

Recurrent Neural Networks

성균관대학교 소프트웨어학과
이 지 형

Sequential Data Modeling

- ▶ **Sequential Data**

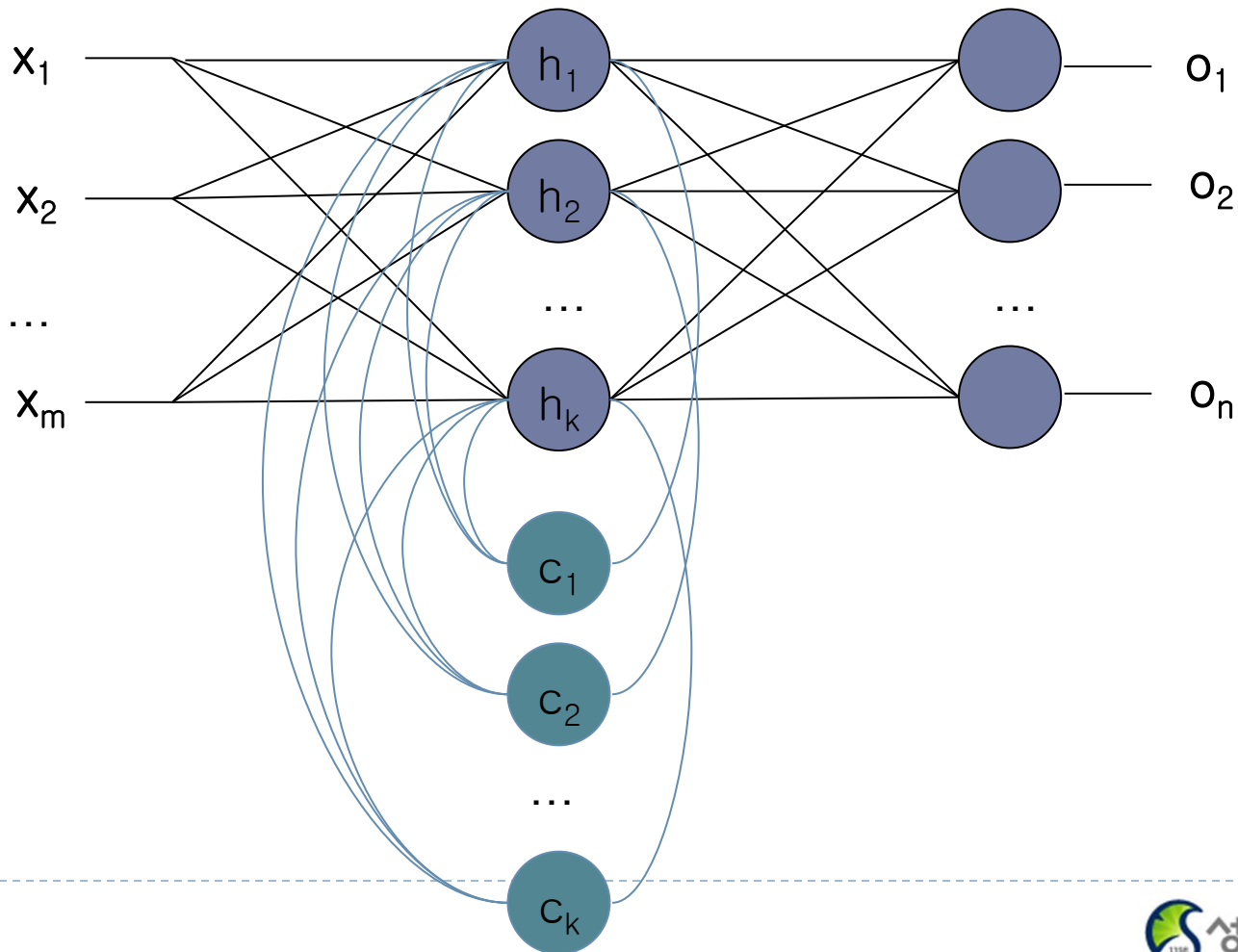
- ▶ Most of data are sequential
- ▶ Speech, Text, Image, ...

- ▶ **Deep Learnings for Sequential Data**

- ▶ **Convolutional Neural Networks (CNN)**
 - ▶ Try to find local features from a sequence
- ▶ **Recurrent Neural Networks: LSTM, GLU**
 - ▶ Try to capture the feature of the past

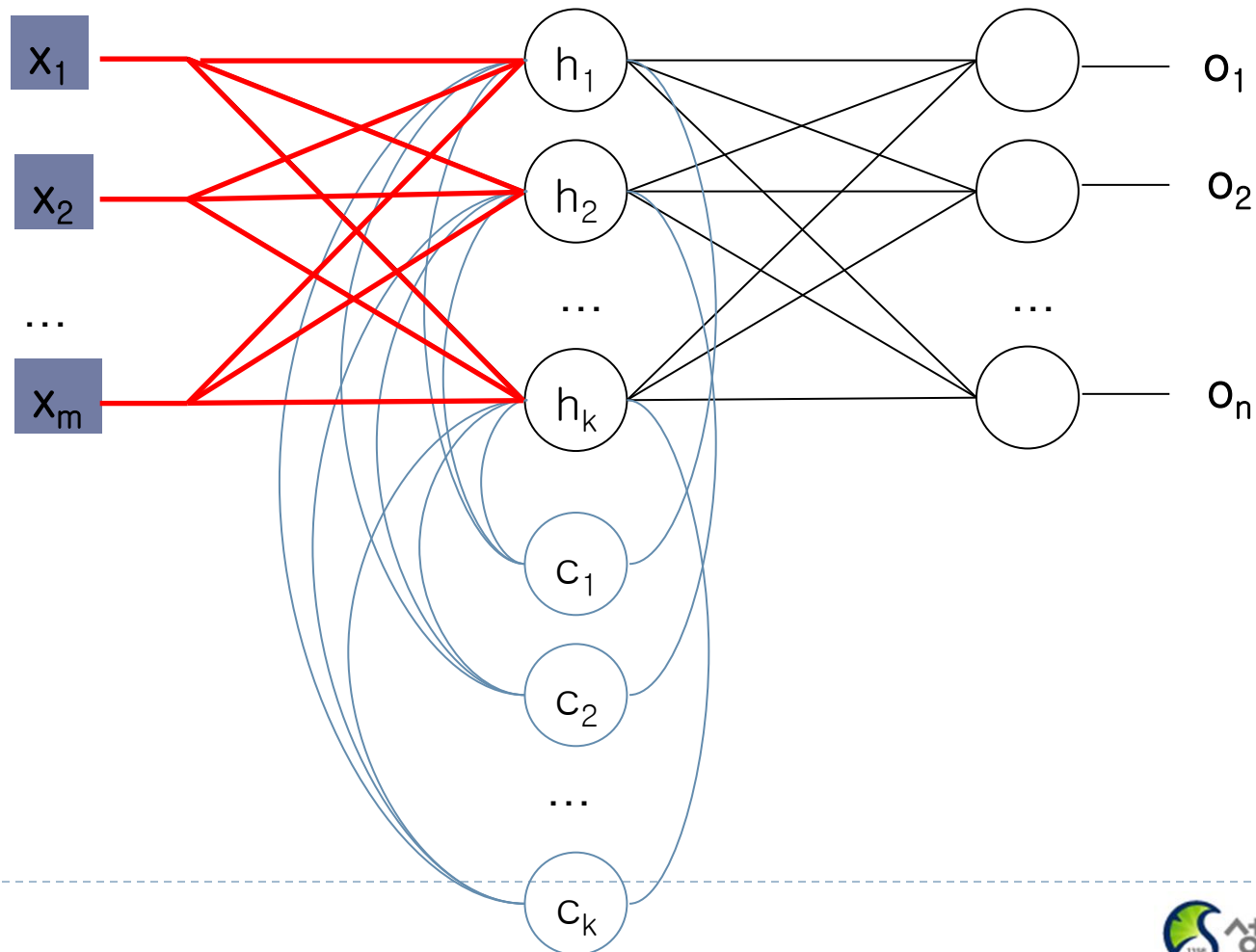
Recurrent Neural Networks

► Connections form cycles



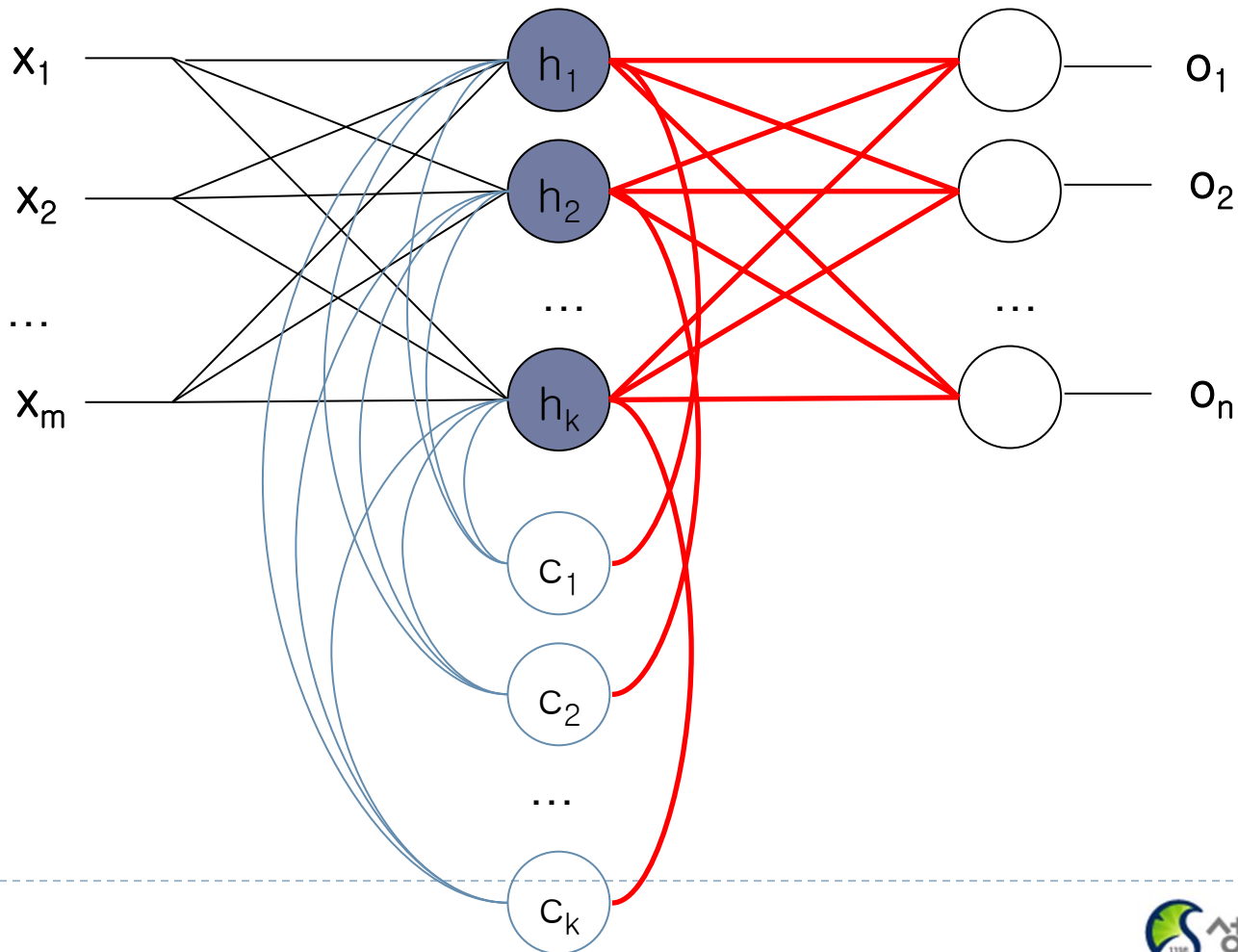
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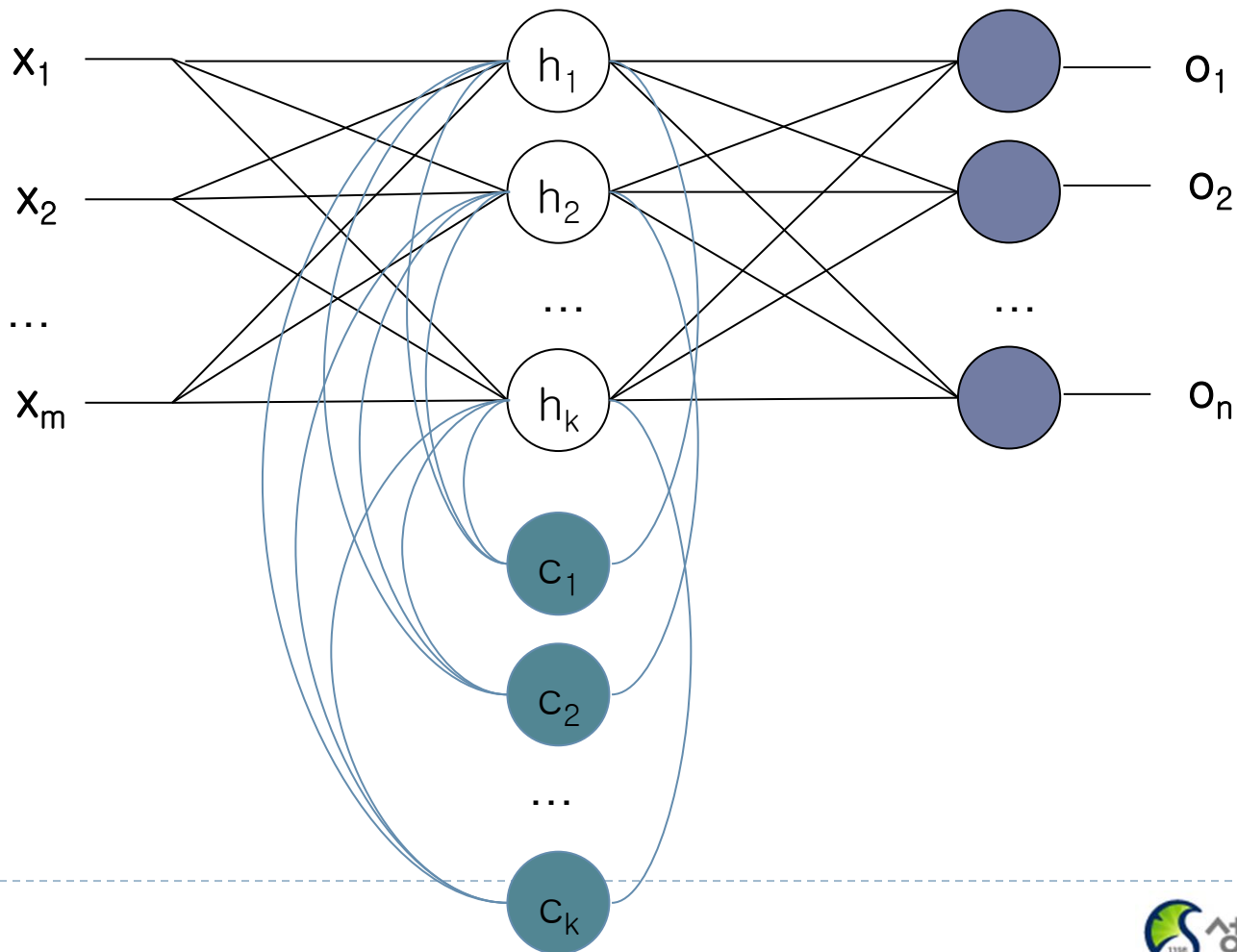
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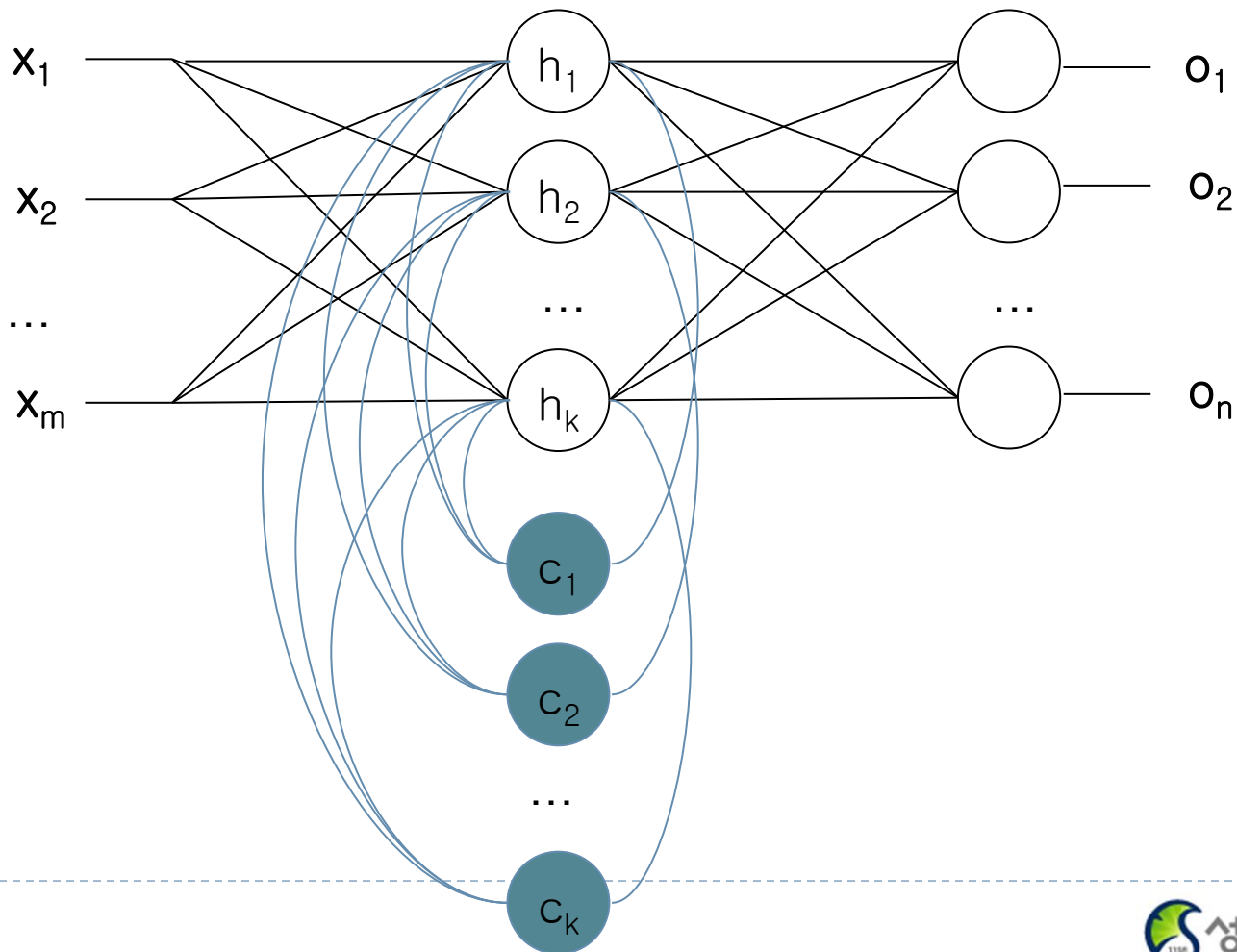
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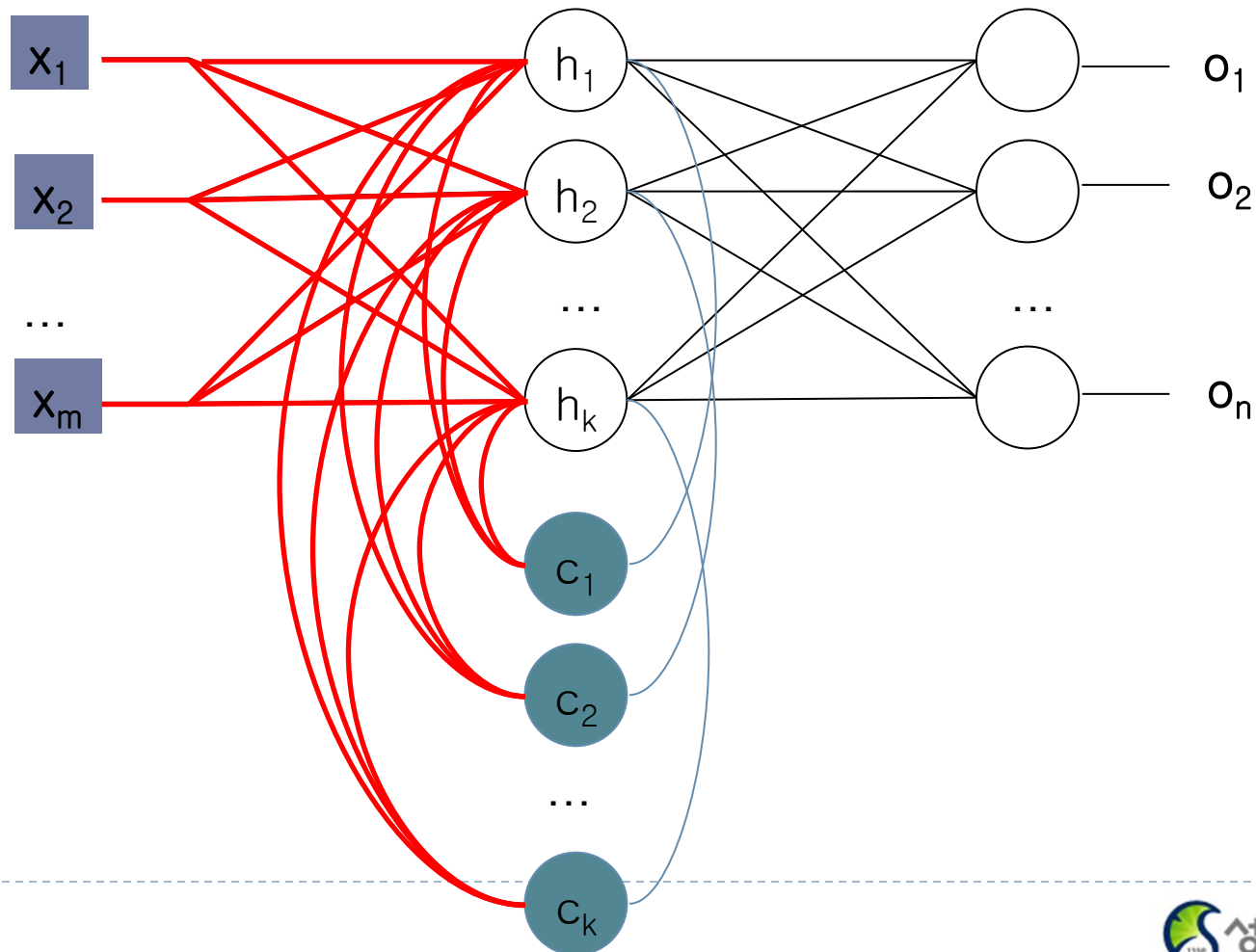
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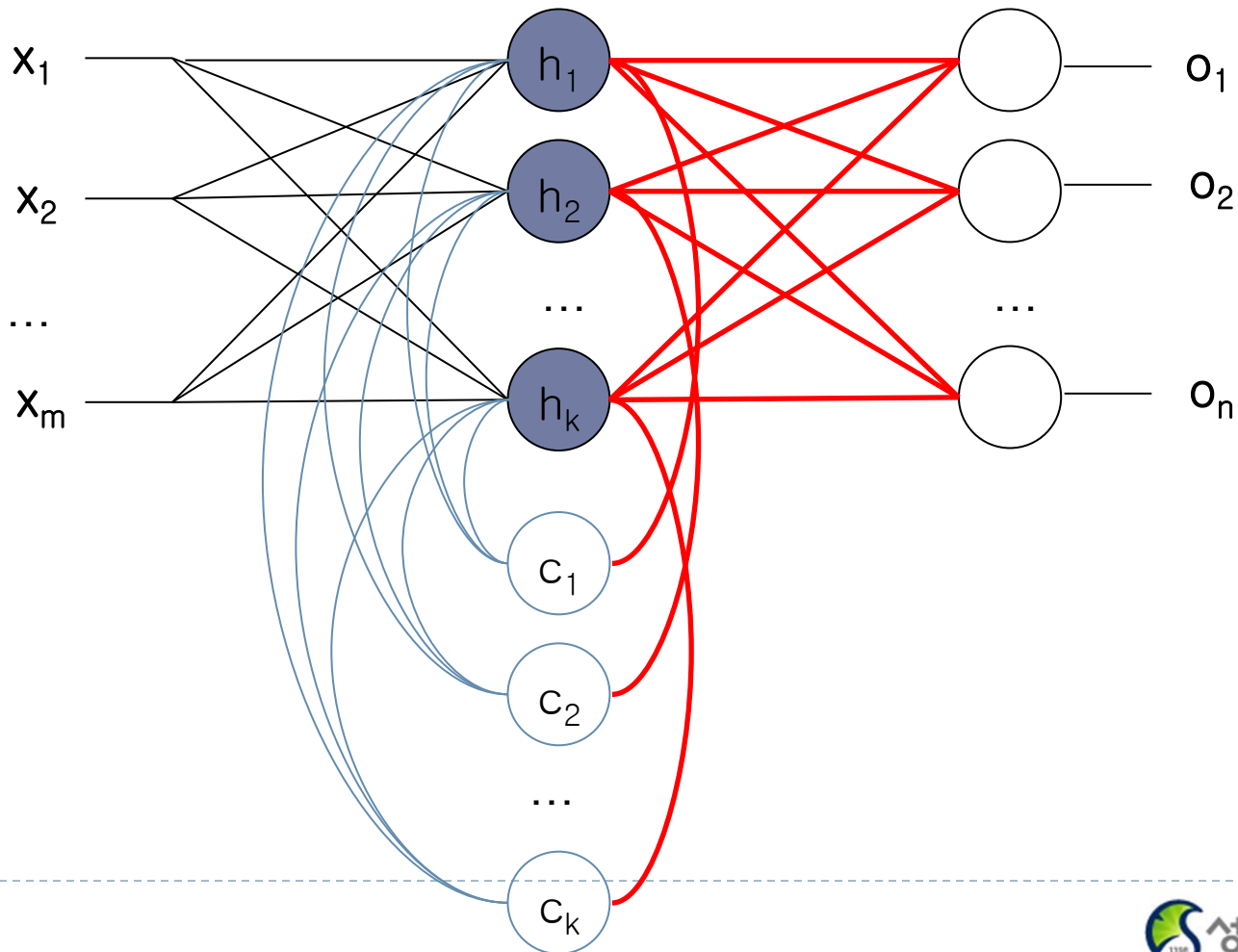
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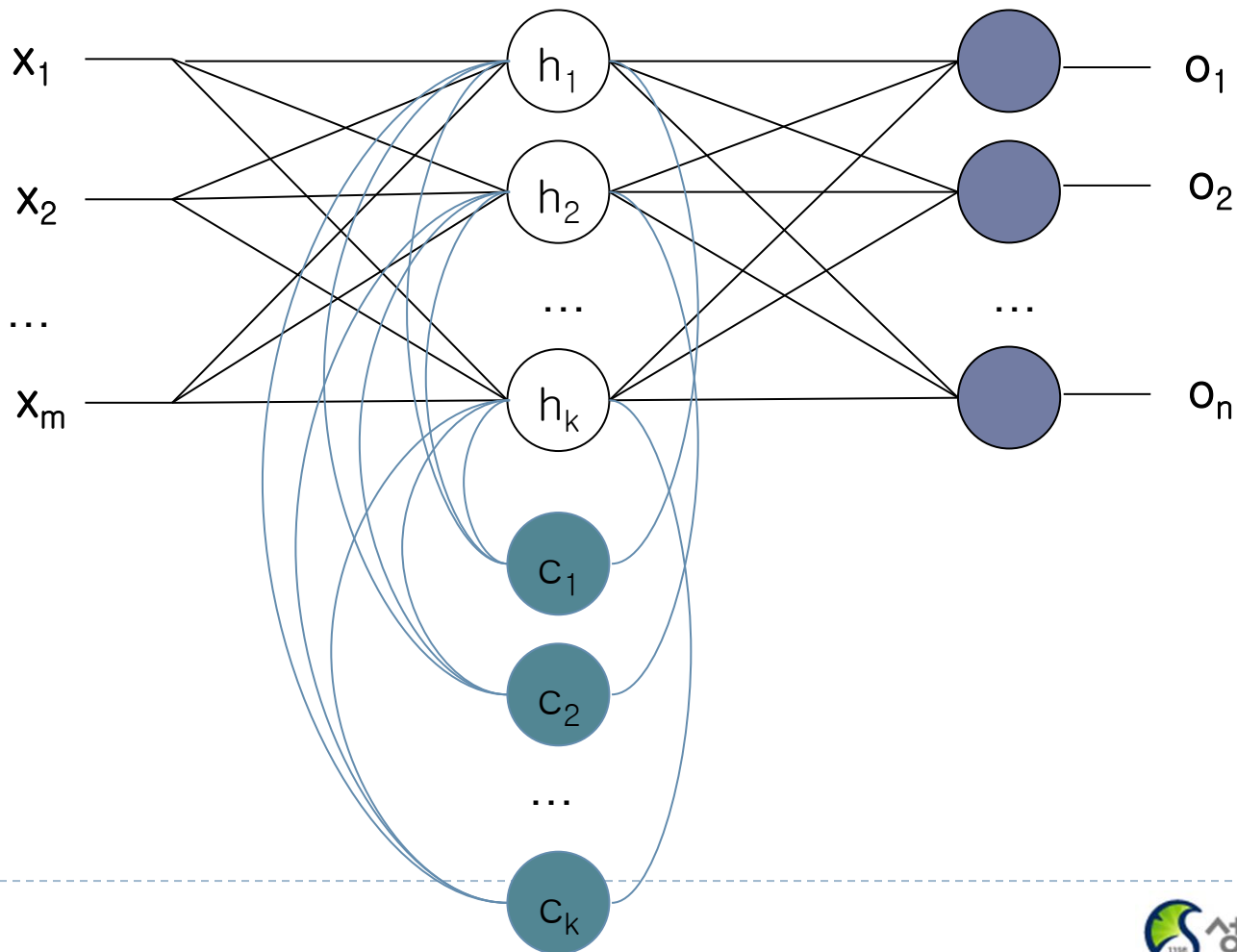
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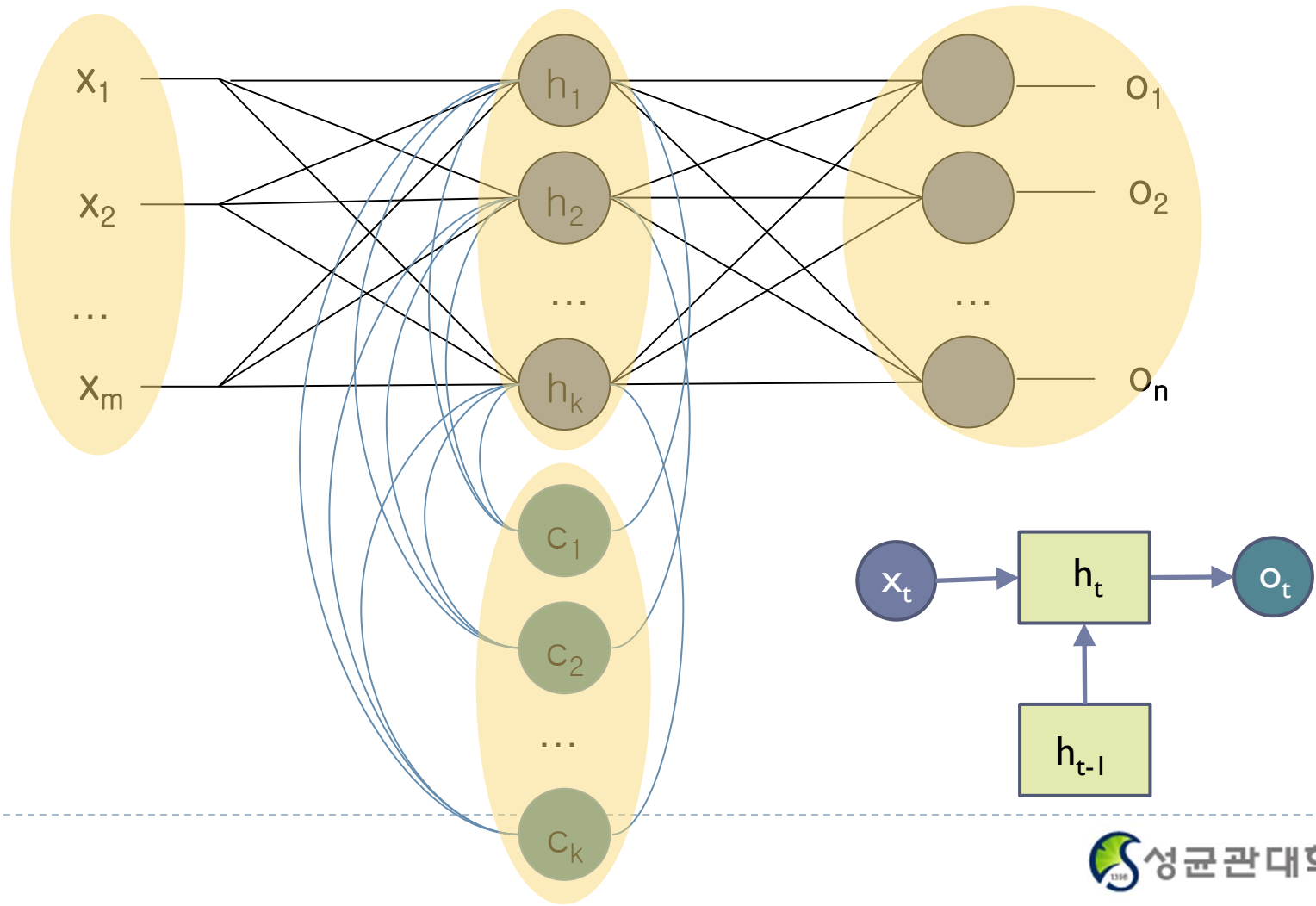
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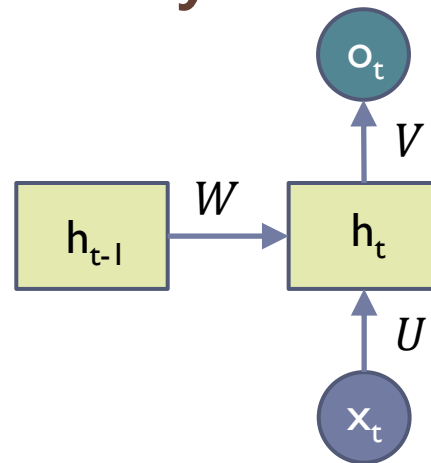
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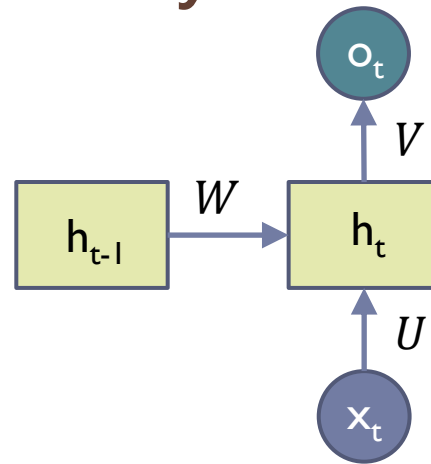
$$h_t = f(Ux_t + Wh_{t-1})$$

$$o_t = g(Vh_t)$$

- x_t : input at time t
- h_t : hidden state at time t
- f : is an activation function
- U, V, W : network parameters
 - RNN shares the same parameters across all time steps
- g : activation function for the output layer

Recurrent Neural Networks

► Connections form cycles

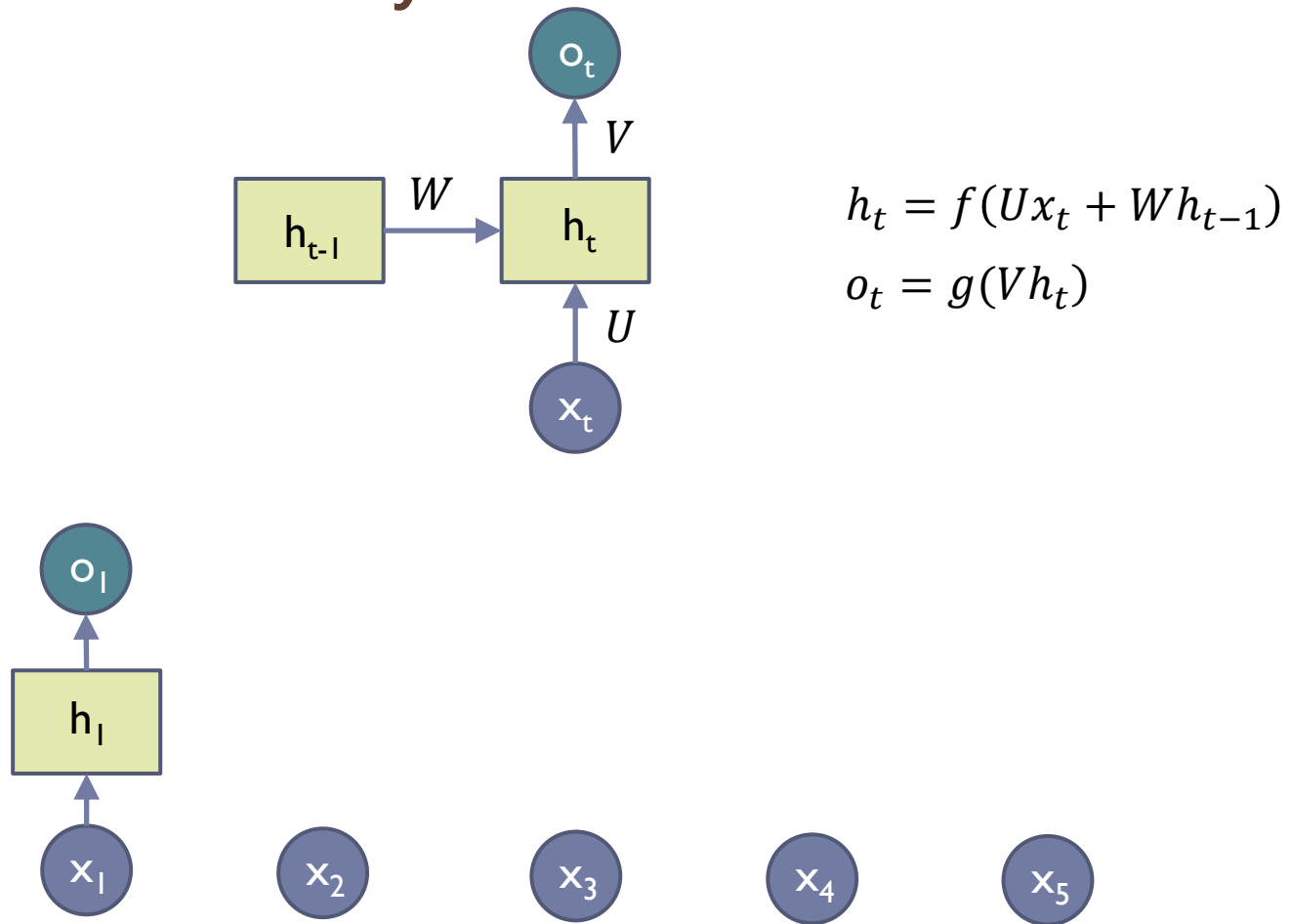


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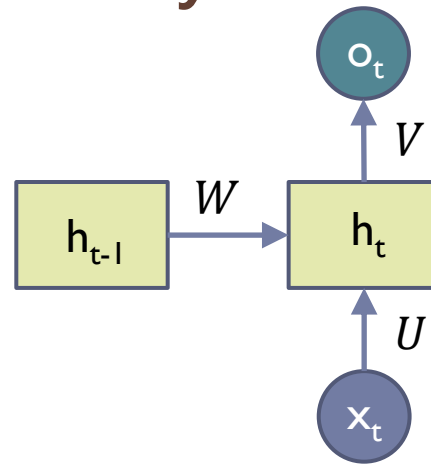
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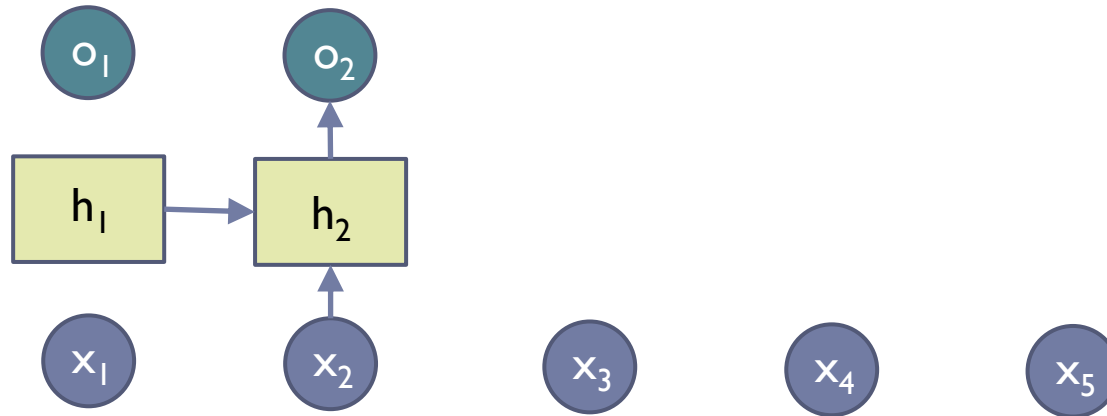


Recurrent Neural Networks

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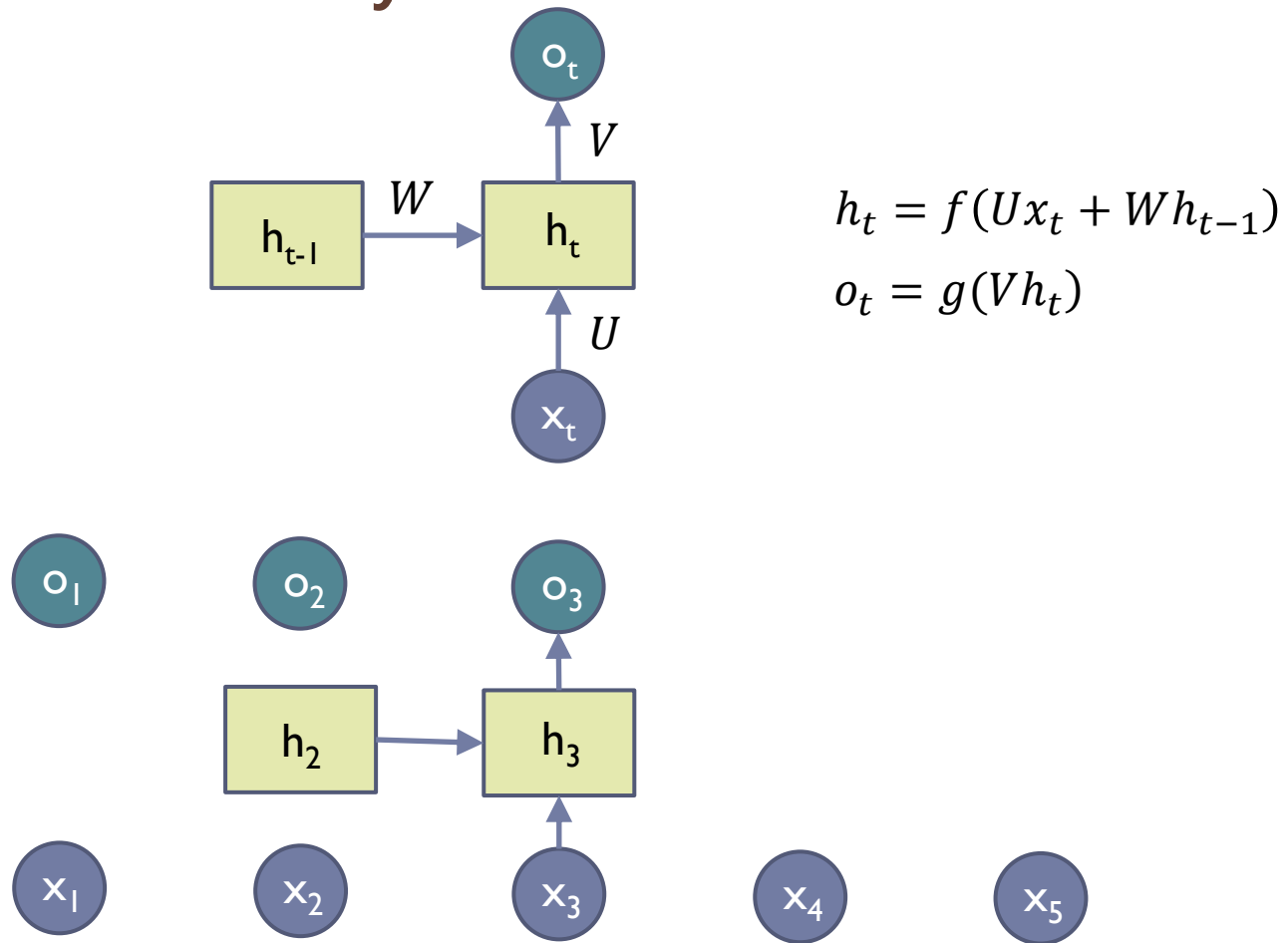


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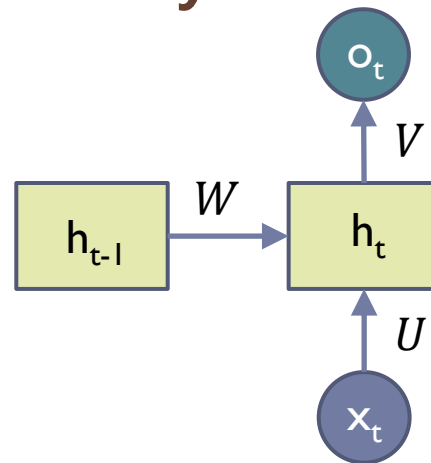
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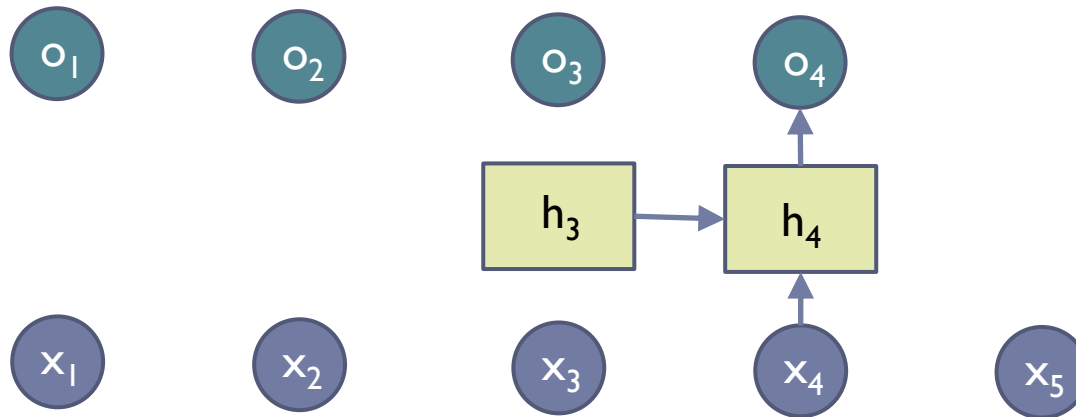


Recurrent Neural Networks

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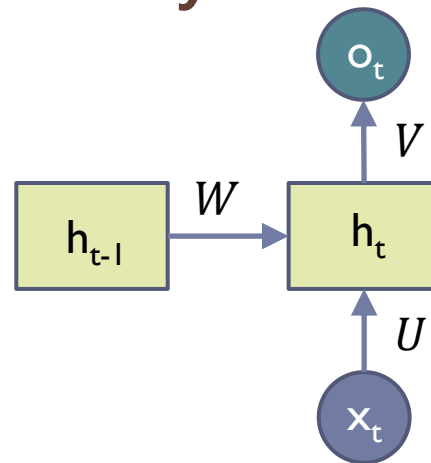


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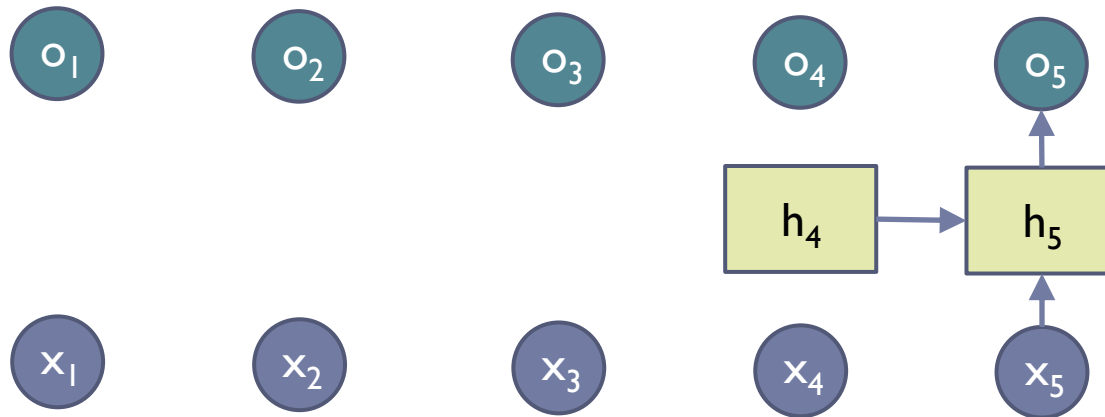


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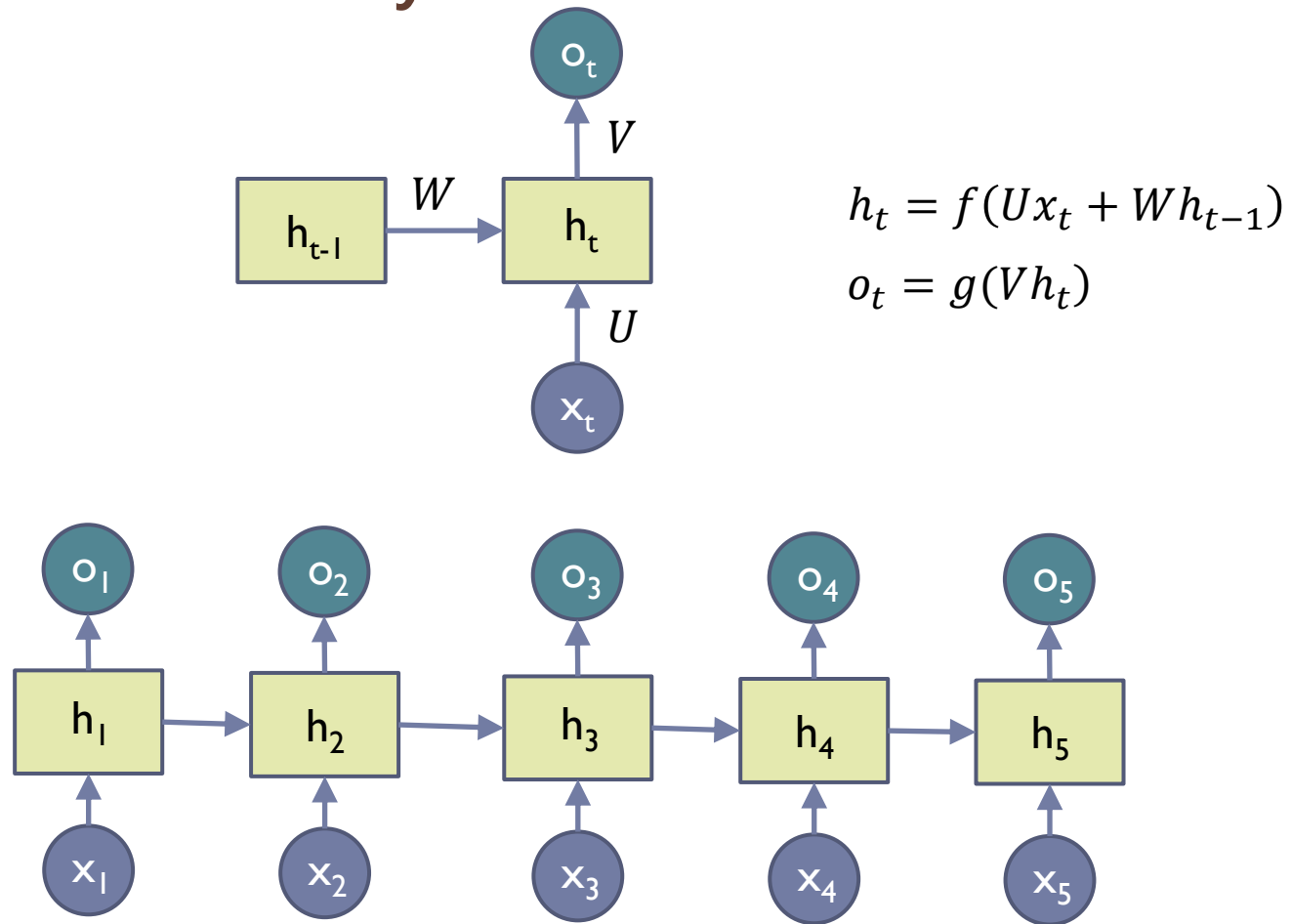


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Recurrent Neural Networks

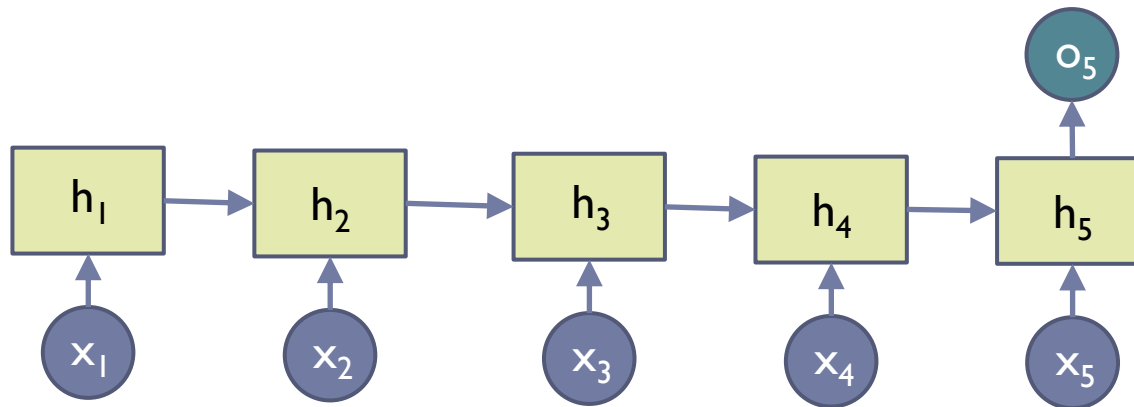
► Connections form cycles



Recurrent Neural Networks

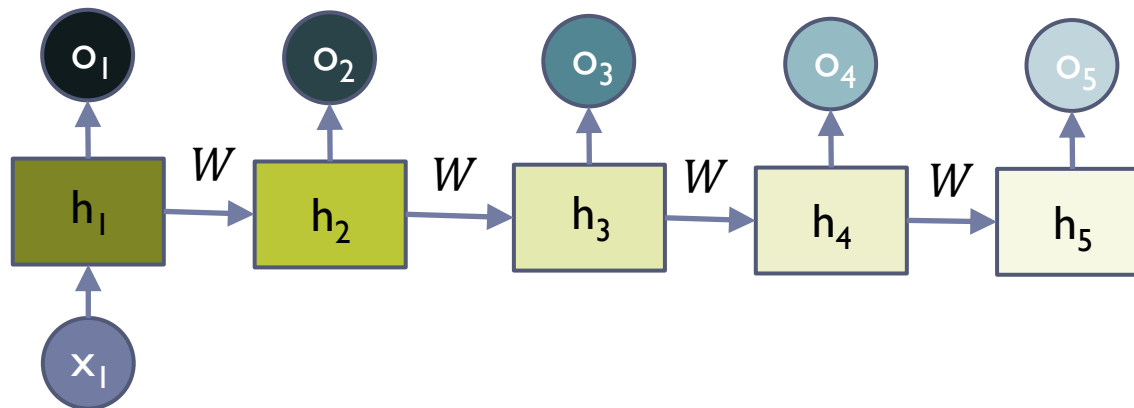
▶ Long Term Dependency

- ▶ $x_1 \sim x_{t-1}$ are encoded into h_{t-1}
- ▶ h_{t-1} has the information on the past
- ▶ It is a context to process x_t



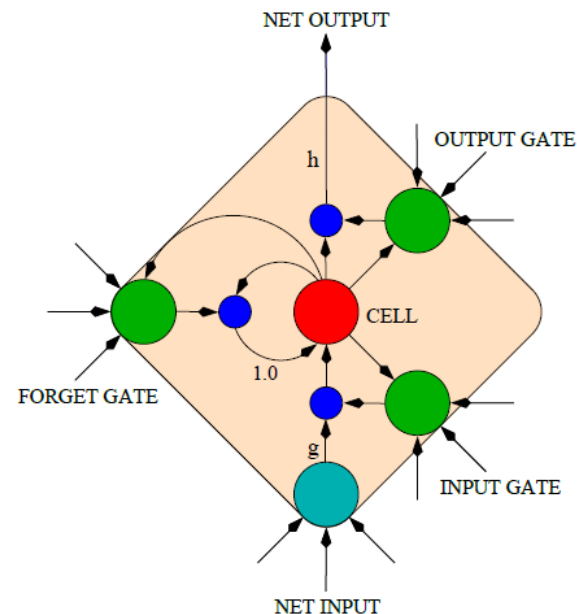
Recurrent Neural Networks

- ▶ **Long Term Dependency of Standard RNN**
 - ▶ However, it may exponentially decay or grow
 - ▶ Usually it is limited to 10 steps



Long Short-Term Memory (LSTM)

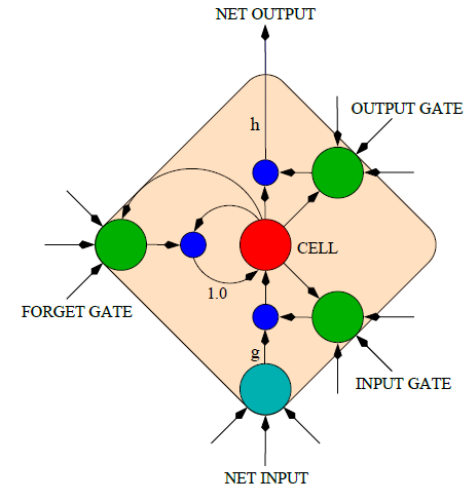
- ▶ **Capable of learning long-term dependencies.**
 - ▶ LSTM networks introduce a new structure called a memory cell
 - ▶ An LSTM can learn to bridge time intervals in excess of 1000 steps
 - ▶ **Gate units that learn to open and close access to the past**
 - ▶ Input gate
 - ▶ Forget gate
 - ▶ Output gate
 - ▶ Neuron with a self-recurrent



Long Short-Term Memory (LSTM)

► Equations

- i : input gate to accept the new
- f : forget gate to forget the past
- o : output gate, how much of the information will be passed to expose to the next time step.
- g : self-recurrent which is equal to standard RNN
- c_t : internal memory
- s_t : hidden state
- y : final output



$$i = \sigma(x_t U^i + s_{t-1} W^i)$$

$$f = \sigma(x_t U^f + s_{t-1} W^f)$$

$$o = \sigma(x_t U^o + s_{t-1} W^o)$$

$$g = \tanh(x_t U^g + s_{t-1} W^g)$$

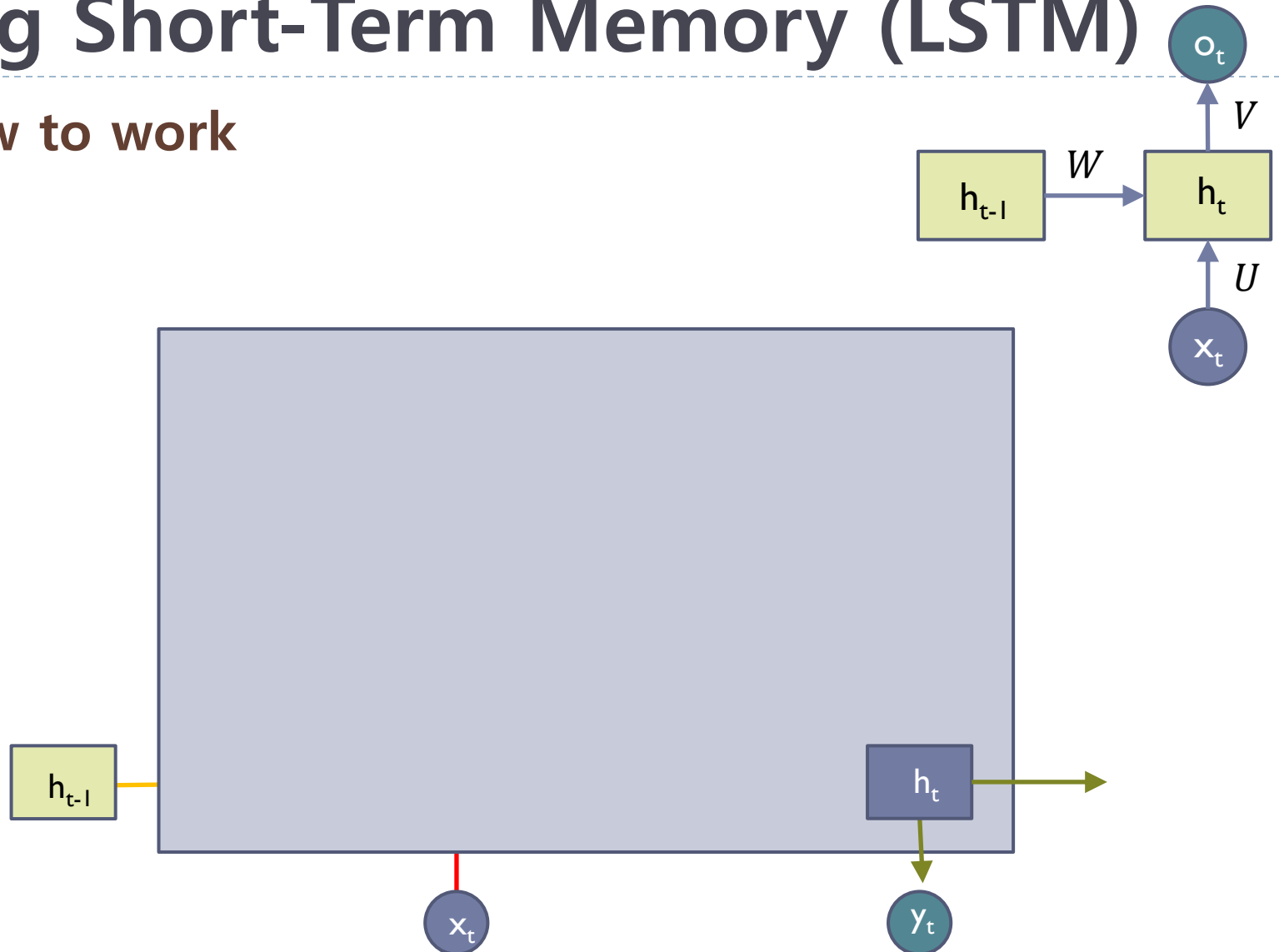
$$c_t = c_{t-1} \circ f + g \circ i$$

$$s_t = \tanh(c_t) \circ o$$

$$y = \text{softmax}(V s_t)$$

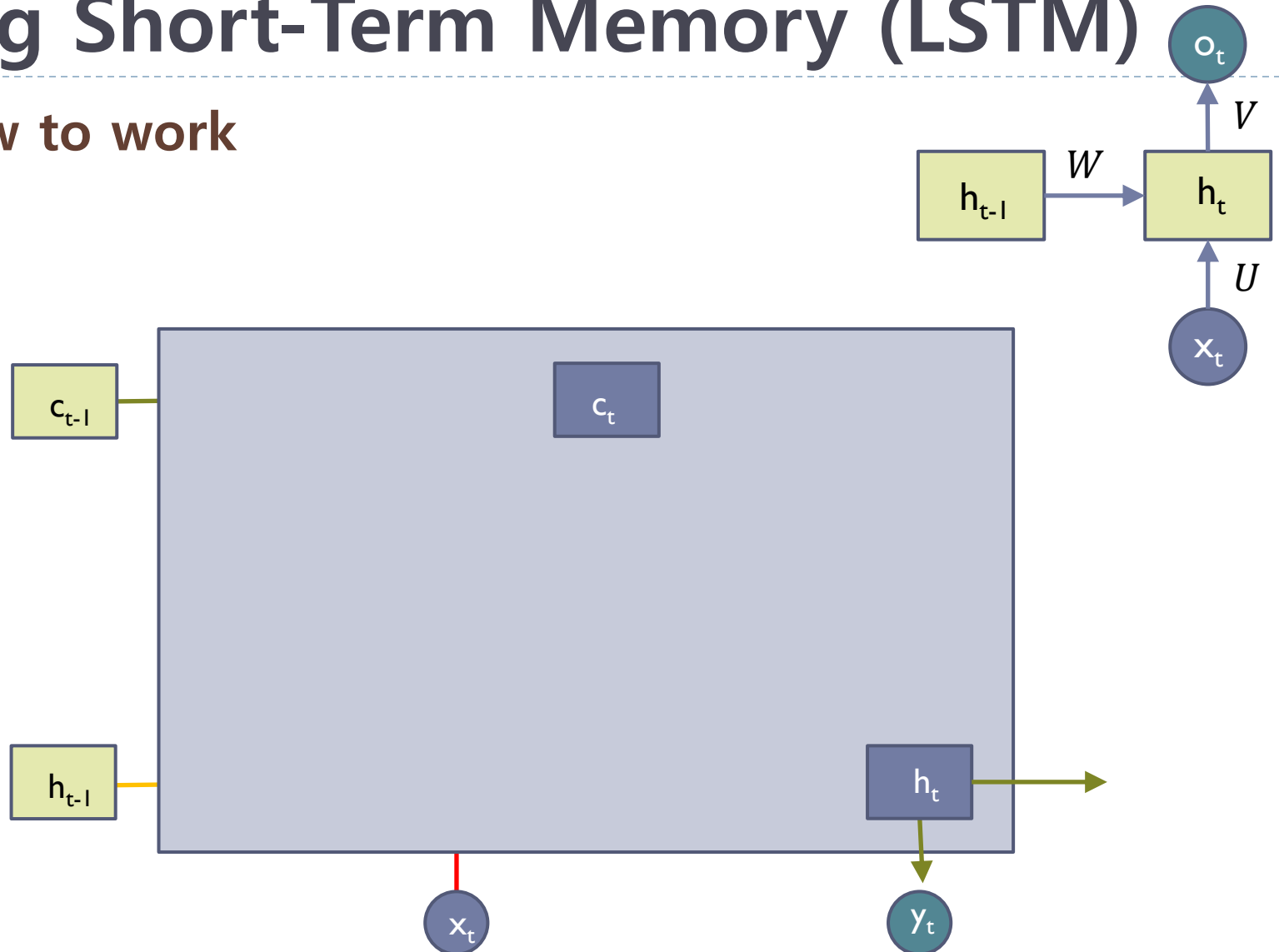
Long Short-Term Memory (LSTM)

▶ How to work



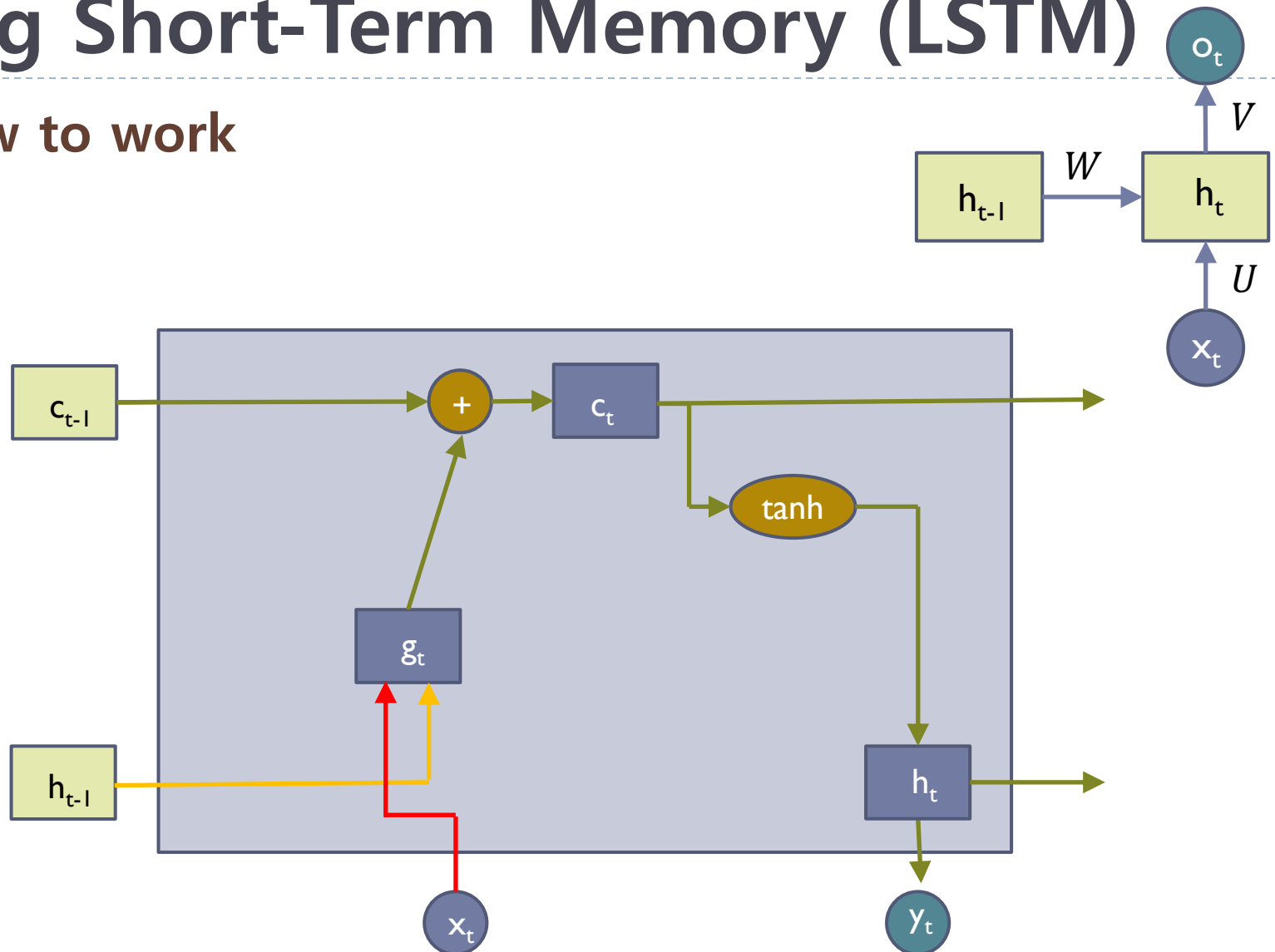
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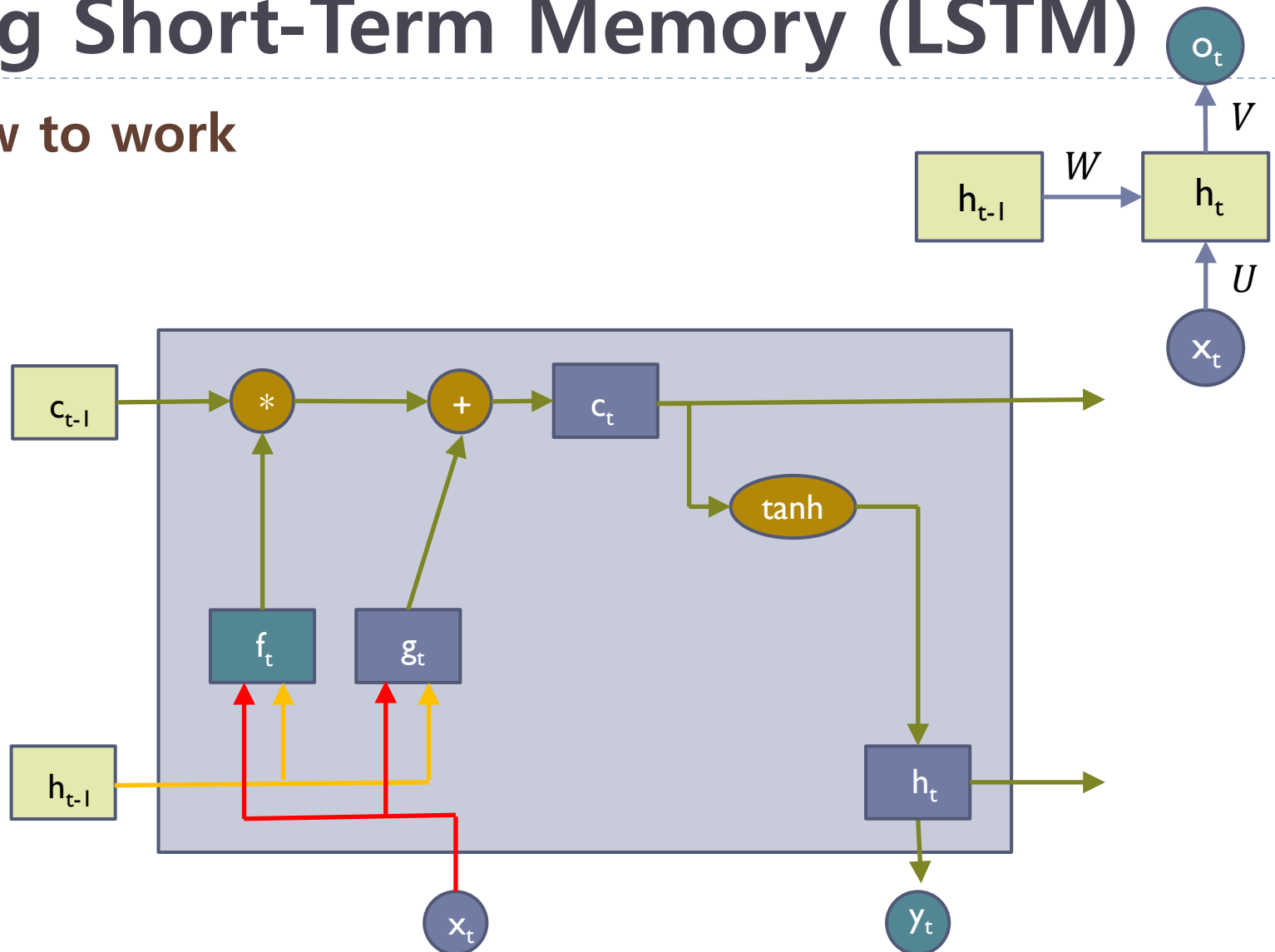
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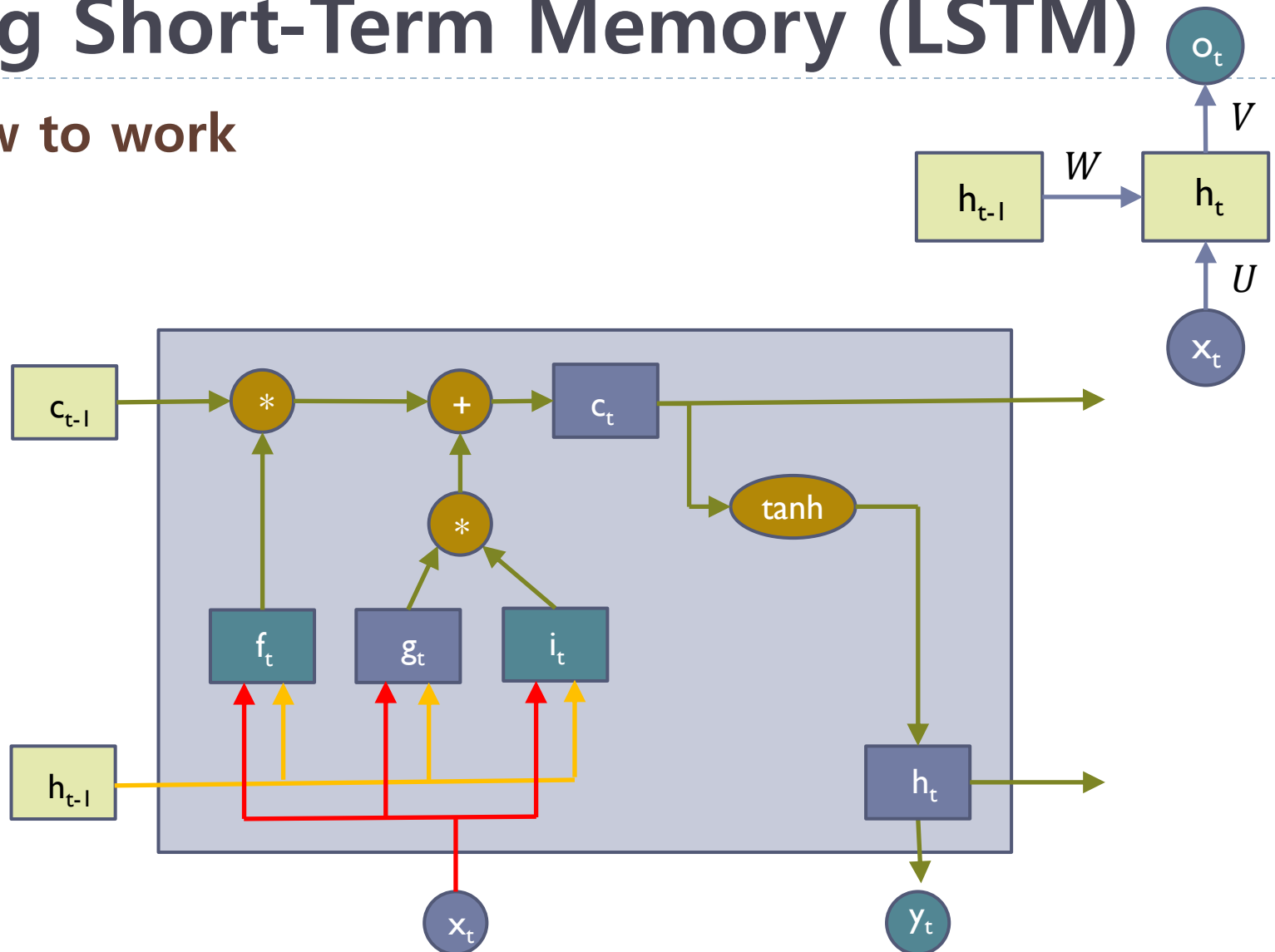
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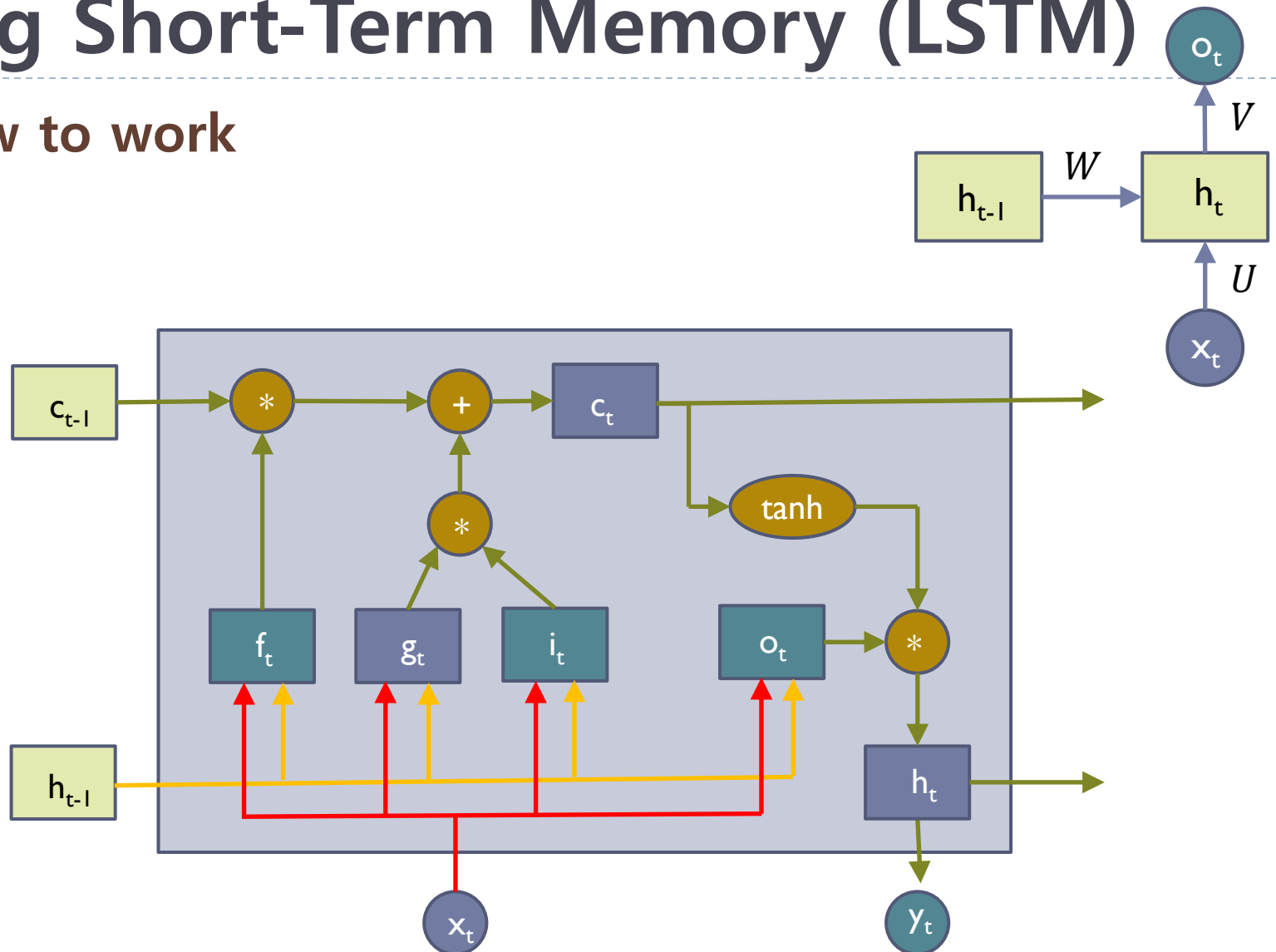
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Long Short-Term Memory (LSTM)

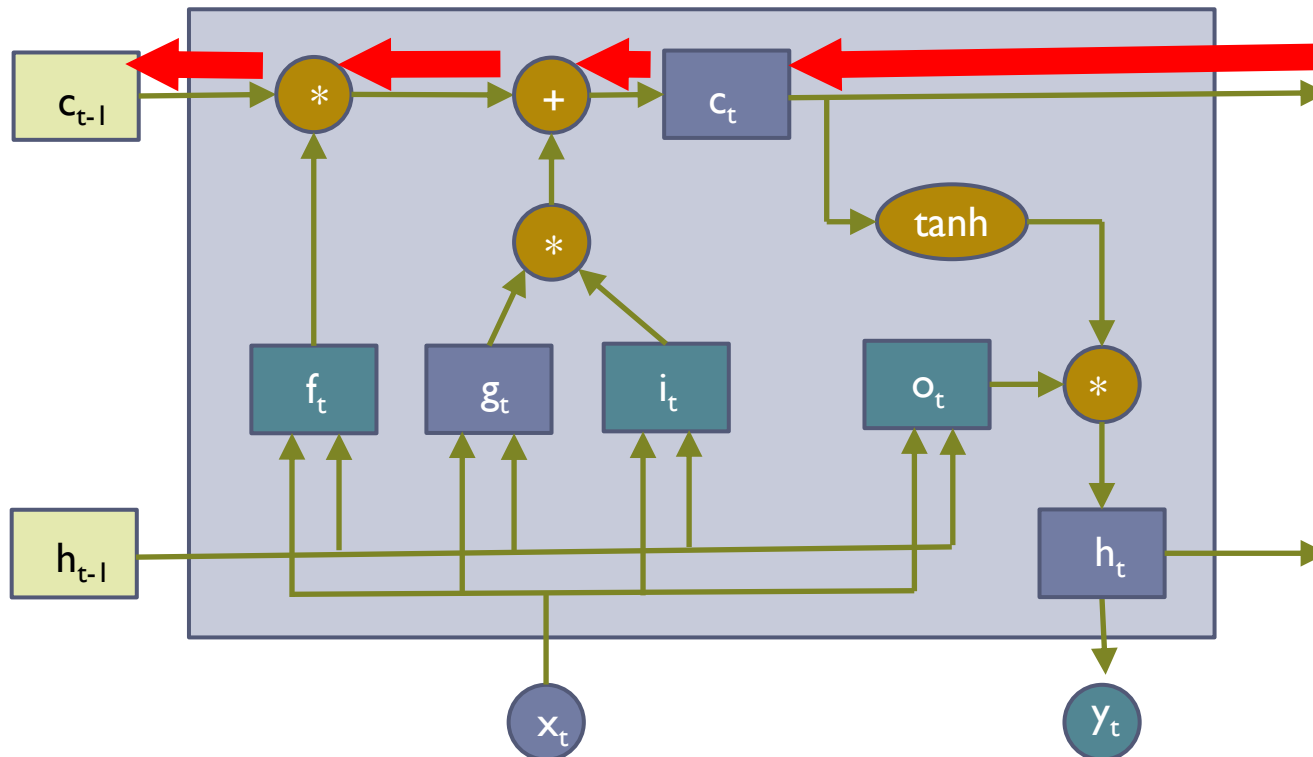
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Long Short-Term Memory (LSTM)

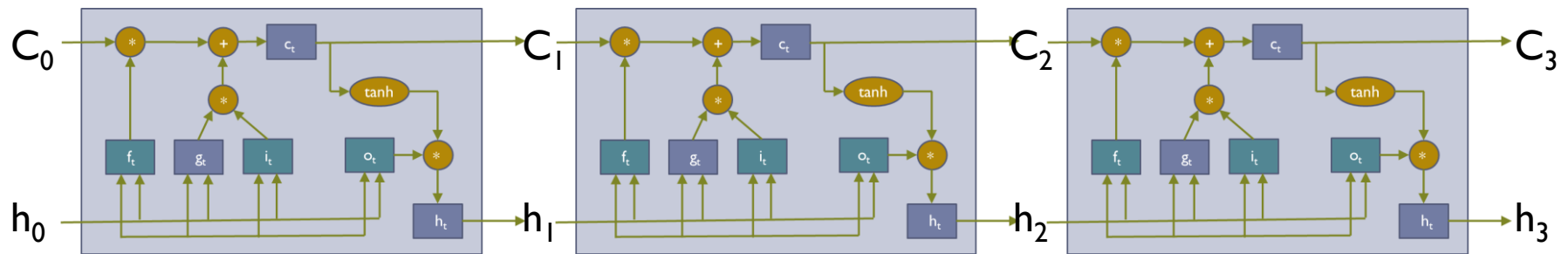
► Gradient Flow

Backpropagation from c_t to c_{t-1} only elementwise multiplication by f , no matrix multiply by W



Long Short-Term Memory (LSTM)

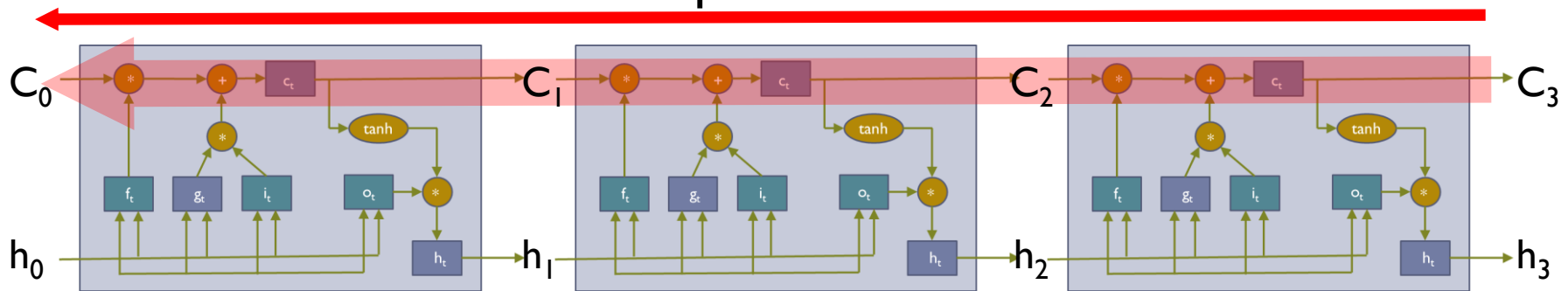
► Gradient Flow



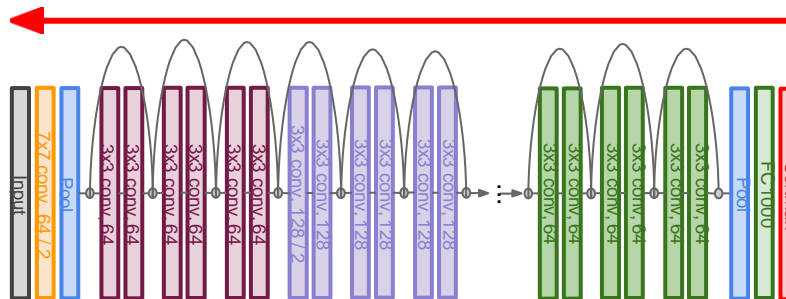
Long Short-Term Memory (LSTM)

► Gradient Flow

Uninterrupted Gradient Flow



Similar to ResNet!



In between:
Highway Networks

$$g = T(x, W_T)$$

$$y = g \odot H(x, W_H) + (1 - g) \odot x$$

Srivastava et al, "Highway Networks",
ICML DL Workshop 2015

Other Variants

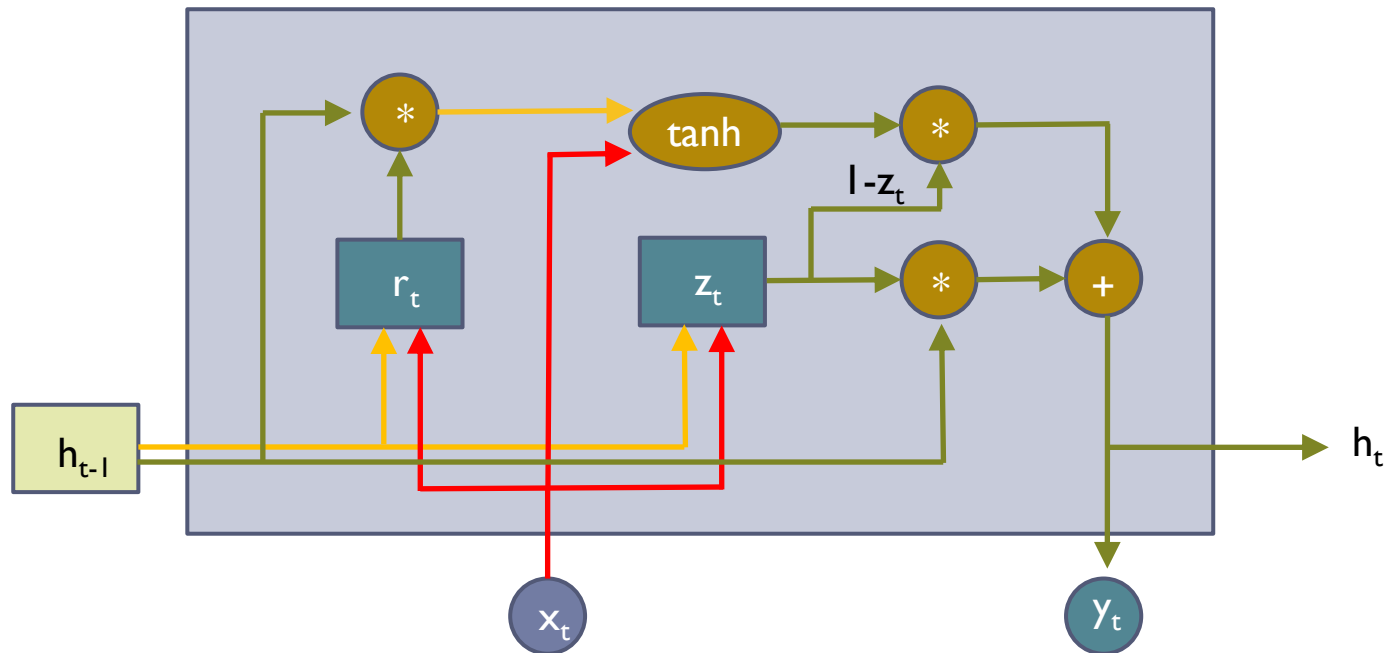
► GRU

$$r_t = \sigma(W_{xr}x_t + W_{hr}h_{t-1} + b_r)$$

$$z_t = \sigma(W_{xz}x_t + W_{hz}h_{t-1} + b_z)$$

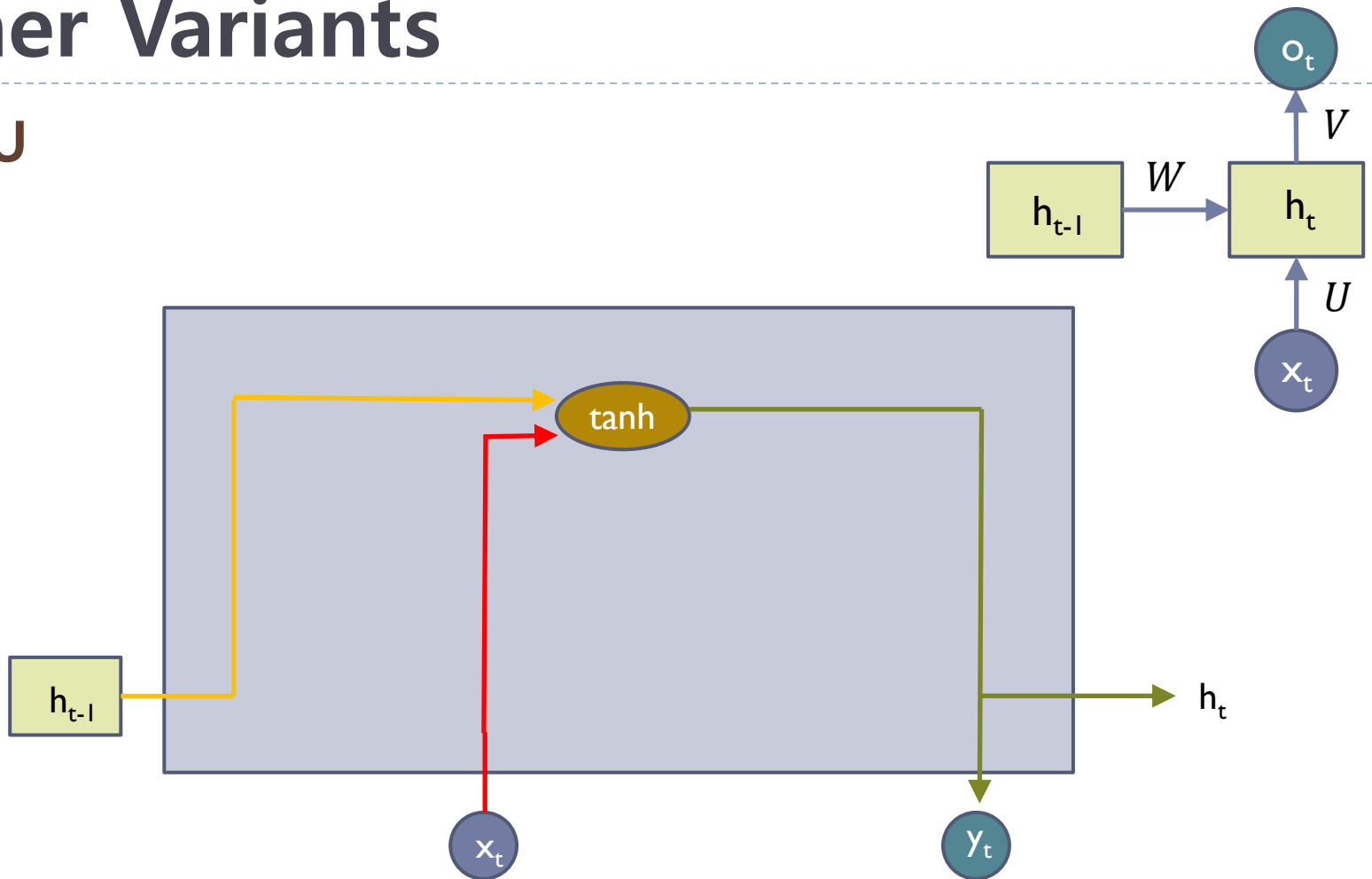
$$\tilde{h}_t = \tanh(W_{xh}x_t + W_{hh}(r_t \odot h_{t-1}) + b_h)$$

$$h_t = z_t \odot h_{t-1} + (1 - z_t) \odot \tilde{h}_t$$



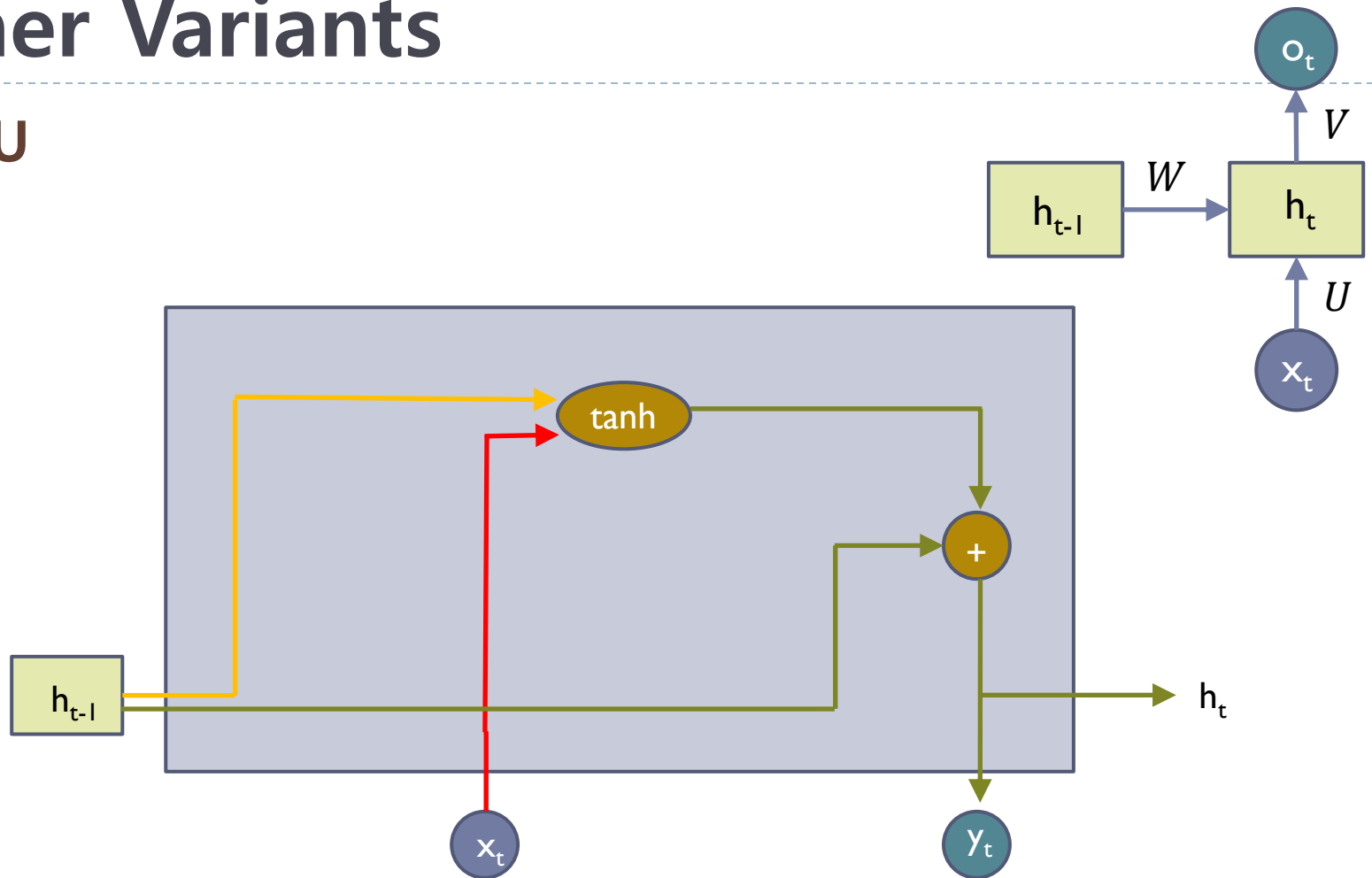
Other Variants

► GRU



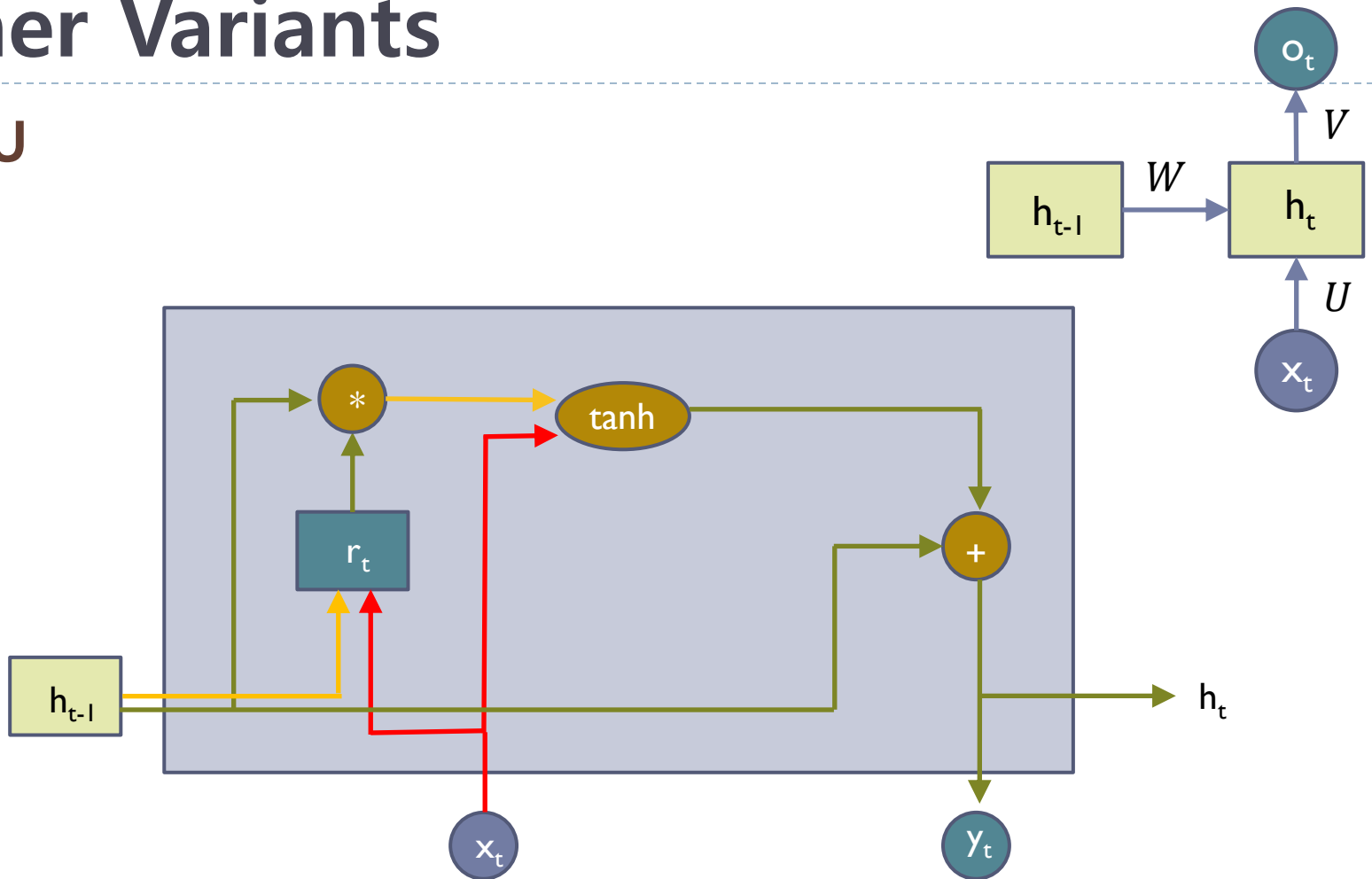
Other Variants

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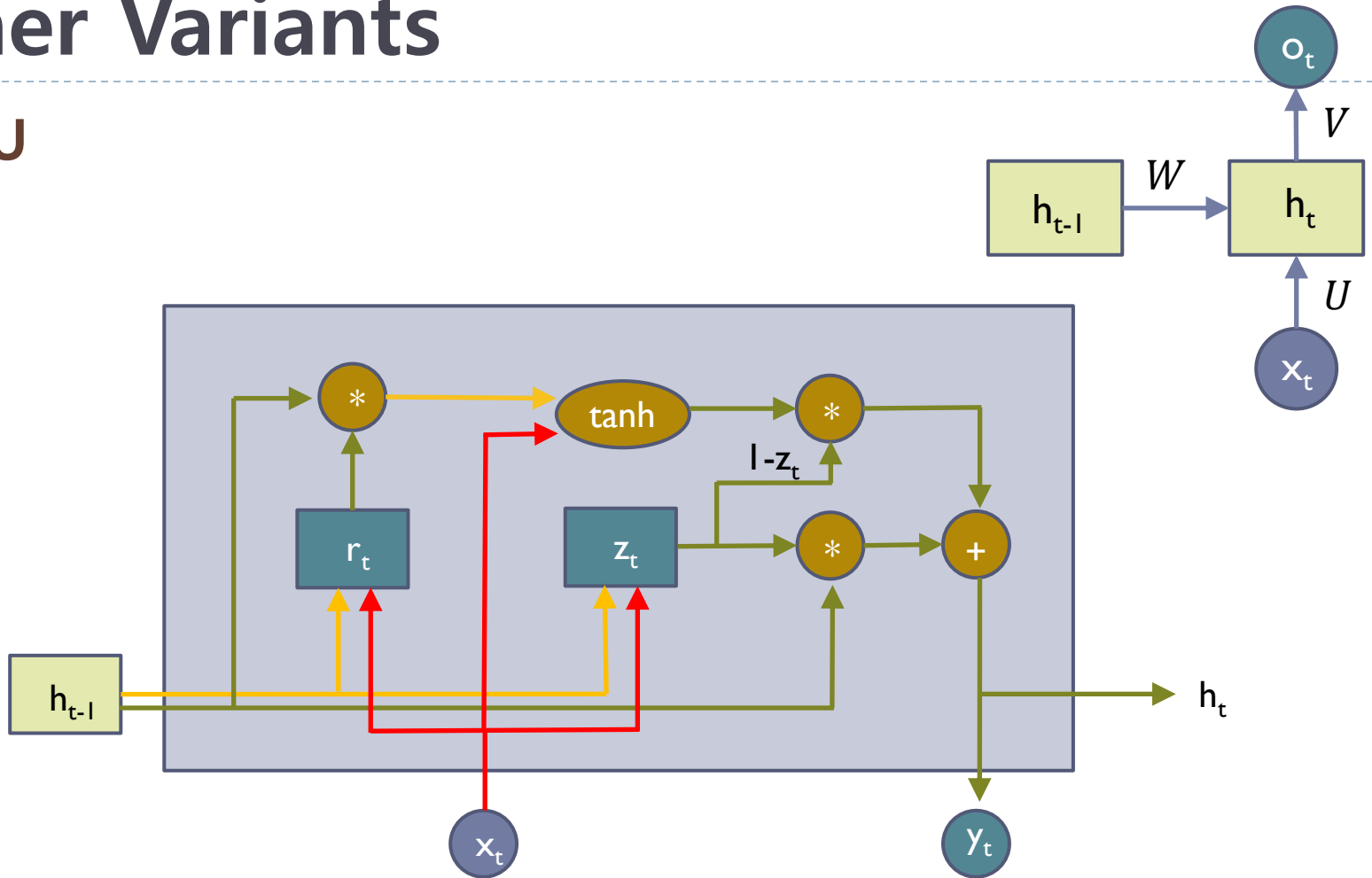
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Question and Answer