

August 23 (Tue)

First Day of the Class

## 1. Organizational meeting

"Green Sheet"

Repo: [github/Pradil10/OpenCV-deep-learning-2022](https://github.com/Pradil10/OpenCV-deep-learning-2022) / the github.

Email: hua.li@sjtu.edu

(650) 400-1116 Cellphone for  
Text message Only.Office Hours: M.W. On Zoom.  
(see syllabus for the  
Zoom link).

## 2. Software Tools:

Anaconda — Install it by the end  
of this week;

TensorFlow, TF 2.0

OpenCV.

## 3. Prerequisites: CMP255 &amp; CMP257

Homework: To upload a copy of  
your un-official transcript to  
show the required courses satisfied.

On CANVAS.

## 4. Textbook: Deep Learning with Python.

Keras (API) for TF.

Robot Vision Book By Horn (theory theoretical  
book, good reference for OpenCV Algorithms.

Good Theoretical Foundations)

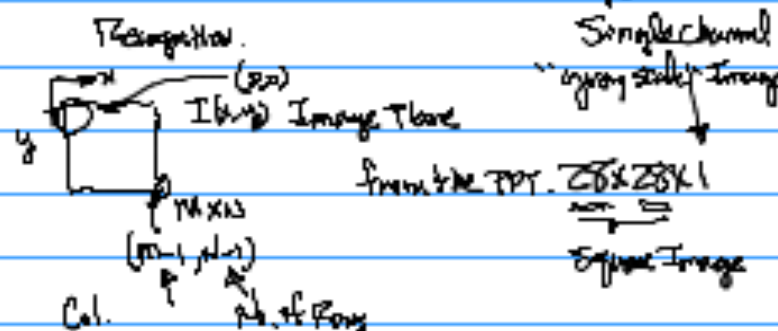
5. Projects { Mandatory Assigned Project  
Team Project  
(Mandatory)4-person Team. Presentation by the  
End of the Semester.

August 23 (Wed)

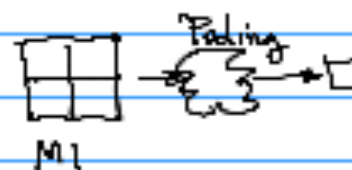
Note: 1. The lecture note will be posted on  
to the github.2. Zoom Recording will be posted on the  
the github.Homework: By A week from today. 1. Anaconda  
Installation; 2. OpenCV Installation. Submission  
On CANVAS. Jpg/Png Image  $\rightarrow$  pdf  $\rightarrow$  zip  
2pts.

Example: (github: 2022-fur-113)

MNIST Architecture for Handwritten Digits

(gray scale image  $\rightarrow$  1 channel  $\rightarrow$  8 bit  $\rightarrow$  [0, 255])

First Layer of the MNIST Architecture

n1 channel/plane of the 1st convolutional layer  
C1Next, pooling  $\rightarrow$  Reduction of Resolution  $\rightarrow$  28x28 becomes

From the Architecture diagram:

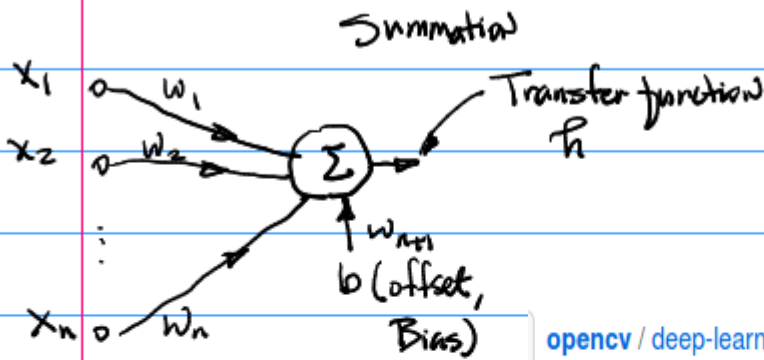
C1 M1  $\rightarrow$  C2 M2  $\rightarrow$  Flatten  $\rightarrow$  FFNN (FF)To generalize the quick inspection of the  
the CNs, we have to investigate the behavior  
of each single neuron as the basic building  
Block.

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Ref. 1

<https://github.com/hualili/opencv/blob/master/deep-learning-2022s/2022F-103b-NN-Intro-Python-v5-2022-8-25.pdf>

[opencv / deep-learning-2022s / 2022S-103a-notation-neuro-loss-function-2022-2-8.pdf](https://github.com/hualili/opencv/blob/master/deep-learning-2022s/2022S-103a-notation-neuro-loss-function-2022-2-8.pdf)

Input/Excitation in Vector Form:  $\mathbf{x} = (x_1, x_2, \dots, x_n) \dots (1)$

Weights, links each excitation to the Neuron

Ref. 2. Code

$$\mathbf{W} = (w_1, w_2, \dots, w_n) \dots (2)$$

<https://github.com/hualili/opencv/blob/master/deep-learning-2022s/2022S-110b-%232019S-31-6mnist-numerals-ch02.py>

$$x_1 w_1 + x_2 w_2 + \dots + x_i w_i + \dots + x_n w_n + b w_{n+1} = h \quad \text{Example:}$$

$$\sum_{i=1}^n x_i w_i + b w_{n+1} = h(x_i w_i) \text{ or simply } h(\mathbf{x} \mathbf{W}) \dots (3)$$

$$h(\mathbf{x} \mathbf{W}; b), h(\mathbf{x} \mathbf{W})$$

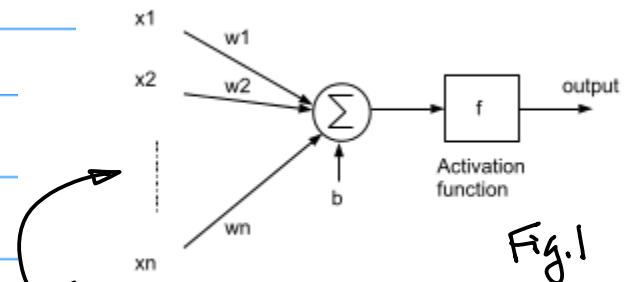
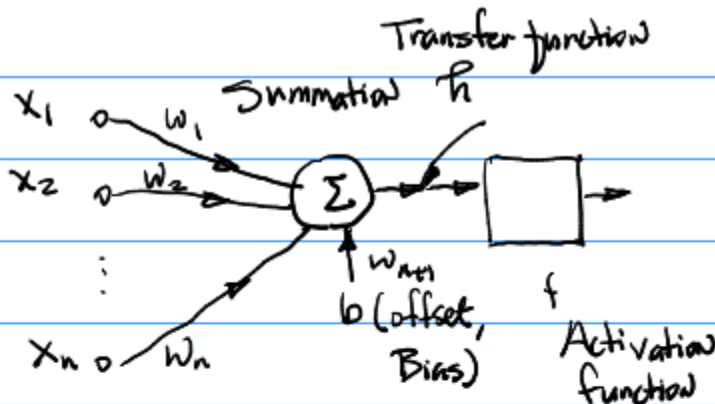


Fig. 1

$(x_1, x_2, \dots, x_n)$  Feature Vector with Dimension  $N$ .

$$f(h(\mathbf{x} \mathbf{W})) = f\left(\sum_{i=1}^n x_i w_i + b w_{n+1}\right) \dots (4)$$

$$h(\mathbf{x} \mathbf{W}) = \sum_{i=1}^n x_i w_i + b w_{n+1}$$

$$h = \sum_{i=1}^N w_i x_i = \mathbf{W} \cdot \mathbf{X} + b \quad (11)$$

Transfer function  $h(\cdot)$ .

$$w_{n+1} b = b'$$

Examples of Different Activation functions include RELU. A piecewise Linear.

Note: Be Able to Build A Single Neuron per a technical Specification, Such as uo11, Activation  $f(\cdot)$ , Draw a Block

$$y = f\left(\sum_{i=1}^N w_i x_i = \mathbf{W} \cdot \mathbf{X} + b\right). \quad (17)$$

Activation function. Its output is the Response of the Neuron.

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Consider the output of the Neuron  $y$  from Eqn (17).

Output of A Single Neuron.

For Multiple Neuron Output, see Fig. 2

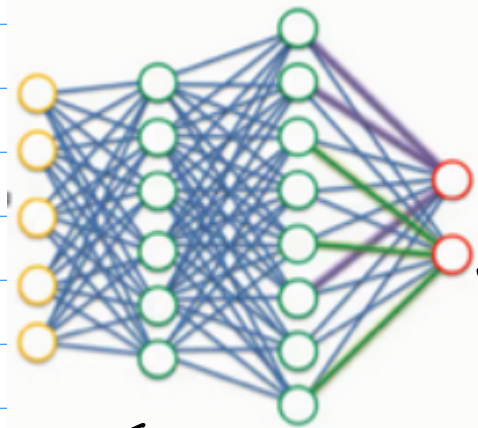


Fig. 2

$y_{di} \dots (1)$

SubScript:  $i=1,2$   
No. of Output at the Output Layer.

$y_i, i=1,2,\dots,M.$

In practical Application,

$y_{di}^j \dots (2)$

SuperScript  
 $j=1,2,\dots,P$  No. of Experiments  
Performed, Training Performed.

Look at the Concept & Definition of Loss function.

Mathematically To Compare a Neural Network Output (Single Neuron Output)

function  $f$ . function  $g$   
Comparison of the Similarity or  
difference between  $f$  and  $g$ .

$$\left\{ \begin{array}{l} f - g \\ f/g \end{array} \right.$$

Difference Between Two Functions.  
Take this Approach to define  
Loss function,

$$y - \hat{y} \dots (3)$$

Ground Truth.

Output (prediction) from  
the Neuron

Outputs

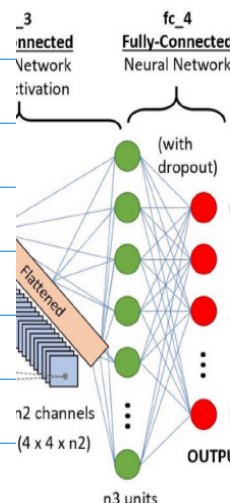


Fig. 3.

$\hat{y}_{di}$   
 $i=0,1,2,\dots,9$

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$$y_i - \hat{y}_i \quad \dots (4-a)$$

To measure All the output for Each

Training/Experiment

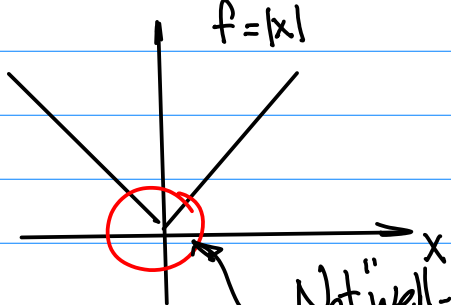
$$\sum_{i=0}^q (y_i - \hat{y}_i) \quad \dots (4-b)$$

Expand this to Experiment/Training up to "P" Times

$$\sum_{j=1}^P \left[ \sum_{i=0}^q (y_i^j - \hat{y}_i^j) \right] \quad \dots (4-c)$$

Note: Eqn (4-c) may lead to positive & Negative Terms Cancellation.

Fix: Absolute Value?  $\rightarrow$  Squared Instead,



"Well Behaved" System (Function)  $\rightarrow$  derivative/partial Derivative up to order "K".

$$L = \sum_{j=1}^P \left[ \sum_{i=0}^q (y_i^j - \hat{y}_i^j)^2 \right] \quad \dots (4-d)$$

$\rightarrow J, \text{ or } \Phi$

$$L_{total} = \frac{1}{2} \sum_{j=1}^P (\tilde{y}^j - y^j)^2 \quad (23)$$

Ground Truth

For a Single Neuron @ the Output Layer

Training Based Steepest Gradient Descent SGD.

Example: Given A

function  $f(x) = x^2$ , Find its Derivative

$$\frac{df}{dx} = 2 \cdot x$$

To get rid of Coefficient from the derivative,

Let's define  $f(x) \triangleq \frac{1}{2} x^2$

$$\frac{d}{dx} f(x) = \frac{1}{2} \cdot 2 \cdot x = x$$

$$\frac{\partial L}{\partial w_{i,k}} = \frac{\partial}{\partial w_{i,k}} \frac{1}{2} \sum_{j=1}^P \sum_{i=1}^M (\tilde{y}_i^j - y_i^j)^2 \quad (24)$$

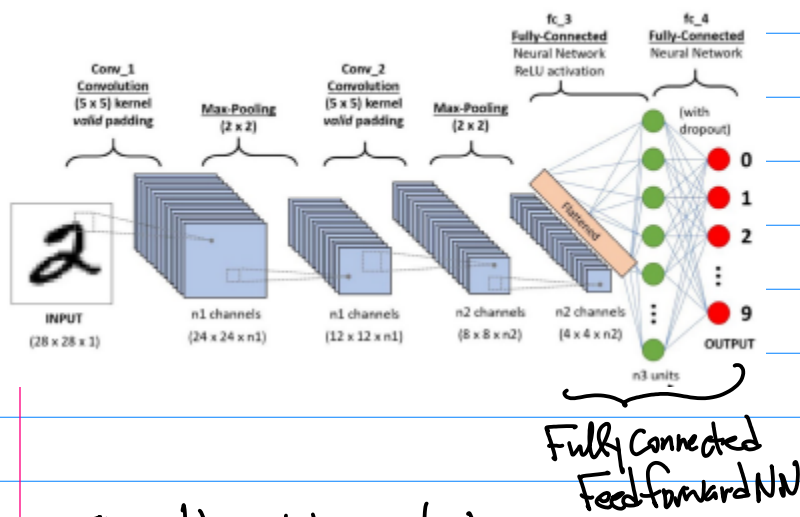
Sept 1st (Th).

Ref:

2022S-103a-notation-neuro-loss-function-2022-2-8.pdf

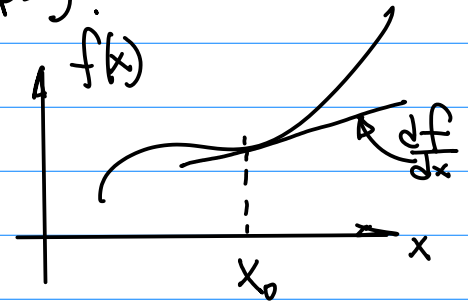
Example: Background on "Learning" of ANN.

2022F-103b-NN-Intro-Python-v5-2022-8-25.pdf



Or Decrease?

Derivative of A given function is a good indicator to give us the description of the function behavior Next Step Ahead (Very small tiny Step  $\Delta$ ).



To Train ANN, we take eqn (23), e.g. Loss function (error function),

$$L(\cdot) \rightarrow L(W_i)$$

Independent Variables

Minimize the Loss  $L(\cdot)$ , which is the process of Training, which leads to Learning for the NN.

Since the Loss function in Eqn (23) is formulated with a ground Truth  $y$ , this defines a Supervised Learning.

Math. Formula: Prediction of Function's Behavior, we like to know given the current function value (Loss function) how this function is going to change at next moment, increase? stay the same?

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x} \quad \dots (1)$$

Intuition

$f(x+\Delta x) - f(x) \rightarrow > 0$  (derivative)  
 $\Delta x \approx 1 \text{ unit}$   
if the derivative is greater than 0

then  $f(x+\Delta x) > f(x)$ , the next Step function  $f(x)$  is increased;

if the derivative  $\frac{df}{dx} < 0$ , then

$$f(x+\Delta x) < f(x)$$

if the derivative  $\frac{df}{dx} = 0$ , then

$$f(x+\Delta x) = f(x)$$

Consider Two Dimensional Case as an Example for  $n$ -dimensional Case.



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$f(x_1, x_2)$   $\left\{ \begin{array}{l} \frac{\partial f(x_1, x_2)}{\partial x_1} \\ \frac{\partial f(x_1, x_2)}{\partial x_2} \end{array} \right\} \rightarrow \text{Single Neuron}$   
In Case of Training They are "Weights"  
 $w_1, w_2$ .

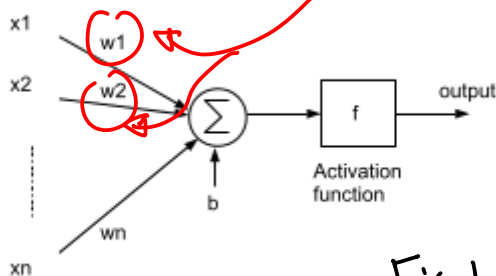


Fig.1

$\frac{\partial f}{\partial x_1} \rightarrow \frac{\partial f}{\partial w_1}$  In the Context of Training.

Conclusion: Use <sup>the</sup> Partial Derivate With respect to the weight  $w_i$  as an indicator to measure if the Loss function is got reduced or not.

$$\frac{\partial L}{\partial w_{i,k}} = \frac{\partial}{\partial w_{i,k}} \frac{1}{2} \sum_{j=1}^P \sum_{i=1}^M (\tilde{y}_i^j - y_i^j)^2$$

Example: Consider A technique which allows training to be more effect, e.g., <sup>the</sup> to minimize training and prediction error (Loss) function

Steps for Development of this technique:

6  
Multidimensional Derivative  
↓  
gradient  
↓  
the Steepest gradient  
↓  
the Steepest Descent gradient  
↓  
The Core technique to train NN. SGD

Ref: from the github

2022S-105c-#20-2021S-4gradient-descent-v2-final-2021-2-8.pdf

Homework (Opt), Due A week from Today.  
Sept. 8th, Thursday. ON CANVAS.

1<sup>o</sup> Installation of TensorFlow. Version 2.0 or higher.

2<sup>o</sup> Screen Capture to show the installation is successful

Note: All Different Development Tools/Environments including google co-lab, jupyter Notebook etc. Are OK, However for the Deployment purpose, projects homework Submission must be in python Stand-Alone form.

Sept. 6 (Th)

Homework: Due 1 week from Today Sept 13.

1. OpenCV Installation, Python.
2. Use Smart phone to Capture 5~10 Seconds Video Clips.  
.avi, .mp4 (mpeg4).
3. Sample Code, github.  
See CANVAS for the Detailed links & Requirements.
4. Submission to CANVAS.
  - ① Python Code;
  - ② Original & Processed image Side by Side with your Name + SID.
  - ③ Create One pdf file to Cover the Source Code, And Screen Captured Images.
5. Naming Convention  
HW-CV-First-LastName-CMPE258-SID.zip

<https://github.com/hualili/opencv/blob/master/deep-learning-2022s/2022S-104d-%232-pdisplay-2019-1-30.py>

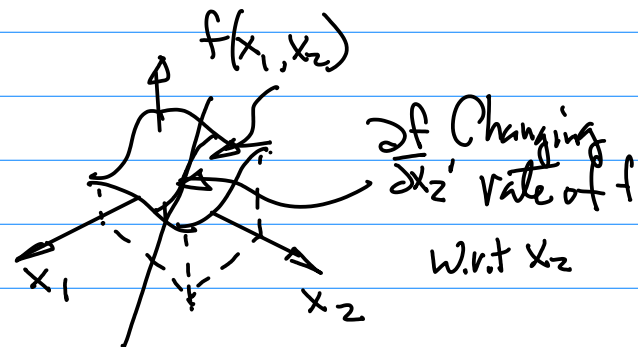
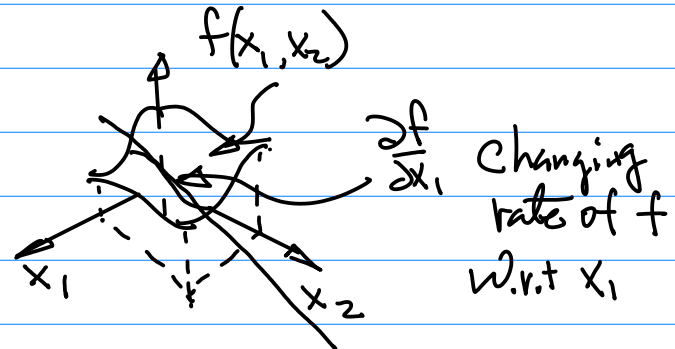
Higher Dimensional Function

$$f(\underbrace{x_1, x_2, \dots, x_n}_{\text{Weights, } w_1, w_2, \dots, w_n}) \dots (z)$$

Partial Derivatives:

$$\frac{\partial f}{\partial x_1} \text{ w.r.t } x_1, \frac{\partial f}{\partial x_2} \text{ for } x_2, \dots$$

$$\frac{\partial f}{\partial x_n} \text{ w.r.t } x_n.$$



Example: Gradient Definition  
Ref:

<https://github.com/hualili/opencv/blob/master/deep-learning-2022s/2022S-105c-%2320-2021S-4gradient-descent-v2-final-2021-2-8.pdf>

Loss function

Derivative, e.g. given  $f(x)$ , then

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x} \dots (1)$$

$$\frac{\partial L}{\partial w_{i,k}} = \frac{\partial}{\partial w_{i,k}} \frac{1}{2} \sum_{j=1}^P \sum_{i=1}^M (\tilde{y}_i^j - y_i^j)^2 \quad (24)$$

Consider the minimization of function  $f$  (Loss Function) w.r.t. All possible weights.

Therefore, put all the partial Derivatives together to form A vector, e.g., gradient.

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_i} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix} \dots (2a)$$

for  $n=2$ ,

$$\nabla f(x_1, x_2) = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{pmatrix} \dots (2b)$$

for  $n=3$

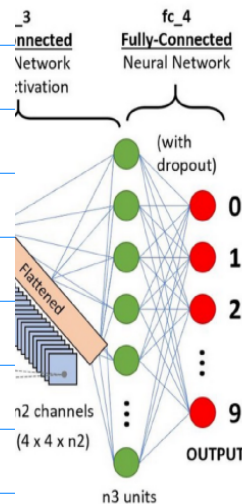
$$\nabla f(x_1, x_2, x_3) = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \end{pmatrix} \dots (2c)$$

d. On the Right hand side of Eqn(5):

$(x_1^k, x_2^k)$  Dimension  $n=2$ ,  $(x_1, x_2)$   
Time Index "k", Superscript

Output of the NN with its weights at Step  $k$  (Time) is

$x_1^k, x_2^k$



e. On the left  $(x_1^{k+1}, x_2^{k+1})$ , at the step  $k+1$ , to Reduce the Loss function, so update the new step By following

$$-\nabla f = -\eta \cdot \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{pmatrix} \dots (3)$$

#### IV. GRADIENT STEEPEST DESCENT FOR MINIMIZATION

Conclusion:

$$(x_1^{k+1}, x_2^{k+1}) = (x_1^k, x_2^k) + [-\eta(\nabla f)^T]$$

a. Loss function  $f$

b.  $n=2$

e.g.

$$f(x_1, x_2, \dots, x_n) \rightarrow f(x_1, x_2)$$

c. Gradient

$$\nabla f(x_1, x_2), \text{ or } \nabla f$$

Background:

Given a function  $f(x)$ , How do you Approximate this function By using Basic Building Blocks ( $\mathbb{R}^3$ )?

$$f(x) = \text{Constant Term} + \text{A Linear Term} + \text{A Quadratic Term} + \text{A Cubic Term} + \dots \dots (4)$$



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9.

Taylor Expansion:

$$f(x) = f(x_0) + \frac{df}{dx} \cdot (x - x_0) + \frac{d^2f}{dx^2} (x - x_0)^2 + \dots + R_n(x) \quad \dots (4)$$

Note: The screen capture for your homework reference.

