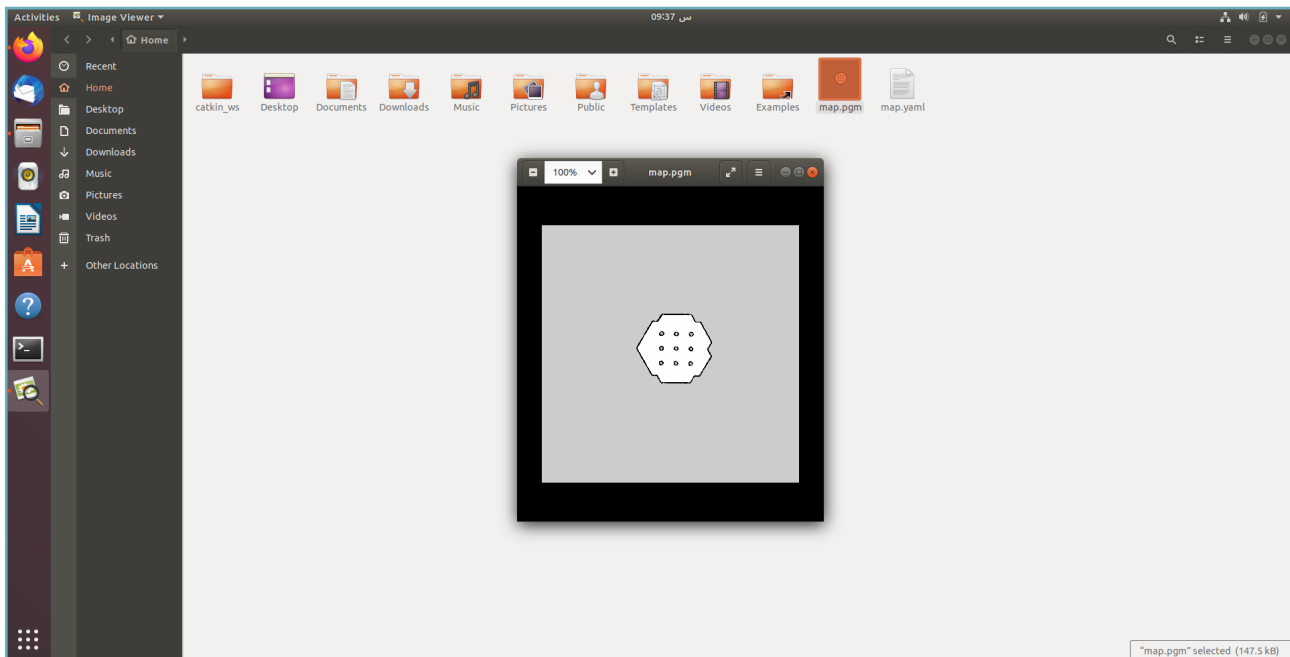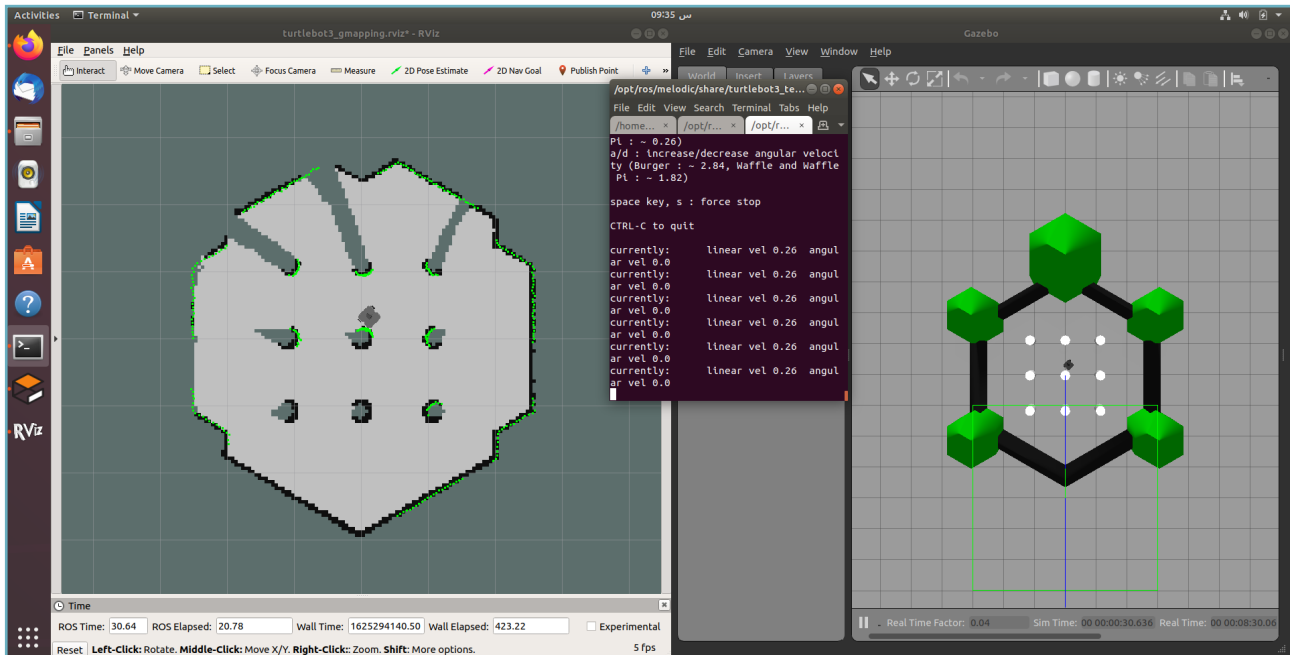# Robot and artificial intelligence

Task 2

Moving the robot base in a smart way

- Use Turtlebot3 with SLAM approach to create and save a map

- Use another ROS robot whit SLAM approach to create and save a map

Name:
Shhad Omar alrahili

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