# http://download.tensorflow.org/example_images/flower_photos.tgz
# Download tiny version of the dataset from VisionCog website
# After download and unzip, remember to comment the following two lines.
```

!wget https://www.visioncog.com/rpk/tiny FR.zip



... DRIVE
... DRIVE
... tiny\_FR
... tiny\_FR.zip Files X



```
Original dataset
 http://download.tensorflow.org/example images flower photos.tgz
 Download tiny version of the dataset from VisionCog website
# After download and unzip, remember to comment the following two lines.
#!wget https://www.visioncog.com/rpk/tiny FR.zip
#!unzip tiny FR.zip
```



```
# Install TensorFlow
try:
  # %tensorflow version only exists in Colab.
  %tensorflow version 2.x
except Exception:
  pass
import tensorflow as tf
print(tf. version
```



```
from tensorflow import keras
tf.random.set_seed(42)
```

import numpy as np
np.random.seed(42)

import matplotlib.pyplot as plt
%matplotlib inline

import glob
import PIL
from PIL Import Image



```
imgFiles = glob.glob("tiny FR/*/*.jpg")
for items in imgFiles[:5]:
  print(items)
 tiny FR/sunflower/1715303025 @7065327e2.jpg
  tiny FR/sunflower/2442985637 8748180f69.jpg
  tiny FR/sunflower/27466794 57e4fe5656.jpg
  tiny FR/sunflower/40411019 526f3fc8d9 m.jpg
  tiny FR/sunflower/253586685 ee5b5f5232.jpg
```



```
X = []
y = []
for fName in imgFiles:
  X i = Image.open(fName) # tiny FR/sunflower/1715303025 e7065327e2 pg
  X i = X i.resize((299,299)) # To make them approriate to Reption model when using Transfer Learning
  X_i = np.array(X_i) / 255.0 \# Normalize to range 0.0 to 1.0 (not stretching, only scaling)
  X.append(X i)
  label = fName.split("") # ['tiny FR', 'sunflower', '1715303025 e7065327e2.jpg']
                    sunflower'
  y.append(y i)
```



```
print(set(y))
# {'daisy', 'sunflower', 'dandelion', 'rose', 'tulip'}
from sklearn.preprocessing import LabelEncoder
lEncoder = LabelEncoder()
y = lEncoder.fit transform(y)
print(set(y))
# {0, 1, 2, 3, 4}
print(lEncoder.classes )
 ['daisp 'dandelion' 'rose' 'sunflower' 'tulip']
```



```
X = np.array(X)
 = np.array(y)
print(X.shape)
  (500, 299, 299, 3)
print(y.shape)
  (500,)
from sklearn.model_selection import train_test_split
X train, X test, y train, y test = train_test_split(X, y, test_size=0.2,
                                                     stratify=y, random state=42)
```

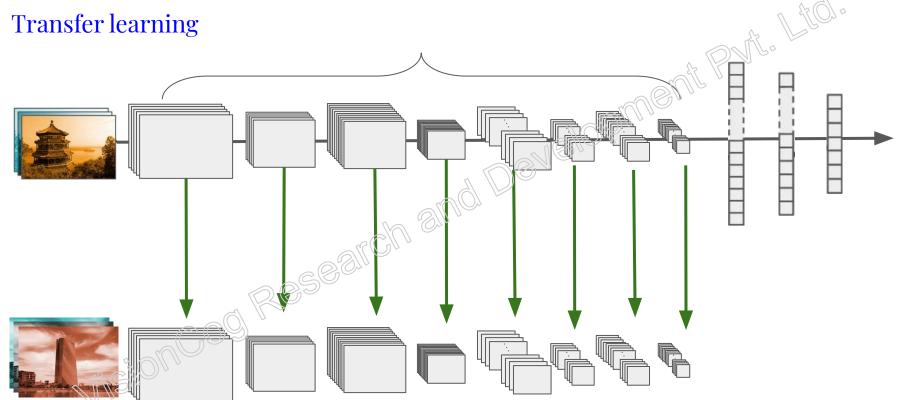


```
print("X train shape: {}".format(X train.shape))
# X train shape: (400, 299, 299, 3)
print("X test shape: {}".format(X test.shape))
# X test shape: (100, 299, 299, 3)
# Standard scaling
mu = X train.mean()
std = X train.std()
X train std = (X train-mu)/std
X test std = (X test-mu)/std
```



```
include_top=False)
```

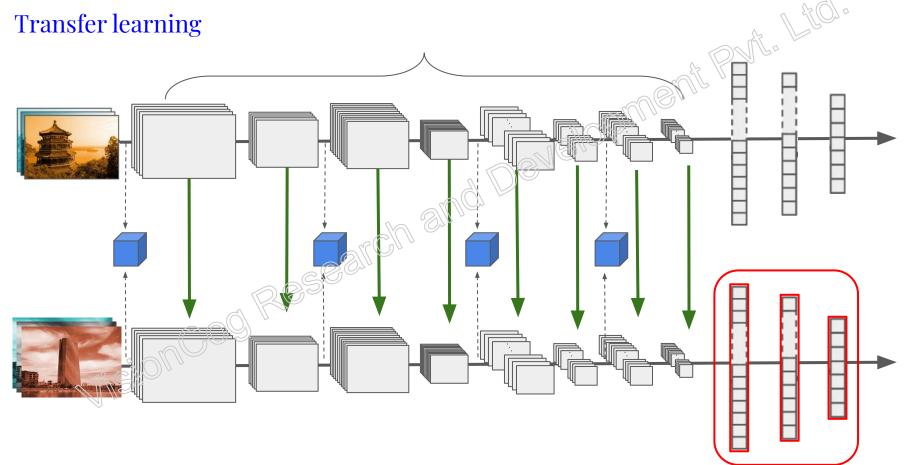






```
base model = keras.applications.xception.Xception(weight@limagenet',
                                                  include top=False)
for layer in base model.layers:
  layer.trainabe = False
global pool = keras.layers.GlobalAveragePooling2D()(base model.output)
output = keras.layers.Dense(units=5, activation='softmax')(global pool)
model TL = keras.models.Model(inputs=[base model.input], outputs=[output])
```







```
history_TL = model_TL.fit(x = X_train_std, y = y_train, epochs=25, validation_split=0.1, batch_size=16)
```

Train on 360 samples, validate on 40 samples

```
Epoch 1/25
360/360 [===]-27s 75ms/sample - loss: 0.9786 - accuracy: 0.6500 - val_loss: 7.0164 - val_accuracy: 0.5500
Epoch 2/25
360/360 [===]-15s 40ms/sample - loss: 0.4938 - accuracy: 0.8583 - val_loss: 10.1537 - val_accuracy: 0.3000
Epoch 3/25
360/360 [===]-14s 40ms/sample - loss: 0.3327 - accuracy: 0.8889 - val_loss: 6.9043 - val_accuracy: 0.4000
```

```
Epoch 24/25
360/360 [===]-14s 39ms/sample - loss: 0.0482 - accuracy: 0.9806 - val_loss: 1.0079 - val_accuracy: 0.7500
Epoch 25/25
360/360 [===]-14s 39ms/sample - loss: 0.0650 - accuracy: 0.9750 - val_loss: 7.1623 - val_accuracy: 0.6250
```



Train on 360 samples, validate on 40 samples

```
Epoch 1/25
360/360 [===]-27s 75ms/sample - loss: 0.9786 - accuracy: 0.6500 val_loss: 7.0164 - val_accuracy: 0.5500
Epoch 2/25
360/360 [===]-15s 40ms/sample - loss: 0.4938 - accuracy: 0.8583 - val_loss: 10.1537 - val_accuracy: 0.3000
Epoch 3/25
360/360 [===]-14s 40ms/sample - loss: 0.3327 - accuracy: 0.8889 - val_loss: 6.9043 - val_accuracy: 0.4000
...

Epoch 24/25
360/360 [===]-14s 39ms/sample - loss: 0.0482 - accuracy: 0.9806 - val_loss: 1.0079 - val_accuracy: 0.7500
Epoch 25/25
360/360 [===]-14s 39ms/sample - loss: 0.0650 - accuracy: 0.9750 - val_loss: 7.1623 - val_accuracy: 0.6250
```



```
testLoss TL, testAccuracy TL = model TL.evaluate(x = X test std, y = y test)
# 100/1 [===] - 3s 26ms/sample - loss: 2.6403 - accuracy: 0.7200
print("Test-loss: %f, Test-accuracy: %f" % (testLoss TL, testAccuracy TL))
# Test-loss: 3.964784, Test-accuracy: 0.720000
```