CSE 101:

Introduction to Computational Thinking

Unit 9:

Computer Architecture and Assembly Language

von Neumann Architecture

- In the beginning of the course we learned the basics of the **von Neumann architecture**, which consists of several components:
 - The central processing unit, or CPU, which performs computations
 - The main memory, which provides temporary storage of data
 - **Input/output (I/O) devices**, which enable data to enter and leave the computer

von Neumann Architecture

- Millions or billions of times per second the CPU performs the following steps (the **fetch-decode-execute** cycle):
 - 1. Fetch the next instruction from memory.
 - 2. Decode the instruction to determine what to do.
 - 3. If necessary, read operands (data) from main memory that are needed to perform the instruction.
 - 4. Execute the instruction.
 - 5. If necessary, write a result back to main memory.

von Neumann Architecture

- The CPU itself is composed of several sub-components:
 - The **arithmetic/logic unit**, which performs the computations
 - The control unit, which decodes the instructions and tells the ALU what to do
 - Registers, which are small memory banks that temporarily hold instruction operands and results
- Registers are needed because the CPU cannot directly perform calculations on values stored in memory
- Rather, the CPU first copies operands from memory to registers, performs the operation (the result of which is saved in a register), and copies the result from the register back to memory

- Ultimately, all data in a computer is reduced to 1s and 0s, even images, audio, video everything
- Therefore, all computations are performed on bits
- We already saw three bitwise operators in Python:

	AND	OR	XOR			
a b	a & b	a b	a ^ b			
0 0	0	0	0			
0 1	0	1	1			
1 0	0	1	1			
1 1	1	1	0			

- These bitwise operators can be used with multi-bit values
- For example, suppose we had the following **bitstrings**:
 - 0010110011001010
 - 1001101010101010
- The operation below:

0010110011001010

& 10011010101010

would perform a bitwise-AND on each pair of bits:

0010110011001010

Perform 16 **AND** operations on each "vertical" pair of bits

These operations can likewise be performed for bitwise OR
 (|) and bitwise XOR (^):

```
0010110011001010
| 1001101010101010
| 1011111011101010
```

```
0010110011001010

^ 10011010101010000

1011011001100000
```

- Two other useful operators for working with bits are the shift left (<<) and shift right (>>) operators
- These operators shift bits by a given number of positions
- For a shift left, bits on the left-hand side are dropped and zeroes are *shifted in* on the right-hand side
- For a shift right, bits on the right-hand side are dropped and copies of the leftmost bit are shifted in on the left-hand side
 - For example, if the leftmost bit is 0, then zeroes are shifted in
 - If the leftmost bit is 1, then ones are shifted in

• Some examples:

```
0010110011001010 >> 3 = 0000010110011001
1010110011001010 << 2 = 1011001100101000
```

- With these five bitwise operators (&, |, ^, >>, <<), we can perform many useful operations
 - One important thing to note: the bits themselves are numbered from right-to-left starting with position #0
 - In the examples so far, which have 16 bits, the bits are numbered from 0 to 15 (right-to-left):

bit:	1	0	1	0	1	1	0	0	1	1	0	0	1	0	1	0
#	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Masking Bits

- Masking is the process of using bitwise operators to read out or change the bits in a bitstring
- Masking operations are used in many kinds of systemslevel applications and scenarios, such as operating systems, network communication, computer graphics, and others

- Example: mask some bits to 1
- Suppose we wanted to turn on certain bits in a particular number, leaving the other bits unaffected
 - To turn a bit *on* means to set it to 1
- We create a mask with 1s in those bit locations (0 for the other bits) and then use bitwise-OR
- If we wanted to turn on bits 5 through 9, we would use the mask **000001111100000**

```
0010110011001010 (input)
| 0000001111100000 (mask)
| 0010111111101010
```

- Example: mask some bits to 0
- Likewise, if we want to turn *off* some bits (set them to 0), leaving other bits unaffected, we create a mask consisting of all 1s except for the bits we want to turn off and use a bitwise-AND operation
- If we wanted to turn off bits 2 through 7, we would use the mask 111111110000011

```
0010110011001010 (input)

<u>& 1111111100000011 (mask)</u>

0010110000000010
```

- Example: reading the value of a bit
- Suppose we want to know if a particular bit is 0 or 1
- We create a mask of all 0s except for the bit position we want to check
- Then we perform a bitwise-AND and check if the result is zero or non-zero (non-zero means the bit is 1)
- If we wanted to check if bit #7 is turned on, we would use the mask **000000010000000**

```
0010110011001010 (input)
```

```
& 000000010000000 (mask)
```

000000010000000 ← non-zero result means that the bit was set to 1

- Example: reading the values of several bits
- Suppose we want to know the values of several bits
- We create a mask of all 0s except for the bit positions we want to check
- Then we perform a bitwise-AND and then shift right by a number of bits equal the position of the lowest bit
- If we wanted to read the values of bits 4-8, we would use the mask 000000111110000 and then shift right by 4
- 0010110011001010 (input)
 - & 000000010000000 (mask)
 - 00000001000000

- Example: toggling bits
- Suppose we want toggle (flip) some of the bits in a number, leaving the other bits unaffected (this is done in graphics hardware sometimes)
- We create a mask of 1s in those places we want to toggle
- Then we perform a bitwise-XOR
- If we wanted to toggle bits 4 through 7, we would use the mask **00000011110000**

```
0010110011001010 (input)
```

^ 000000011110000 (mask)

0010110000111010

- Example: consider the binary representations of several multiples of 4:
 - 8₁₀: 1000₂
 - 24₁₀: 11000₂
 - 36₁₀: 100100₂
- What they all have in common is that the rightmost two bits are both 0
- How might we write a Boolean expression that uses only bitwise operators and relational operators to set the value of a variable to **True** only if a number is divisible by 4?

- Suppose we turn off bits 2 through 31, leaving bits 0 and 1 unaffected
- If the resulting number is all zeroes (i.e., the number zero), that means our original number ended in 00, which makes it divisible by 4
- If the result is not all zeroes, it means that the number ended in 01, 10 or 11

```
000000001100100 (input)
```

& 000000000000011 (mask)

000000000000000

• Since the result is zero, this means that the original number is divisible by 4

- In Python, if we prepend **0b** to a set of 1s and 0s, the computer interprets as a binary number, like **0b10011**
- Suppose we wanted to perform:

0010110011001010

- & 10011010101010
- We would write it in Python like this:
- 0b0010110011001010 & 0b10011010101010
- See unit09/bitwise.py for examples of bitwise operations in Python

Programming the CPU

- Python is an example of a **high-level language**, which means that the instructions we write are generally easy to read
- In contrast, the CPU can process only simple instructions that consist of 0s and 1s
 - The CPU's language is called **machine language** and is specific to each product line of CPU
- Because writing instructions using only 0s and 1s is very difficult and error-prone, early computer scientists created **assembly languages** instead
 - Assembly language consists of easier-to remember *mnemonics* that map directly to machine language

Programming the CPU

- - MIPS is the name of a product line of CPUs
 - The same instruction written in MIPS assembly language is add \$s0, \$s1, \$s2
 - Although this still looks a little mysterious, it's definitely less mysterious than thirty-two 0s and 1s!

MIPS Assembly Language Overview

- To get an idea of how assembly language really works, we'll look at a real assembly language: 32-bit MIPS assembly
 - A MIPS CPU has thirty-two 32-bit registers, with names like \$s0, \$t0 and \$a0
 - We will confine ourselves only to registers \$t0 through
 \$t9
 - Each register can hold 32 bits of data, such as an integer
 - Our assembly language instructions will allow us to refer to them by name (e.g., \$t0)

MIPS Assembly Language Overview

- Every MIPS assembly language program has two sections:
 - The .data section stores the data values we will process
 - The .text section stores the instructions themselves
- Recall from earlier in the semester the concept of the stored-program computer
 - The idea is that data and instructions are stored together in the main memory
 - This is done so that the computer can be easily reprogrammed to execute different tasks
 - We will see very clearly now how this is actually done in a real computer

MIPS: Loading Values

- One of the most basic operations in MIPS assembly is to load a register with a value
- The instruction is called **li**, which is short for *load* immediate
- The word **immediate** refers to a constant value that appears in an instruction
- The 1i instruction is similar to an assignment statement in Python (e.g., x = 28)
- For example, if we wanted to load (copy) the value 28 into register \$t2, we would write this: 1i \$t2, 28
- Note how the destination is given first, just like an assignment statement

MIPS: Loading Values

- Assembly languages don't directly support concepts like variables or functions
 - Instead, we have labels
- A label is a name given to a 32-bit cell of main memory in the computer. It's very similar to a Python variable.
- Sometimes the CPU needs to read a value from memory
 - We can identify this value by the label of the memory cell where the data exists
 - We will also have to tell the CPU which register to store the data in
 - The relevant MIPS assembly language instruction is **lw**, which is short for *load word*

MIPS: Loading Values

- Recall that a **word** is the native unit of data for a CPU. In MIPS, a word is 32 bits in size.
- Suppose we have a label called **salary** that currently stores the value 5000, and we want to add 200 to it
- First we load (copy) the value from memory into a register
- Let's assume we want to copy the value into register \$t0
- Here's the code:
 - .data

```
salary: .word 5000
```

.text

lw \$t0, salary

• .word means that salary is a word (i.e., an integer)

MIPS: Arithmetic

- Suppose now that we wanted to add 200 to **salary**
- MIPS assembly language has a variety of instructions for performing arithmetic
- One of these is **addi**, which is short for *add immediate*
- addi would correspond to a statement like
 new_salary = salary + 200 in Python
- We need to provide **addi** with the *destination register* (where the new value will be saved), the *source register* (where the current value is saved), and an *increment* (how much to add to the source value)
- Here's the code, along with an explanatory comment:
 addi \$t1, \$t0, 200 # \$t1 = \$t0 + 200

MIPS: Arithmetic

- In Python, we know that we can use notation like += to increment a variable by some amount
- For example, we could write **salary += 200** to add **200** to the variable **salary**
- We can do the same thing in MIPS assembly of we use the same register for the source and destination
- In the example below, 200 is added to the value in \$t0, overwriting the current value with the new sum

```
addi $t0, $t0, 200 # $t0 += 200
```

• There is no **subi** instruction in MIPS assembly, but we can simulate it if we use a negative immediate value:

```
addi $t0, $t1, -50 # $t0 = $t1 - 50
```

MIPS: Storing Values

- To copy data from a register into a memory cell we can use a label
- This operation is known as a **store** because we are storing a piece of data in the main memory
- The instruction is **sw**, which is short for *store word*
- First we give the register that has the value we want to copy, and then we give the label that says where the value should be copied to
- Suppose we wanted to copy the value in \$t0 to the memory cell called salary
- The code below will accomplish this task:
 sw \$t0, salary # salary = \$t0

MIPS: More Arithmetic

- Sometimes we need to perform arithmetic using only registers (no immediate values)
- Consider the Python statement salary += raise
- Perhaps raise is determined by some calculation, and is not a constant
- Let's assume that register \$t0 contains salary for someone and \$t1 contains raise
- We can use the add instruction to add the contents of two registers and store the result
- The destination register is given first, followed by the two registers that hold the operands, as in this example:

```
add $t0, $t0, $t1 # $t0 = $t0 + $t1
```

MIPS: More Arithmetic

- MIPS assembly also supports sub for subtraction, mul for multiplication and div for integer division
- All instructions have the same format: [instruction] [destination] [operand1] [operand2]
- Note that none of these instructions uses immediates, so any constants must first be loaded into registers using li
- The code below doubles the value stored in \$t3 and divides that result by 7, storing the quotient in \$t4

Compute $f(x) = Ax^2 + Bx + C$

- Suppose we wanted to write a program that computes the value of a quadratic polynomial $f(x) = Ax^2 + Bx + C$
- First we would need a way to store the values of A, B, C and
- In the .data section of our program we will create a label for each of these values:

.data

x: .word 6

A: .word 3

B: .word 4

C: .word 5

Compute $f(x) = Ax^2 + Bx + C$

- Now we can create a .text section where we will write the operations themselves
- Let's load these four values into registers so that we can use them in calculations:

```
.text
lw $t0, x
lw $t1, A
lw $t2, B
lw $t3, C
```

Compute
$$f(x) = Ax^2 + Bx + C$$

- Let's consider what arithmetic we need to perform to compute $Ax^2 + Bx + C$
- Looking closely we see we will need 5 operations: three multiplications and two additions
- We can perform these in any order, provided that we implement the correct order of operations
- To make things manageable, let's do the multiplications first:

```
mul $t4, $t0, $t0  # $t4 = x^2

mul $t5, $t1, $t4  # $t5 = A*x^2

mul $t6, $t2, $t0  # $t6 = B*x
```

Compute
$$f(x) = Ax^2 + Bx + C$$

- With most of the hard work done we can now perform the additions
- However, we didn't decide earlier where we want to save the final result, so let's decide now to save it in \$t8

```
add $t7, $t5, $t6 # $t7 = A*x^2 + B*x
add $t8, $t7, $t3 # $t8 = A*x^2 + B*x + C
```

Compute $f(x) = Ax^2 + Bx + C$

```
# $t4 = x^2
.data
                 mul $t4, $t0, $t0
x: .word 6
A: .word 3
                                     See unit09/
                 # $t5 = A*x^2
                                     quadratic.asm
B: .word 4
                 mul $t5, $t1, $t4
C: .word 5
                 # $t2 = B*x
                 mul $t6, $t2, $t0
.text
lw $t0, x
                 # $t0 = A*x^2 + B*x
lw $t1, A
                 add $t7, $t5, $t6
lw $t2, B
                 # $t0 = A*x^2 + B*x + C
lw $t3, C
                 add $t8, $t7, $t3
```

- We don't have access to a real MIPS-based computer, but we can create a Python program that emulates a MIPS computer
- Such a program is called a **virtual machine**
- Our program will need to perform the essential functions of a von Neumann machine
- We will also need to simulate the CPU's registers and main memory
- To that end we will create two dictionaries: **registers** and **labels**:

```
registers = {}
labels = {}
```

- Now we need a way to read and write values into the registers and main memory to support the li, lw and sw instructions
- Our approach will be to write a function for each of these operations

```
def li(reg, immed):
    registers[reg] = immed

def lw(reg, label):
    registers[reg] = labels[label]

def sw(reg, label):
    labels[label] = registers[reg]
```

• Next we have the various arithmetical operators:

```
def addi(dest, src, immed):
    registers[dest] = registers[src] +
                      immed
def add(dest, src1, src2):
    registers[dest] = registers[src1] +
                      registers[src2]
def sub(dest, src1, src2):
    registers[dest] = registers[src1] -
                      registers[src2]
```

• And likewise for **mul**, **div** and **mod** (for %)

- Last, we need to write a Python function to read a MIPS assembly program from disk and execute it
- The essential elements of this function are:
 - 1. Open the file and read it into a list of strings
 - 2. For each string:
 - a. Identify labels (which are basically variables) and store the associated values in labels
 - b. Identify li/lw/sw instructions and perform loads and stores
 - c. Identify addi/add/sub/mul/div/mod instructions and perform the arithmetical operations
- See unit09/mips_vm.py for the code and examples

MIPS Change-maker

- One of the first programs we wrote in the course was the change-making program
- Given a total number of cents, we want to know many dimes, nickels and pennies are needed to make that change while minimizing the number of coins
- Python code to solve this problem is on the right

```
cents = 138
dimes = cents // 10
cents = cents % 10
nickels = cents // 5
cents = cents % 5
pennies = cents
print(dimes, nickels,
      pennies)
```

MIPS Change-maker

- Let's translate this program into MIPS assembly
- Assume that the number of cents is stored at a label called cents
- We will store the final number of dimes in a label dimes, nickels in a label nickels and pennies in a label pennies

MIPS Change-maker

.data .text li \$t0, 10 cents: .word 138 dimes: .word 0 lw \$t1, cents div \$t2, \$t1, \$t0 nickels: .word 0 pennies: .word 0 sw \$t2, dimes mod \$t1, \$t1, \$t0 li \$t0, 5 See unit09/change.asm div \$t2, \$t1, \$t0 sw \$t2, nickels mod \$t1, \$t1, \$t0 sw \$t1, pennies

Final Note on MIPS Programming

- You will NOT be required to read or write MIPS code on any examination in this course
- The main purpose of our brief exploration of assembly language was to help you develop a general understanding and appreciation of what instructions the CPU is actually executing as it runs software