

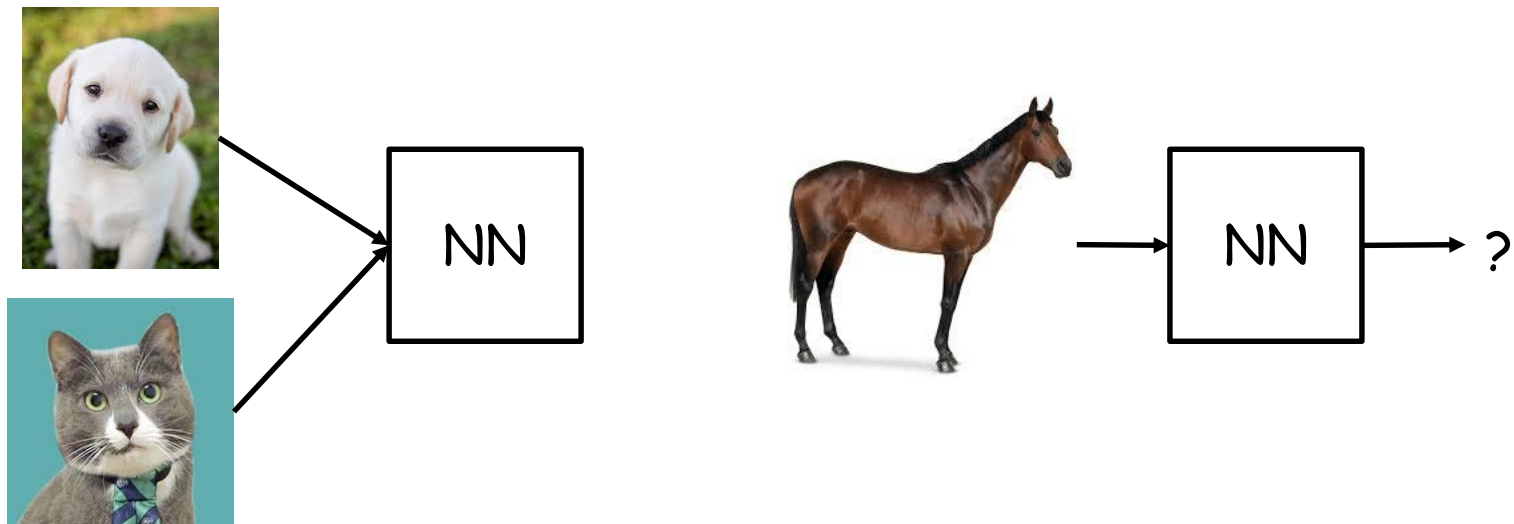


Out-of-Distribution Detection

Jee-Hyong Lee
Sungkyunkwan Univ.

Introduction

- **In the World, there are many instances which we never expect they are given.**
 - Does deep neural network can say “I don’t know” ?

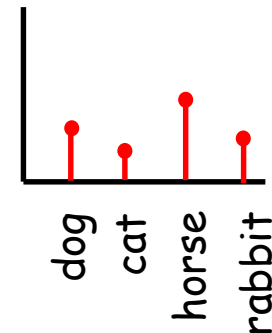
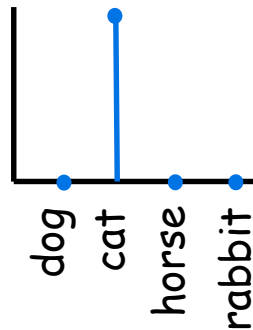


Out of distribution

Introduction

■ A Simple Way

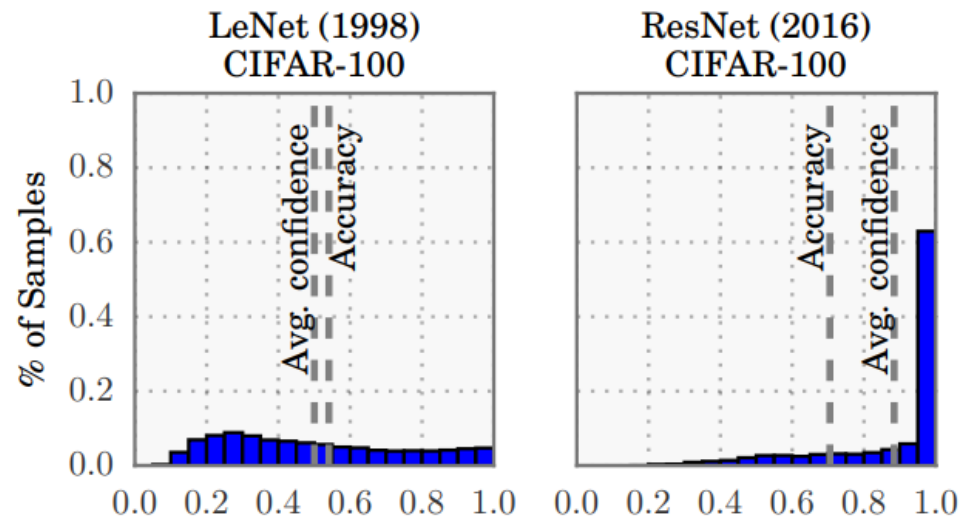
- We choose the maximum of softmax for classification
 - For an image in domain, softmax will produce a sharp output
 - For an image out of domain, softmax will produce rather a vague output
- Let's check the value of the maximum



Introduction

■ Over Confidence

- Modern NN tends to output overconfident prediction
 - Confidence : Max softmax probability
- NN returns prediction with high confidence for noise image



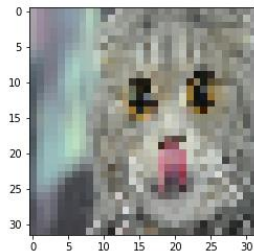
Guo, Chuan, et al. "On calibration of modern neural networks." *Proceedings of the 34th International Conference on Machine Learning-Volume 70*. JMLR. org, 2017.

Introduction

■ Over Confidence

- ResNet-20 trained on CIFAR10 (Test Acc: 92%)
- Prediction & Activation before softmax

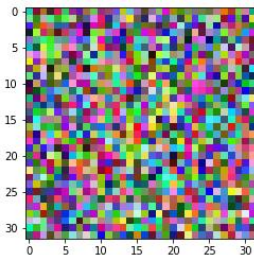
In-domain



Cat: 87%

```
array([-11.121608 , -12.295707 , -1.5396624 , 1.8473705 ,  
       -4.0719457 , -0.40232527, -4.8595014 , -9.229726 ,  
       -7.4466705 , -11.751272 ], dtype=float32)
```

Out-of-domain



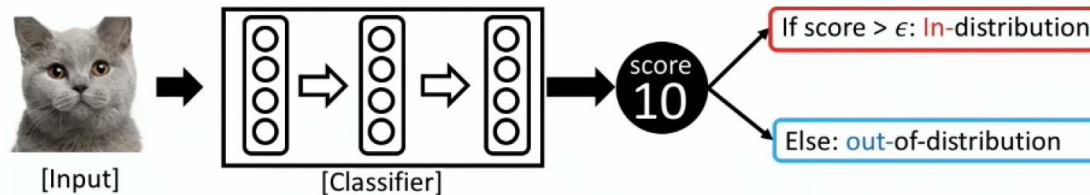
Bird: 84%

```
array([ -8.550764 , -0.03473853, 2.1666217 , -0.5177511 ,  
       -9.423397 , -11.470142 , -5.384335 , -11.936867 ,  
       -8.519983 , -6.6835756 ], dtype=float32)
```

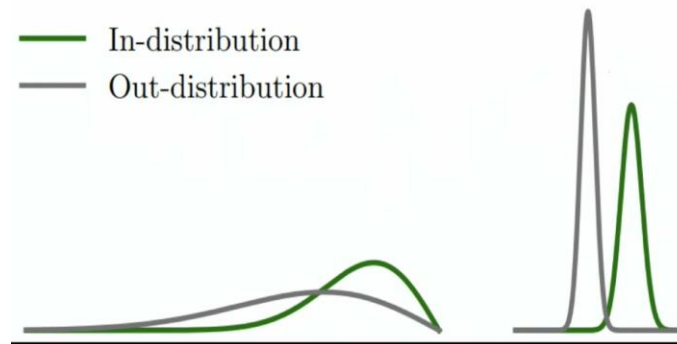
Over-confident prediction

Approaches

■ Threshold-based Detection



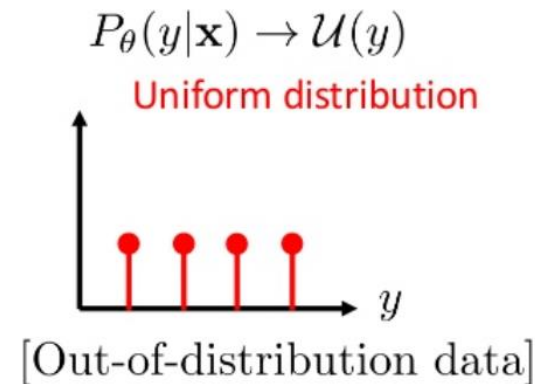
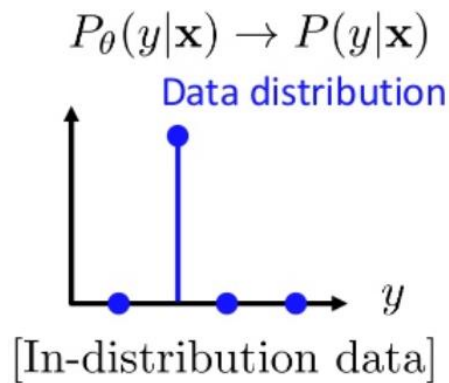
- Limitations: Performance of prior works highly depends on how to train the classifiers



Approaches

■ Confidence Calibration

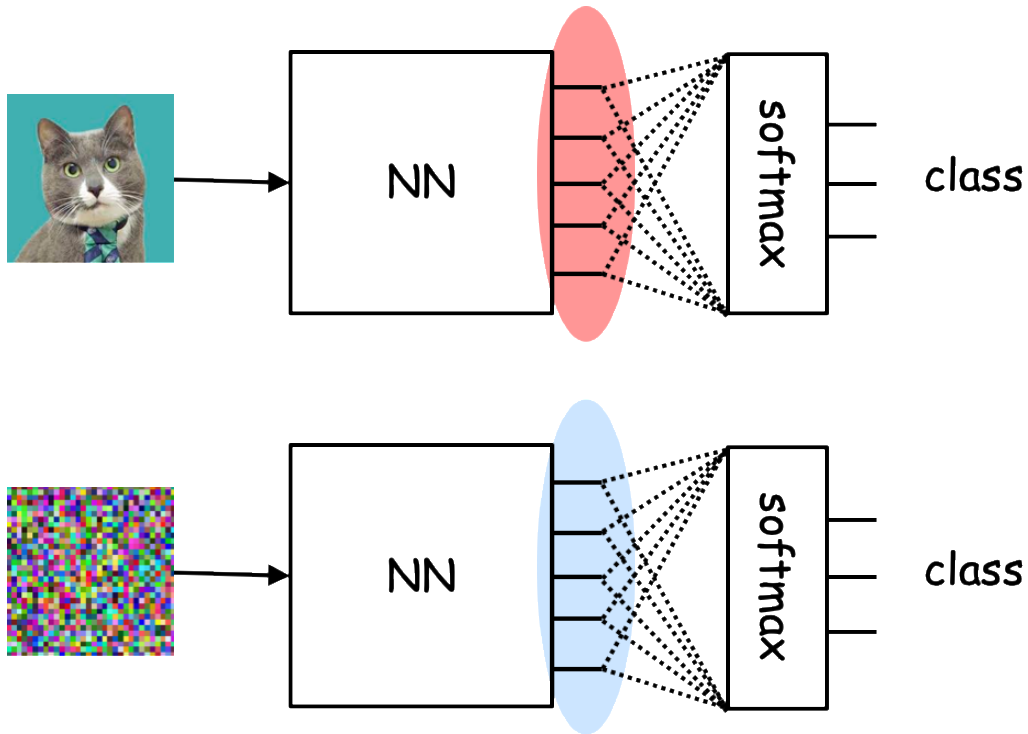
- Specially train a neural network so that it has low confidence for out-of-distribution samples



Approaches

■ Distribution-based Detection

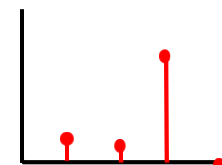
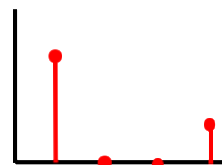
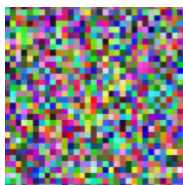
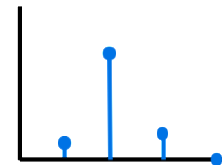
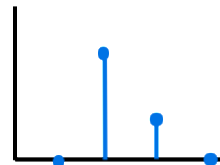
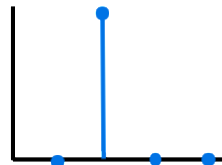
- Output of each layer may be different between in-distribution and out-of-distribution samples



Approaches

■ Variance-based Detection

- NN cannot perform extrapolation as much as interpolation
- Check the variance of output
 - Similar output for in-distribution data
 - Different output for out-of-distribution data



Model 1

Model 2

Model 3

Approaches

- **Confidence Calibration**

- K. Lee, et al., Training Confidence-calibrated Classifiers for Detecting Out-of-Distribution Samples, ICLR 2018

- **Distribution-based Detection**

- K. Lee, et al., A Simple Unified Framework for Detecting Out-of-Distribution Samples and Adversarial Attacks, NIPS 2018

- **Variance-based Detection**

- B. Lakshminarayanan, et al., Simple and Scalable Predictive Uncertainty Estimation using Deep Ensembles, NIPS 2017

Approaches

- **Confidence Calibration**

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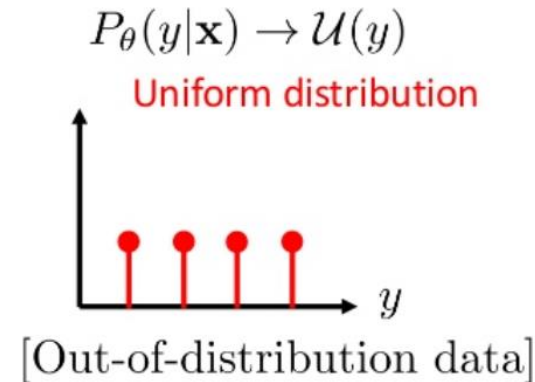
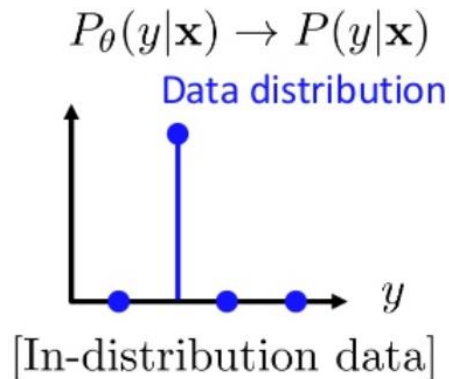
- **Variance-based Detection**

- B. Lakshminarayanan, et al., Simple and Scalable Predictive Uncertainty Estimation using Deep Ensembles, NIPS 2017

Confidence Calibration

■ Calibrate confidence

- Train a neural network so that it outputs higher maximum prediction values to in-distribution samples than out-of-distribution ones
- We need out-of-distribution data when training

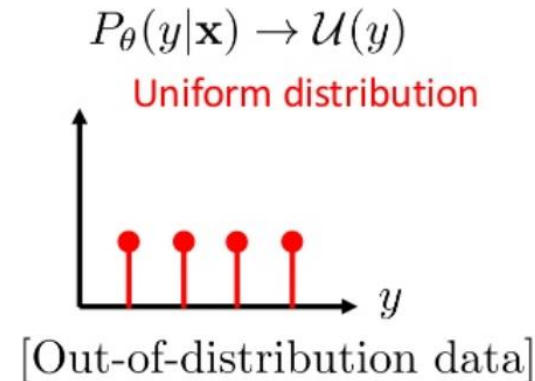
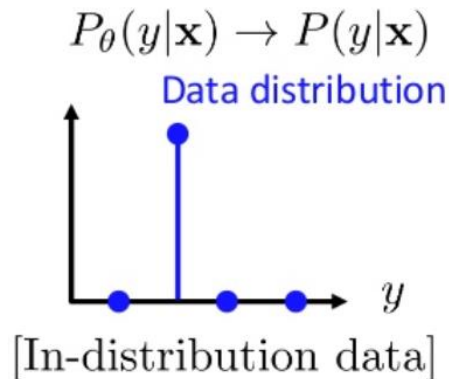


Confidence Calibration

■ Confident Loss

- Minimize the KL divergence on data from out-of-distribution

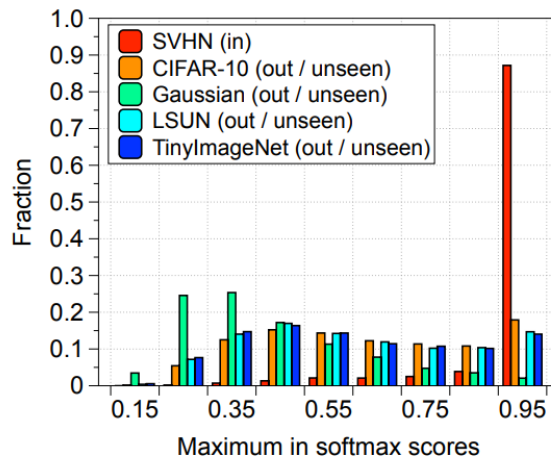
$$\min_{\theta} \underbrace{\mathbb{E}_{P_{\text{in}}(\hat{\mathbf{x}}, \hat{y})}}_{\text{Data from in-distribution}} \left[-\log P_{\theta}(y = \hat{y} | \hat{\mathbf{x}}) \right] + \beta \underbrace{\mathbb{E}_{P_{\text{out}}(\mathbf{x})}}_{\text{Data from out-of-distribution}} \left[\overbrace{KL(\mathcal{U}(y) \parallel P_{\theta}(y | \mathbf{x}))}^{\text{Uniform distribution}} \right]$$



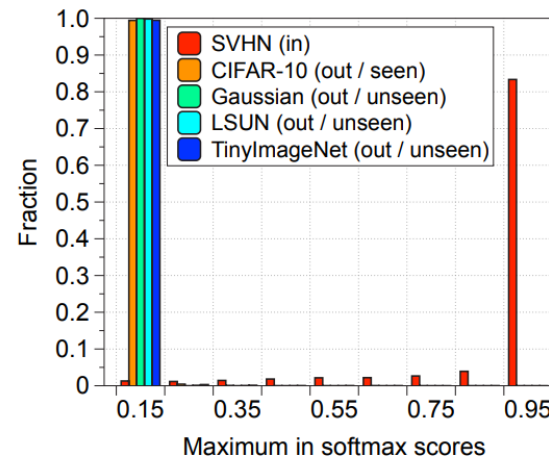
Confidence Calibration

■ Confident Loss

— Simple test



(a) Cross entropy loss



(b) Confidence loss in (1)

- Model: 2 conv + 3 FC
- Train data: SVHN(in-dist), MNIST(out-of-dist)

Confidence Calibration

- **Confidence Loss**

- Usually given out-of-distribution data is not enough to generally model out-of-distribution samples
- We need more out-of-distribution samples

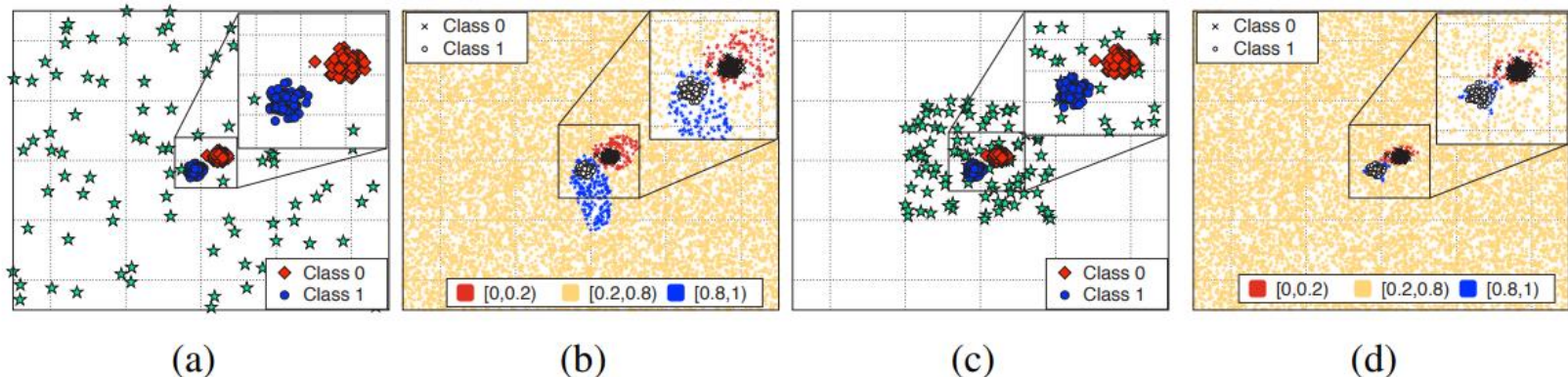
- **What about generating out-of-distribution data with GAN?**



Confidence Calibration

■ Generating out-of-distribution data with GAN

- (a) & (b) out-of-distribution data is sparse around in-dist.
- (c) & (d) out-of-distribution data is dense around in-dist.



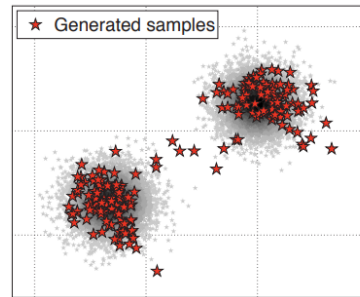
Red & blue : in-distribution data
Green : out-of-distribution data
Yellow: synthetic out-of-distribution data

=> We need to densely generate synthetic OOD around ID

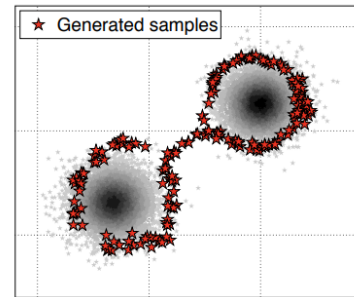
Confidence Calibration

- **Generating out-of-distribution data with GAN**

In-distribution



In-distribution
(on border line)



Confidence Calibration

■ Generating out-of-distribution data with GAN

- GAN loss to generate synthetic in-distribution samples on border lines

$$\min_G \max_D \underbrace{\beta \mathbb{E}_{P_G(\mathbf{x})} [KL(\mathcal{U}(y) \parallel P_\theta(y|\mathbf{x}))]}_{(a)} + \underbrace{\mathbb{E}_{P_{in}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{P_G(\mathbf{x})} [\log(1 - D(\mathbf{x}))]}_{(b)}$$

Output of classifier
(Need to be trained)

(a) Forces the generator to generate low-density samples

(b) Original GAN loss

Confidence Calibration

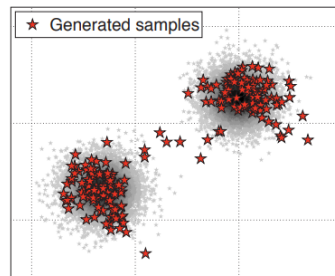
■ Generating out-of-distribution data with GAN

- GAN loss to generate synthetic in-distribution samples on border lines

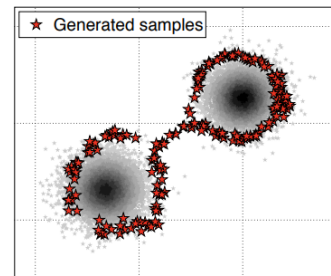
$$\min_G \max_D \underbrace{\beta \mathbb{E}_{P_G(\mathbf{x})} [KL(\mathcal{U}(y) \parallel P_\theta(y|\mathbf{x}))]}_{(a)} + \underbrace{\mathbb{E}_{P_{in}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{P_G(\mathbf{x})} [\log(1 - D(\mathbf{x}))]}_{(b)}$$

Output of classifier
(Need to be trained)

Original
GAN loss



New
GAN loss

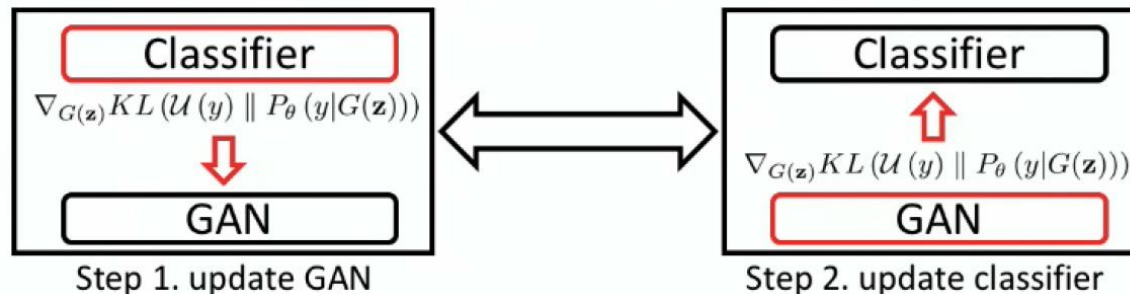


Confidence Calibration

Joint Loss: Confidence Loss + GAN Loss

$$\min_G \max_D \min_{\theta} \underbrace{\mathbb{E}_{P_{\text{in}}(\hat{\mathbf{x}}, \hat{y})} \left[-\log P_{\theta}(y = \hat{y} | \hat{\mathbf{x}}) \right]}_{(c)} + \underbrace{\beta \mathbb{E}_{P_G(\mathbf{x})} \left[KL(\mathcal{U}(y) \parallel P_{\theta}(y | \mathbf{x})) \right]}_{(d)} + \underbrace{\mathbb{E}_{P_{\text{in}}(\hat{\mathbf{x}})} \left[\log D(\hat{\mathbf{x}}) \right] + \mathbb{E}_{P_G(\mathbf{x})} \left[\log(1 - D(\mathbf{x})) \right]}_{(e)}.$$

- Classifier's confidence loss: (c) + (d)
- GAN loss: (d) + (e)



Confidence Calibration

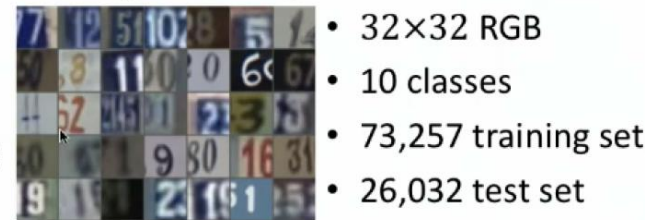
■ Experiment

— Data set

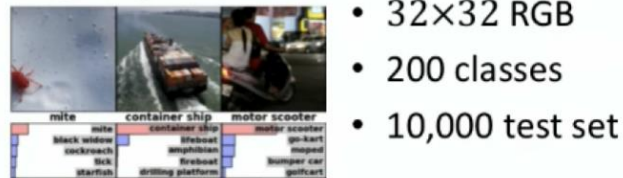
CIFAR-10 [Krizhevsky' 09]



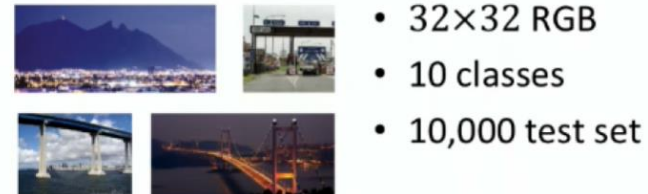
SVHN [Netzer' 11]



TinyImageNet



LSUN



— Used model: VGGNet

Confidence Calibration

■ Experiment

- Result with Confident loss (without GAN loss)

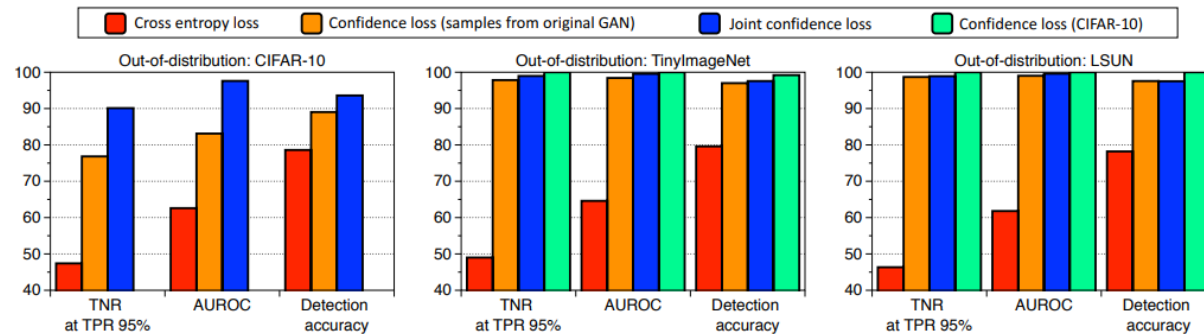
| In-dist | Out-of-dist | Classification accuracy | TNR at TPR 95% | AUROC | Detection accuracy | AUPR in | AUPR out |
|--------------------------------------|-----------------------|----------------------------|---------------------|---------------------|-----------------------|---------------------|--------------------|
| Cross entropy loss / Confidence loss | | | | | | | |
| SVHN | CIFAR-10 (seen) | 93.82 / 94.23 | 47.4 / 99.9 | 62.6 / 99.9 | 78.6 / 99.9 | 71.6 / 99.9 | 91.2 / 99.4 |
| | TinyImageNet (unseen) | | 49.0 / 100.0 | 64.6 / 100.0 | 79.6 / 100.0 | 72.7 / 100.0 | 91.6 / 99.4 |
| | LSUN (unseen) | | 46.3 / 100.0 | 61.8 / 100.0 | 78.2 / 100.0 | 71.1 / 100.0 | 90.8 / 99.4 |
| | Gaussian (unseen) | | 56.1 / 100.0 | 72.0 / 100.0 | 83.4 / 100.0 | 77.2 / 100.0 | 92.8 / 99.4 |
| CIFAR-10 | SVHN (seen) | 80.14 / 80.56 | 13.7 / 99.8 | 46.6 / 99.9 | 66.6 / 99.8 | 61.4 / 99.9 | 73.5 / 99.8 |
| | TinyImageNet (unseen) | | 13.6 / 9.9 | 39.6 / 31.8 | 62.6 / 58.6 | 58.3 / 55.3 | 71.0 / 66.1 |
| | LSUN (unseen) | | 14.0 / 10.5 | 40.7 / 34.8 | 63.2 / 60.2 | 58.7 / 56.4 | 71.5 / 68.0 |
| | Gaussian (unseen) | | 2.8 / 3.3 | 10.2 / 14.1 | 50.0 / 50.0 | 48.1 / 49.4 | 39.9 / 47.0 |

Sometimes good but sometime bad

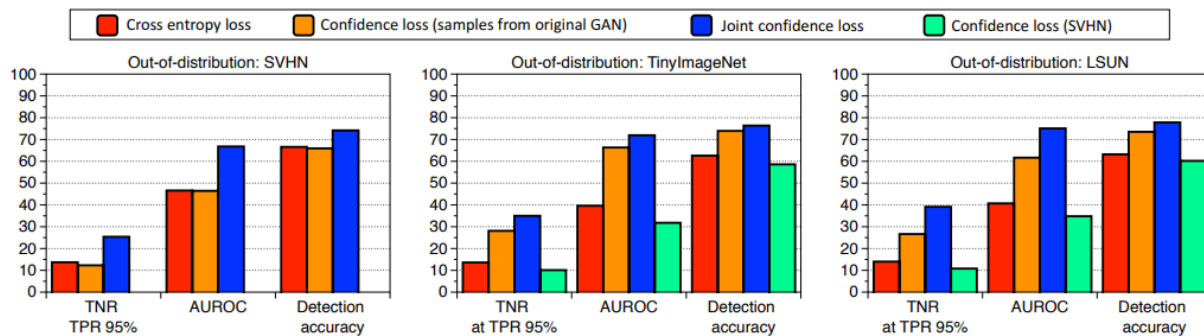
Confidence Calibration

■ Experiment

— Result with Joint Loss (with GAN Loss)



(a) In-distribution: SVHN



(b) In-distribution: CIFAR-10