## Experiments cifar100

August 10, 2025

### 1 Model load

```
[1]: import google.colab.drive as drive
    drive.mount('/content/drive')
    Mounted at /content/drive
```

```
[2]: import os
     import random
     import torch
     import torchvision
     import numpy as np
     import pandas as pd
     import seaborn as sns
     from tqdm import tqdm
     import matplotlib.pyplot as plt
     import torch.nn.functional as F
     from sklearn.manifold import TSNE
     from sklearn.decomposition import PCA
     from torch.utils.data import DataLoader
     from matplotlib.patches import Ellipse
     from sklearn.datasets import make_blobs
     from sklearn.mixture import GaussianMixture
     from torchvision.transforms import transforms
     from scipy.spatial.distance import mahalanobis
     from sklearn.preprocessing import StandardScaler
     from torch.distributions import Normal, kl_divergence
     from sklearn.discriminant_analysis import LinearDiscriminantAnalysis as LDA
     from sklearn.metrics import roc_auc_score, average precision_score, roc_curve, u
      →classification_report
     os.chdir("/content/drive/MyDrive/Colab Notebooks/Self_Study/ZClassifier")
```

```
[3]: from models import * from models import ZClassifier, SoftmaxClassifier, ResNetFeature, VGGFeature device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
```

```
[4]: path = "/content/drive/MyDrive/Colab Notebooks/Self Study/ZClassifier/
      \hookrightarrowpretrained"
     def load_model(model_class, path, device='cpu', **model_kwargs):
         Load a model from a state_dict.
         Args:
             model_class (callable): Class of the model to instantiate (e.g., __
      \hookrightarrow ZClassifier)
             path (str): File path to .pth file
             device (str): 'cuda' or 'cpu'
             model_kwargs: keyword arguments passed to model_class
         Returns:
             nn.Module: Loaded model
         model = model_class(**model_kwargs)
         state_dict = torch.load(path, map_location=device)
         model.load_state_dict(state_dict)
         model.to(device)
         model.eval()
         print(f"[] Loaded model from: {path}")
         return model
```

```
[5]: modelA = load_model(
         model_class=ZClassifier,
         path=f'{path}/modelA.pth',
         device=device,
         feature_extractor=ResNetFeature(), num_classes=100, latent_dim=60, beta=1.0
     )
     modelB = load model(
         model_class=ZClassifier,
         path=f'{path}/modelB.pth',
         device=device,
         feature_extractor=VGGFeature(), num_classes=100, latent_dim=60, beta=1.0
     softmax_model = load_model(
         model_class=SoftmaxClassifier,
         path=f'{path}/softmax_model.pth',
         device=device,
         feature_extractor=ResNetFeature(), num_classes=100
     nokl model = load model(
         model_class=ZClassifier,
         path=f'{path}/model_nokl.pth',
```

```
device=device,
         feature_extractor=ResNetFeature(), num_classes=100, latent_dim=60, beta=1.0
     )
    /usr/local/lib/python3.11/dist-packages/torchvision/models/_utils.py:208:
    UserWarning: The parameter 'pretrained' is deprecated since 0.13 and may be
    removed in the future, please use 'weights' instead.
      warnings.warn(
    /usr/local/lib/python3.11/dist-packages/torchvision/models/_utils.py:223:
    UserWarning: Arguments other than a weight enum or `None` for 'weights' are
    deprecated since 0.13 and may be removed in the future. The current behavior is
    equivalent to passing `weights=ResNet18_Weights.IMAGENET1K_V1`. You can also use
    `weights=ResNet18_Weights.DEFAULT` to get the most up-to-date weights.
      warnings.warn(msg)
    Downloading: "https://download.pytorch.org/models/resnet18-f37072fd.pth" to
    /root/.cache/torch/hub/checkpoints/resnet18-f37072fd.pth
              | 44.7M/44.7M [00:02<00:00, 17.1MB/s]
    100%|
    [] Loaded model from: /content/drive/MyDrive/Colab
    Notebooks/Self_Study/ZClassifier/pretrained/modelA.pth
    Downloading: "https://download.pytorch.org/models/vgg11-8a719046.pth" to
    /root/.cache/torch/hub/checkpoints/vgg11-8a719046.pth
    100%|
              | 507M/507M [00:15<00:00, 34.5MB/s]
    [] Loaded model from: /content/drive/MyDrive/Colab
    Notebooks/Self_Study/ZClassifier/pretrained/modelB.pth
    [] Loaded model from: /content/drive/MyDrive/Colab
    Notebooks/Self_Study/ZClassifier/pretrained/softmax_model.pth
    [] Loaded model from: /content/drive/MyDrive/Colab
    Notebooks/Self_Study/ZClassifier/pretrained/model_nokl.pth
[6]: transform = transforms.Compose([
         transforms.Resize((224, 224)),
         transforms.ToTensor(),
         transforms.Normalize((0.5,), (0.5,))
     ])
     # Load CIFAR-10 train set for training
     cifar10 = torchvision.datasets.CIFAR100(root='./data', train=True,_
      ⇒download=True, transform=transform)
     train_loader = DataLoader(cifar10, batch_size=100, shuffle=True)
     # Load CIFAR-10 test set for analysis
     cifar10 = torchvision.datasets.CIFAR100(root='./data', train=False,
      →download=True, transform=transform)
     eval_loader = DataLoader(cifar10, batch_size=100, shuffle=False)
     test_loader = DataLoader(cifar10, batch_size=100, shuffle=False)
```

### 1.1 1. Calibration Robustness under Logit Perturbation

Test ZClassifier's robustness to softmax calibration under Gaussian logit noise.

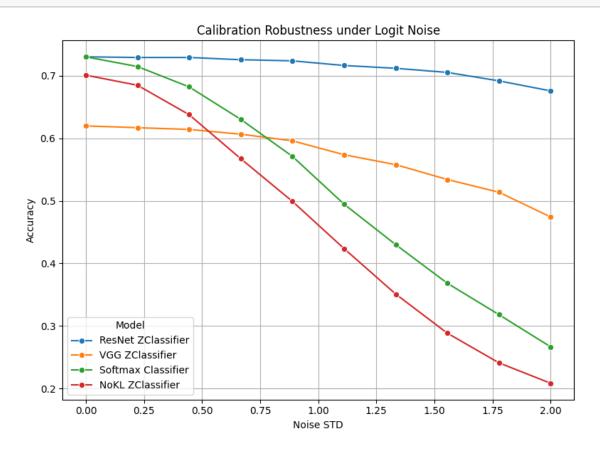
```
[7]: def evaluate_calibration_with_noise(model, test_loader, noise_std_list):
         model.eval()
         results = []
         with torch.no_grad():
             for noise_std in noise_std_list:
                 correct, total = 0, 0
                 all_probs, all_labels = [], []
                 for images, labels in test_loader:
                     images, labels = images.to(device), labels.to(device)
                     logits = model(images)
                     noise = torch.randn_like(logits) * noise_std * logits.std()
                     noisy_logits = logits + noise
                     probs = F.softmax(noisy_logits, dim=1)
                     preds = probs.argmax(dim=1)
                     correct += (preds == labels).sum().item()
                     total += labels.size(0)
                     all_probs.append(probs.cpu())
                     all_labels.append(labels.cpu())
                 acc = correct / total
                 print(f"Noise STD: {noise_std:.2f} → Accuracy: {acc:.4f}")
                 results.append((noise_std, acc))
         return results
     def plot_calibration_results(results_dict):
         records = []
         for model_name, results in results_dict.items():
             for noise_std, acc in results:
                 records.append({
                     'Model': model_name,
                     'Noise STD': float(noise_std),
                     'Accuracy': float(acc)
                 })
         df = pd.DataFrame.from_records(records)
         plt.figure(figsize=(8, 6))
         sns.lineplot(data=df, x='Noise STD', y='Accuracy', hue='Model', marker='o')
         plt.title('Calibration Robustness under Logit Noise')
```

```
plt.show()
[8]: noises = np.linspace(0, 2, num=20, endpoint=True).tolist()
[9]: # : 4
                  device
                           , test loader
     noise_std_list = torch.linspace(0.0, 2.0, steps=10)
     results_dict = {}
     print('ResNet ZClassifier Calibration')
     results_dict['ResNet ZClassifier'] = evaluate_calibration_with_noise(modelA,_
      stest_loader, noise_std_list)
     print('VGG ZClassifier Calibration')
     results_dict['VGG ZClassifier'] = evaluate_calibration_with_noise(modelB,_
      →test_loader, noise_std_list)
     print('Softmax Classifier Calibration')
     results_dict['Softmax Classifier'] = __
      evaluate_calibration_with_noise(softmax_model, test_loader, noise_std_list)
     print('NoKL ZClassifier Calibration')
     results_dict['NoKL ZClassifier'] = evaluate_calibration_with_noise(nokl_model,_
      stest_loader, noise_std_list)
    ResNet ZClassifier Calibration
    Noise STD: 0.00 → Accuracy: 0.7301
    Noise STD: 0.22 → Accuracy: 0.7291
    Noise STD: 0.44 → Accuracy: 0.7291
    Noise STD: 0.67 → Accuracy: 0.7255
    Noise STD: 0.89 → Accuracy: 0.7237
    Noise STD: 1.11 → Accuracy: 0.7163
    Noise STD: 1.33 → Accuracy: 0.7118
    Noise STD: 1.56 → Accuracy: 0.7052
    Noise STD: 1.78 → Accuracy: 0.6917
    Noise STD: 2.00 → Accuracy: 0.6757
    VGG ZClassifier Calibration
    Noise STD: 0.00 → Accuracy: 0.6197
    Noise STD: 0.22 → Accuracy: 0.6169
    Noise STD: 0.44 → Accuracy: 0.6141
    Noise STD: 0.67 → Accuracy: 0.6065
    Noise STD: 0.89 → Accuracy: 0.5959
    Noise STD: 1.11 → Accuracy: 0.5737
    Noise STD: 1.33 → Accuracy: 0.5578
    Noise STD: 1.56 → Accuracy: 0.5341
    Noise STD: 1.78 → Accuracy: 0.5137
    Noise STD: 2.00 → Accuracy: 0.4742
    Softmax Classifier Calibration
```

plt.grid(True)
plt.tight\_layout()

```
Noise STD: 0.00 → Accuracy: 0.7301
Noise STD: 0.22 → Accuracy: 0.7146
Noise STD: 0.44 → Accuracy: 0.6821
Noise STD: 0.67 → Accuracy: 0.6302
Noise STD: 0.89 → Accuracy: 0.5710
Noise STD: 1.11 → Accuracy: 0.4947
Noise STD: 1.33 → Accuracy: 0.4300
Noise STD: 1.56 → Accuracy: 0.3683
Noise STD: 1.78 → Accuracy: 0.3181
Noise STD: 2.00 → Accuracy: 0.2667
NoKL ZClassifier Calibration
Noise STD: 0.00 → Accuracy: 0.7008
Noise STD: 0.22 → Accuracy: 0.6847
Noise STD: 0.44 → Accuracy: 0.6377
Noise STD: 0.67 → Accuracy: 0.5673
Noise STD: 0.89 → Accuracy: 0.4991
Noise STD: 1.11 → Accuracy: 0.4237
Noise STD: 1.33 → Accuracy: 0.3510
Noise STD: 1.56 → Accuracy: 0.2885
Noise STD: 1.78 → Accuracy: 0.2411
Noise STD: 2.00 → Accuracy: 0.2085
```

### [10]: plot\_calibration\_results(results\_dict)



### 1.2 2. Latent Logit Geometry Consistency

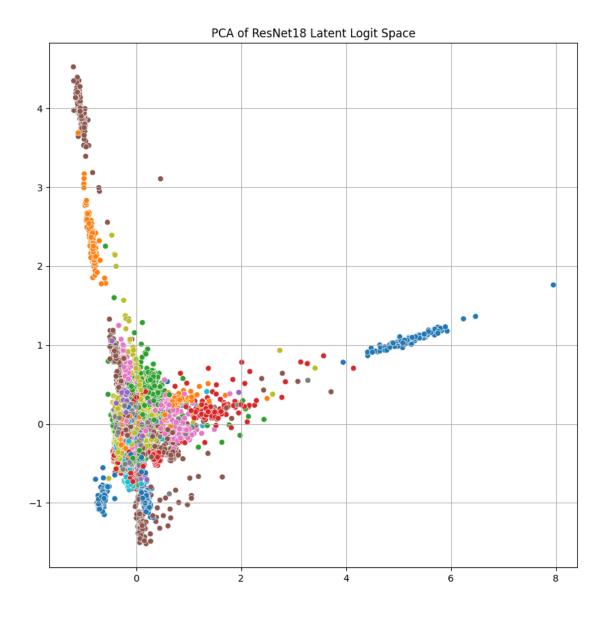
Compare latent structure between backbones (e.g., ResNet vs VGG).

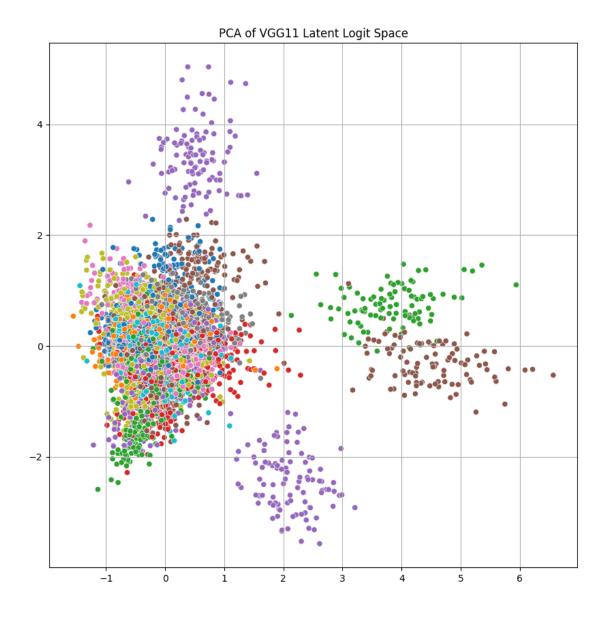
### 1.2.1 PCA on train set

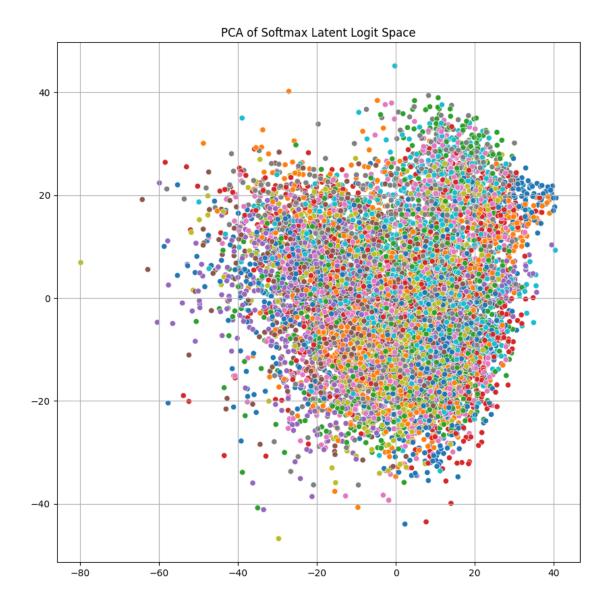
Most general linear dimensionality reduction.

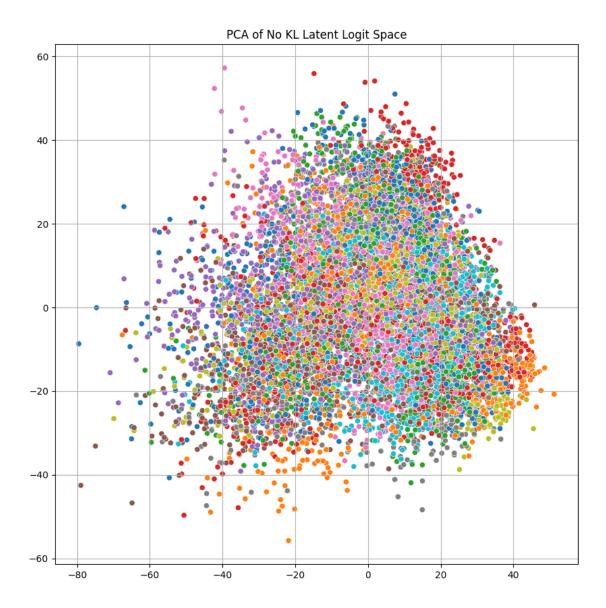
```
[11]: def visualize_latent_geometry(model, dataloader, name, num_batches=100):
          model.eval()
          all_latents, all_labels = [], []
          with torch.no_grad():
              for i, (images, labels) in enumerate(dataloader):
                  if i >= num_batches: break
                  images = images.to(device)
                  z = model(images)
                  z_flat = z.view(z.size(0), -1)
                  all_latents.append(z_flat.cpu())
                  all_labels.append(labels)
          X = torch.cat(all_latents, dim=0).numpy()
          y = torch.cat(all_labels, dim=0).numpy()
          X_pca = PCA(n_components=2).fit_transform(X)
          plt.figure(figsize=(10, 10))
          sns.scatterplot(x=X_pca[:, 0], y=X_pca[:, 1], hue=y, palette='tab10',__
       →legend=False)
          plt.title(f"PCA of {name} Latent Logit Space")
          plt.grid(True)
          plt.show()
```

```
[12]: visualize_latent_geometry(modelA, train_loader, name="ResNet18")
visualize_latent_geometry(modelB, train_loader, name="VGG11")
visualize_latent_geometry(softmax_model, train_loader, name="Softmax")
visualize_latent_geometry(nokl_model, train_loader, name="No KL")
```









### 1.2.2 t-SNE

```
transforms.Resize((224, 224)), # Fit to VGG/ResNet input size
       transforms.ToTensor(),
   1)
    cifar10 = torchvision.datasets.CIFAR100(root='./data', train=False,
 →download=True, transform=transform)
   loader = DataLoader(cifar10, batch size=batch size, shuffle=False)
    # 2. Load pretrianed models
   if model_type == 'resnet':
       model = modelA
   elif model_type == 'vgg':
       model = modelB
    elif model_type == 'softmax':
       model = softmax_model
   elif model_type == 'nokl':
       model = nokl_model
   else:
       raise ValueError("model_type must be one of: ['resnet', 'vgg', _
 model.eval()
   # 3. Logits
   all_latents = []
   all_labels = []
   with torch.no_grad():
       for x, y in tqdm(loader, desc=f"Simulating {model_type}"):
           x = x.to(device)
           z = model(x).detach().cpu()
            all_latents.append(z)
            all_labels.append(y)
   all_latents = torch.cat(all_latents, dim=0).numpy()
   all_labels = torch.cat(all_labels, dim=0).numpy()
   return all_latents, all_labels
# 2. Simulate latent logit outputs
resnet_latents, resnet_labels = simulate_latents('resnet')
vgg_latents, vgg_labels = simulate_latents('vgg')
softmax_latents, softmax_labels = simulate_latents('softmax')
nokl_latents, nokl_labels = simulate_latents('nokl')
```

Simulating resnet: 0% | 0/100 [00:00<?, ?it/s] Simulating vgg: 0% | 0/100 [00:00<?, ?it/s]

```
Simulating softmax: 0%| | 0/100 [00:00<?, ?it/s]
Simulating nokl: 0%| | 0/100 [00:00<?, ?it/s]
```

```
[15]: # features: latent vector (e.g. model.z.mean(-1).detach().cpu().numpy())
# labels: ground-truth class labels
plot_tsne(resnet_latents, resnet_labels, title="ResNet18 - t-SNE Embedding")
plot_tsne(vgg_latents, vgg_labels, title="VGG11 - t-SNE Embedding")
plot_tsne(softmax_latents, softmax_labels, title="Softmax - t-SNE Embedding")
plot_tsne(nokl_latents, nokl_labels, title="NoKL - t-SNE Embedding")
```

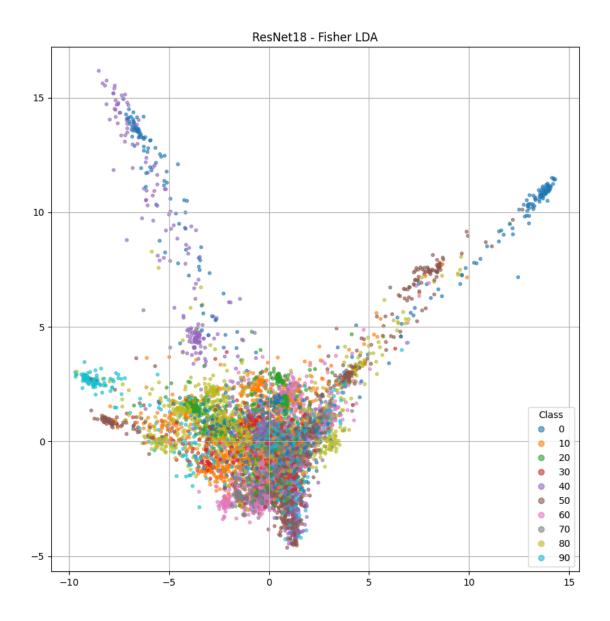
Output hidden; open in https://colab.research.google.com to view.

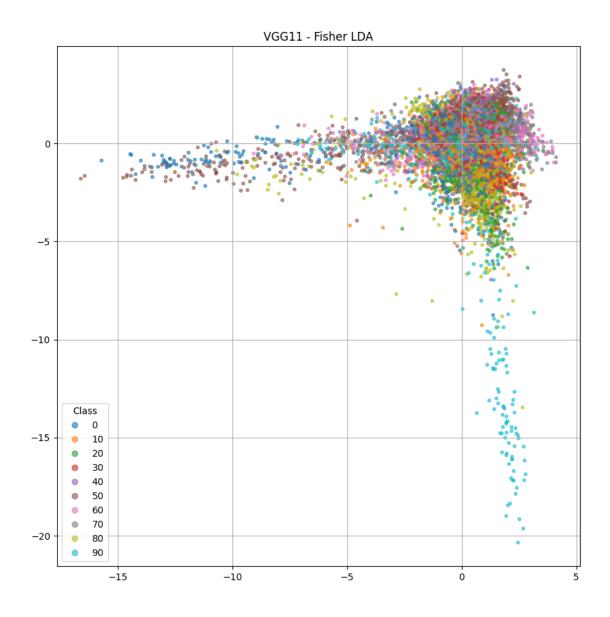
#### 1.2.3 Fisher LDA

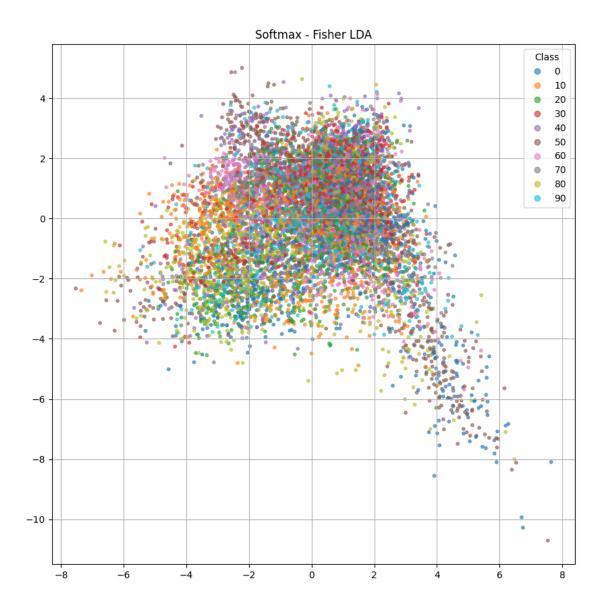
```
def plot_fisher_lda(features, labels, title="Fisher LDA Embedding"):
    lda = LDA(n_components=2)
    features_2d = lda.fit_transform(features, labels)

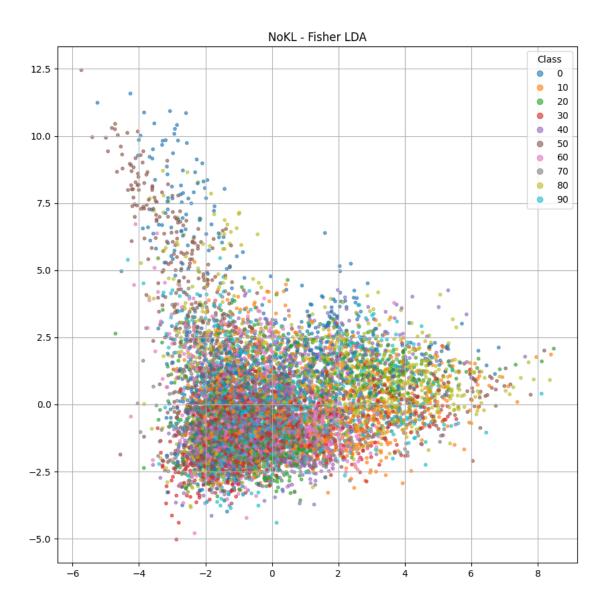
plt.figure(figsize=(10, 10))
    scatter = plt.scatter(features_2d[:, 0], features_2d[:, 1], c=labels,
cmap='tab10', s=10, alpha=0.6)
    plt.title(title)
    plt.legend(*scatter.legend_elements(), title="Class")
    plt.grid(True)
    plt.show()
```

```
[17]: plot_fisher_lda(resnet_latents, resnet_labels, title="ResNet18 - Fisher LDA")
    plot_fisher_lda(vgg_latents, vgg_labels, title="VGG11 - Fisher LDA")
    plot_fisher_lda(softmax_latents, softmax_labels, title="Softmax - Fisher LDA")
    plot_fisher_lda(nokl_latents, nokl_labels, title="NoKL - Fisher LDA")
```









### 1.2.4 PCA on validation set

```
def plot_classwise_pca(latents, labels, model_name='Model'):
    pca = PCA(n_components=2)
    z2d = pca.fit_transform(latents)

    plt.figure(figsize=(10, 10))
    sns.scatterplot(x=z2d[:, 0], y=z2d[:, 1], hue=labels, palette='tab10', us=30, alpha=0.8, legend=False)
    plt.title(f'PCA of Latent Logit Space ({model_name})')
    plt.xlabel('PC1')
    plt.ylabel('PC2')
    plt.grid(True)
```

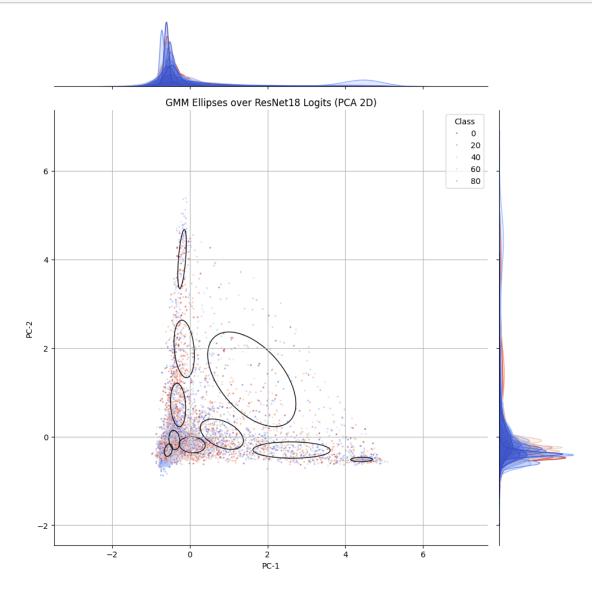
```
plt.show()
```

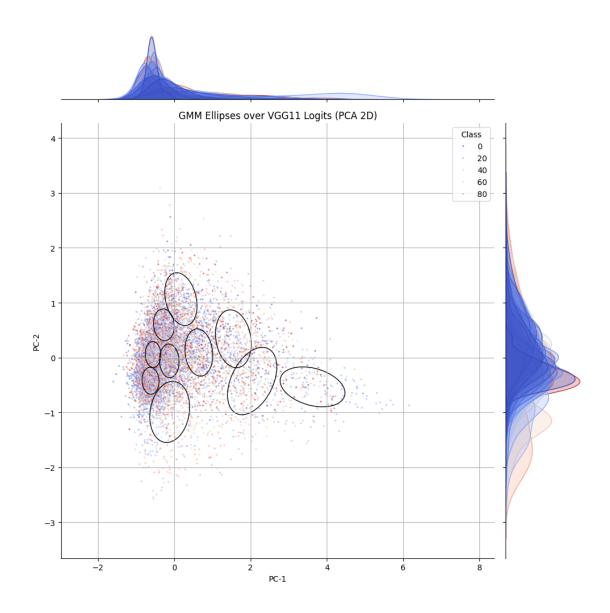
Output hidden; open in https://colab.research.google.com to view.

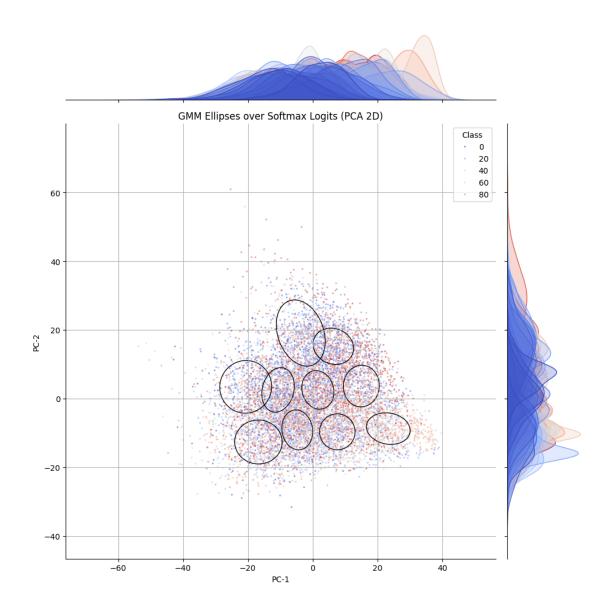
### 1.2.5 GMM Ellipsis with PCA

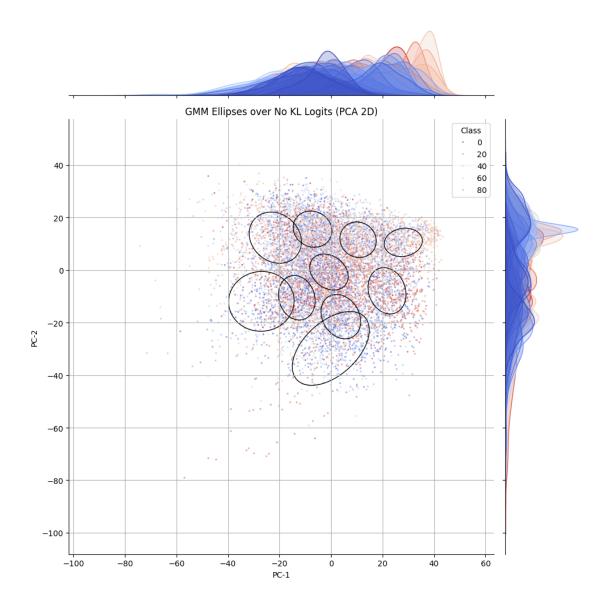
```
[20]: def plot_gmm_ellipses(z_all, labels_all, name, n_components=10):
          N, C = z all.shape
          # 2D PCA
          z_2d = PCA(n_components=2).fit_transform(z_all)
          gmm = GaussianMixture(n components=n components, covariance type='full')
          gmm.fit(z_2d)
          # Ellipsis
          sns.jointplot(x=z_2d[:, 0], y=z_2d[:, 1],
                        height=10,
                        s=5, hue=labels_all, alpha=0.6,
                        palette="coolwarm")
          for i in range(n components):
              mean = gmm.means_[i]
              cov = gmm.covariances [i]
              eigvals, eigvecs = np.linalg.eigh(cov)
              angle = np.degrees(np.arctan2(eigvecs[1, 0], eigvecs[0, 0]))
              width, height = 2 * np.sqrt(eigvals)
              ell = Ellipse(xy=mean, width=width, height=height, angle=angle,__
       ⇔edgecolor='k', facecolor='none')
              plt.gca().add_patch(ell)
          plt.title(f"GMM Ellipses over {name} Logits (PCA 2D)")
          plt.xlabel("PC-1")
          plt.ylabel("PC-2")
          plt.legend(title='Class')
          plt.grid(True)
          plt.tight_layout()
          plt.show()
```

```
[21]: plot_gmm_ellipses(resnet_latents, resnet_labels, name="ResNet18")
plot_gmm_ellipses(vgg_latents, vgg_labels, name="VGG11")
plot_gmm_ellipses(softmax_latents, softmax_labels, name="Softmax")
plot_gmm_ellipses(nokl_latents, nokl_labels, name="No KL")
```









### 1.3 3. OOD Detection via KL Score

Use the KL divergence to the closest one-hot Gaussian to detect OOD samples. SoftmaxClassifier doesn't outputs distributions or random vectors, so it is out of the evalutaions.

```
[22]: def compute_kl_scores(mu, logvar):
    """

    KL divergence between N(mu, sigma^2) and N(0,1)
    """

    var = logvar.exp()
    std_normal = Normal(torch.zeros_like(mu), torch.ones_like(var))
    pred_normal = Normal(mu, var.sqrt())
    kl = kl_divergence(pred_normal, std_normal) # shape: [batch, classes]
```

```
return kl.mean(dim=(1, 2)) # [batch]
def evaluate_ood_score(in_scores, ood_scores):
   labels = np.array([1] * len(in scores) + [0] * len(ood_scores)) # 1: In, 0:
 → 00D
   scores = np.concatenate([in scores, ood scores])
   # Check if labels are binary
   unique_labels = np.unique(labels)
   if not np.all(np.sort(unique_labels) == [0, 1]):
        raise ValueError(f"Labels must be binary (0 or 1), but found:⊔

√{unique_labels}")
    # Add small noise to scores if all are identical
   if len(np.unique(scores)) == 1:
        scores = scores + np.random.rand(len(scores)) * 1e-6
   auroc = roc_auc_score(labels, -scores)
   aupr = average_precision_score(labels, -scores)
    # Ensure fpr and tpr are calculated correctly for binary classification
   fpr, tpr, _ = roc_curve(labels, -scores)
    # Find FPR at 95% TPR, handling cases where TPR doesn't reach 95%
   if np.any(tpr >= 0.95):
        fpr95 = fpr[np.argmax(tpr >= 0.95)]
   else:
        fpr95 = 1.0 # If TPR never reaches 95%, FPR@95 is 1.0
   return {'AUROC': auroc, 'AUPR': aupr, 'FPR@95': fpr95}, labels, scores
def evaluate_ood_detection(model, in_loader, ood_loader, device=device):
   model.eval()
    in_scores, ood_scores = [], []
   with torch.no_grad():
        for images, _ in in_loader:
            images = images.to(device)
            = model(images)
            mu, logvar = model.mu.clone(), model.logvar.clone()
            kl = compute_kl_scores(mu, logvar)
            in_scores.extend(kl.cpu().numpy())
        for images, _ in ood_loader:
            images = images.to(device)
            _ = model(images)
           mu, logvar = model.mu.clone(), model.logvar.clone()
            kl = compute_kl_scores(mu, logvar)
```

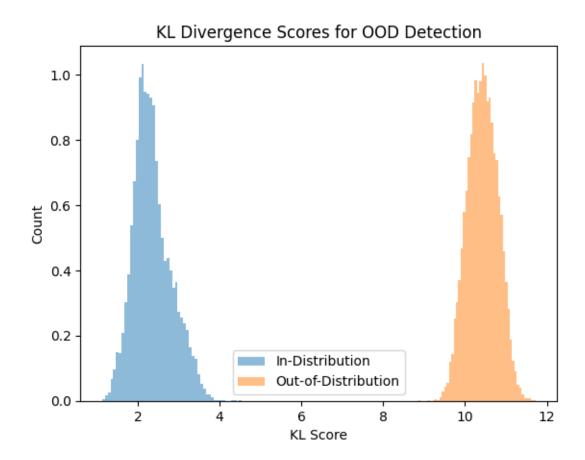
```
ood_scores.extend(kl.cpu().numpy())
  # metrics
  metrics, labels, scores = evaluate_ood_score(in_scores, ood_scores)
  in_scores = np.array(in_scores)
  ood_scores = np.array(ood_scores)
  # report
  # Use a percentile that exists within the data
  if len(in scores) > 0:
      threshold = np.percentile(-in_scores, min(5, 100)) # conservative_
⇔thresholding (5% percentile)
  else:
      threshold = -np.inf # If no in-distribution scores, threshold is_{\sqcup}
⇔effectively negative infinity
  predicted = (-np.array(scores) > threshold).astype(int)
  report = classification_report(labels, predicted, target_names=['00D',__
print(" OOD Detection Performance:")
  for k, v in metrics.items():
      print(f"{k}: {v:.4f}")
  print("\n Classification Report (Threshold = {:.4f}):".format(threshold))
  print(report)
  # visualize
  plt.hist(in_scores, bins=50, density=True, alpha=0.5,__
⇔label="In-Distribution")
  plt.hist(ood_scores, bins=50, density=True, alpha=0.5,__
⇔label="Out-of-Distribution")
  plt.title("KL Divergence Scores for OOD Detection")
  plt.xlabel("KL Score")
  plt.ylabel("Count")
  plt.legend()
  plt.show()
  return metrics
```

```
[23]: from torchvision.datasets import SVHN
from torchvision.datasets import CIFAR10

class SyntheticNoiseDataset(torch.utils.data.Dataset):
    def __init__(self, kind='gaussian', size=10000, image_shape=(3, 32, 32)):
        self.kind = kind
```

```
self.size = size
              self.image_shape = image_shape
          def __getitem__(self, idx):
              if self.kind == 'gaussian':
                  img = torch.randn(self.image_shape)
              elif self.kind == 'uniform':
                  img = torch.rand(self.image_shape)
              else:
                  raise ValueError("Unsupported noise type.")
              return img, 0 # dummy label
          def __len__(self):
              return self.size
      def get_noise_loader(kind='gaussian', batch_size=100):
          dataset = SyntheticNoiseDataset(kind=kind)
          return DataLoader(dataset, batch_size=batch_size, shuffle=False)
      def get_svhn_loader(batch_size=100):
          transform = transforms.Compose([transforms.Resize((32, 32)), transforms.
       →ToTensor()])
          svhn = SVHN(root='./data', split='test', download=True, transform=transform)
          return DataLoader(svhn, batch size=batch size, shuffle=False)
      def get_cifar10_loader(batch_size=100):
          transform = transforms.Compose([
              transforms.ToTensor(),
              transforms.Normalize(mean=[0.4914, 0.4822, 0.4465],
                                   std=[0.2023, 0.1994, 0.2010])
          ])
          cifar10 = CIFAR10(root='./data', train=False, download=True,
       →transform=transform)
          return DataLoader(cifar10, batch size=batch size, shuffle=False)
[24]: ood_svhn = get_svhn_loader()
      ood_gaussian = get_noise_loader('gaussian')
      ood_uniform = get_noise_loader('uniform')
      ood_cifar10 = get_cifar10_loader()
[25]: evaluate_ood_detection(modelA, eval_loader, ood_svhn)
      evaluate_ood_detection(modelB, eval_loader, ood_svhn)
      evaluate_ood_detection(nokl_model, eval_loader, ood_svhn)
      OOD Detection Performance:
     AUROC: 1.0000
     AUPR: 1.0000
     FPR@95: 0.0000
```

Classification Report (Threshold = $-3.2196$ ):				
	precision	recall	f1-score	support
00D	0.98	1.00	0.99	26032
In-Distribution	1.00	0.95	0.97	10000
accuracy			0.99	36032
macro avg	0.99	0.97	0.98	36032
weighted avg	0.99	0.99	0.99	36032



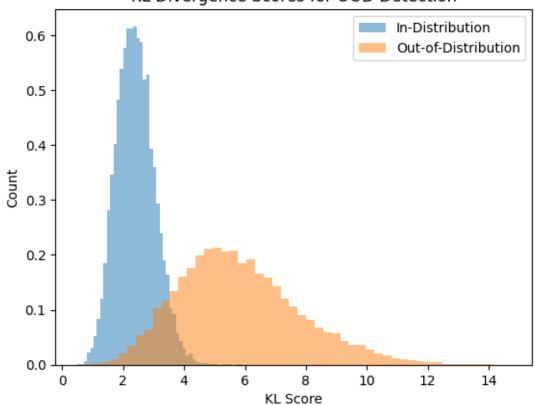
00D Detection Performance:

AUROC: 0.9682 AUPR: 0.8921 FPR@95: 0.1063

Classification Report (Threshold = -3.4704):

precision recall f1-score support

00D	0.98	0.89	0.93	26032
In-Distribution	0.77	0.95	0.85	10000
accuracy			0.91	36032
macro avg	0.88	0.92	0.89	36032
weighted avg	0.92	0.91	0.91	36032



### OOD Detection Performance:

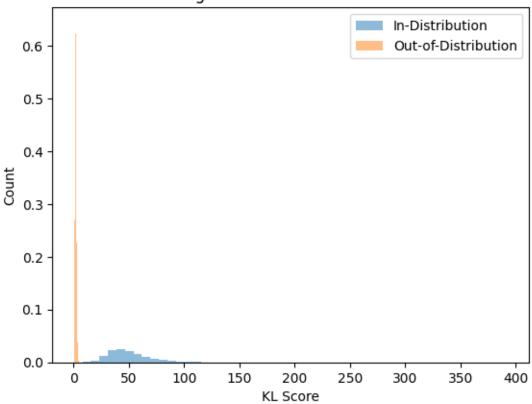
AUROC: 0.0000 AUPR: 0.1538 FPR@95: 1.0000

Classification Report (Threshold = -85.8196):

	precision	recall	f1-score	support
00D In-Distribution	0.00 0.27	0.00 0.95	0.00 0.42	26032 10000
accuracy			0.26	36032

macro avg 0.13 0.47 0.21 36032 weighted avg 0.07 0.26 0.12 36032

## KL Divergence Scores for OOD Detection



[26]: evaluate\_ood\_detection(modelA, eval\_loader, ood\_gaussian) evaluate\_ood\_detection(modelB, eval\_loader, ood\_gaussian) evaluate\_ood\_detection(nokl\_model, eval\_loader, ood\_gaussian)

OOD Detection Performance:

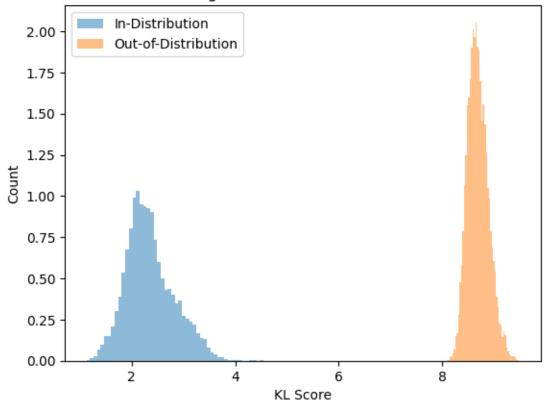
AUROC: 1.0000 AUPR: 1.0000 FPR@95: 0.0000

Classification Report (Threshold = -3.2196):

precision recall f1-score support

OOD 0.95 1.00 0.98 10000

In-Distribution	1.00	0.95	0.97	10000
accuracy			0.97	20000
macro avg	0.98	0.97	0.97	20000
weighted avg	0.98	0.97	0.97	20000



### OOD Detection Performance:

AUROC: 1.0000 AUPR: 1.0000 FPR@95: 0.0000

### Classification Report (Threshold = -3.4704):

	precision	recall	f1-score	support
00D In-Distribution	0.95 1.00	1.00 0.95	0.98 0.97	10000 10000
accuracy macro avg	0.98	0.97	0.97 0.97	20000 20000

weighted avg 0.98 0.97 0.97 20000

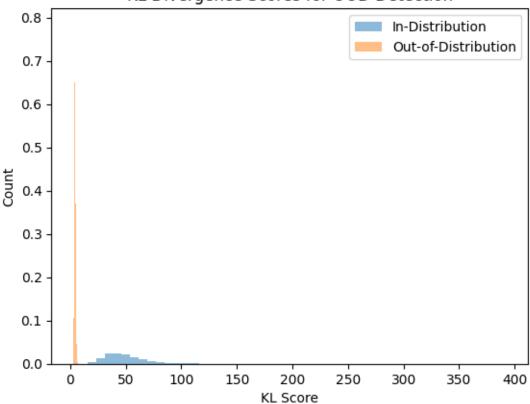
## KL Divergence Scores for OOD Detection In-Distribution 0.6 Out-of-Distribution 0.5 0.4 Count E.0 0.2 0.1 0.0 ż 6 12 16 8 10 14 KL Score

### OOD Detection Performance:

AUROC: 0.0000 AUPR: 0.3069 FPR@95: 1.0000

Classification Report (Threshold = -85.8196):

	precision	recall	f1-score	support
OOD	0.00	0.00	0.00	10000
In-Distribution	0.49	0.95	0.64	10000
accuracy			0.47	20000
macro avg	0.24	0.47	0.32	20000
weighted avg	0.24	0.47	0.32	20000



```
[26]: {'AUROC': np.float64(0.0),
```

'AUPR': np.float64(0.3068778611725624),

'FPR@95': np.float64(1.0)}

[27]: evaluate\_ood\_detection(modelA, eval\_loader, ood\_uniform)
 evaluate\_ood\_detection(modelB, eval\_loader, ood\_uniform)
 evaluate\_ood\_detection(nokl\_model, eval\_loader, ood\_uniform)

OOD Detection Performance:

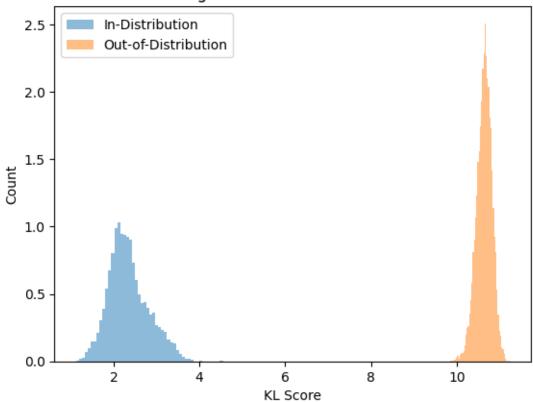
AUROC: 1.0000 AUPR: 1.0000 FPR@95: 0.0000

Classification Report (Threshold = -3.2196):

	precision	recall	f1-score	support
00D In-Distribution	0.95 1.00	1.00 0.95	0.98 0.97	10000 10000
accuracy			0.97	20000

macro avg 0.98 0.97 0.97 20000 weighted avg 0.98 0.97 0.97 20000

# KL Divergence Scores for OOD Detection

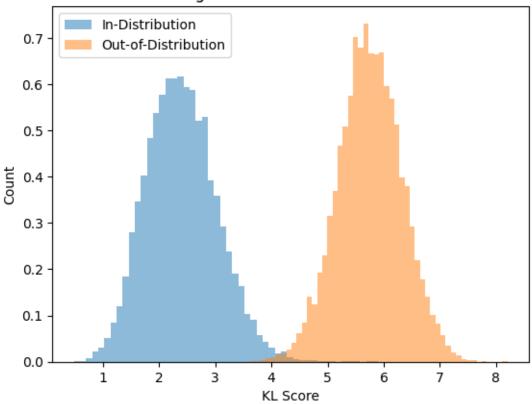


OOD Detection Performance:

AUROC: 0.9997 AUPR: 0.9997 FPR@95: 0.0000

Classification Report (Threshold = -3.4704):

0_000	p ( o		0	
	precision	recall	f1-score	support
OOD	0.95	1.00	0.98	10000
In-Distribution	1.00	0.95	0.97	10000
accuracy			0.97	20000
macro avg	0.98	0.97	0.97	20000
weighted avg	0.98	0.97	0.97	20000

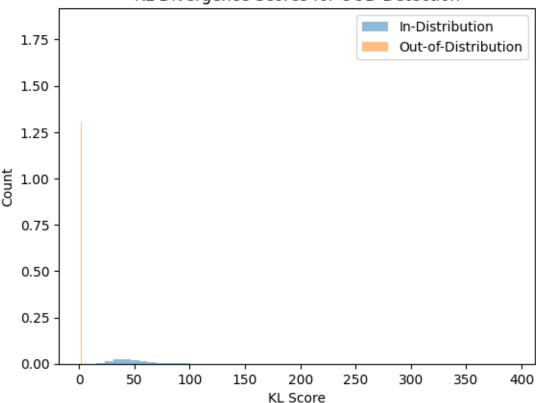


### OOD Detection Performance:

AUROC: 0.0000 AUPR: 0.3069 FPR@95: 1.0000

## Classification Report (Threshold = -85.8196):

	precision	recall	f1-score	support
00D	0.00	0.00	0.00	10000
In-Distribution	0.49	0.95	0.64	10000
			0.45	00000
accuracy			0.47	20000
macro avg	0.24	0.47	0.32	20000
weighted avg	0.24	0.47	0.32	20000



```
[27]: {'AUROC': np.float64(0.0),
```

'AUPR': np.float64(0.3068778611725624),

'FPR@95': np.float64(1.0)}

[28]: evaluate\_ood\_detection(modelA, eval\_loader, ood\_cifar10)
evaluate\_ood\_detection(modelB, eval\_loader, ood\_cifar10)
evaluate\_ood\_detection(nokl\_model, eval\_loader, ood\_cifar10)

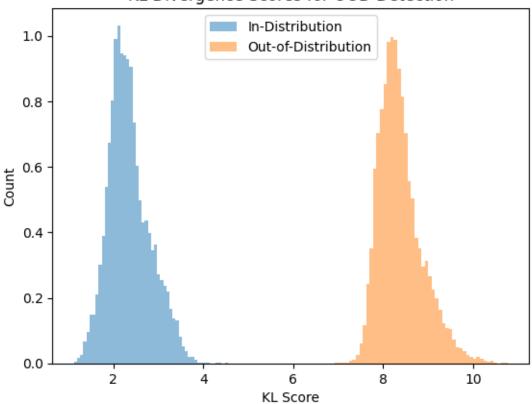
OOD Detection Performance:

AUROC: 1.0000 AUPR: 1.0000 FPR@95: 0.0000

Classification Report (Threshold = -3.2196):

	precision	recall	f1-score	support
00D In-Distribution	0.95 1.00	1.00 0.95	0.98 0.97	10000 10000
accuracy			0.97	20000

macro avg	0.98	0.97	0.97	20000
weighted avg	0.98	0.97	0.97	20000

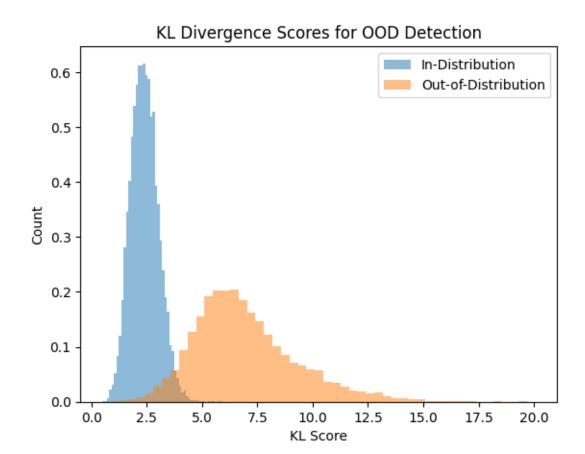


### OOD Detection Performance:

AUROC: 0.9897 AUPR: 0.9835 FPR@95: 0.0331

## Classification Report (Threshold = -3.4704):

	precision	recall	f1-score	support
OOD	0.95	0.97	0.96	10000
In-Distribution	0.97	0.95	0.96	10000
accuracy			0.96	20000
macro avg	0.96	0.96	0.96	20000
weighted avg	0.96	0.96	0.96	20000



### OOD Detection Performance:

AUROC: 0.0000 AUPR: 0.3069 FPR@95: 1.0000

## Classification Report (Threshold = -85.8196):

	precision	recall	f1-score	support
00D	0.00	0.00	0.00	10000
In-Distribution	0.49	0.95	0.64	10000
0.001170.017			0.47	20000
accuracy			0.47	20000
macro avg	0.24	0.47	0.32	20000
weighted avg	0.24	0.47	0.32	20000

