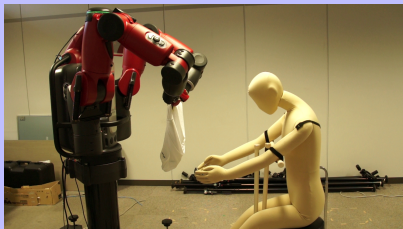


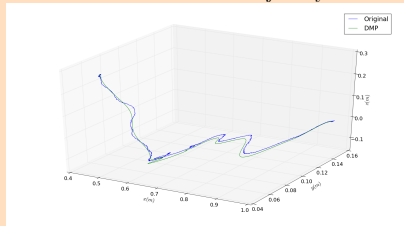
## Teaching Phase



A demonstration is performed by moving the Baxter arms in the appropriate trajectory

## Trajectory Parameterization

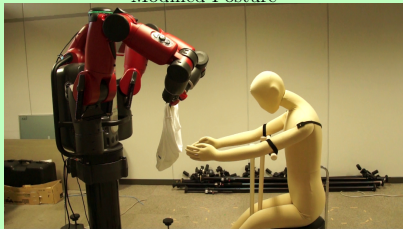
### Baxter Left Arm Trajectory



Recorded trajectory is parameterized by DMP

## Testing Phase

### Modified Posture



DMP can accomodate any posture by changing goal parameter

## DMP Generalization

### DMP Trajectory

