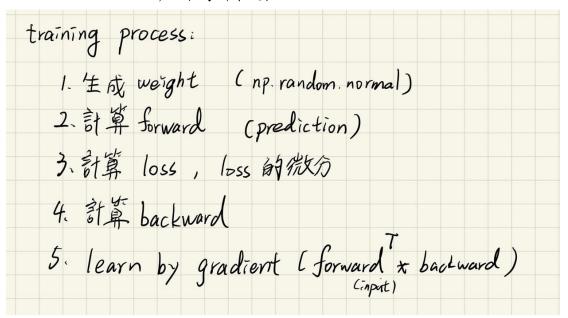
### 1. Introduction

此次 lab 實作 neural network ,data 使用的是自己生成的(inputs, label) pair,code 中只使用 numpy 套件計算矩陣以及 matplotlib 來畫圖,neural network 實作 backpropagation 計算 gradient 拿來更新各個 layer 的 weight,以使機器學習更接近 ground truth 的知識,neural network 以及 layer 各自透過 class 來實作,其中因為要計算 gradient,所以需要使用微分後的 activation function 和 weight 以及 forward 的資訊來計算 backward derivative,以下為訓練流程



### 2. Experiments setups

### A. Sigmoid functions

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

$$\frac{d}{dx}\sigma(x) = \frac{e^{-x}}{(1+e^{-x})^2} = (1-\sigma(x))*\sigma(x)$$

### B. Neural network

```
class NeuralNetwork:
    def __init__(self,epoch, learning_rate, layers, inputs, hidden_units, activation, optimizer):
    def forward(self, inputs): ...

    def backward(self, loss_derivative): ...

    def learn(self): ...

    def train(self, inputs, ground_truth): ...
```

如圖, neural network 當中有實作 forward, backward, learn, 以及 train 等的 functions, 而 train 則會在每個 epoch(掃過一次所有資料)去做 Introduction 中圖片的 training process

其中最核心的部分其實是實作 layer 的部分

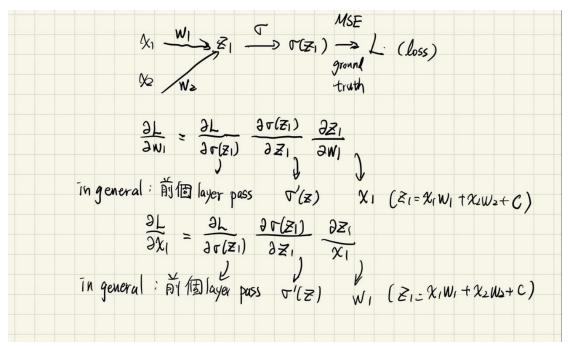
```
class Layer:
    def __init__(self, input_num, output_num, activation , optimizer , learning_rate ):
    def forward_pass(self, inputs): ...
    def backward_pass(self, inputs): ...
    def learn(self): ...
```

其中會根據 input size, output size 生成 random 的 weight, 以及實作 forward pass, backward pass 的計算, learn 的部分則是根據計算出來的 gradient 去進行梯度下降的學習(gradient descent)

### C. Backpropagation

```
def backward_pass(self, inputs):
    self.backward_output = None
    if self.activation == 'sigmoid':
        self.backward_output = np.multiply(derivative_sigmoid(self.forward_output),inputs)
    return np.matmul(self.backward_output, self.weight[:-1].T)
```

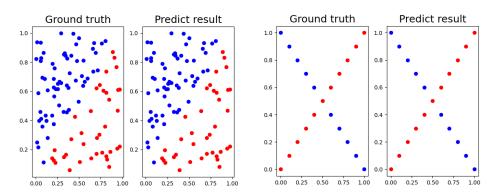
Backward pass 的部分會先將 pass 過來的 input(derivative loss)跟 sigmoid 之微分相乘(elementwise), 並且乘上 weight 再往前傳, 以下為推導圖



因此, 若不是 input layer, 則乘上 weight 的矩陣並將結果往前傳, 若是的話則乘上 input 的 vector 就會是 input layer 的 weight

### 3. Result of your testing

A. Screenshot and comparison figure (left is linear, right is XOR)



### B. Show the accuracy of your prediction

### Linear:

Accuracy: 1.0

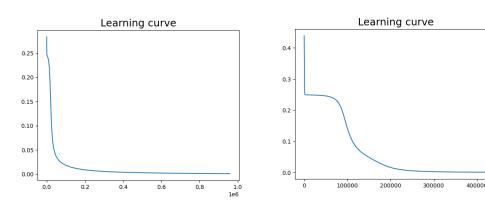
### XOR:

### Accuracy: 1.0

兩個預測準確度都是 100%

### C. Learning Curve

(left is linear, right is XOR)

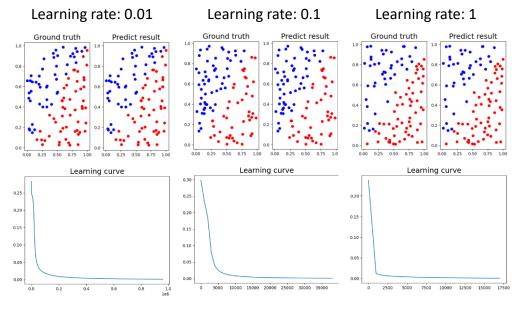


可以觀察到, linear 的 learning curve 是較為平滑的

### 4. Discussion

# A. Try different learning rates

(linear):



Learning rate: 0.01

Learning rate: 0.1

Learning rate: 0.1

Learning rate: 1

Ground truth

Predict result

Output

Description

Fredict result

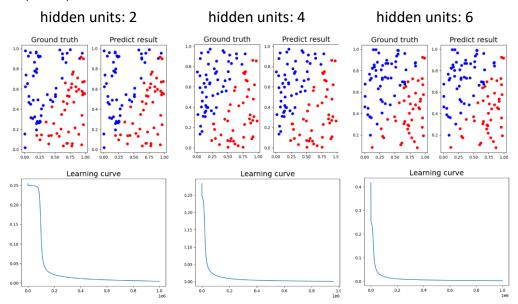
Output

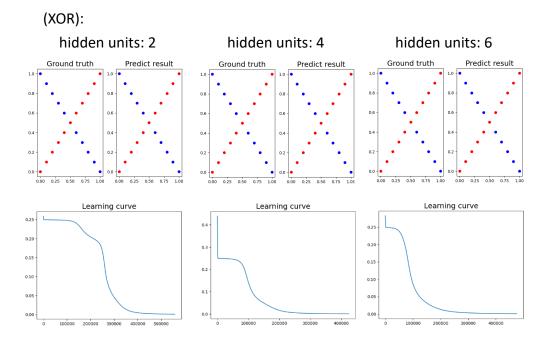
Description

Descrip

從上面的實驗可以得知, learning rate 越高不一定代表 loss 收斂的越快, XOR 在 0.1 和 0.01 時的表現其實差不多, 甚至 0.1 更差一點

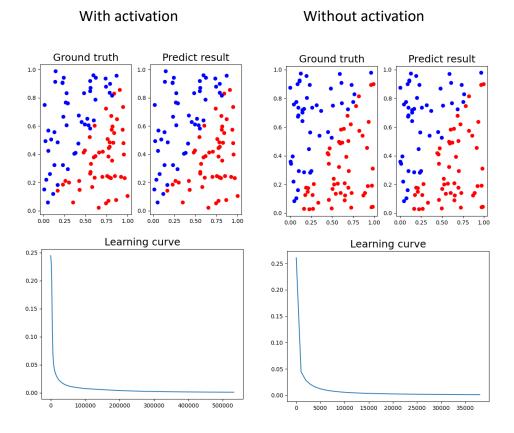
B. Try different numbers of hidden units (learning rate = 0.01) (linear):





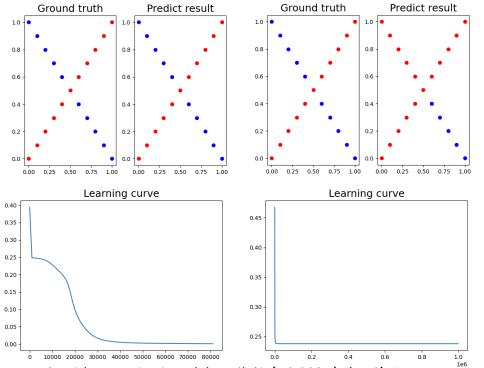
由以上實驗可得知, hidden unit 也不一定是越多越好, 反而可能造成模型過於複雜並造成 loss 較高(觀察 linear 的例子)

C. Try without activation functions (learning rate =0.05, hidden unit =4) (linear)



以上兩者 accuracy 皆為 1.0 但 with activation function 的收斂的比較慢

### Without activation



以上 without activation 的 loss 收斂在 0.238 左右, 並且 Accuracy 只有 0.761, 左上角的資料預測錯誤

### 5. Extra

### A. Implement different optimizer

### a. Momentum

模擬物理中動量的概念, 在同方向上的維度學習的速度會變快, 方向改變的時候學習速度會變慢

以下為 momentum optimizer 更新公式

$$V_t \leftarrow \beta V_{t-1} - \eta \frac{\partial L}{\partial W}$$

$$W_t \leftarrow W_{t-1} + V_t$$

其中,

 $V_t$   $\not$ amomentum,

β可以想像成空氣阻力或是地面摩擦力,通常設定成 0.9,

η 為learning rate,

L 為 loss function,

W為 weight 權重

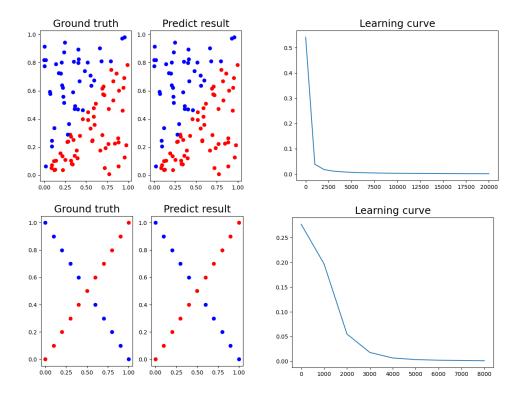
### Implementation:

In Layer constructor, set momentum to 0

```
self.momentum = 0
```

in Layer.learn(), implement momentum algorithm

Result and Learning curve (learning rate = 0.05, hidden units =4, layers
 =2, activation = 'sigmoid')



### b. Adagrad

AdaGrad 就會依照梯度去調整 learning rate, 公式為以下

$$W \leftarrow W - \eta \frac{1}{\sqrt{n+\varepsilon}} \frac{\partial L}{\partial W}$$

$$n = \sum_{r=1}^{t} \left( \frac{\partial L_r}{\partial W_r} \right)^2$$

ε為了使分母不為 0 通常設為 1e-8

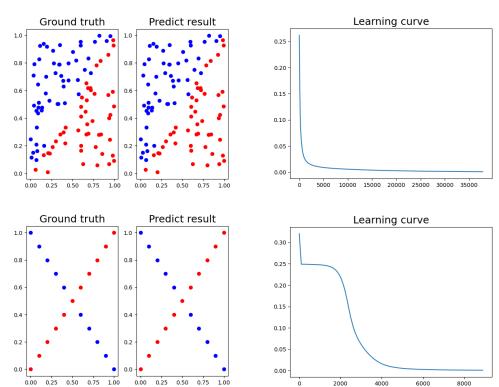
implementation:

In layer constructor, set n = 0

```
self.n = 0
```

in Layer.learn(), implement Adagrad algorithm

Result and Learning curve (learning rate = 0.05, hidden units =4, layers =2, activation = 'sigmoid')



### B. Implement different activation functions

a. implementations

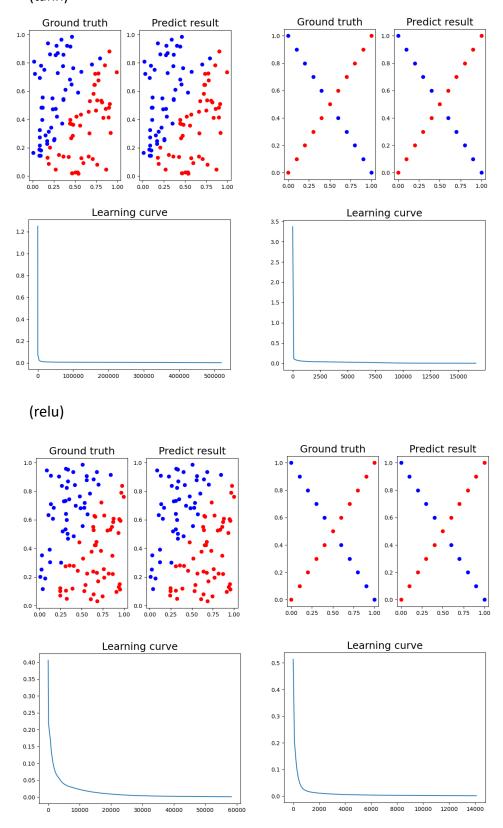
```
def tanh(x):
    return np.tanh(x)
def derivative_tanh(x):
    return 1.0 - x**2
def relu(x):
   return np.maximum(0.0, x)
def derivative_relu(x):
    return np.heaviside(x, 0.0)
def leaky_relu(x):
   alpha = 0.005
   return np.maximum(alpha * x, x)
def derivative_leaky_relu(x):
   alpha = 0.005
   y = copy.deepcopy(x);
   y[y > 0.0] = 1.0
   y[y <= 0.0] = alpha
   return y
```

- $tanh(x) = \frac{e^x e^x}{e^x + e^x}$
- $\bullet \ \frac{d}{dx} tanh(x) \ = \ \frac{(e^x + e^{-x})(e^x e^{-x}) (e^x e^{-x})(e^x e^{-x})}{(e^x + e^{-x})^2} \ = \ 1 \frac{(e^x e^{-x})^2}{(e^x + e^{-x})^2} \ = \ 1 tanh^2(x)$
- ReLu(x) = max(x, 0)
- $\bullet \ \, \frac{d}{dx} ReLu(x) \, = \, \begin{cases} 0 \text{ if } x \, < 0 \\ 0 \text{ if } x \, = = \, 0 \text{, by definition in numpy document, it is equivalent} \\ 1 \text{ if } x \, > \, 0 \end{cases}$

to np.heaviside(x,0)

- leaky\_ReLu(x) =  $max(\alpha x, x)$ , where  $\alpha$  is a small number, we set it 0.005 there
- $\frac{d}{dx}$  leaky\_ReLu(x) =  $\begin{cases} \alpha \text{ if } x < 0 \\ \alpha \text{ if } x == 0, \text{ then we can define it as above} \\ 1 \text{ if } x > 0 \end{cases}$

# b. 實驗(optimizer = 'gd', learning rate = 0.05) (tanh)



## (leaky\_relu)

