

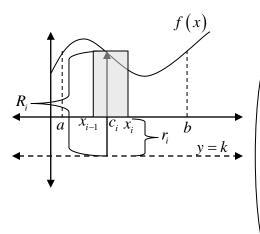
$$V_{\text{slice}} = \pi \left(f\left(c_{i}\right) \right)^{2} \left(\Delta x\right)_{i}$$

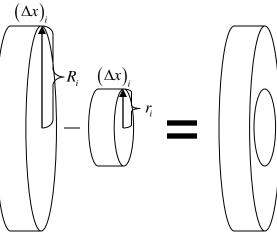
$$V_{\text{solid}} \approx \sum_{i=1}^{n} \pi \left(f\left(c_{i}\right) \right)^{2} \left(\Delta x\right)_{i}$$

$$= \lim_{\|\Delta\| \to 0} \sum_{i=1}^{n} \pi \left(f\left(c_{i}\right) \right)^{2} \left(\Delta x\right)_{i}$$

$$= \int_{a}^{b} \pi \left[f\left(x\right) \right]^{2} dx$$

$$= \pi \int_{a}^{b} \left[f\left(x\right) \right]^{2} dx$$





$$V = \pi \left(R_i\right)^2 \left(\Delta x\right)_i \qquad V = \pi \left(r_i\right)^2 \left(\Delta x\right)_i \qquad V = \pi \left(R_i\right)^2 \left(\Delta x\right)_i - \pi \left(r_i\right)^2 \left(\Delta x\right)_i$$
$$= \pi \left(f(x) - k\right)^2 \left(\Delta x\right)_i \qquad = \pi \left(0 - k\right)^2 \left(\Delta x\right)_i \qquad = \pi \left(f(x) - k\right)^2 \left(\Delta x\right)_i - \pi \left(0 - k\right)^2 \left(\Delta x\right)_i$$

$$V_{\text{slice}} = \pi (R_i)^2 (\Delta x)_i - \pi (r_i)^2 (\Delta x)_i$$
$$= \pi (f(x) - k)^2 (\Delta x)_i - \pi (0 - k)^2 (\Delta x)_i$$
$$\downarrow$$

$$V_{\text{solid}} \approx \sum_{i=1}^{n} \pi (f(x) - k)^{2} (\Delta x)_{i} - \pi (0 - k)^{2} (\Delta x)_{i}$$

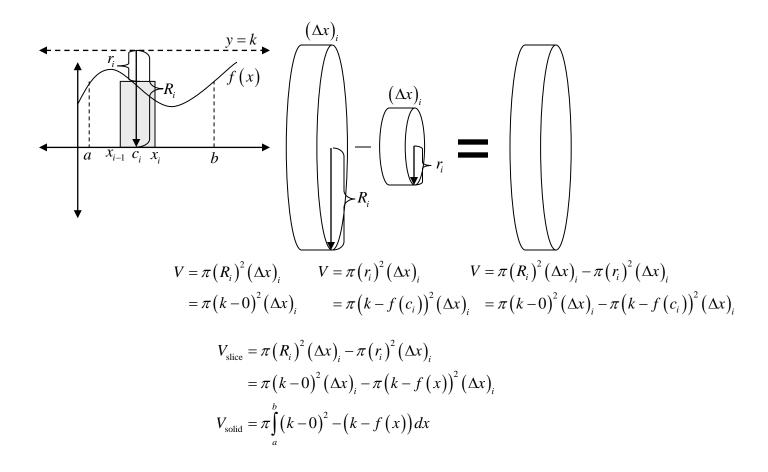
$$= \lim_{\|\Delta\| \to 0} \sum_{i=1}^{n} \pi (f(x) - k)^{2} (\Delta x)_{i} - \pi (0 - k)^{2} (\Delta x)_{i}$$

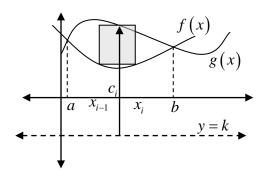
$$= \lim_{\|\Delta\| \to 0} \pi \sum_{i=1}^{n} (f(x) - k)^{2} (\Delta x)_{i} - (0 - k)^{2} (\Delta x)_{i}$$

$$= \lim_{\|\Delta\| \to 0} \pi \sum_{i=1}^{n} (f(x) - k)^{2} - (0 - k)^{2} (\Delta x)_{i}$$

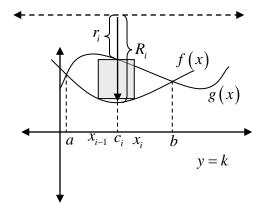
$$= \pi \int_{a}^{b} (f(x) - k)^{2} - (0 - k)^{2} dx$$

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$$V_{\text{slice}} = \pi (R_i)^2 (\Delta x)_i - \pi (r_i)^2 (\Delta x)_i$$
$$= \pi (g(c_i) - k)^2 (\Delta x)_i - \pi (f(c_i) - k)^2 (\Delta x)_i$$
$$V_{\text{solid}} = \pi \int_a^b (g(x) - k)^2 - (f(x) - k)^2 dx$$



$$V_{\text{slice}} = \pi (R_i)^2 (\Delta x)_i - \pi (r_i)^2 (\Delta x)_i$$

$$= \pi (f(c_i) - k)^2 (\Delta x)_i - \pi (g(c_i) - k)^2 (\Delta x)_i$$

$$V_{\text{solid}} = \pi \int_a^b (f(x) - k)^2 - (g(x) - k)^2 dx$$

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