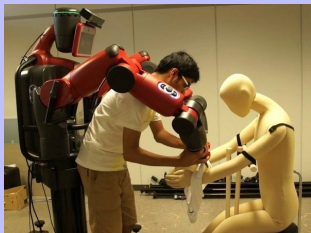


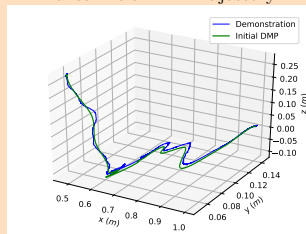
Teaching Phase



A demonstration is performed by moving the Baxter arms in the appropriate trajectory

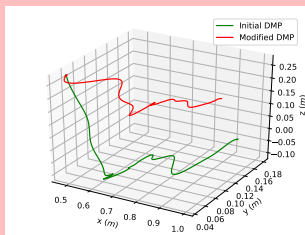
Learn Trajectory

Baxter Left Arm Trajectory



Recorded trajectory is parameterized by DMP

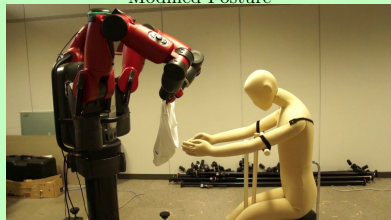
DMP Generalization



Arms posture of the mannequin is changed. Accordingly goal parameter of DMP is modified

Testing Phase

Modified Posture



DMP can accommodate any posture by changing goal parameter