

Capstone Project on Pneumonia Detection

INTERIM REPORT

Participants

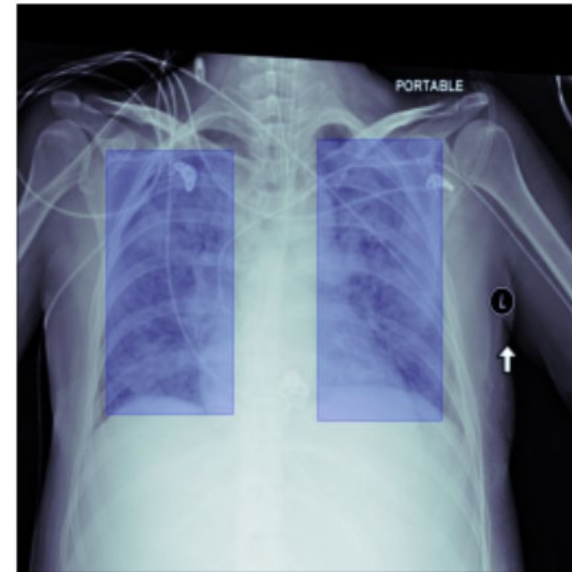
- Mrs Shilpa Kulkarni
- Mr Jignesh Mistry
- Mr Samit Biswas
- Mr Aarish Shahab

Pneumonia and Diagnosis

- ▶ Pneumonia is an infection of the lungs caused by bacteria, viruses and fungi. Pneumonia causes inflammation in the air sacs of one or both lungs which fill with fluid or pus, making it difficult to breathe and may result in fatality.
- ▶ World Health Organization (WHO) estimates, approximately 150 million lung infections and 4 million deaths can be attributed annually to Pneumonia. Small children and seniors are more susceptible to this infection. Fast, timely and accurate diagnosis is of utmost importance.
- ▶ Chest X-Ray (CXR) analysis is the first step in the diagnosis of Pneumonia.

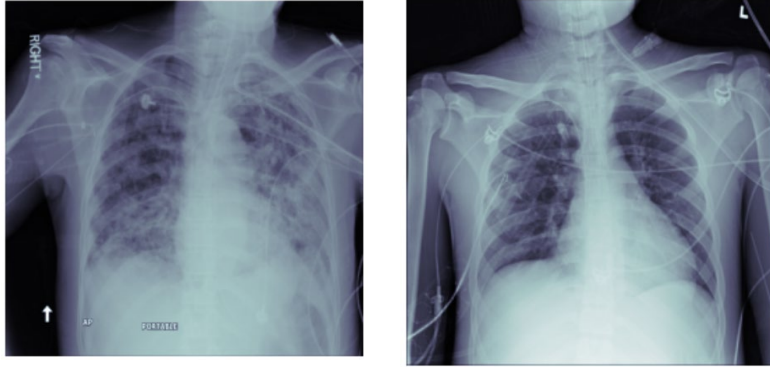
Problem Statement:

- ▶ The goal of this project is to build a model which detects if a given patient's CXR image indicates the presence of Pneumonia or not and also predicts the location of the Pneumonic patch. Both, accuracy and speed of detection are of utmost importance.
- ▶ To achieve these, we performed object (opacity) detection using a Neural Network(NN) with labelled samples of Chest X-Ray(CXR) images.



Data:

- ▶ Train and Test Images - The CXR images are present in the Digital Imaging and Communications in Medicine (DICOM) format, with .dcm file extension. They are separated into training and test sets



- ▶ Patients by class - A .csv file which has information about the class detected per patient is provided

	patientId	class
19529	b5234584-1487-492c-8742-444b9ca41c3d	Normal
807	0a8ccb49-debc-4e9a-b5dc-eefc3fe909ca	No Lung Opacity / Not Normal
1733	1851dff6-31ec-4453-9ddc-95c0aedace5b	Lung Opacity

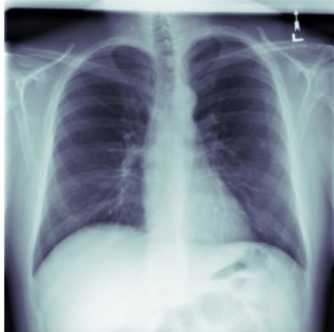
- ▶ Training labels - A .csv file with co-ordinates for each bounding box per patient is provided.

	patientId	x	y	width	height	Target
2508	3251dea8-4f74-4f4b-8f56-167b0213414b	140.0	583.0	188.0	114.0	1
2283	2feb2bad-6b36-4067-87f1-54d39235e3c5	247.0	503.0	163.0	155.0	1
24491	dc139a0e-0bbf-4ba4-8e71-c949022a542e	NaN	NaN	NaN	NaN	0

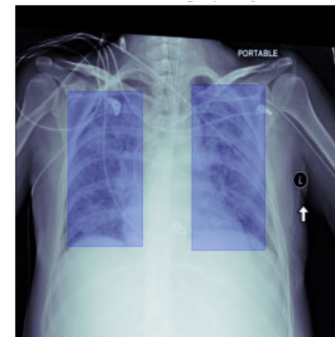
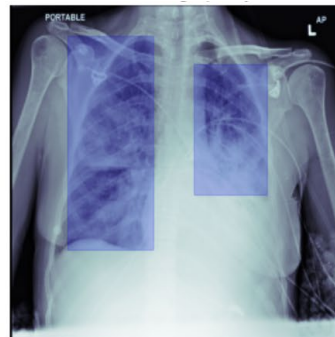
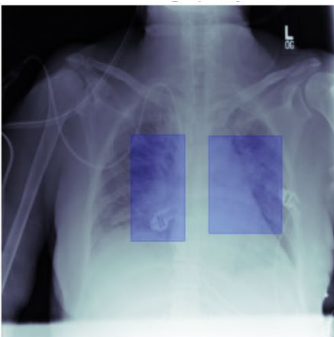
EDA, Pre-processing and findings

Approach to EDA:

- ▶ Row counts: There are same number of rows in both .csv files
 - ▶ There are multiple entries for some patients
- ▶ Target Values are 0 (Non-Pneumonic) and 1 (Pneumonic)
- ▶ 2 target values are mapped to 3 class values
 - ▶ Target 0 is mapped to “Normal” & “No Lung Opacity/Not Normal” classes

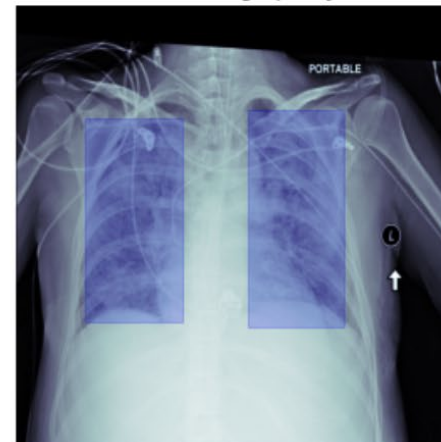
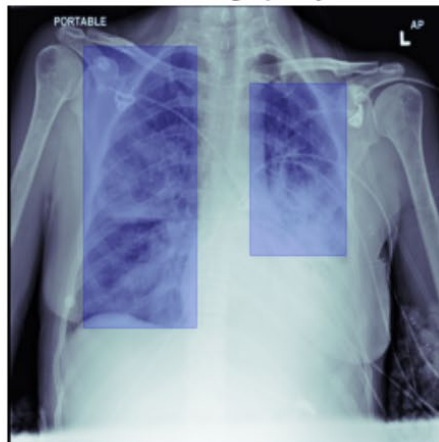
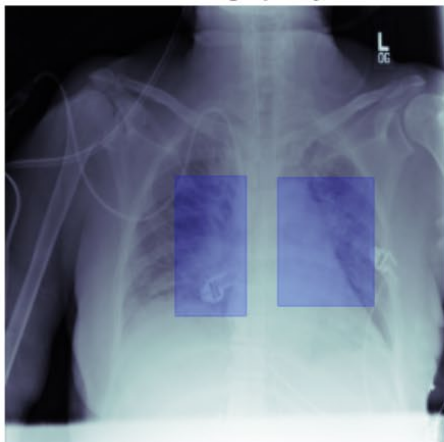
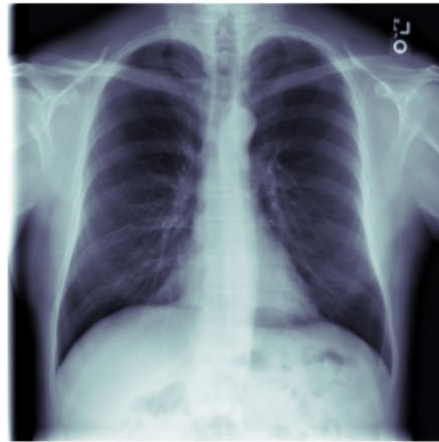


- ▶ Target 1 is mapped to “Lung Opacity” class



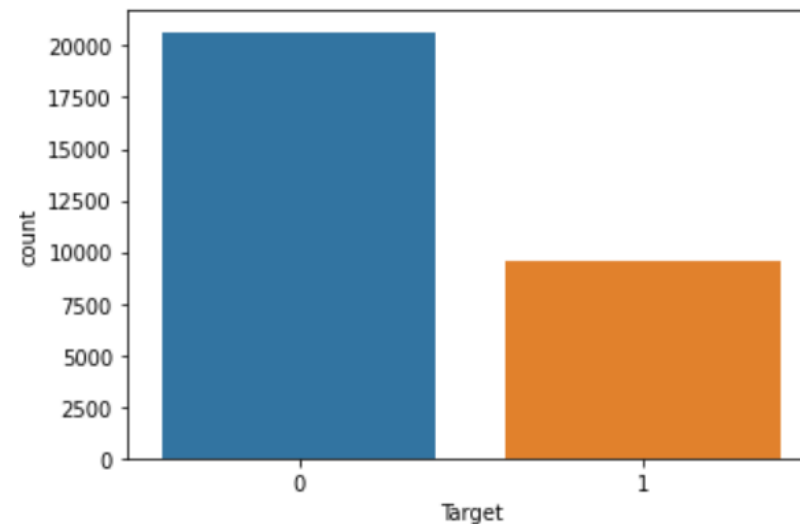
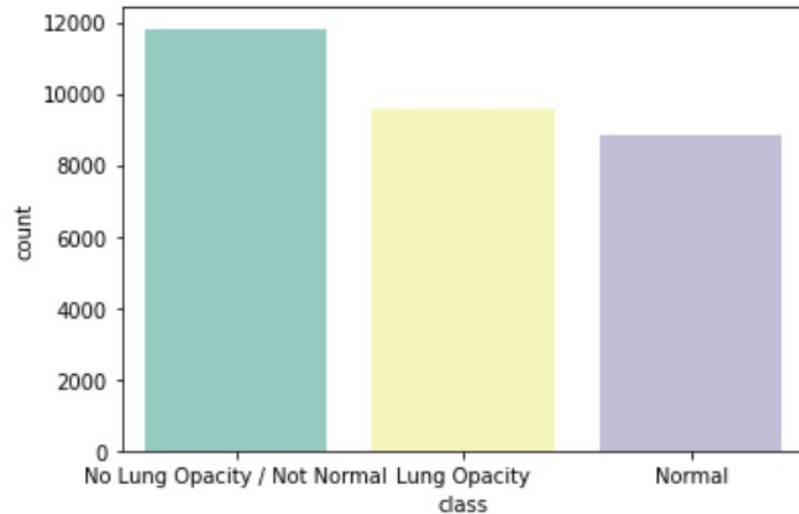
Approach to EDA:

- Used pydicom package to load the .dcm images from the training dataset and visualized samples positive as well as negative cases.



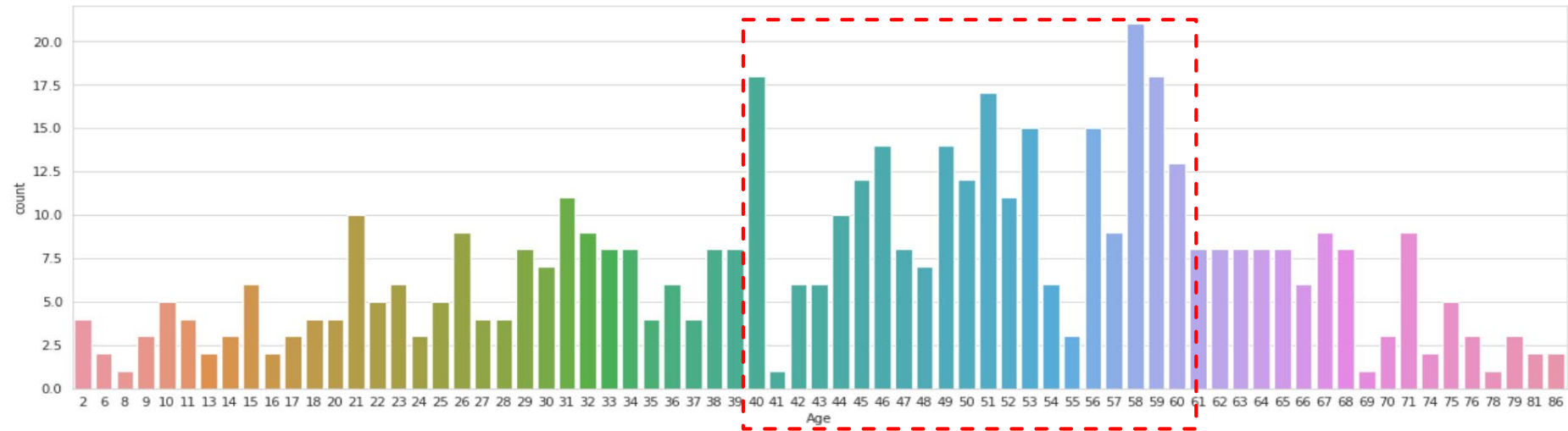
Approach to EDA:

- ▶ Missing Values:
 - ▶ Class Details - There are no missing values
- ▶ Training Labels:
 - ▶ 68.3% of the data is missing values in columns x, y, width and height where Target = 0 (non-Pneumonia)
 - ▶ For 31.3% of data, there are no missing values where Target = 1
- ▶ Check for Class imbalance
 - ▶ No noticeable difference between row counts for classes (Normal, No Lung Opacity/Not Normal, Lung Opacity)
 - ▶ Target=0 includes 2 classes, only 31%.

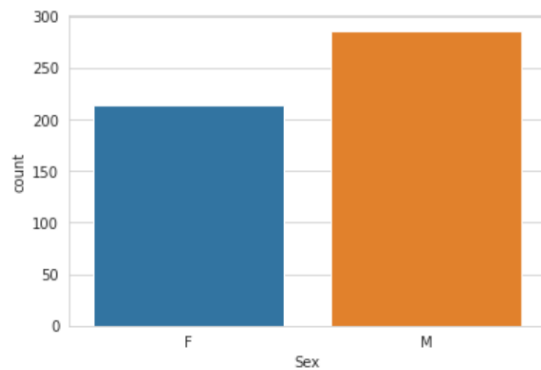


Approach to EDA:

- ▶ Maximum number of cases lies between 40 to 60 (for 500 random samples).
- ▶ Normally distributed.

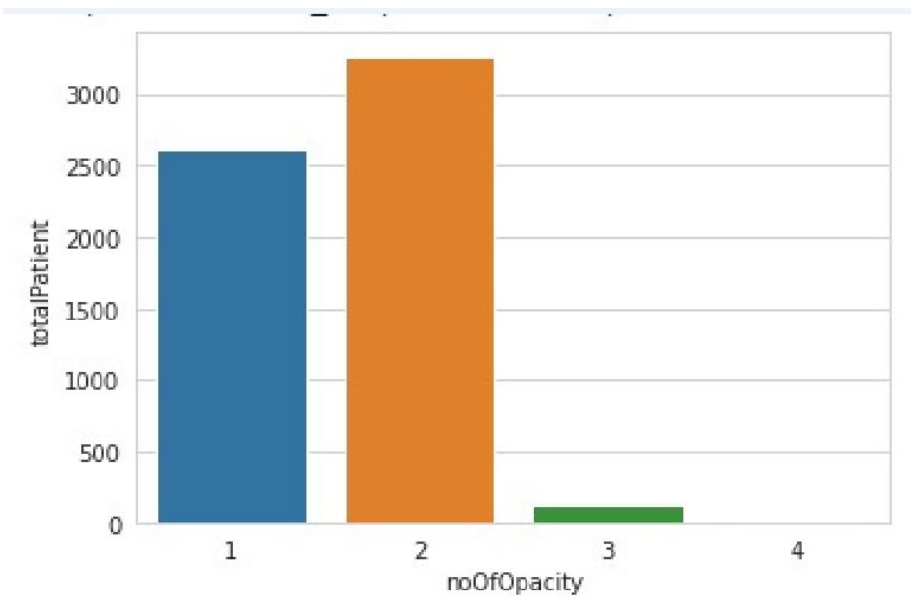


- ▶ Occurrence is more in male patients than female patients



Approach to EDA:

- Frequency of 2 bounding box (opacity) is higher

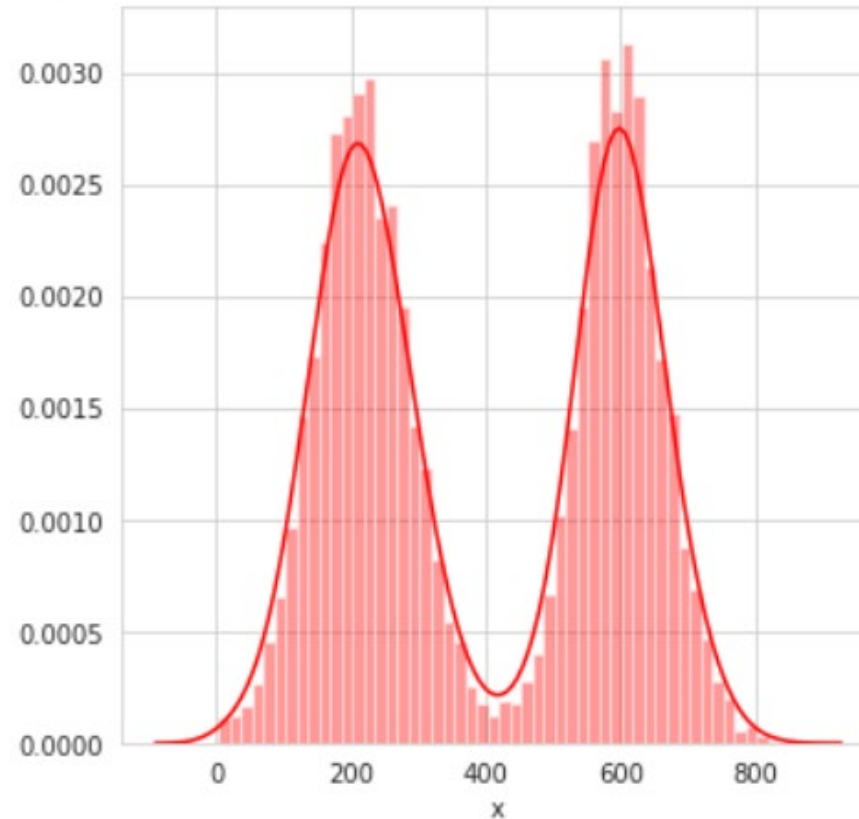
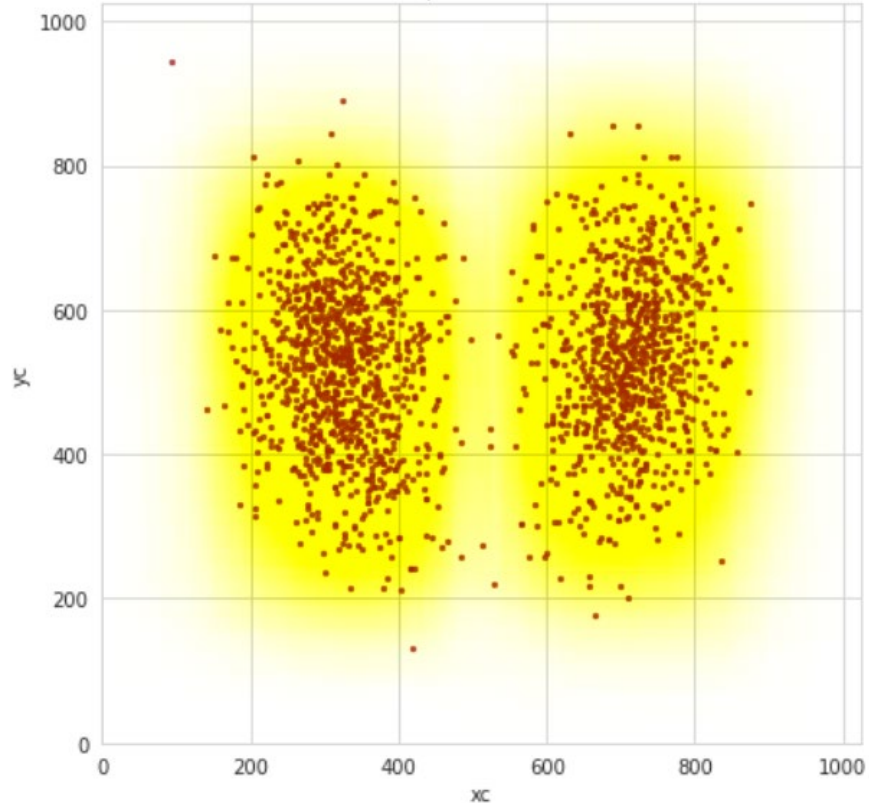


noOfOpacity		Target		Class	totalPatient
0	1	0	No Lung Opacity / Not Normal		11821
1	1	0	Normal		8851
2	1	1	Lung Opacity		2614
3	2	1	Lung Opacity		3266
4	3	1	Lung Opacity		119
5	4	1	Lung Opacity		13

Approach to EDA:

- Analyse the Lung Opacity Window
 - For 2000 samples of training data, plotted the centres of the bounding boxes (bbox) for lung opacities over the actual boxes.
 - Probability is pneumonic patch is more around the centre of both the lungs .

Centers of Lung Opacity rectangles (brown) over rectangles (yellow)
Sample size: 2000



Data Pre-processing

```
# Data Generator using Sequence for multiprocessing
from tensorflow.keras.utils import Sequence
class DataSequence(Sequence):
    def __init__(self, folder, filenames, pneumonia_locations=None, batch_size=BATCH_SIZE,
                 image_size=IMAGE_SIZE, shuffle=True, augment=False, predict=False):
        self.folder = folder
        self.filenames = filenames
        self.pneumonia_locations = pneumonia_locations
        self.batch_size = batch_size
        self.image_size = image_size
        self.shuffle = shuffle
        self.augment = augment
        self.predict = predict
        self.on_epoch_end()

    def __load__(self, filename):
        # Load DICOM file as numpy array
        img = pydicom.dcmread(self.folder + filename).pixel_array

        # Create empty mask
        mask = np.zeros(img.shape)
        filename = filename.split('.')[0] # Remove the file extension
        if filename in pneumonia_locations:
            for location in pneumonia_locations[filename]:
                x, y, width, height = location
                mask[x:x+width, y:y+height] = 1 # Broadcast value of 1 to all the pixels within

        # If augment flag is on, then flip the image and mask horizontally half the times
        if self.augment and random.random() > 0.5:
            img = np.fliplr(img)
            mask = np.fliplr(mask)

        # Resize both the image and mask
        img = resize(img, (self.image_size, self.image_size), mode='symmetric')
        mask = resize(mask, (self.image_size, self.image_size), mode='symmetric') > 0.5

        # Add the channel dimension to both the image and masks files
        img = np.expand_dims(img, -1)
        mask = np.expand_dims(mask, -1)
```

Data Pre-processing

```
def __load_predict__(self, filename):
    # Load DICOM file as numpy array
    img = pydicom.dcmread(self.folder + filename).pixel_array
    img = resize(img, (self.image_size, self.image_size), mode='symmetric')
    img = np.expand_dims(img, -1)
    return img

def __getitem__(self, idx):
    # select batch
    filenames = self.filenames[idx*self.batch_size : (idx + 1)*self.batch_size] # Image path

    if self.predict:
        # Load files for this batch
        imgs = [self.__loadpredict__(filename) for filename in filenames]
        imgs = np.array(imgs) # Create numpy arrays for batch images
        return imgs, filenames
    else:
        # Load files for this batch
        items = [self.__load__(filename) for filename in filenames]
        imgs, msk = zip(*items) # Output of __load__ is a tuple with imgs and masks, so uUnzip
        imgs = np.array(imgs) # Create numpy arrays for batch images
        msk = np.array(msk) # Create numpy arrays for batch masks
        return imgs, msk

def on_epoch_end(self):
    if self.shuffle:
        random.shuffle(self.filenames)

def __len__(self):
    if self.predict:
        return int(np.ceil(len(self.filenames) / self.batch_size))
    else:
        return int(len(self.filenames) / self.batch_size)
```

Models Used

- ▶ Model with Conv2D Layers
- ▶ Model with SeparableConv2D Layers
- ▶ Model with SeparableConv2D Layers additional layers
- ▶ Model with Resnet Blocks
- ▶ Model for Classification with SeparableConv2D Layers

Deciding Models and Model Building

► Model 1 with Conv2D Layers

```
# Model 1 with Conv2D Layers
model1 = Sequential()

# Add Convolution layers with 32 kernels of 3X3 shape with activation function ReLU
model1.add(Conv2D(4, (3, 3), input_shape = (IMAGE_SIZE, IMAGE_SIZE, 1), activation = 'relu', padding = 'same'))
model1.add(MaxPooling2D(pool_size = (2, 2))) # Max Pooling layer of size 2X2

model1.add(Conv2D(16, (2, 2), activation = 'relu', padding = 'same'))
model1.add(MaxPooling2D(pool_size = (2, 2)))
model1.add(BatchNormalization())

model1.add(Conv2D(64, (2, 2), activation = 'relu', padding = 'same'))
model1.add(BatchNormalization())
model1.add(MaxPooling2D(pool_size = (2, 2)))
model1.add(Dropout(0.4))

model1.add(Conv2D(128, (2, 2), activation = 'relu', padding = 'same'))
model1.add(MaxPooling2D(pool_size = (2, 2)))
model1.add(Dropout(0.3))

# 1 unit with Sigmoid activation for binary classification
model1.add(Conv2D(1, 1, activation='sigmoid'))

# UpSampling Layer to bring the image back to the input size
model1.add(UpSampling2D(16))

model1.summary()

model1.compile(optimizer='adam', loss='binary_crossentropy', metrics=['accuracy'])
```

Training accuracy : 97.34%
Validation accuracy : 97.55%

Deciding Models and Model Building

► Model 2 with SeperableConv2D Layers

```
# Model 2 with SeperableConv2D Layers
model2 = Sequential() # Create and instance of Sequential Model

model2.add(Conv2D(filters=16, kernel_size=(2,2), input_shape=(IMAGE_SIZE, IMAGE_SIZE, 1), activation='relu', padding='same'))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(SeperableConv2D(filters=32, kernel_size=(2,2), activation='relu', padding='same'))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(SeperableConv2D(filters=64, kernel_size=(2,2), activation='relu', padding='same'))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(SeperableConv2D(filters=128, kernel_size=(2,2), activation='relu', padding='same'))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(SeperableConv2D(filters=256, kernel_size=(2,2), activation='relu', padding='same'))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(SeperableConv2D(filters=256, kernel_size=(2,2), activation='relu', padding='same'))
model2.add(BatchNormalization(momentum=0.9))
model2.add(MaxPooling2D(pool_size = (2, 2)))

model2.add(Conv2D(1, 1, activation='sigmoid'))

model2.add(UpSampling2D())
model2.add(UpSampling2D())
model2.add(UpSampling2D())
model2.add(UpSampling2D())
model2.add(UpSampling2D())
model2.add(UpSampling2D())

model2.summary()

# Compile model
model2.compile(optimizer='adam', loss='binary_crossentropy', metrics=['accuracy'])
```

Training accuracy : 97.33%
Validation accuracy : 97.37%

Deciding Models and Model Building

► Model 3 with SeperableConv2D blocks with greater depth

```
# Model 3 with SeperableConv2D Layers
inputs = Input(shape=(IMAGE_SIZE, IMAGE_SIZE, 1))

# First conv block
x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(inputs)
x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Second conv block
x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Third conv block
x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Fourth conv block
x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)
x = Dropout(rate=0.2)(x)

# Fifth conv block
x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)
x = Dropout(rate=0.2)(x)

# Sigmoid activation for binary classification
x = Conv2D(filters=1, kernel_size=(2,2), activation='sigmoid', padding='same')(x)

output = UpSampling2D(32)(x)

# Creating model
model3 = Model(inputs=inputs, outputs=output)

model3.summary()
```

Training accuracy : 96.21%
Validation accuracy : 96.01%

Deciding Models and Model Building

► Model 4 with ResNet blocks

```
def create_downsample(channels, inputs):
    x = keras.layers.BatchNormalization(momentum=0.9)(inputs)
    x = keras.layers.LeakyReLU(0)(x)
    x = keras.layers.Conv2D(channels, 1, padding='same', use_bias=False)(x)
    x = keras.layers.MaxPool2D(2)(x)
    # Added start
    #x = keras.layers.Conv2D(channels, 1, padding='same', use_bias=False)(x)
    #x = keras.layers.MaxPool2D(2)(x)
    # Added End
    return x
```

```
def create_resblock(channels, inputs):
    x = keras.layers.BatchNormalization(momentum=0.9)(inputs)
    x = keras.layers.LeakyReLU(0)(x)
    x = keras.layers.Conv2D(channels, 3, padding='same', use_bias=False)(x)
    x = keras.layers.BatchNormalization(momentum=0.9)(x)
    x = keras.layers.LeakyReLU(0)(x)
    x = keras.layers.Conv2D(channels, 3, padding='same', use_bias=False)(x)

    #Added Start
    x = keras.layers.BatchNormalization(momentum=0.9)(x)
    x = keras.layers.LeakyReLU(0)(x)
    x = keras.layers.Conv2D(channels, 3, padding='same', use_bias=False)(x)
    #Added End

    addInput = x;
    print("Add input shape:", addInput.shape)
    print("Resnet block input shape:", inputs.shape)
    resBlockOut = keras.layers.add([addInput, inputs])
    print("Resnet block out shape:", resBlockOut.shape)
    out = keras.layers.concatenate([resBlockOut, addInput], axis=3)
    print("concat block out shape:", out.shape)
    out = keras.layers.Conv2D(channels, 1, padding='same', use_bias=False)(out)
    print("mixed block out shape:", out.shape)
    return out
```

Training accuracy : 96.57%
Validation accuracy : 95.48%

BCE + IOU as Loss

Mean IOU as Metric

```
# Define IOU or Jaccard Loss function
def iou_loss(y_true, y_pred):
    y_true = tf.reshape(y_true, [-1])
    y_pred = tf.reshape(y_pred, [-1])
    intersection = tf.reduce_sum(y_true * y_pred)
    score = (intersection + 1.) / (tf.reduce_sum(y_true) + tf.reduce_sum(y_pred) - intersection + 1.)
    return 1 - score

# Combine BCE Loss and IOU Loss
def iou_bce_loss(y_true, y_pred):
    return 0.5 * keras.losses.binary_crossentropy(y_true, y_pred) + 0.5 * iou_loss(y_true, y_pred)

# Mean IOU as a metric
def mean_iou(y_true, y_pred):
    y_pred = tf.round(y_pred)
    intersect = tf.reduce_sum(y_true * y_pred, axis=[1, 2, 3])
    union = tf.reduce_sum(y_true, axis=[1, 2, 3]) + tf.reduce_sum(y_pred, axis=[1, 2, 3])
    smooth = tf.ones(tf.shape(intersect))
    return tf.reduce_mean((intersect + smooth) / (union - intersect + smooth))
```

Model Training

```
[ ] # Define Callbacks
checkpoint = ModelCheckpoint(filepath='best_weights.hdf5', save_best_only=True, save_weights_only=True)
lr_reduce = ReduceLROnPlateau(monitor='val_loss', factor=0.3, patience=1, verbose=2, mode='max')
early_stop = EarlyStopping(monitor='val_loss', min_delta=0.1, patience=1, mode='min')
```

```
[ ] # Generate training and validation datasets
folder = 'stage_2_train_images/'
train_gen = DataSequence(folder, train_filenames, pneumonia_locations, batch_size=BATCH_SIZE, image_size=IMAGE_SIZE, shuffle=False, augment=True, predict=False)
valid_gen = DataSequence(folder, valid_filenames, pneumonia_locations, batch_size=BATCH_SIZE, image_size=IMAGE_SIZE, shuffle=False, predict=False)
```

```
[ ] # Model1
history1 = model1.fit_generator(train_gen, validation_data=valid_gen, callbacks=[lr_reduce], epochs=2, shuffle=True, verbose=1)
```

```
Epoch 1/2
30/755 [>.....] - ETA: 3:54:07 - loss: 0.5515 - accuracy: 0.9611 - mean_iou: 0.6355/usr/local/lib/python3.6/dist-packages/keras/utils/data_utils.py:100: UserWarning:
200/755 [=====>.....] - ETA: 2:57:00 - loss: 0.5385 - accuracy: 0.9695 - mean_iou: 0.7040/usr/local/lib/python3.6/dist-packages/keras/utils/data_utils.py:100: UserWarning)
253/755 [=====>.....] - ETA: 2:39:54 - loss: 0.5375 - accuracy: 0.9699 - mean_iou: 0.7098/usr/local/lib/python3.6/dist-packages/keras/utils/data_utils.py:100: UserWarning)
584/755 [=====>.....] - ETA: 53:30 - loss: 0.5335 - accuracy: 0.9710 - mean_iou: 0.7155/usr/local/lib/python3.6/dist-packages/keras/utils/data_utils.py:100: UserWarning)
755/755 [=====>.....] - 15352s 20s/step - loss: 0.5313 - accuracy: 0.9703 - mean_iou: 0.7049 - val_loss: 0.5768 - val_accuracy: 0.8882 - val_mean_iou: 0.6355
Epoch 2/2
755/755 [=====>.....] - 3494s 5s/step - loss: 0.5224 - accuracy: 0.9671 - mean_iou: 0.6679 - val_loss: 0.5386 - val_accuracy: 0.9670 - val_mean_iou: 0.6355

Epoch 00002: ReduceLROnPlateau reducing learning rate to 0.0003000000142492354.
```

Classification Model

```
def __getitem__(self, idx):
    # select batch
    filenames = self.filenames[idx*self.batch_size : (idx + 1)*self.batch_size]

    if self.predict:
        # Load files for this batch
        imgs = [self.__loadpredict__(filename) for filename in filenames]
        imgs = np.array(imgs) # Create numpy arrays for batch images
        return imgs, filenames
    else:
        # Load files for this batch
        items = [self.__load__(filename) for filename in filenames]
        imgs, tgts = zip(*items) # Output of __load__ is a tuple with imgs and targets, so Unzip the images and targets
        imgs = np.array(imgs)    # Create numpy arrays for batch images
        tgts = np.array(tgts)    # Create numpy arrays for target
        return imgs, tgts
```

Classification Model

```
[ ] inputs = Input(shape=(IMAGE_SIZE, IMAGE_SIZE, 1))

# First conv block
x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(inputs)
x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Second conv block
x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Third conv block
x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)

# Fourth conv block
x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)
x = Dropout(rate=0.2)(x)

# Fifth conv block
x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
x = BatchNormalization()(x)
x = MaxPool2D(pool_size=(2, 2))(x)
x = Dropout(rate=0.2)(x)
```

Classification Model

```
# FC layer
x = Flatten()(x)
x = Dense(units=512, activation='relu')(x)
x = Dropout(rate=0.7)(x)
x = Dense(units=128, activation='relu')(x)
x = Dropout(rate=0.5)(x)
x = Dense(units=64, activation='relu')(x)
x = Dropout(rate=0.3)(x)

# Output layer
output = Dense(units=1, activation='sigmoid')(x)
```

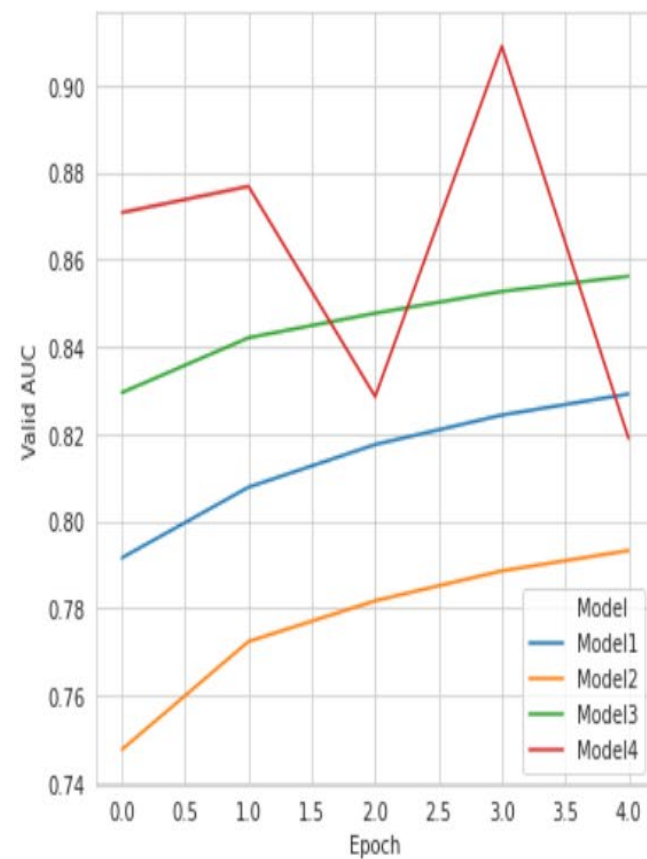
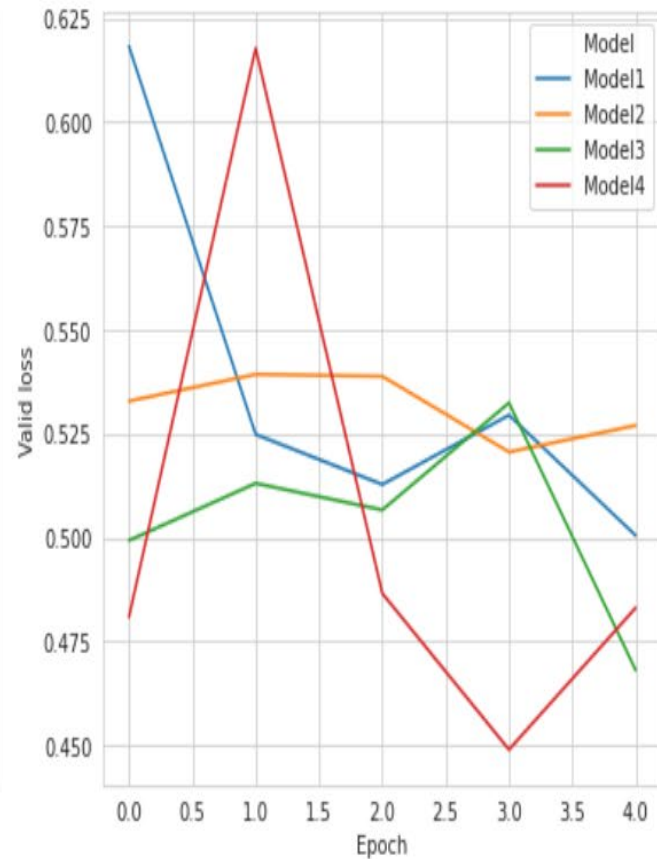
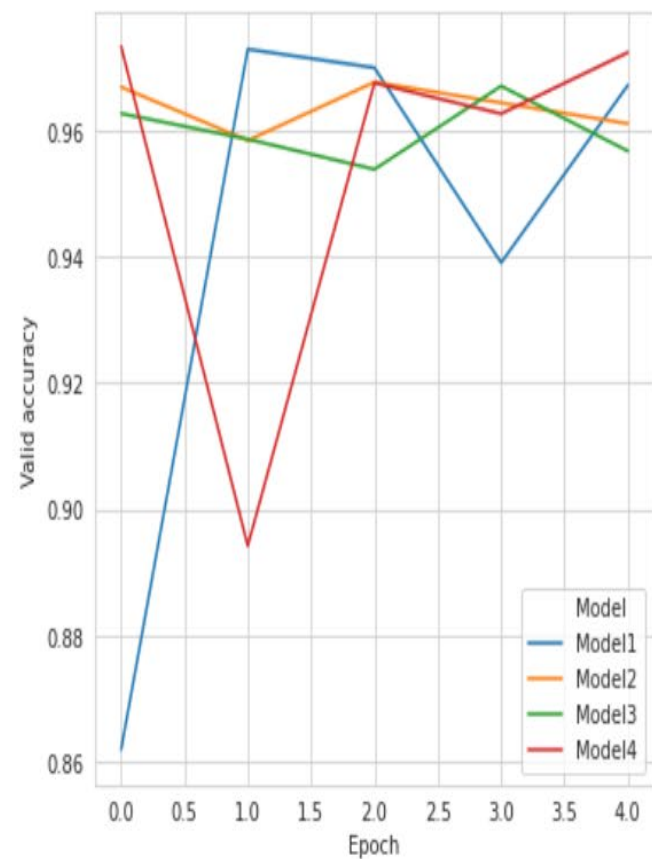
Training accuracy : 81.97%
Validation accuracy : 80.69%

Model Comparison

Model	Training accuracy	Validation accuracy	AUC
Model 1: Conv2D Layers	97.34%	97.55%	82.92
Model 2: SeperableConv2D Layers	97.33%	97.37%	79.32
Model 3: SeperableConv2D blocks with greater depth	96.21%	96.01%	85.62
Model 4: ResNet blocks	96.57%	95.48%	81.90
Classification Model	81.97%	80.69%	-

Model Comparison

`<matplotlib.axes._subplots.AxesSubplot at 0x7f479a0469e8>`



Step by Step Approach

- ▶ Pre-processing by splitting training data into batches of size 32
- ▶ Created a basic model with only Conv2D layers
- ▶ To reduce the training parameters, created model with SeparableConv2D
- ▶ Built 4 models for predicting bounding boxes and evaluated based on Accuracy metric
- ▶ Built Classification model for predicting the presence of Pneumonia
- ▶ Picked model 3, SeperableConv2D blocks with greater depth, based on accuracy and loss.
- ▶ Verified actual and predicted bounding boxes using 1 batch(32) of validation samples
- ▶ Created submission file

Model Evaluation

- Based on AUC, Accuracy and Loss, selected model 3, SeperableConv2D blocks

```
1  # REGRESSION MODEL TO PREDICT BBOX COORDINATES
2  inputs = Input(shape=(IMAGE_SIZE, IMAGE_SIZE, 1))
3
4  # First conv block
5  x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(inputs)
6  x = Conv2D(filters=16, kernel_size=(3, 3), activation='relu', padding='same')(x)
7  x = MaxPool2D(pool_size=(2, 2))(x)
8
9  # Second conv block
10 x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
11 x = SeparableConv2D(filters=32, kernel_size=(3, 3), activation='relu', padding='same')(x)
12 x = BatchNormalization()(x)
13 x = MaxPool2D(pool_size=(2, 2))(x)
14
15 # Third conv block
16 x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
17 x = SeparableConv2D(filters=64, kernel_size=(3, 3), activation='relu', padding='same')(x)
18 x = BatchNormalization()(x)
19 x = MaxPool2D(pool_size=(2, 2))(x)
20
21 # Fourth conv block
22 x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
23 x = SeparableConv2D(filters=128, kernel_size=(3, 3), activation='relu', padding='same')(x)
24 x = BatchNormalization()(x)
25 x = MaxPool2D(pool_size=(2, 2))(x)
26 x = Dropout(rate=0.2)(x)
27
28 # Fifth conv block
29 x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
30 x = SeparableConv2D(filters=256, kernel_size=(3, 3), activation='relu', padding='same')(x)
31 x = BatchNormalization()(x)
32 x = MaxPool2D(pool_size=(2, 2))(x)
33 x = Dropout(rate=0.2)(x)
34
35 # Sigmoid activation for binary classification
36 x = Conv2D(filters=1, kernel_size=(2, 2), activation='sigmoid', padding='same')(x)
37
38 output = UpSampling2D(32)(x)
39
40 # Creating model
41 model3 = Model(inputs=inputs, outputs=output)
42 model3.summary()
```

Model Evaluation

- ▶ Model Structure for Model 3
 - ▶ 5 SeparableConv2D blocks with MaxPooling and BatchNormalization layers
 - ▶ Conv2D Sigmoid Activation
 - ▶ 32 Upsampling Layers
 - ▶ Optimizer = Adam
 - ▶ Loss = iou_bce_loss
 - ▶ Metrics = accuracy
 - ▶ Epochs = 8

Model Evaluation

```
1 # Use Adam optimizer, combination of BCE and IOU loss, and monitor model performance using accuracy and average IOU
2 model3.compile(optimizer='adam', loss=iou_bce_loss, metrics=['accuracy', mean_iou, tf.keras.metrics.Precision(), tf.keras.metrics.Recall(), tf.keras.metrics.AUC()])
```

```
[ ] 1 # Model3
    2 #history3 = model3.fit_generator(train_gen, validation_data=valid_gen, epochs=2, callbacks=[checkpoint, lr_reduce], verbose=1, shuffle=True)
```

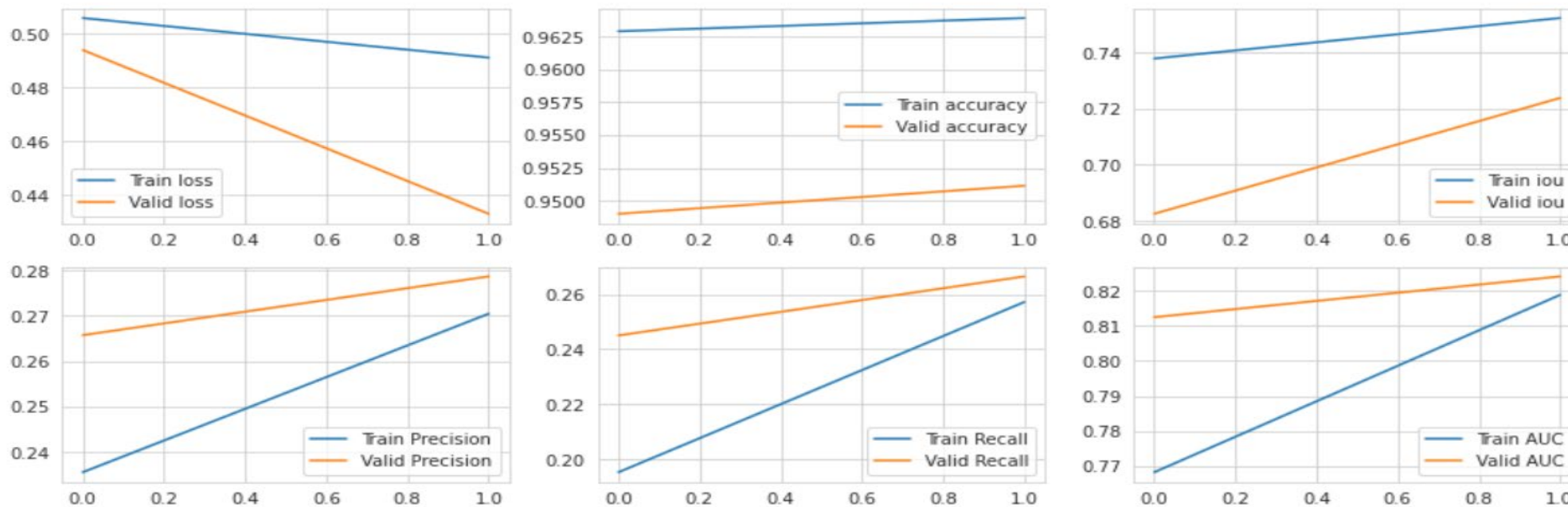
Epoch 1/2

755/755 [=====] - 5751s 8s/step - loss: 0.5060 - accuracy: 0.9629 - mean_iou: 0.7378 - precision_1: 0.2355 - recall_1: 0.1952 - auc_1: 0.7682 - val_loss: 0.4941 - val_accuracy:

Epoch 2/2

755/755 [=====] - 5684s 8s/step - loss: 0.4912 - accuracy: 0.9639 - mean_iou: 0.7523 - precision_1: 0.2705 - recall_1: 0.2572 - auc_1: 0.8189 - val_loss: 0.4330 - val_accuracy:

Epoch 00002: ReduceLROnPlateau reducing learning rate to 0.00030000000142492354.



Model Evaluation

- Based on accuracy and loss, selected model 3, SeperableConv2D blocks

```
1 df_regr_metrics = pd.DataFrame(columns=['Model','Epoch','Train loss','Valid loss','Train accuracy','Valid accuracy','Train iou','Valid iou','Train Precision','Valid Precision'],
2 for i, epoch_num in enumerate(history.epoch):
3     df_regr_metrics = df_regr_metrics.append({
4         'Model': 'Model3',
5         'Epoch': int(epoch_num),
6         'Train loss': history.history["loss"][i],
7         'Valid loss': history.history["val_loss"][i],
8         'Train accuracy': history.history["accuracy"][i],
9         'Valid accuracy': history.history["val_accuracy"][i],
10        'Train iou': history.history["mean_iou"][i],
11        'Valid iou': history.history["val_mean_iou"][i],
12        'Train Precision': history.history["precision_1"][i],
13        'Valid Precision': history.history["val_precision_1"][i],
14        'Train Recall': history.history["recall_1"][i],
15        'Valid Recall': history.history["val_recall_1"][i],
16        'Train AUC': history.history["auc_1"][i],
17        'Valid AUC': history.history["val_auc_1"][i]}, ignore_index=True)
18 df_regr_metrics
```

	Model	Epoch	Train loss	Valid loss	Train accuracy	Valid accuracy	Train iou	Valid iou	Train Precision	Valid Precision	Train Recall	Valid Recall	Train AUC	Valid AUC
0	Model3	0	0.506007	0.494073	0.962898	0.949001	0.737834	0.682489	0.235494	0.265730	0.19519	0.245055	0.768172	0.812514
1	Model3	1	0.491239	0.432990	0.963905	0.951135	0.752271	0.723777	0.270460	0.278685	0.25725	0.266564	0.818901	0.824171



Submission File Creation

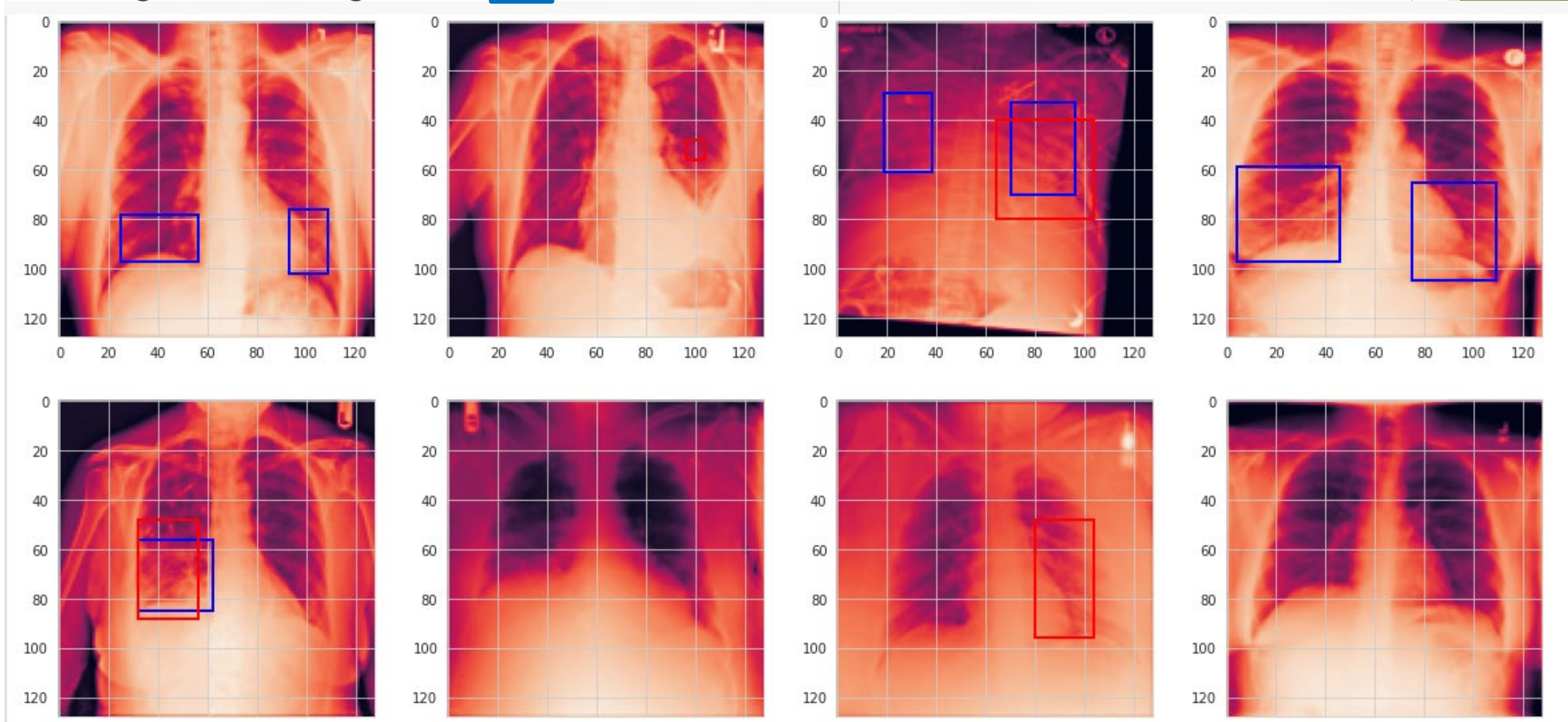
```
1 submission_dict = {}
2 # Predict the bbox coordinates for the test dataset and
3 for imgs, filenames in test_gen:
4     # predict batch of images
5     preds = model.predict(imgs)
6     print(filenames.shape)
7     print(preds.shape)
8
9     for filename, pred in zip(filenames, preds):
10        # resize predicted mask
11        pred = resize(pred, (1024, 1024), mode='reflect')
12        # threshold predicted mask
13        comp = pred[:, :, 0] > 0.5
14        # apply connected components
15        comp = measure.label(comp)
16        # apply bounding boxes
17        predictionString = ''
18        for region in measure.regionprops(comp):
19            # retrieve x, y, height and width
20            y, x, y2, x2 = region.bbox |
21            height = y2 - y
22            width = x2 - x
23            # proxy for confidence score
24            conf = np.mean(pred[y:y+height, x:x+width])
25            predictionString += str(conf) + ' ' + str(x) + ' ' + str(y) + ' ' + str(width) + ' ' + str(height)
26            filename = filename.split('.')[0]
27            submission_dict[filename] = predictionString
28        # stop if we've got them all
29        if len(submission_dict) >= len(test_filenames):
30            break
31        #submission_df = submission_df.append({'patientId':patientId, 'PredictionString': predictionString}, ignore_index=True)
32
33 # save dictionary as csv file
34 sub = pd.DataFrame.from_dict(submission_dict,orient='index')
35 sub.index.names = ['patientId']
36 sub.columns = ['PredictionString']
37 sub.to_csv('submission.csv')
38
39 sub.to_csv('/content/drive/My Drive/MainProject/submission.csv')
```


Submission File

patientId	PredictionString	
24fe325a-be98-405e-bbf5-cbe64aa82e5c		
25f09d92-e440-4e16-aca2-5baca1a76c89		
26636455-c98d-49a1-8b48-7025f535f982	0.77659607 508 257 259 510	
255354f6-9379-493a-90d1-5dd36ac660bc		
25c98e9d-637f-4e6f-8ad3-f9f85a7f7590		
25d2e423-40f3-4c47-becd-e05908e3ced4		
264d4100-0a4a-460d-81fd-e781bbf6ca86		
266490ca-ce52-4f5b-92ff-082dae7967c0		
26903582-dbc1-4427-b9da-45e2fa00ed17		
24e04bef-a0c2-439e-9181-5fa26c162fa4	0.5576752 259 258 507 507	
2634cbd2-0a3f-4503-bc07-b8f4f2da80c4		
2557ee07-5fc1-4eba-915e-f52d3d898f1e	0.7287349 257 257 511 511	
25840be8-f6cf-4df1-893b-80412b99a417	0.52446324 515 260 249 504	
2657b0a9-63ec-43b2-810e-b665f879f309		
2568153b-bdde-4292-8968-47f8e74cd400		
26a937bc-a3e4-41a1-9a1a-a63506d4b49d	0.8797624 256 256 512 512	
265dd221-9049-4bca-b5c0-4118dafa55c5		
268116a6-2304-4316-b5b3-3073fc5467b1		
257e34f1-f461-45fd-ab15-ec4cbfada52a		
2578fa2d-6cf3-41d1-b233-89587b1126d8		
2676fc9d-7ace-4896-b698-17fc68131851	0.6088609 258 258 255 507	
258f5240-8010-4472-91fe-494f75d59a46	0.56559247 513 258 252 506	

Model Output for Training Data(Model 3)

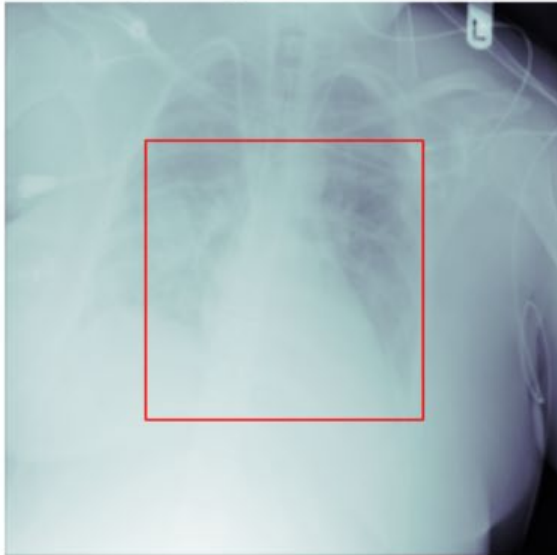
- Predicted bounding box 
- Original bounding box 



Model Output for Test Data(Model 3)

► Predicted bounding box 

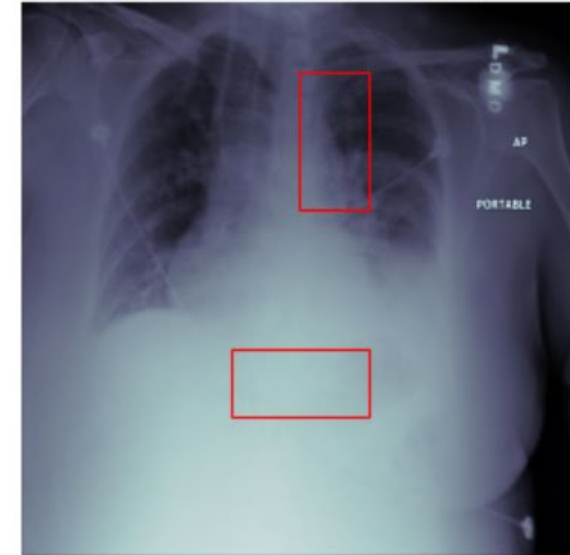
☞ ID: 1f5f2bb2-acc2-4c18-b6d5-212f9a9980b5
Modality: CR Age: 30 Sex: F Target: 1



ID: 2b9990c6-dd10-44e4-9d5a-5701a964a57d
Modality: CR Age: 58 Sex: F Target: 0



ID: 0066ba32-08b6-4ac9-8d5a-abec69825d53
Modality: CR Age: 52 Sex: F Target: 1



As we can see, the model is predicting correctly.

- For the first patient, the bounding box is bigger as the whole chest looks congested
- For the second patient, we don't have a bounding box, as the lungs appear to be clear
- For the third patient, pneumonia is detected in 2 different areas marked by the two separate bounding boxes.

Conclusion

- ▶ Our model is able to predict the bounding boxes around Pneumonic patches with accuracy of 87% on test data.
- ▶ Out of 3000 patients in the test set, 935 appear to have pneumonia for whom one or more bounding boxes are predicted by our model.
- ▶ Approximately 31% of patients are predicted to have pneumonia which is consistent with the training set data.
- ▶ This project uses recent techniques in the field of computer vision and deep learning and visualizations of key outcomes.

Implications

- ▶ Application can predict if the patient is affected with Pneumonia
- ▶ It pinpoints the affected areas of lungs using bounding boxes and the confidence levels associated with each of them
- ▶ This will help the doctors by reducing the number of CXRs they have to look through
- ▶ This project will help health care professionals by making quick and accurate predictions of pneumonia in CXR images.

Limitations

- ▶ Currently, input images size is fixed. This can be modified to accept images of different sizes.

How to improve model performance?

- ▶ Image Augmentation to increase the number of images where Target=1, which is our class of interest
- ▶ Increase the number of training epochs
- ▶ Choose models based on performance

Closing Reflections

► Learnings

- Use of pydicom package to view .dcm medical images
- Preprocessing of image related data
- Use of custom loss and metric functions
- Resnet and SeperableConv2D Layers
- Collaboration between team members for different tasks
- Understanding of complexity of real-world data and projects

► Possible Improvements

- Use a pretrained model such as YOLO or Faster-RCNN as benchmark
- Image Augmentation

Thank you!