# "Pattern Recognition"

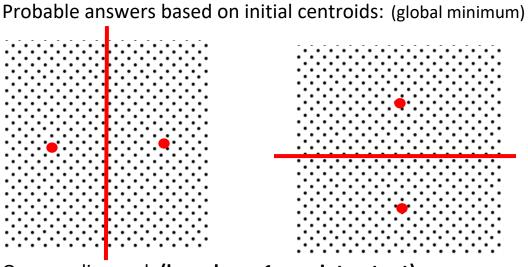
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Homework 5

1.

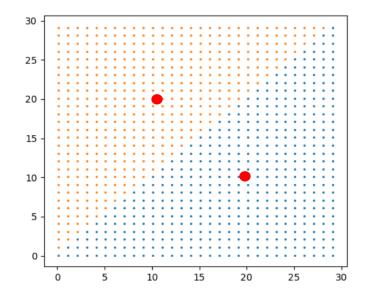
Considering K-Means algorithm converges to local minimum, the final clusters depend on initial centroids. Thus, for some parts more than one probable clustering is shown (clusters' separating lines and centroids are shown by red lines and red dots respectively):

a.



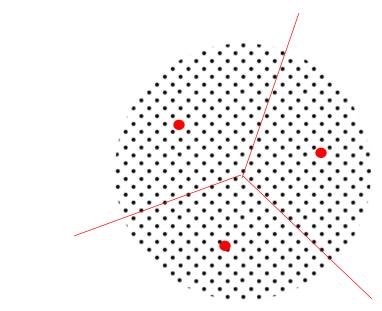
Or even diagonal: (based on p1.a script output)

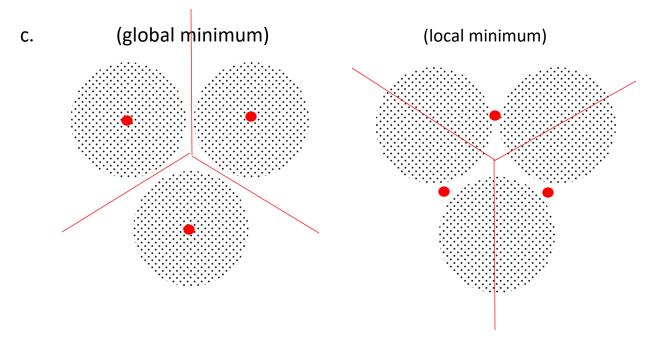
(local minimum)



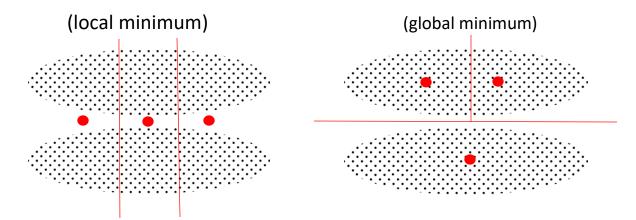
b.

For a single cyclic shaped datapoints, any three equal clusters (k=3) obtained by each triple of diameters is probable. That is, angle between diameters should be 120° degree.

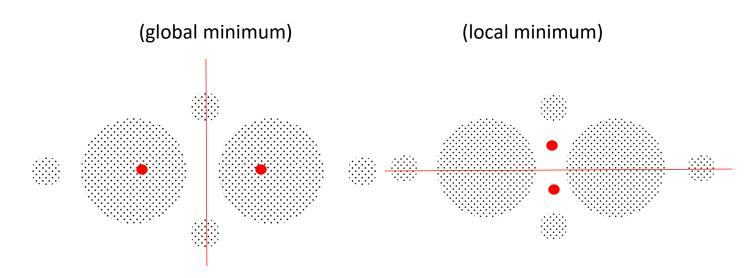




d.



e.



f.

???

g.

???

h.

Result (2). Since K-means tends to cluster data into equally shaped and sized groups.

i. Result (1)

j. Result (2)

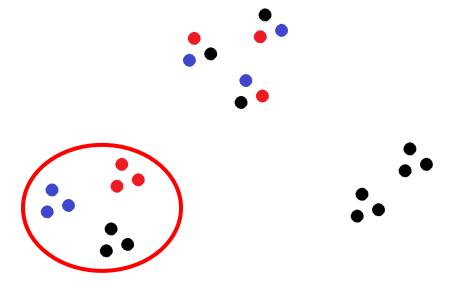
k. Result (2)

Result (1)

m.

١.

The only group consisting well seperated clusters is shown with red circle:



2.

Note:

"c1" denotes: center of cluster 1

"mean 1" denotes: mean of cluster 1 datapoints

a.

Step1: c1 = [1,3], c2 = [5,3]

Considering euclidean distances:

 $\rightarrow$  Cluster1 includes: (1,2,3)  $\rightarrow$  mean 1: [5/3 , 3]

Cluster2 includes:  $(4,5,6) \rightarrow \text{mean 2: } [13/3,3]$ 

Step2: c1 = [5/3, 3], c2 = [13/3, 3]

Considering euclidean distances:

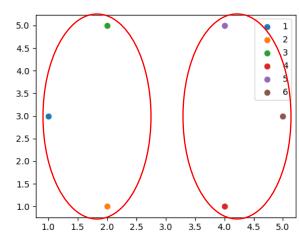
 $\rightarrow$  Cluster1 includes: (1,2,3)  $\rightarrow$  mean 1: [5/3, 3]

Cluster2 includes:  $(4,5,6) \rightarrow \text{mean 2: } [13/3,3]$ 

"Non of datapoints' clusters changed in step 2"

With only two steps we can say kmeans converged with the centroids of [5/3, 3] and [13/3, 3].

Clusters:



Step1: 
$$c1 = [2,5]$$
,  $c2 = [4,1]$ 

Considering euclidean distances:

 $\rightarrow$  Cluster1 includes: (1,3,5)  $\rightarrow$  mean 1: [7/3, 13/3]

Cluster2 includes:  $(2,4,6) \rightarrow \text{mean 2: } [11/3, 5/3]$ 

Step2: 
$$c1 = [7/3, 13/3], c2 = [11/3, 5/3]$$

Considering euclidean distances:

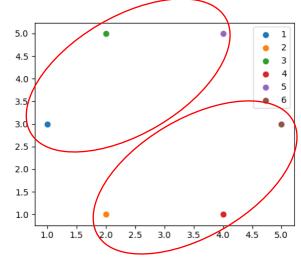
 $\rightarrow$  Cluster1 includes: (1,2,3)  $\rightarrow$  mean 1: [7/3, 13/3]

Cluster2 includes:  $(4,5,6) \rightarrow \text{mean 2: } [11/3, 5/3]$ 

### "Non of datapoints' clusters changed in step 2"

With only two steps we can say kmeans converged with the centroids of [7/3, 13/3] and [11/3, 5/3].

Clusters:



C.

Note:

"dis(#1, C1)" denotes: euclidean distance between datapoint '1' and centroid 'C1'.

Cosidering equation below:

$$SSE = \sum_{k=1}^{K} \sum_{\forall x_i \in C_k} ||x_i - \mu_k||^2$$

Clustering 'a':

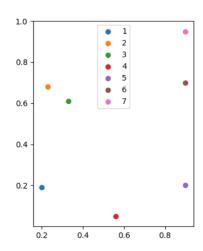
SSE(a) = 
$$dis(1, c1) + dis(2, c1) + dis(3, c1) + dis(4, c2)$$
  
+  $dis(5, c2) + dis(6, c2) = 17.3 = SSE(a)$ 

Clustering 'b':

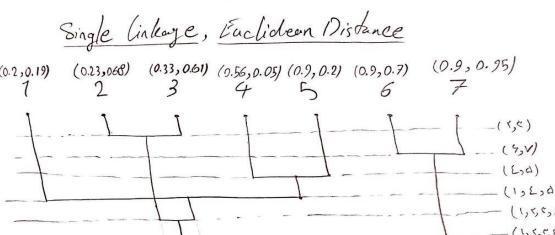
SSE(b) = 
$$dis(1, c1) + dis(3, c1) + dis(5, c1) + dis(2, c2)$$
  
+  $dis(4, c2) + dis(6, c2) = 15 = SSE(b)$ 

Therefore, comparing two SSE values, 'b' clustering is better.

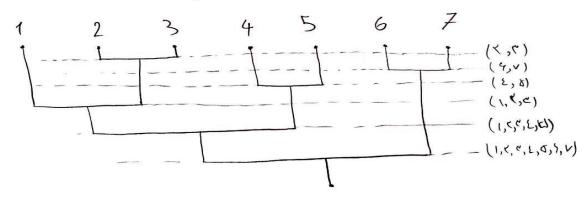




Hierarchical Chustering 8



Complete linkage, Buclèdean Distance



a.

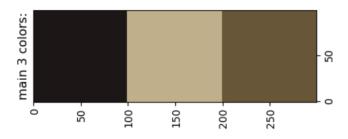
Probably the idea behind this problem is to apply K-means clustering on the dataset of RGB values in photo, as if these RGBs are sample points in three dimensional space. And lasly, introduce the mean of each cluster as one the main colors of the photo! (The 'k' just refers to the number of clusters desired in the final output)

## (Related script is p3.a)

Note: Due to high runtime of implemented K-means code, for the image of shape (495,600), the Scikit library was used.

#### K = 3:

#### Main 3 colors:



#### K = 5:

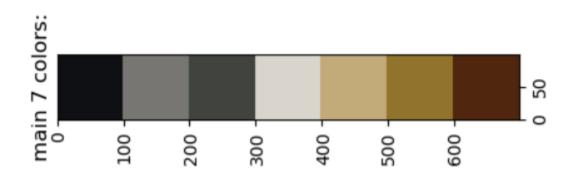
#### Main 5 colors:



### K = 7:

```
main 7 colors in RGB is:
[[ 14.34446811
               16.26746566
                              20.680938
 [119.5195302
               118.40846908 114.93519935]
 [ 65.27225348
                68.78746288
                              62.72378065]
 [217.23042616 212.05358913 204.9287838 ]
 [194.22560119 170.68587109 121.7533473 ]
 [146.33622253 115.21973598
                              44.31515195]
 [ 81.92767454
                38.67988089
                              14.71207936]]
```

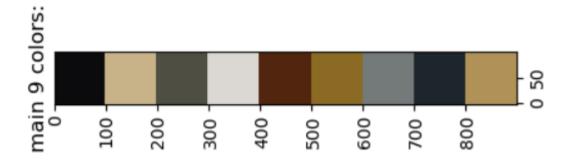
#### Main 7 colors:



#### K = 9:

```
main 9 colors in RGB is:
[[ 11.13797796
                11.15741472
                              14.1440691 ]
 [200.30509962 179.68301956 137.40208371]
  79.06746928
                78.348201
                              66.51336162]
 [219.70875711 216.88441648 212.15462851]
  81.60257336
                37.95849301
                              14.32209571]
 [139.75627942 107.29120649
                              36.304347831
 [116.66271686 121.55250028 121.54314548]
 [ 29.83386142
                38.12580032
                              45.84052619]
 [176.70182717 146.74172648
                            88.19944999]]
```

#### Main 9 colors:

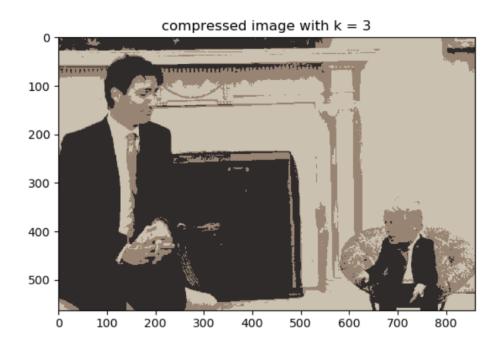


b.

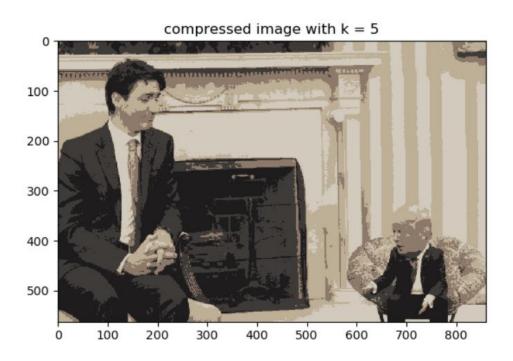
The idea behind this problem (Image Segmentation) is probably finding 'K' clusters then assign centroids' values (Centroid RGB) of each cluster to all datapoint (RGB pixel) whitin that cluster as a representation of the color of that cluster.

## (Related script is p3.b)

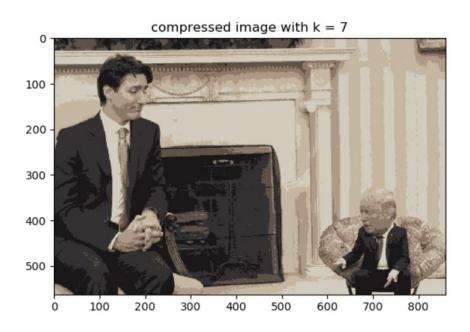
k = 3:



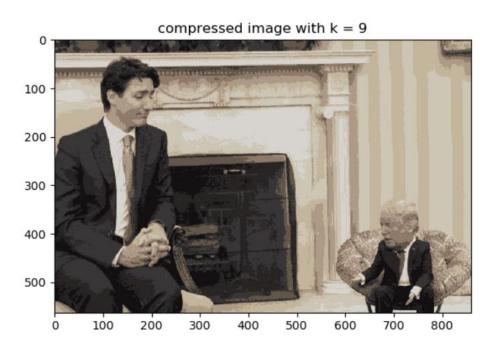
k = 5:



## k = 7:



## k = 9:

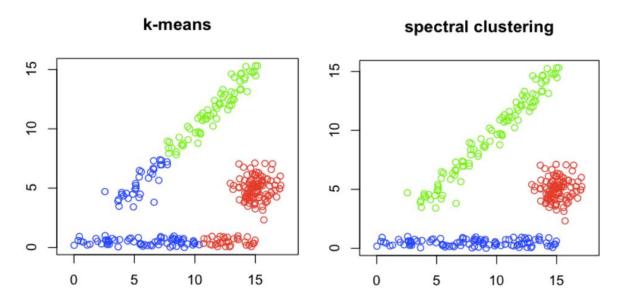


c.

a.

One probable solution for clustering compact and elongated clusters simultaneously may be Spectral Clustering. Spectral Clustering separate clusters based on connectedness of datapoints (as against k-means which work with distance metrics). Spectral clustering uses the spectrum (eigenvalues) of a matrix to cluster the points.

Below, an example is shown on performance of both Spectral Clustering and K-means:



b.

Unlike similar names thanks to letter 'K', K-means and KNN are completely different methods with no meaningful relations. Each of the mentioned learning algorithms works under separate categories. KNN is a classification (or regression) supervised learning algorithm which is applied to classify datapoints based on K nearest neighbors of that

point, hence, in KNN label of each datapoint is known. Reversely, K-means becomes under unsupervised learning algorithm (clustering) which tries to find K number of clusters which do exist based on a given data consisting of datapoints with no specified labels or classes. The only similarity between the two mentioned algorithms is that their function is based on distance metrices.

C.

Solely, under one criterion, the final clustering result may vary even with the same starting points! That criterion is existing of datapoints which may be exactly in the middle of centroids. Since, in the mentioned situations the datapoint may be assigned randomly to each cluster with the same distance from centroids. Ignoring this condition, the solution with same number of clusters and starting points will always be the same.