

# Supplementary Material for the paper “Design Guidelines for Nonlinear Kalman Filters via Covariance Compensation”

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## I. USEFUL EQUATIONS APPEARED IN THE MAIN TEXT

The following equations from the main text will be used in the theorems and proofs in the subsequent sections.

**Page 2, Equation (1).** Consider random vectors  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{z} \in \mathbb{R}^m$  and a nonlinear measurable mapping  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  that satisfies:

$$\mathbf{x} \sim (0, I_{n \times n}), \mathbf{z} = f(\mathbf{x}), \quad (1)$$

**Page 3, Equation (4).** With the conditions in (1), EKF2 estimates  $\bar{\mathbf{z}}$ ,  $P_z$ , and  $P_{xz}$  by [1]:

$$\begin{cases} \bar{\mathbf{z}}^{\text{EKF2}} = f(\mathbf{0}) + \frac{1}{2}[\text{tr}(f''(\mathbf{0}))]_i \\ P_z^{\text{EKF2}} = f'(\mathbf{0})(f'(\mathbf{0}))^T + \frac{1}{2}[\text{tr}(f''(\mathbf{0})f''(\mathbf{0}))]_{ij} \\ P_{xz}^{\text{EKF2}} = (f'(\mathbf{0}))^T \end{cases}, \quad (2)$$

**Page 4, Equation (12).** SKF and CKF both assume that the states follow a uniform discrete distribution. With this assumption, SKF and CKF estimates  $\bar{\mathbf{z}}$ ,  $P_z$ , and  $P_{xz}$  by:

$$\begin{cases} \bar{\mathbf{z}}^{\text{SKF/CKF}} = \frac{1}{N} \sum_{i=1}^N f(\xi_i^{\text{SKF/CKF}}) \\ P_z^{\text{SKF/CKF}} = \frac{1}{N} \sum_{i=1}^N (f(\xi_i^{\text{SKF/CKF}}) - \bar{\mathbf{z}}^{\text{SKF/CKF}})(\cdot)^T \\ P_{xz}^{\text{SKF/CKF}} = \frac{1}{N} \sum_{i=1}^N \xi_i^{\text{SKF/CKF}} (f(\xi_i^{\text{SKF/CKF}}) - \bar{\mathbf{z}}^{\text{SKF/CKF}})^T \end{cases} \quad (3)$$

**Page 7, Equation (39).** The optimization problem is formulated as:

$$\min_{\beta} \mathbb{E}[\text{tr}(\mathbf{P}_{k|k,ac})]. \quad (4)$$

## II. PROOF OF EQUATION (6) ON PAGE 3

**Proposition 1.** When  $\mathbf{x}$  satisfies (1) and is evenly distributed on the sphere  $\|\mathbf{x}\|_2^2 = n$ , the covariance compensation matrix given by the EKF2 should be:

$$P_{com}^{\text{EKF2, Sphere}} = \frac{n[\text{tr}(f''(\mathbf{0})f''(\mathbf{0})) - \frac{1}{n}\text{tr}(f''(\mathbf{0}))\text{tr}(f''(\mathbf{0}))]_{ij}}{2(n+2)}, \quad (5)$$

and  $P_{com}^{\text{EKF2, Sphere}}$  is PSD.

*Proof.* By isotropy on the sphere of radius  $\sqrt{n}$ , one has  $\mathbb{E}[\mathbf{x}] = \mathbf{0}$  and  $\mathbb{E}[\mathbf{x}\mathbf{x}^T] = I_n$ . Moreover, the fourth moments are (see Lemma 2.22 in [2]):

$$\mathbb{E}[x_a x_b x_c x_d] = \frac{n}{n+2}(\delta_{ab}\delta_{cd} + \delta_{ac}\delta_{bd} + \delta_{ad}\delta_{bc}), \quad (6)$$

where  $a, b, c, d \in \{1, \dots, n\}$  and  $\delta$  is the Kronecker delta, which satisfies:

$$\delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}. \quad (7)$$

EKF2 approximates the system up to the second order. Write the second-order Taylor model componentwise as

$$z_i \approx f_i(\mathbf{0}) + f'_i(\mathbf{0})\mathbf{x} + \frac{1}{2}\mathbf{x}^T f''_i(\mathbf{0})\mathbf{x}. \quad (8)$$

Since  $\mathbf{x}$  has a distribution symmetric about the origin, all third moments vanish. Hence, for any  $i, j$ ,

$$\text{Cov}(f'_i(\mathbf{0})\mathbf{x}, \mathbf{x}^T f'_j(\mathbf{0})\mathbf{x}) = 0 \quad (9)$$

Therefore, the covariance compensation coming from the quadratic part is

$$\begin{aligned} P_{com,ij}^{\text{EKF2, Sphere}} &= \text{Cov}\left(\frac{1}{2}\mathbf{x}^T f''_i(\mathbf{0})\mathbf{x}, \frac{1}{2}\mathbf{x}^T f''_j(\mathbf{0})\mathbf{x}\right) \\ &= \frac{1}{4}\left(\mathbb{E}[(\mathbf{x}^T f''_i(\mathbf{0})\mathbf{x})(\mathbf{x}^T f''_j(\mathbf{0})\mathbf{x})] \right. \\ &\quad \left. - \mathbb{E}[\mathbf{x}^T f''_i(\mathbf{0})\mathbf{x}] \mathbb{E}[\mathbf{x}^T f''_j(\mathbf{0})\mathbf{x}]\right). \end{aligned} \quad (10)$$

Using (6) and standard index gymnastics,

$$\begin{aligned} \mathbb{E}[(\mathbf{x}^T A \mathbf{x})(\mathbf{x}^T B \mathbf{x})] &= \sum_{a,b,c,d} A_{ab} B_{cd} \mathbb{E}[x_a x_b x_c x_d] \\ &= \frac{n}{n+2} \left( \text{tr}(A)\text{tr}(B) + 2 \text{tr}(AB) \right), \end{aligned} \quad (11)$$

for any  $A, B \in \mathbb{R}^{n \times n}$ . Also,

$$\mathbb{E}[\mathbf{x}^T A \mathbf{x}] = \text{tr}(A \mathbb{E}[\mathbf{x}\mathbf{x}^T]) = \text{tr}(A). \quad (12)$$

Applying these with  $A = f''_i(\mathbf{0})$ ,  $B = f''_j(\mathbf{0})$  gives

$$\begin{aligned} P_{com,ij}^{\text{EKF2, Sphere}} &= \frac{1}{4} \left( \frac{n}{n+2} \left( \text{tr}(f''_i(\mathbf{0})) \text{tr}(f''_j(\mathbf{0})) + 2 \text{tr}(f''_i(\mathbf{0})f''_j(\mathbf{0})) \right) \right. \\ &\quad \left. - \text{tr}(f''_i(\mathbf{0})) \text{tr}(f''_j(\mathbf{0})) \right) \\ &= \frac{1}{2(n+2)} \left( n \text{tr}(f''_i(\mathbf{0})f''_j(\mathbf{0})) - \text{tr}(f''_i(\mathbf{0}))\text{tr}(f''_j(\mathbf{0})) \right) \\ &= \frac{n}{2(n+2)} \left( \text{tr}(f''_i(\mathbf{0})f''_j(\mathbf{0})) - \frac{1}{n}\text{tr}(f''_i(\mathbf{0}))\text{tr}(f''_j(\mathbf{0})) \right). \end{aligned} \quad (13)$$

This proves the stated formula (5). The rest is to prove that (5) is PSD. Define the “trace-centered” matrices

$$H_i := f''_i(\mathbf{0}) - \frac{\text{tr}(f''_i(\mathbf{0}))}{n} I_n. \quad (14)$$

Then

$$\text{tr}(H_i H_j) = \text{tr}(f''_i(\mathbf{0})f''_j(\mathbf{0})) - \frac{1}{n} \text{tr}(f''_i(\mathbf{0}))\text{tr}(f''_j(\mathbf{0})). \quad (15)$$

Hence the  $m \times m$  matrix with  $(i, j)$  entry inside the bracket of (5) is the Gram matrix  $G = [\langle H_i, H_j \rangle_F]_{ij}$  under the Frobenius inner product, so (5) is PSD.  $\square$

### III. PROOFS OF THE THEOREMS

**Theorem 1.** *With the conditions in (1), and when the nonlinear mapping  $f$  is real analytic at the origin, we have  $P_{com}^{CKF} \succeq 0$ .*

*Proof.* Consider the Taylor expansion of the nonlinear mapping  $f(\mathbf{a})$  at the origin as a sum of homogeneous parts. For any  $\mathbf{a}$  in the domain of  $\mathbf{x}$ , we have:

$$f(\mathbf{a}) = \sum_{k=0}^{\infty} f^{(k)}(\mathbf{a}), \quad (16)$$

where  $f^{(k)}$  represents homogeneous of degree  $k$ . Specifically,  $f^{(0)}(\mathbf{a}) = f(\mathbf{0})$ ,  $f^{(1)}(\mathbf{a}) = f'(\mathbf{0})\mathbf{a}$ . Split  $f(\mathbf{a})$  into odd and even components:

$$f_{\text{odd}}(\mathbf{a}) = \sum_{j \geq 0} f^{(2j+1)}(\mathbf{a}), f_{\text{even}}(\mathbf{a}) = \sum_{j \geq 1} f^{(2j)}(\mathbf{a}). \quad (17)$$

Recall the equation for  $\bar{\mathbf{z}}^{\text{CKF}}$  in (3). Because the point set is symmetric, all odd contributions vanish, and only even parts remain in the mean. Therefore, we can define the centered residuals for an arbitrary sigma point  $\xi_r^{\text{CKF}}$  (also simply written as  $\xi_r$  in this proof) by:

$$\delta f(\xi_r) = f(\xi_r) - \bar{\mathbf{z}}^{\text{CKF}} = f_{\text{odd}}(\xi_r) + (f_{\text{even}}(\xi_r) - \sum_{i=1}^{2n} \frac{f_{\text{even}}(\xi_i)}{2n}). \quad (18)$$

By symmetry, cross terms between odd and even parts vanish in the weighted sum. Hence

$$P_z^{\text{CKF}} = \sum_r w_r \delta f(\xi_r) \delta f(\xi_r)^T = P_{\text{odd}} + \Sigma_{\text{even}}, \quad (19)$$

where both summands are PSD, and  $\Sigma_{\text{even}}$  is defined as:

$$\Sigma_{\text{even}} = (f_{\text{even}}(\xi_r) - \sum_{i=1}^{2n} \frac{f_{\text{even}}(\xi_i)}{2n})(\cdot)^T. \quad (20)$$

Now expand the odd part:

$$f_{\text{odd}}(\mathbf{a}) = f'(\mathbf{0})\mathbf{a} + \sum_{j \geq 1} f^{(2j+1)}(\mathbf{a}). \quad (21)$$

Since the cross terms vanish by central symmetry and the covariance of the sigma points is the identity matrix, we have:

$$P_{\text{odd}} = f'(\mathbf{0})f'(\mathbf{0})^T + \sum_{j, \ell \geq 1} \sum_{r=1}^{2n} \frac{f^{(2j+1)}(\xi_r) f^{(2\ell+1)}(\xi_r)^T}{2n}. \quad (22)$$

Notice that the first part of  $P_{\text{odd}}$  is equal to  $P_z^{\text{EKF}}$ , and the second part can be denoted as a PSD matrix,  $\Sigma_{\text{odd}, \geq 3}$ . Therefore,

$$P_{com}^{\text{CKF}} = \underbrace{\Sigma_{\text{odd}, \geq 3}}_{\succeq 0} + \underbrace{\Sigma_{\text{even}}}_{\succeq 0} \succeq 0. \quad (23)$$

□

**Theorem 2.** *Consider the conditions in (1), and further assume that  $\mathbf{x}$  follows a radially symmetric distribution, i.e., its probability density depends only on  $\|\mathbf{x}\|_2^2$ . Let  $f: \mathbb{R}^n \rightarrow$*

$\mathbb{R}^m$  be a vector of quadratic functions of the form

$$\mathbf{z} = f(\mathbf{x}) = \mathbf{c} + f'(\mathbf{0})\mathbf{x} + \frac{1}{2}[\mathbf{x}^T f''(\mathbf{0})\mathbf{x}]_i. \quad (24)$$

Then the following equations hold:

$$\begin{cases} \bar{\mathbf{z}} = f(\mathbf{0}) + \frac{1}{2}[\text{tr}(f''(\mathbf{0}))]_i \\ P_z \succeq f'(\mathbf{0})(f'(\mathbf{0}))^T + P_{com}^{\text{EKF2, Sphere}} \\ P_{xz} = (f'(\mathbf{0}))^T \end{cases}. \quad (25)$$

*Proof.* The two equalities in (25) have appeared in (2), and have been proved in [1]. Therefore, we only need to prove the inequality. Decompose

$$\mathbf{z} = f'(\mathbf{0})\mathbf{x} + \mathbf{q}(\mathbf{x}), \quad \mathbf{q}(\mathbf{x}) = \frac{1}{2}[\mathbf{x}^T f''(\mathbf{0})\mathbf{x}]_i + \mathbf{c}. \quad (26)$$

Since the cross term  $\mathbb{E}[(f'(\mathbf{0})\mathbf{x})(\mathbf{q}(\mathbf{x}) - \mathbb{E}[\mathbf{q}(\mathbf{x})])^T] = 0$  by oddness, we have

$$P_z = f'(\mathbf{0})(f'(\mathbf{0}))^T + \text{Cov}(\mathbf{q}(\mathbf{x})). \quad (27)$$

Consider the radial representation  $\mathbf{x} = R\mathbf{u}$ , where  $R$  is defined by  $\sqrt{\mathbf{x}^T \mathbf{x}}$ , and  $\mathbf{u}$  is uniformly distributed on the unit sphere  $\mathbb{S}^{n-1} := \{\mathbf{v} \in \mathbb{R}^n : \mathbf{v}^T \mathbf{v} = 1\}$ . Since  $\mathbf{x}$  follows a radially symmetric distribution,  $R$  and  $\mathbf{u}$  are independent. Therefore,  $\mathbb{E}[R^2] = n$ , and

$$\text{Cov}(\mathbf{q}(\mathbf{x})) = \mathbb{E}[R^4] \text{Cov}(\mathbf{q}(\mathbf{v})) \succeq n^2 \text{Cov}(\mathbf{q}(\mathbf{v})). \quad (28)$$

From (5), we already know that

$$\text{Cov}(\mathbf{q}(\mathbf{v})) = \frac{[\text{tr}(f''_i(\mathbf{0})f''_j(\mathbf{0})) - \frac{1}{n}\text{tr}(f''_i(\mathbf{0}))\text{tr}(f''_j(\mathbf{0}))]_{ij}}{2n(n+2)}. \quad (29)$$

Therefore

$$P_z \succeq f'(\mathbf{0})(f'(\mathbf{0}))^T + P_{com}^{\text{EKF2, Sphere}}, \quad (30)$$

establishing the second line of (25). Equality holds when  $\|\mathbf{x}\|^2 = n$  almost surely. □

**Theorem 3.** (i) *In case 1, the global minimizer  $\beta^*$  of (4) exists (finite if  $\bar{P} \neq 0$ , and infinite otherwise) and satisfies  $\beta^* \geq \beta_0$ . Additionally, when  $\|\bar{P}\|_F^2 \geq 0$ ,  $\min f$  and  $\beta^*$  both increase monotonically as  $\mathbb{E}[\|\Delta P\|_F^2]$  increases. (ii) In case 2, the global minimizer  $\beta^*$  of (4) exists (possibly infinite) and satisfies  $\beta^* \geq \beta_0$ .*

*Proof. Case 1.* Let  $\mathbf{P}$  be a random matrix with mean  $\bar{P} = \mathbb{E}[\mathbf{P}]$ . Define

$$f(\beta) := \mathbb{E} \left[ \text{tr} \left( \left( \frac{\mathbf{P}}{1+\beta-\beta_0} - \bar{P} \right) \left( \frac{\mathbf{P}}{1+\beta-\beta_0} - \bar{P} \right)^T \right) \right]. \quad (31)$$

Note that in case 1, we have  $\mathbb{E}[\text{tr}(\mathbf{P}_{k|k,ac})] = f(\beta) + \text{tr}(\mathbf{P}_{k|k-1} - \bar{P}\bar{P}^T)$ . Therefore, the minimizer of  $f$  is also the solution to (4) in Case 1. We only need to prove that the global minimizer  $\beta^*$  of  $f$  exists (finite if  $\bar{P} \neq 0$ , and infinite otherwise) and satisfies  $\beta^* \geq \beta_0$ . Specifically, when  $H := \|\bar{P}\|_F^2 > 0$ , we want to prove that:

$$\beta^* = \beta_0 + \frac{\sigma^2}{H}, \quad \min f = \frac{\sigma^2 H}{\sigma^2 + H}, \quad (32)$$

where  $\sigma^2 := \mathbb{E}[\|\Delta P\|_F^2] \geq 0$  and  $\Delta P := \mathbf{P} - \bar{P}$ .

To prove (32), write  $b := \beta - \beta_0$ . Then

$$\frac{\bar{P}}{1 + \beta - \beta_0} - \bar{P} = \frac{\bar{P}}{1 + b} - \bar{P} = \frac{\Delta P - b\bar{P}}{1 + b}. \quad (33)$$

Therefore,

$$\begin{aligned} f(b) &= \mathbb{E} \left[ \left\| \frac{\Delta P - b\bar{P}}{1 + b} \right\|_F^2 \right] \\ &= \frac{1}{(1 + b)^2} \mathbb{E} [\|\Delta P\|_F^2 - 2b\langle \Delta P, \bar{P} \rangle_F + b^2\|\bar{P}\|_F^2]. \end{aligned} \quad (34)$$

Since  $\mathbb{E}[\langle \Delta P, \bar{P} \rangle_F] = 0$ ,

$$f(b) = \frac{\sigma^2 + b^2 H}{(1 + b)^2}, \quad b \neq -1. \quad (35)$$

First, assume that  $H > 0$ . Take the derivative of  $f(b)$ :

$$f'(b) = \frac{2(bH - \sigma^2)}{(1 + b)^3}. \quad (36)$$

Thus the unique stationary point is at  $b^* = \sigma^2/H$ , which lies in  $(-1, \infty)$ . Equation (32) can be derived by substituting  $b^*$  into the cost function. Note that this critical point is the unique global minimizer because  $f(b) \rightarrow +\infty$  when  $b \rightarrow -1^\pm$ , and  $f(b) \rightarrow H > f(b^*)$  as  $b \rightarrow \pm\infty$ .

Then, consider the situation where  $H = 0$ . In this case,  $\bar{P} = 0$  and  $f(b)$  is strictly decreasing for  $b > -1$  and tends to 0 as  $b \rightarrow +\infty$ . Thus, the infimum 0 is achieved only in the limit  $b^* \rightarrow +\infty$ , which is again consistent with  $b^* \geq 0$ . Therefore, in all cases, a global minimizer exists (possibly at infinity) and satisfies  $\beta^* \geq \beta_0$ .

**Case 2.** Let  $c := (1 + \beta - \beta_0)^{-1} > 0$ . Define

$$f(c) := c^2 \text{tr}(\bar{P} \mathbb{E}[\Delta S^{-2}] \bar{P}^T) - 2c \text{tr}(\bar{P} \mathbb{E}[\Delta S^{-1}] \bar{P}^T). \quad (37)$$

Note that in case 2, we have  $\mathbb{E}[\text{tr}(P_{k|k,ac})] = f(c) + \text{tr}(P_{k|k-1})$ . Therefore, the minimizer of  $f$  is also the solution to (4) in Case 2. Note that (37) is a convex quadratic in  $c > 0$ . The unique minimizer  $c^*$  is:

$$c^* = \frac{\text{tr}(\bar{P} \mathbb{E}[\Delta S^{-1}] \bar{P}^T)}{\text{tr}(\bar{P} \mathbb{E}[\Delta S^{-2}] \bar{P}^T)}. \quad (38)$$

Since  $X \mapsto X^{-1}$  is operator convex on the cone of positive-definite matrices, Jensen's inequality yields

$$\mathbb{E}[\Delta S^{-1}] \succeq (\mathbb{E}[\Delta S])^{-1} = I. \quad (39)$$

Therefore,

$$\mathbb{E}[\Delta S^{-2}] \succeq (\mathbb{E}[\Delta S^{-1}])^2 \succeq \mathbb{E}[\Delta S^{-1}] \quad (40)$$

Hence  $c^* \leq 1$ . Therefore,

$$\beta^* = \frac{1}{c^*} - 1 + \beta_0 \geq \beta_0. \quad (41)$$

□

## REFERENCES

- [1] A. Gelb, *Applied Optimal Estimation*. MIT Press, 1974.
- [2] E. S. Meckes, *The random matrix theory of the classical compact groups*. Cambridge University Press, 2019, vol. 218.