

Delivery Drone Route Optimization Using Genetic Algorithm

- **What is the Genetic Algorithm?**

A GA is an optimization technique inspired by the principles of natural selection, and genetics.

Main Idea:

- **Population Initialization:** start with many random routes.
- **Fitness Evaluation:** measure how good each route.
- **Selection:** pick better routes to reproduce.
- **Crossover:** combine two routes to produce new ones.
- **Mutation:** randomly alter parts of a route.
- **Generation Loop:** repeat to improve solutions over time.

- **Why Use Genetic in the Drone Delivery Problem?**

- Efficiently finds near-optimal routes among many possible paths.
- Handles complex and nonlinear constraints, such as distance limits or multiple delivery points.
- Mutation and crossover allow the algorithm to explore diverse solutions and avoid getting stuck in poor routes.

- **Python Implementation**

```

import random

# Example list of delivery points
delivery_points = ['A', 'B', 'C', 'D', 'E', 'F']
# Example distance matrix (dictionary of distances)
distance = {
    ('A', 'B'): 2, ('A', 'C'): 4, ('A', 'D'): 7, ('A', 'E'): 3, ('A', 'F'): 5,
    ('B', 'C'): 1, ('B', 'D'): 5, ('B', 'E'): 6, ('B', 'F'): 4,
    ('C', 'D'): 8, ('C', 'E'): 2, ('C', 'F'): 3,
    ('D', 'E'): 4, ('D', 'F'): 6,
    ('E', 'F'): 2,
}
# Make symmetric, means distance of A,b = distance of b,a
for (u,v),d in list(distance.items()):
    distance[(v,u)] = d

# Fitness: total route distance (lower is better)
def compute_distance(route):
    total = 0
    for i in range(len(route) - 1):
        total += distance[(route[i], route[i+1])] ## add distance between current and next point
    return total

# Generate initial random population
def create_population(size):
    return [random.sample(delivery_points, len(delivery_points)) for _ in range(size)]


# Selection (tournament)
def select(pop, fitnesses):
    selected = []
    for _ in range(len(pop)):
        i, j = random.sample(range(len(pop)), 2)
        selected.append(pop[i] if fitnesses[i] < fitnesses[j] else pop[j])
    return selected


# Crossover (ordered)
def crossover(parent1, parent2):
    size = len(parent1)
    start, end = sorted(random.sample(range(size), 2))
    child = parent1[start:end]
    for gene in parent2:
        if gene not in child:
            child.append(gene)
    return child


# Mutation: swap two points
def mutate(route, rate=0.1):
    r = route.copy()
    for i in range(len(r)):
        if random.random() < rate:
            j = random.randrange(len(r))
            r[i], r[j] = r[j], r[i]
    return r

```

```

# GA main loop
def genetic_algorithm(generations=100, pop_size=50):
    pop = create_population(pop_size)
    for gen in range(generations):
        fitnesses = [compute_distance(r) for r in pop]
        parents = select(pop, fitnesses)
        next_pop = []
        for i in range(0, len(parents), 2):
            p1, p2 = parents[i], parents[(i+1)%len(parents)]
            child1 = crossover(p1, p2)
            child2 = crossover(p2, p1)
            next_pop += [mutate(child1), mutate(child2)]
        pop = next_pop

    best = min(pop, key=compute_distance)
    return best, compute_distance(best)

best_route, best_dist = genetic_algorithm()
print("Best Route:", best_route)
print("Distance:", best_dist)

```

- **Output**

```

... Best Route: ['A', 'B', 'C', 'F', 'E', 'D']
Distance: 12

```

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- GA efficiently reached all delivery points efficiently.
- The path is optimal.
- GA minimizes total route distance.

- **Advantages of Using a GA for Drone Delivery**

- Produces shorter routes than simple search methods.
- Explores multiple solutions simultaneously.
- Handles large and complex search spaces.
- Flexible for multi-objective problems.

- **Limitations**
 - GA doesn't guarantee a mathematically optimal solution.
 - GA uses more resources (time and memory) than simpler algorithms like DFS.
 - Parameter selection (population size, mutation rate) is critical, which means poor choices may reduce performance or prevent convergence.

- **Genetic Algorithm (GA) Evaluation Metrics**

1. Execution Time

GA may take longer than simple search algorithms because it evaluates many solutions over multiple generations.

2. Memory Usage

Stores the population and fitness values; memory grows with population size and number of delivery points.

3. Success Rate

GA reliably finds a feasible route that visits all delivery points. Mutation and crossover help explore diverse solutions and avoid getting stuck.

4. Solution Optimality

GA produces near optimal or optimal routes, minimizing total distance or cost.

5. Scalability

By adjusting population size and number of generations, it can handle more delivery points without exploring unnecessary paths.