Hypothesis Evaluation

- Two definitions of error

. The true error of hypothesis h with respect to target function f and distribution D is the probability that h will misclassify an instance drawn at random according to D:

$$error_D(h) \equiv \Pr_{x \in D}[f(x) \neq h(x)]$$

. The sample error of h with respect to target function f and data sample S is proportion of examples h misclassifies

$$error_S(h) \equiv \frac{1}{n} \sum_{x \in S} I(f(x) \neq h(x))$$

where $I(f(x) \neq h(x))$ is 1 if $f(x) \neq h(x)$, and 0 otherwise.

- Problems of estimating error

- . $error_S(h)$ is an estimator of $error_D(h)$.
- . How well does $error_S(h)$ estimate $error_D(h)$?
- . bias of $error_S(h)$ as an estimator of $error_D(h)$:

$$b_{error_D}(error_s) = E[error_s] - error_D$$

if $b_{error_D}(error_s)=0$ for all $error_D$, we say $error_s$ is an unbiased estimator of $error_D$.

. The mean square error of error_s is given as follows:

$$\begin{split} E[(error_s - error_D)^2] &= E[(error_s - E[error_s] + E[error_s] - error_D)^2] \\ &= E[(error_s - E[error_s])^2] + E[(E[error_s] - error_D)^2] + \\ &\quad 2E[(E[error_s] - error_D](error_s - E[error_s])] \\ &= E[(error_s - E[error_s])^2] + (E[error_s] - error_D)^2 \\ &= Var(error_s) + b_{error_D}^2(error_s) \end{split}$$

That is, the mean square error of $error_s$ is equivalent to the variance of $error_s$ plus the square of bias of $error_s$.

. Let $X_i \in \{0,1\}$ be a random variable which has the mean $error_D$, that is, $E[X_i] = error_D$. Here, we assume that X_i s are

independent and identically distributed.

Then, $error_s$ can be described by

$$error_S = \frac{1}{N} \sum_{i=1}^{N} X_i$$

where N represents the total number of trials.

In this case,

$$E[error_S] = E[\frac{1}{N} \sum_{i=1}^{N} X_i] = \frac{1}{N} \sum_{i=1}^{N} E[X_i] = error_D.$$

That is, $error_S$ is an unbiased estimator of $error_D$.

. example:

Hypothesis h misclassifies 50 of the 100 samples in S. In this case,

$$error_S(h) = \frac{50}{100} = 0.50$$
.

Then, what is $error_D(h)$?

. Given observed $error_S(h)$ what can we conclude about $error_D(h)$?

- Binomial probability distribution

- . Let X be a binomial random variable with parameters (n,p). Then, X represents the number of successes in n trials and p represents the probability of success.
- . example: tossing a coin.

Probability Pr(r) of r heads in n coin flips can be described by

$$\Pr(r) = \binom{n}{r} p^r (1-p)^{n-r} = \frac{n!}{r!(n-r)!} p^r (1-p)^{n-r}$$

where p = Pr(head).

In this case, the mean value of X is

$$E[X] = \sum_{i=0}^{n} i \Pr(i) = np \quad \text{and}$$

the variance of X is

$$Var(X) = E[(X - E[X])^2] = np(1-p).$$

. $error_S(h)$ follows a binomial distribution, that is,

$$error_S(h) = \frac{X}{n}$$
,

$$E[error_S] = E[\frac{X}{n}] = \frac{1}{n}E[X] = p = error_D$$
, and

$$Var(error_S) = Var(\frac{X}{n}) = \frac{1}{n^2} Var(X) = \frac{p(1-p)}{n} = \frac{error_D(1-error_D)}{n}.$$

- Normal distribution approximates Binomial

. Let X_i be a random variable which has the value of 0 or 1 and $\Pr[X_i=1]=p$.

Then, the random variable X having binomial distribution with parameters (n,p) can be described by

$$X = \sum_{i=1}^{n} X_{i}.$$

Here, the mean of X_i is

$$E[X_i] = 1 \cdot p + 0 \cdot (1 - p) = p$$
 and

the variance of X_i is

$$Var(X_i) = E[X_i^2] - E^2[X_i] = p - p^2 = p(1-p).$$

. Central Limit Theorem:

Consider a set of independent, identically distributed (i. i. d.) random variables X_1, X_2, \dots, X_n all governed by an arbitrary probability distribution with mean μ and finite variance σ^2 . Let us define a new random vector

$$X = \sum_{i=1}^{n} X_{i}.$$

Then, as n goes to infinity, the distribution governing X approaches a normal (or Gaussian) distribution, with mean $n\mu$ and variance $n\sigma^2$. That is,

$$X \sim N(n\mu, n\sigma^2)$$
.

cf. In the case of Bernoulli trial, $X \sim N(n\mu, n\sigma^2)$ when $n \geq 30$. That is, X has an approximately Normal distribution with mean $n\mu$ and variance $n\sigma^2$. Here, the sample error of h can be described by

$$error_S(h) = \frac{X}{n} \stackrel{\cdot}{\sim} N(\mu, \frac{\sigma^2}{n})$$

where

$$\mu = error_D(h)$$
 and
$$\frac{\sigma^2}{n} = \frac{error_D(1 - error_D)}{n} \approx \frac{error_S(1 - error_S)}{n}.$$

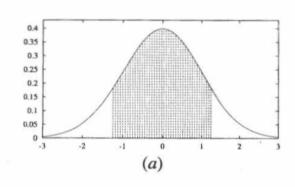
- Normal distribution

. The probability density function is given by

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2}.$$

- . The mean value of X: $E[X] = \mu$.
- . The variance of X: $Var(X) = \sigma^2$
- . The standard deviation of X: $\sigma_X = \sigma$.

- Calculating confidence intervals



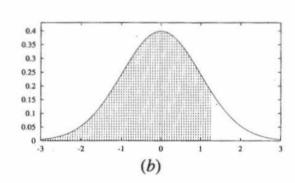


FIGURE 5.1

A Normal distribution with mean 0, standard deviation 1. (a) With 80% confidence, the value of the random variable will lie in the two-sided interval [-1.28, 1.28]. Note $z_{.80} = 1.28$. With 10% confidence it will lie to the right of this interval, and with 10% confidence it will lie to the left. (b) With 90% confidence, it will lie in the one-sided interval $[-\infty, 1.28]$.

. a $100(1-\alpha)\%$ two-sided confidence interval for μ : $\hat{\mu}\pm z_{\alpha/2}\sigma$.

Values of $z_{\alpha/2}$ for two-sided confidence intervals:

| % | 50% | 68% | 80% | 90% | 95% | 98% | 99% |
|--------------|------|------|------|------|------|------|------|
| $z_{lpha/2}$ | 0.67 | 1.00 | 1.28 | 1.64 | 1.96 | 2.33 | 2.58 |

eg. a 95% two-sided confidence interval for μ : $\hat{\mu} \pm 1.96\sigma$.

Let $\hat{\mu}$ is an estimator of μ and

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} X_i$$

where X_i s are i. i. d. random variables having mean $\mu=p$ and variance $\sigma^2=p(1-p)$. Then,

$$\hat{\mu} \sim N(\mu, \frac{\sigma^2}{n}).$$

Let us make a unit (or standard) normal distribution of $\hat{\mu}$:

$$\frac{\hat{\mu}-\mu}{\sigma/\sqrt{n}}$$
 $\sim N(0,1)$.

This implies that

$$-1.96 < \frac{\hat{\mu} - \mu}{\sigma / \sqrt{n}} < 1.96$$
 with the probability of 0.95.

Due to the symmetry of normal distribution,

$$-1.96 < \frac{\mu - \hat{\mu}}{\sigma / \sqrt{n}} < 1.96.$$

Therefore, we get

$$\hat{\mu} - 1.96 \frac{\sigma}{\sqrt{n}} < \mu < \hat{\mu} + 1.96 \frac{\sigma}{\sqrt{n}}$$

where $\sigma = \sqrt{p(1-p)}$.

-> True mean μ lies in $\hat{\mu} \pm 1.96 \frac{\sigma}{\sqrt{n}}$ with the probability of 0.95.

In general, if $\hat{\mu} \sim N(\mu, \sigma^2)$,

the N% confidence interval of $\hat{\mu}$: $\hat{\mu} \pm z_N \sigma$

-> With N% probability, μ lies in interval $\hat{\mu} \pm z_N \sigma$.

The sample error is given by

$$error_{S}(h) = \frac{X}{n} \stackrel{\cdot}{\sim} N(\mu, \frac{\sigma^{2}}{n})$$

where

$$\mu = error_D(h)$$
 and

$$\frac{\sigma^2}{n} = \frac{error_D(1 - error_D)}{n} \approx \frac{error_S(1 - error_S)}{n}$$
.

With approximately 95% probability, $error_D(h)$ lies in interval

$$error_S(h) \pm 1.96 \sqrt{\frac{error_S(h)(1-error_S(h))}{n}} \; .$$

example.

Hypothesis h misclassifies 50 of the 100 samples in S.

In this case,

$$error_S(h) = \frac{50}{100} = 0.50$$
 and

$$Var(error_S(h)) = \frac{0.5 \cdot 0.5}{100}$$
.

Then, with approximately 95% probability, $error_D(h)$ lies in interval $0.50\pm1.96\sqrt{\frac{0.50\cdot0.50}{100}}=0.50\pm0.098.$

That is, the 95% confidence interval of $error_S(h)$ is 0.50 ± 0.098 .

- Comparing two hypotheses

- . Problem: What is the probability that $error_D(h_1) > error_D(h_2)$?
- . Let

$$d \equiv error_D(h_1) - error_D(h_2)$$

and an estimator of d

$$\hat{d} \equiv error_{S_1}(h_1) - error_{S_2}(h_2)$$
.

If $error_{S_i}(h_i)$, i=1,2 are unbiased estimators,

$$E[\hat{d}] = d_{\bullet}$$

. Variance of \hat{d} :

$$Var(\hat{d}) = Var(error_{S_{\!{}^{1}}}(h_{1})) + Var(error_{S_{\!{}^{2}}}(h_{2}))$$

assuming $error_{S_{\!\scriptscriptstyle 1}}(h_1)$ and $error_{S_{\!\scriptscriptstyle 2}}(h_2)$ are independent each other.

From the previous results,

$$Var(error_{S_1}(h_1))pprox rac{error_{S_1}(h_1)(1-error_{S_1}(h_1))}{n_1}$$
 and $error_{S_1}(h_2)(1-error_{S_1}(h_2))$

$$Var(error_{S_{\!\scriptscriptstyle 2}}(h_2)) pprox rac{error_{S_{\!\scriptscriptstyle 2}}(h_2)(1-error_{S_{\!\scriptscriptstyle 2}}(h_2))}{n_2}.$$

Therefore,

$$Var(\hat{d}) \approx \frac{error_{S_{\!1}}(h_1)(1 - error_{S_{\!1}}(h_1))}{n_1} + \frac{error_{S_{\!2}}(h_2)(1 - error_{S_{\!2}}(h_2))}{n_2}.$$

Example:

What is the probability that $d=error_D(h_2)-error_D(h_1)>0$ when $error_{S_1}(h_1)=0.2$ and $error_{S_2}(h_2)=0.3$ using two sample sets of 100 instances?

Let
$$\hat{d} = error_{S_2}(h_2) - error_{S_1}(h_1)$$
. Then,
$$\mu_{\hat{d}} = 0.3 - 0.2 = 0.1 \quad \text{and}$$

$$\sigma_{\hat{d}} = \sqrt{Var(\hat{d})} = \sqrt{\frac{0.2 \cdot 0.8}{100} + \frac{0.3 \cdot 0.7}{100}} = 0.0608.$$

Since

$$\begin{split} Z &= \frac{\hat{d} - \mu_{\hat{d}}}{\sigma_{\hat{d}}} = \frac{\hat{d} - 0.1}{0.0608} \sim N(0, 1) \text{ and } \hat{d} > 0, \\ Z &> \frac{-0.1}{0.0608} = -1.644 \text{ or } Z < \frac{0.1}{0.0608} = 1.644. \end{split}$$

From the definition of z quantity; that is, $P(Z>z_{\alpha})=\alpha$, $z_{0.05}=1.644.$

Therefore,

$$P(Z < 1.644) = 1 - P(Z \ge 1.644) = 1 - 0.05 = 0.95;$$

that is, h_1 is better than h_2 with 95% confidence.

- k-fold cross-validation

- . Evaluation of learning algorithms
- . Partition the available data into k disjoint subsets.
- . k-1 disjoint sets are used to training samples and the remaining 1 disjoint set is used to test samples.
- . Usually, k is set to 10.

k-fold cross-validation method

- Step 1. Partition the available data D_0 into k disjoint subsets T_1, T_2, \dots, T_k of equal size, where this size is at least 30.
- Step 2. For i from 1 to k, do

use T_i for the test set, and the remaining data for training set S_i :

- (1) $S_i \leftarrow \{D_0 T_i\}$
- (2) $h_i \leftarrow L(S_i)$
- (3) Evaluate $error_{T_i}(h_i)$.

Step 3. Evaluate the error mean $\hat{\mu}$ and standard deviation s:

$$\begin{split} \hat{\mu} &= \frac{1}{k} \sum_{i=1}^{k} error_{T_i}(h_i) \\ s &= \sqrt{\frac{1}{k-1} \sum_{i=1}^{k} (error_{T_i}(h_i) - \hat{\mu})^2} \end{split}$$

What is the relationship between $\hat{\mu}$ and μ ?

- t-distribution

. If Z and χ^2_n are independent random variables, with Z having standard normal distribution and χ^2_n having a chi-square distribution with n degrees of freedom, then the random variable T_n defined by

$$T_n = \frac{Z}{\sqrt{\chi_n^2/n}}$$

is said to have a t-distribution with n degrees of freedom.

. The t-density is symmetric about zero.

If n becomes larger, it becomes more and more like a standard normal density since

$$E[\chi_n^2/n] = E[\sum_{i=1}^n Z_i^2/n] \approx E[Z_i^2] = 1.$$

. The mean and variance of T_n :

$$E[T_n] = 0, \quad n > 1$$

$$Var(T_n) = \frac{n}{n-2}, \quad n > 2$$

Thus the variance of T_n decreases to 1 as n increases to ∞ .

- t-Test

. From the result of k-fold cross-validation method,

$$\frac{\hat{\mu}-\mu}{s/\sqrt{k}} \sim T_{k-1}.$$

. This implies that with the probability of $1-\alpha$,

$$\hat{\mu} - t_{\alpha/2,k-1} \frac{s}{\sqrt{k}} < \mu < \hat{\mu} + t_{\alpha/2,k-1} \frac{s}{\sqrt{k}}$$

where $t_{lpha/2,k-1}$ represents a constant such that

$$\Pr[T_{k-1} \ge t_{\alpha/2,k-1}] = \alpha/2.$$

Values of $t_{\alpha/2,n}$:

| | $\alpha = 0.1$ | $\alpha = 0.05$ | $\alpha = 0.02$ | $\alpha = 0.01$ |
|--------------|----------------|-----------------|-----------------|-----------------|
| n=2 | 2.92 | 4.30 | 6.96 | 9.92 |
| n=5 | 2.02 | 2.57 | 3.36 | 4.03 |
| n = 10 | 1.81 | 2.23 | 2.76 | 3.17 |
| n = 20 | 1.72 | 2.09 | 2.53 | 2.84 |
| n = 30 | 1.70 | 2.04 | 2.46 | 2.75 |
| n = 120 | 1.66 | 1.98 | 2.36 | 2.62 |
| $n = \infty$ | 1.64 | 1.96 | 2.33 | 2.58 |

Note that n=k-1.

Example: k-fold cross-validation method

11 subsets and each subset has 30 instances.

After measuring the performance of learning algorithm using the k-fold cross-validation method, we get

$$\hat{\mu} = 0.1$$
 and $s = 0.01$.

In this case, k=11. Let $\alpha = 0.05$. Then, $t_{0.025,10} = 2.23$.

Then, with the probability of 0.95,

 $0.1 - 2.23 \cdot 0.01 < \mu < 0.1 + 2.23 \cdot 0.01$, that is,

 $0.0819 < \mu < 0.1181.$

- Comparing two learning algorithms

. What we would like to estimate is

$$E_{S \subset D}[error_D(L_A(S)) - error_D(L_B(S))]$$

where L(S) is the hypothesis output by the learning algorithm L using training set S.

That is, the expected difference in true error between hypotheses output by learning algorithms L_A and L_B when trained using randomly selected training sets S drawn according to distribution D.

- . But given limited data \mathcal{D}_0 what is a good estimator?
 - (1) We could partition ${\cal D}_0$ into training set ${\cal S}$ and test set ${\cal T}_0$, and measure

$$error_{T_0}(L_{\boldsymbol{A}}(S_{\!\boldsymbol{0}})) - error_{T_{\!\boldsymbol{0}}}(L_{\boldsymbol{B}}(S_{\!\boldsymbol{0}})).$$

(2) Even better, repeat this many times and average the results. That is, apply the k-fold cross-validation method.

k-fold cross-validation method

- Step 1. Partition the available data D_0 into k disjoint subsets $T_1,\,T_2,\,\cdots,\,T_k$ of equal size, where this size is at least 30.
- Step 2. For i from 1 to k, do use T_i for the test set, and the remaining data for training set S_i :

(1)
$$S_i \leftarrow \{D_0 - T_i\}$$

(2)
$$h_A \leftarrow L_A(S_i)$$

(3)
$$h_B \leftarrow L_B(S_i)$$

(4)
$$\delta_i \leftarrow error_{T_i}(h_A) - error_{T_i}(h_B)$$

Step 3. Return the average value of δ_i :

$$\overline{\delta} \equiv \frac{1}{k} \sum_{i=1}^{k} \delta_{i}.$$

. From the t-distribution, the approximate $(1-\alpha)\times 100\%$ confidence interval for δ is

$$\bar{\delta} \pm t_{\delta/2,k-1} \frac{s_{\delta}}{\sqrt{k}}$$

where

$$s_{\delta} = \sqrt{\frac{1}{k-1} \sum_{i=1}^{k} (\delta_i - \overline{\delta})^2}.$$

- . k-fold cross-validation method comments
 - (1) Every example gets used as a test example.
 - (2) Every test set is independent.
 - (3) Training sets overlap significantly.
 - (4) 10 is a standard number of folds, that is, k=10.
 - (5) No method for comparing learning systems with limited data is perfect. However, some statistical analysis is preferable to ignoring the issue of random variation in testing and training.

Reference: T. Mitchell, "Machine Learning," chapter 5.

- Bootstrap method

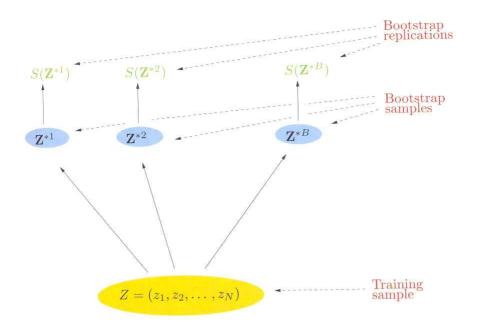
- . Bootstrap method is a general tool for accessing statistical accuracy.
- . Let us consider the sample set

$$Z = (z_1, z_2, \dots, z_N)$$
 and

. the statistical quantity S(Z) computed from the sample set Z. eg. sample mean:

$$S(Z) = \frac{1}{N} \sum_{i=1}^{N} Z_i$$

. bootstrap process



 Z^{*b} , $b=1,2,\cdots,B$ are bootstrap samples in which each sample is drawn randomly with replacement from Z.

. variance estimation

From the bootstrap process, variance can be estimated as

$$\widehat{Var}(S(Z)) = \frac{1}{B-1} \sum_{b=1}^{B} (S(Z^{*b}) - \overline{S}^{*b})^{2}$$

where

$$\overline{S}^* = \frac{1}{B} \sum_{b=1}^{B} S(Z^{*b}).$$

We can consider $\widehat{Var}(S(Z))$ as a Monte-Carlo estimation of Var(S(Z)) under the sampling from the empirical distribution \widehat{F} for the data $Z=(Z_1,Z_2,\,\cdots,Z_N)$.

For this estimation, the proper value of B is typically between 25 and 200.

Bootstrap theorem shows that

$$\lim_{R \to \infty} \widehat{Var}(S(Z)) = Var(S(Z))$$

under the distribution of \hat{F} .

. confidence interval

From the bootstrap process, percentile interval is obtained.

Let $\hat{\theta}$ be an estimation of parameter θ

eg.
$$\hat{\theta} = S(Z) = \frac{1}{N} \sum_{i=1}^{N} Z_i$$

and $\hat{\theta}^*$ be $\hat{\theta}$ for bootstrap samples, that is,

$$\hat{\theta}^* = S(Z^*).$$

Then, $1-2\alpha$ percentile interval is given by

$$\left[\hat{\theta}_{\%lo}, \hat{\theta}_{\%up}\right] = \left[\hat{G}^{-1}(\alpha), \hat{G}^{-1}(1-\alpha)\right]$$

where \hat{G} represents the cumulative distribution function of $\hat{ heta}^*$.

eg. If $\alpha = 0.05$ and B = 1000,

 $\hat{\theta}_{\%lo}$ and $\hat{\theta}_{\%up}$ represent the 50th and 950th samples from the sorted $\hat{\theta}^*$ in ascending order respectively.

This estimate of confidence interval is good for unbiased estimate of θ .

. bias

The bias of bootstrap estimate is defined by

$$bias_B = \frac{1}{B} \sum_{b=1}^{B} \hat{\theta}^{*b}$$

where

$$\hat{\theta}^{*b} = S(Z^{*b}).$$

If $bias_B \ll (\widehat{Var}(S(Z))^{1/2}$, $\hat{\theta}$ is a good estimator. Otherwise, use the bias corrected estimator $\bar{\theta} = \hat{\theta} - bias_B$.

Reference: B. Fron and R. Tibshirani, "An Introduction to the Bootstrap," Chapman and Hall, 1993.

Model Evaluation

- ▶ Metrics for Performance Evaluation
 - ▶ How to evaluate the performance of a model?
- ▶ Methods for Performance Evaluation
 - ▶ How to obtain reliable estimates?
- ▶ Methods for Model Comparison
 - ▶ How to compare the relative performance among competing models?

Model Evaluation

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•

Metrics for Performance Evaluation

- Focus on the predictive capability of a model
 - Rather than how fast it takes to classify or build models, scalability, etc.
- ▶ Confusion Matrix:

| | PREDICTED CLASS | | |
|--------|-----------------|-----------|----------|
| | | Class=Yes | Class=No |
| ACTUAL | Class=Yes | а | b |
| CLASS | Class=No | С | d |

a:TP (true positive) b: FN (false negative) c: FP (false positive) d:TN (true negative)

Metrics for Performance Evaluation...

| | PREDICTED CLASS | | | |
|--------|-----------------|-----------|-----------|--|
| | | Class=Yes | Class=No | |
| ACTUAL | Class=Yes | a (TP) | b (FN) | |
| CLASS | Class=No | c (FP) | d (TN) | |

▶ Most widely-used metric:

Accuracy =
$$\frac{a+d}{a+b+c+d} = \frac{TP+TN}{TP+TN+FP+FN}$$

Limitation of Accuracy

- ▶ Consider a 2-class problem
 - Number of Class 0 examples = 9990
 - Number of Class I examples = 10
- ▶ If model predicts everything to be class 0, accuracy is 9990/10000 = 99.9 %
 - Accuracy is misleading because model does not detect any class I example

Cost Matrix

| | PREDICTED CLASS | | |
|--------|-----------------|------------|-----------|
| | C(i j) | Class=Yes | Class=No |
| ACTUAL | Class=Yes | C(Yes Yes) | C(No Yes) |
| CLASS | Class=No | C(Yes No) | C(No No) |

C(i|j): Cost of misclassifying class j example as class i

| Cost Matrix | PREDICTED CLASS | | |
|-----------------|-----------------|----|-----|
| ACTUAL CLASS | C(i j) | + | • |
| | + | -1 | 100 |
| | - | 1 | 0 |

| Model M ₁ | PREDICTED CLASS | | |
|-------------------------|-----------------|-----|-----|
| | | + | - |
| ACTUAL CLASS | + | 150 | 40 |
| | - | 60 | 250 |

 $\begin{array}{c|c} \mathsf{Model} \\ \mathsf{M}_2 \end{array} \begin{array}{c|c} \mathsf{PREDICTED} \; \mathsf{CLASS} \\ \hline \mathsf{ACTUAL} \\ \mathsf{CLASS} \end{array} \begin{array}{c|c} & \mathsf{+} & \mathsf{-} \\ \\ \mathsf{+} & 250 & 45 \\ \hline \mathsf{-} & 5 & 200 \\ \hline \end{array}$

Accuracy = 80%

Cost = 3910

Accuracy = 90%

Cost = 4255

Cost vs Accuracy

| Count | PREDICTED CLASS | | |
|--------|-----------------|-----------|----------|
| | | Class=Yes | Class=No |
| ACTUAL | Class=Yes | а | b |
| CLASS | Class=No | С | d |

Accuracy is proportional to cost if I. C(Yes|No)=C(No|Yes)=q 2. C(Yes|Yes)=C(No|No)=p

N = a + b + c + d

Accuracy = (a + d)/N

| Cost | PREDICTED CLASS | | |
|--------|-----------------|-----------|----------|
| | | Class=Yes | Class=No |
| ACTUAL | Class=Yes | р | q |
| CLASS | Class=No | q | р |

| Cost = $p(a + d) + q(b + c)$ |
|-----------------------------------|
| = p (a + d) + q (N - a - d) |
| = q N - (q - p)(a + d) |
| = N $[q - (q-p) \times Accuracy]$ |
| |

4

Cost-Sensitive Measures

Precision (p) =
$$\frac{a}{a+c}$$

Recall (r) =
$$\frac{a}{a+b}$$

F-measure (F) =
$$\frac{2rp}{r+p}$$
 = $\frac{2a}{2a+b+c}$

- Precision is biased towards C(Yes|Yes) & C(Yes|No)
- Recall is biased towards C(Yes|Yes) & C(No|Yes)
- F-measure is biased towards all except C(No|No)

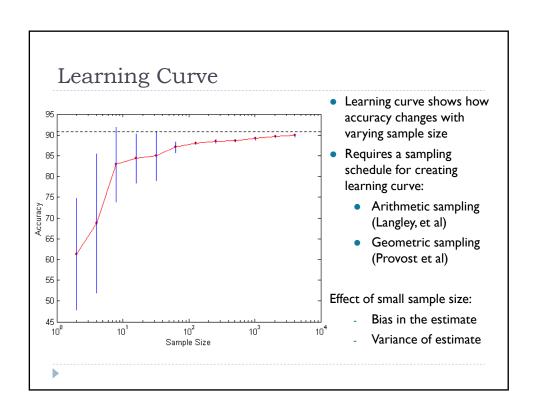
Weighted Accuracy =
$$\frac{w_1 a + w_4 d}{w_1 a + w_2 b + w_3 c + w_4 d}$$

Model Evaluation

- ▶ Metrics for Performance Evaluation
 - ▶ How to evaluate the performance of a model?
- ▶ Methods for Performance Evaluation
 - ▶ How to obtain reliable estimates?
- Methods for Model Comparison
 - ▶ How to compare the relative performance among competing models?

Methods for Performance Evaluation

- ▶ How to obtain a reliable estimate of performance?
- ▶ Performance of a model may depend on other factors besides the learning algorithm:
 - Class distribution
 - Cost of misclassification
 - Size of training and test sets



Methods of Estimation

- ▶ Holdout
 - ▶ Reserve 2/3 for training and 1/3 for testing
- Random subsampling
 - Repeated holdout
- ▶ Cross validation
 - ▶ Partition data into k disjoint subsets
 - ▶ k-fold: train on k-1 partitions, test on the remaining one
 - ▶ Leave-one-out: k=n
- Stratified sampling
 - oversampling vs undersampling
- Bootstrap
 - Sampling with replacement

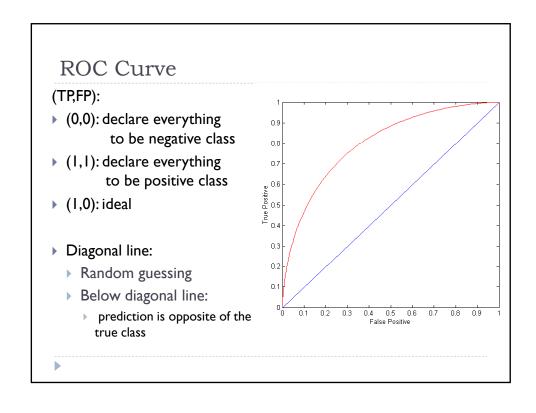
Model Evaluation

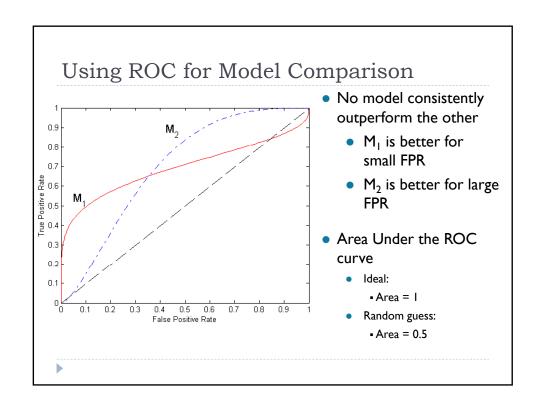
- ▶ Metrics for Performance Evaluation
 - ▶ How to evaluate the performance of a model?
- ▶ Methods for Performance Evaluation
 - How to obtain reliable estimates?
- Methods for Model Comparison
 - ▶ How to compare the relative performance among competing models?

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ROC (Receiver Operating Characteristic)

- Developed in 1950s for signal detection theory to analyze noisy signals
 - Characterize the trade-off between positive hits and false alarms
- ▶ ROC curve plots TP (on the y-axis) against FP (on the x-axis)
- Performance of each classifier represented as a point on the ROC curve
 - changing the threshold of algorithm, sample distribution or cost matrix changes the location of the point





How to Construct an ROC curve

| Instance | P(+ A) | True Class |
|----------|--------|------------|
| 1 | 0.95 | + |
| 2 | 0.93 | + |
| 3 | 0.87 | - |
| 4 | 0.85 | - |
| 5 | 0.85 | - |
| 6 | 0.85 | + |
| 7 | 0.76 | - |
| 8 | 0.53 | + |
| 9 | 0.43 | - |
| 10 | 0.25 | + |
| | | |

- Use classifier that produces posterior probability for each test instance P(+|A)
- ullet Sort the instances according to P(+|A) in decreasing order
- Apply threshold at each unique value of P(+|A)
- Count the number of TP, FP, TN, FN at each threshold
- TP rate, TPR = TP/(TP+FN)
- FP rate, FPR = FP/(FP + TN)

How to construct an ROC curve 0.25 0.43 0.53 0.85 0.85 0.85 0.87 0.93 1.00 Threshold 0.95 5 3 4 5 2 0 0 2 3 5 5 1 5 0.8 0 **ROC Curve:** 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9