



**Ahsanullah University of Science and Technology (AUST)**  
Department of Computer Science and Engineering

**Assignment 2**

Course No: CSE4108

Course Title: Artificial Intelligence Lab

**Date of Submission:-**

30/05/2023

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Year- 4<sup>th</sup>

Semester-1<sup>st</sup>

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**Question:** Define a recursive procedure in Python and in Prolog to find the length of a path between two vertices of a directed weighted graph.

**Solution:**

**Python Code:**

```
def find_path_length(graph, start, end, acc_distance=0):

    if start == end: return

        acc_distance

    if not graph[start]:

        return float('inf')

    min_distance = float('inf') for

    neighbor, weight in graph[start]:

        length = find_path_length(graph, neighbor, end, acc_distance + weight)

        min_distance = min(min_distance, length)

    return min_distance

graph = {

    'i': [('a', 35), ('b', 45)],

    'a': [('c', 22), ('d', 32)],

    'b': [('d', 28), ('e', 36), ('f', 27)],

    'c': [('d', 31), ('g', 47)],

    'd': [('g', 30)],

    'e': [('g', 26)],

    'g': []

}
```

```
path_length = find_path_length(graph, 'a', 'g')
```

```
print("Length of the path between 'a' and 'g':", path_length)
```

**Prologue:**

```
neighbor(i,a,35).
```

```
neighbor(i,b,45).
```

```
neighbor(a,c,22).
```

```
neighbor(a,d,32).
```

```
neighbor(b,d,28).
```

```
neighbor(b,e,36).
```

```
neighbor(b,f,27).
```

```
neighbor(c,d,31).
```

```
neighbor(c,g,47).
```

```
neighbor(d,g,30).
```

```
neighbor(e,g,26).
```

```
pathLength(X,Y,L):- neighbor(X,Y,L),!. pathLength(X,Y,L):-
```

```
neighbor(X,Z,L1), pathLength(Z,Y,L2), L is L1+L2.
```

```
findPathLength :- write('Source: '), read(Src),
```

```
write('Destination: '), read(Des),
```

```
pathLength(Src, Des, Length), write('Length of
```

```
the path: '), write(Length), nl.
```

```
findPathLength.
```

**Question:** Modify the Python and Prolog codes demonstrated above to find  $h_2$  and  $h_3$  discussed above

## Python Code for H2: # Goal

configuration

goal\_config = {

1: (1, 1, 1),

2: (2, 1, 2),

3: (3, 1, 3),

4: (4, 2, 3),

5: (5, 3, 3),

6: (6, 3, 2),

7: (7, 3, 1),

8: (8, 2, 1)

}

goal\_blank = (2, 2)

# Target configuration

target\_config = {

1: (1, 1, 2),

2: (2, 1, 3),

3: (3, 2, 1),

4: (4, 2, 3),

5: (5, 3, 3),

6: (6, 2, 2),

7: (7, 3, 2),

8: (8, 1, 1)

}

target\_blank = (3, 1)

```
# Function to calculate the Manhattan distance between two cells
```

```
def manhattan_distance(cell1, cell2):
```

```
    x1, y1 = cell1[1:] x2, y2 =
```

```
    cell2[1:] return abs(x1 - x2) +
```

```
    abs(y1 - y2)
```

```
# Function to calculate the heuristic values
```

```
def calculate_heuristics(): heuristics = []
```

```
for tile in range(1, 9):
```

```
    tile_goal = goal_config[tile] tile_target =
```

```
    target_config[tile] distance =
```

```
    manhattan_distance(tile_goal, tile_target)
```

```
    heuristics.append(distance) return heuristics
```

```
# Calculate heuristics for each tile
```

```
heuristics = calculate_heuristics()
```

```
# Calculate the sum of heuristics
```

```
total_heuristic = sum(heuristics)
```

```
# Output
```

```
print("Heuristics:", total_heuristic)
```

### **Python Code for H3:**

```
graph={
```

```
    'Q1':[(6,1)],
```

```
    'Q2':[(1,2)],
```

```
    'Q3':[(5,3)],
```

```
'Q4':[(7,4)],  
'Q5':[(4,5)],  
'Q6':[(3,6)],  
'Q7':[(8,7)],  
'Q8':[(1,8)]  
}  
queens=['Q1','Q2','Q3','Q4','Q5','Q6','Q7','Q8']
```

```
def cheack(row,column):
```

```
    for queen in queens:
```

```
        for xrow,xcolumn in graph[queen]:
```

```
            if(row==xrow and column==xcolumn):
```

```
                return 1;
```

```
    return 0;
```

```
def attacking_queen():
```

```
    cnt =0; for j in
```

```
    range(8):
```

```
        for row,column in graph[queens[j]]:
```

```
            new_row=row
```

```
            new_col=column # In a same
```

```
            row
```

```
            for i in range(8):
```

```

        new_col=new_col+1;

        if(new_row<=8):
            cnt=cnt+cheack(new_row,new_col)

new_row=row new_col=column
#Diagonally up for i in range(8):
new_row=new_row+1;
new_col=new_col+1; if
new_row<=8 and new_col<=8:
    cnt=cnt+cheack(new_row,new_col)
#Diagonally Down new_row=row
new_col=column for i in range(8):
new_row=new_row-1;
new_col=new_col+1; if new_row>=1
and new_col>=1:
    cnt=cnt+cheack(new_row,new_col)
#print(queens[j], " ",cnt);

return cnt;

```

```
print("Attacking pairs: ",attacking_queen())
```

### **Prologue Code for H3:**

```

:-dynamic(hval/1).

/* Evaluates a 8-queens' state given as list of 8 digits */

evalState(L,V):- assert(hval(0)),hl(1,L),
di_up(1,L),di_dn(1,L),hval(V),
                retractall(hval(_)).

hl(8,_):-!. hl(I,L):- nthel(I,L,X), chk_incr(I,L,X), I1 is I+1,
hl(I1,L).

```

```

chk_incr(8,_,_):-!. chk_incr(I,L,X):- I1 is I+1, nthel(I1,L,Y),
                                     do_incr(X,Y),chk_incr(I1,L,X).
do_incr(X,Y):- X=Y, incr_hval. do_incr(,_,_). incr_hval:-hval(V),
V1 is V+1, retract(hval(_)), assert(hval(V1)).

di_up(8,_,_):-!. di_up(I,L):- nthel(I,L,X), chkup_incr(I,L,X,0), I1 is
I+1, di_up(I1,L).
chkup_incr(8,_,_,_):-!.
chkup_incr(I,L,X,K):- I1 is I+1, nthel(I1,L,Y), K1 is K+1,
                    doup_incr(X,Y,K1), chkup_incr(I1,L,X,K1).

doup_incr(X,Y,K1):- X1 is X+K1, Y=X1, incr_hval. doup_incr(,_,_,_).

di_dn(8,_,_):-!. di_dn(I,L):- nthel(I,L,X), chkdn_incr(I,L,X,0), I1 is
I+1, di_dn(I1,L).

chkdn_incr(8,_,_,_):-!.
chkdn_incr(I,L,X,K):- I1 is I+1, nthel(I1,L,Y), K1 is K+1,
                    dodn_incr(X,Y,K1), chkdn_incr(I1,L,X,K1).
dodn_incr(X,Y,K1):- X1 is X-K1, Y=X1, incr_hval. dodn_incr(,_,_,_).

% A procedure to find the nth element of a list

nthel(N,[_|T],E1):- N1 is N-1, nthel(N1,T,E1).
nthel(1,[H|_],H):-!.

```

### **Prologue Code for H2:**

/\*Goal configaretion\*/

gtp(1,1,1). gtp(2,1,2).

gtp(3,1,3). gtp(4,2,3).

gtp(5,3,3). gtp(6,3,2).

gtp(7,3,1). gtp(8,2,1).

gblnk(2,2). /\*Target

configaretion\*/

tp(1,1,2).

tp(2,1,3).

tp(3,2,1).

tp(4,2,3).



tp(5,3,3).

tp(6,2,2).

tp(7,3,2).

tp(8,1,1).

blnk(3,1).

go:- calcH(1,[],L), sumList(L,V),write('Heuristics: '),write(V).

calcH(9,X,X):-!. calcH(T,X,Y):- dist(T,D), append(X,[D],X1), T1 is T+1,  
calcH(T1,X1,Y). dist(T,V):-tp(T,A,B), gtp(T,C,D), V is abs(A-C) + abs(B-  
D).

sumList([],0):-!. sumList(L,V):-L=[H|T],

sumList(T,V1), V is V1+H.