

「彩色影像處理」期末作業

一、 題目

自行選用十二幅以上交通號誌的影像，撰寫能夠根據輸入影像(query image)自動辨識的程式。

二、 程式註解

建database程式:

```
#include <cv.h>
#include <highgui.h>
#include <stdio.h>
#include <math.h>
#include <iostream>
#include <stdlib.h>
#include <fstream>
using namespace cv;
using namespace std;

int main(int argc, char *argv[])
{
    char *input = argv[1]; //讀入輸入檔名
    char *output = argv[2]; //讀入輸出檔名
    if (argc != 3)
    {
        cerr << "<exe> <input-file> <out-file>" << endl;
        return EXIT_FAILURE;
    }
    Mat image = imread(input, CV_LOAD_IMAGE_COLOR); //讀入照片
    ofstream PupartionInfo;
    PupartionInfo.open("image_data.txt", ios::app); //開啟一個txt檔，便於將參數書出建data base
    int cols = image.cols; //width
    int rows = image.rows; //height
    double meanR, meanG, meanB;
    int i, j, m, l;
    int part = 8; //將影像切割列跟行分別成8等份
```

```

for (j = 0; j < cols; j = j + cols / part)//垂直切
{
    //for (i = 0; i < rows; i++)
    {
        meanR = 0;
        meanG = 0;
        meanB = 0;
        for (m = 0; m < cols / part; m++)
        {
            for (l = 0; l < rows; l++)
            {
                if ((j + m) < cols)
                {
                    meanR += (double)image.at<Vec3b>(l, j + m)[0] / (cols / part) /
rows;

                    meanG += (double)image.at<Vec3b>(l, j + m)[1] / (cols / part) /
rows;

                    meanB += (double)image.at<Vec3b>(l, j + m)[2] / (cols / part) /
rows;

                }
            }
        }
        PupartionInfo << (double)meanR << " " << (double)meanG << " " <<
(double)meanB << " ";//輸出平均值到 txt 檔
        PupartionInfo << "\n";
    }
}

```

```

//for (j = 0; j < cols; j++)//水平切
{
    for (i = 0; i < rows; i = i + rows / part)
    {
        meanR = 0;
        meanG = 0;
        meanB = 0;
        for (m = 0; m < cols; m++)

```

```

        {
            for (l = 0; l < rows / part; l++)
            {
                if ((i + l) < rows)
                {
                    meanR += (double)image.at<Vec3b>(l + i, m)[0] / (cols / part) /
rows;

                    meanG += (double)image.at<Vec3b>(l, m)[1] / (cols / part) / rows;
                    meanB += (double)image.at<Vec3b>(l, m)[2] / (cols / part) / rows;
                }
            }
        }

        PupartionInfo << (double)meanR << " " << (double)meanG << " " <<
(double)meanB << " ";//輸出平均值到 txt 檔

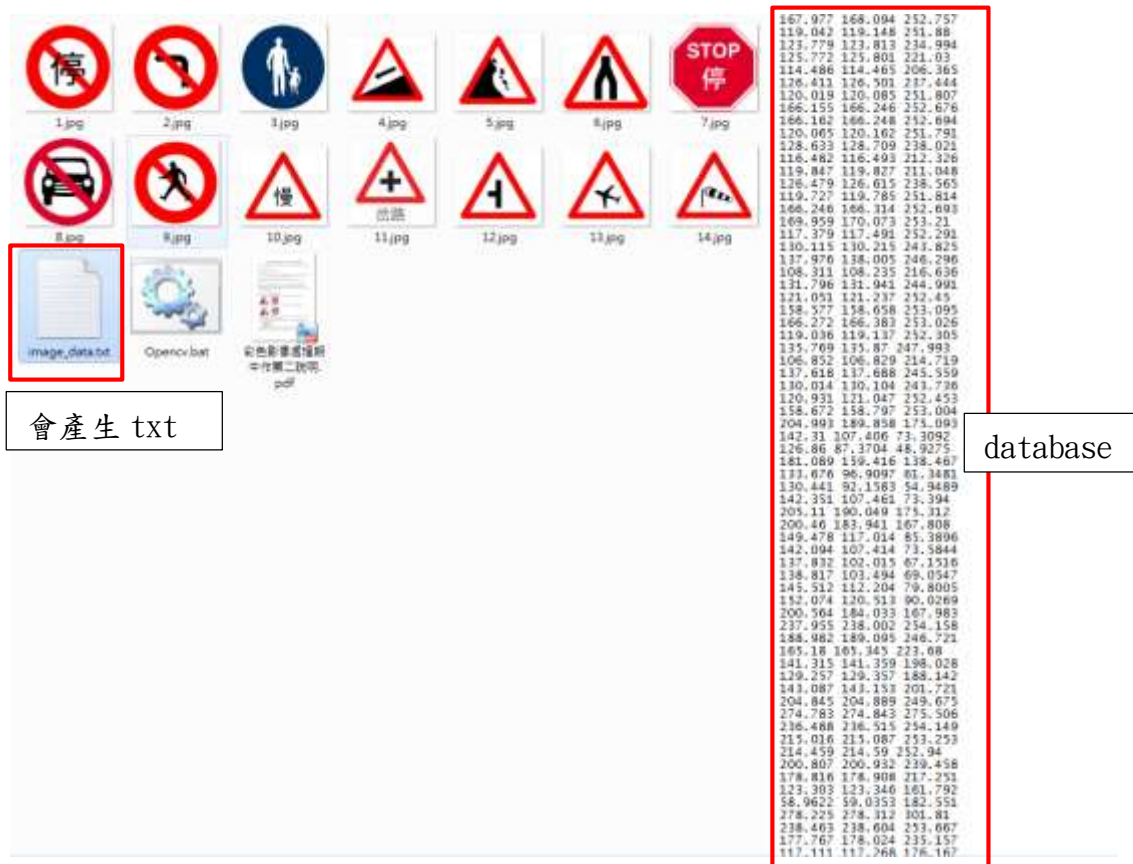
        PupartionInfo << "\n";
    }
}

PupartionInfo.close();

system("pause");
return 0;

```

三、執行成果影像範例



找出最相似的五張號誌圖片程式碼

```
#include <stdio.h>
#include <math.h>
#include <iostream>
#include <stdlib.h>
#include <fstream>
#include <opencv2/core/core.hpp>
#include <opencv2/highgui/highgui.hpp>
using namespace cv;
using namespace std;
char filename[100];
char windowname[100];

int main(int argc, char *argv[])
{

    ifstream in("image_data.txt");//讀取 database
    double s;
    double Control_Group[1000];
    int i = 0;
    if (!in.is_open())
    {
        cout << "Error opening file"; exit(1);
    }
    while (!in.eof())
    {
        while (in >> s)
        {
            Control_Group[i] = s;
            i++;
        }
    }
    Mat image = imread("13.jpg", CV_LOAD_IMAGE_COLOR);//讀取比較圖片
    cvNamedWindow("原圖", 0);
    imshow("原圖", image);
```

```

int cols = image.cols;//width
int rows = image.rows;//height
//printf("%d,%d", cols, rows);
double meanR, meanG, meanB;
int j, m, l;
int part;
part = 8;
double data[100];

int p = 0;

for (j = 0; j < cols; j = j + cols / part)//垂直切-1
{
    //for (i = 0; i < rows; i++)
    {
        meanR = 0;
        meanG = 0;
        meanB = 0;
        for (m = 0; m < cols / part; m++)
        {
            for (l = 0; l < rows; l++)
            {
                if ((j + m) < cols)
                {
                    meanR += (double)image.at<Vec3b>(l, j + m)[0] /
(cols / part) / rows;
                    meanG += (double)image.at<Vec3b>(l, j + m)[1] /
(cols / part) / rows;
                    meanB += (double)image.at<Vec3b>(l, j + m)[2] /
(cols / part) / rows;
                }
            }
        }
        data[p] = meanR;
        data[p+1] = meanG;
        data[p+2] = meanB;
        p = p + 3;
    }
}

```

```

    }

    //for (j = 0; j < cols; j++)//水平切-1
    {
        for (i = 0; i < rows; i = i + rows / part)
        {
            meanR = 0;
            meanG = 0;
            meanB = 0;
            for (m = 0; m < cols; m++)
            {
                for (l = 0; l < rows / part; l++)
                {
                    if ((i + l) < rows)
                    {
                        meanR += (double)image.at<Vec3b>(l+i, m)[0] /
(cols / part) / rows;
                        meanG += (double)image.at<Vec3b>(l, m)[1] / (cols
/ part) / rows;
                        meanB += (double)image.at<Vec3b>(l, m)[2] / (cols
/ part) / rows;
                    }
                }
            }
            data[p] = meanR;
            data[p + 1] = meanG;
            data[p + 2] = meanB;
            p = p + 3;
        }
    }

    double min = 100000;
    double difference;
    double d[12];
    int num[12];
    int n = 0;

```

```

for (int s = 0; s < 12; s++)//算圖片與 database 的差異
{
    difference = 0;
    for (i = 0; i < 48; i++)
    {
        difference = double(difference + fabs(data[i] -
Control_Group[n]));
        /*cout << difference << " " << data[i] << " " <<
Control_Group[n] << " ";*/
        n++;
    }
    d[s] = difference;
    num[s] = s+1;
}

for (int n = 11; n > 0; n--)//泡沫排序法，由小到大
{
    for (int m = 0; m < n; m++)
    {
        if (d[m] > d[m + 1])
        {
            int h;
            h = d[m];
            d[m] = d[m + 1];
            d[m + 1] = h;

            int h0;
            h0 = num[m];
            num[m] = num[m + 1];
            num[m + 1] = h0;
        }
    }
}

for (int i = 0; i < 5; i++)//展現差異最小前五名的圖片
{

```



```
    int a = num[i];  
    sprintf(filename, "%d.jpg", a);  
    sprintf(windowname, "圖片%d 排名%d", a, i+1);  
    IplImage* pScr = cvLoadImage(filename, 1);  
    cvNamedWindow(windowname, 0);  
    cvResizeWindow(windowname, 300, 300);  
    cvShowImage(windowname, pScr);  
  
}  
  
waitKey(0);  
  
return 0;  
}
```

四、執行成果影像範例

資料庫圖片如下：



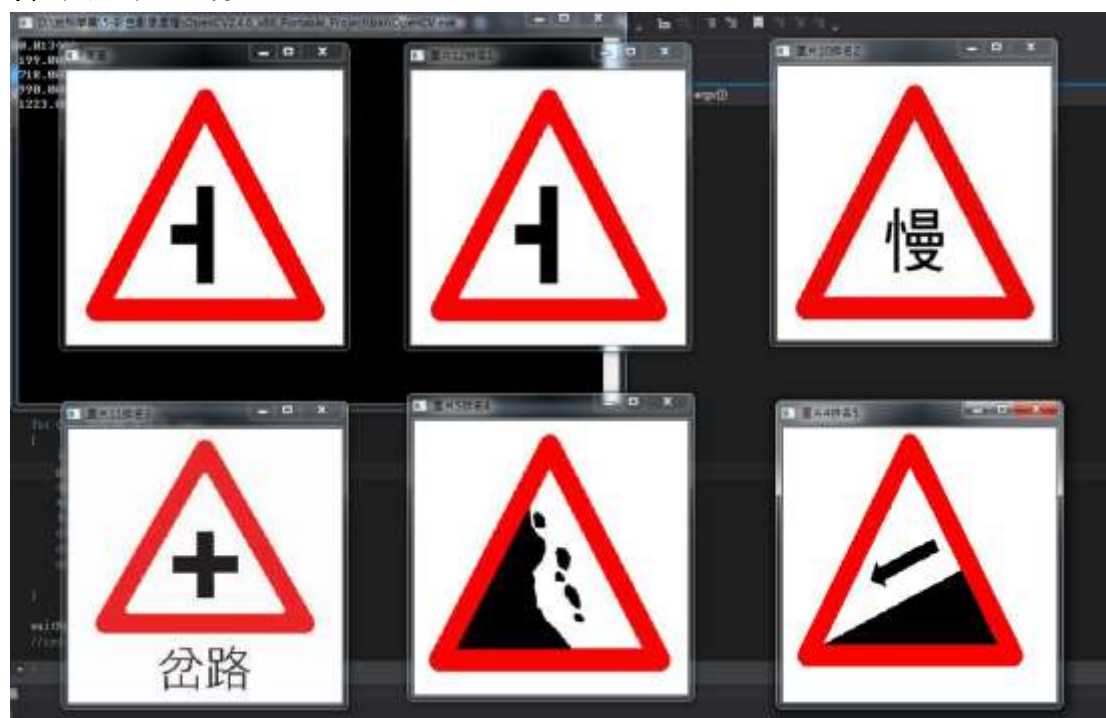
示意圖：

程式執行結果:左圖為輸入影像，下圖為前五名圖片。



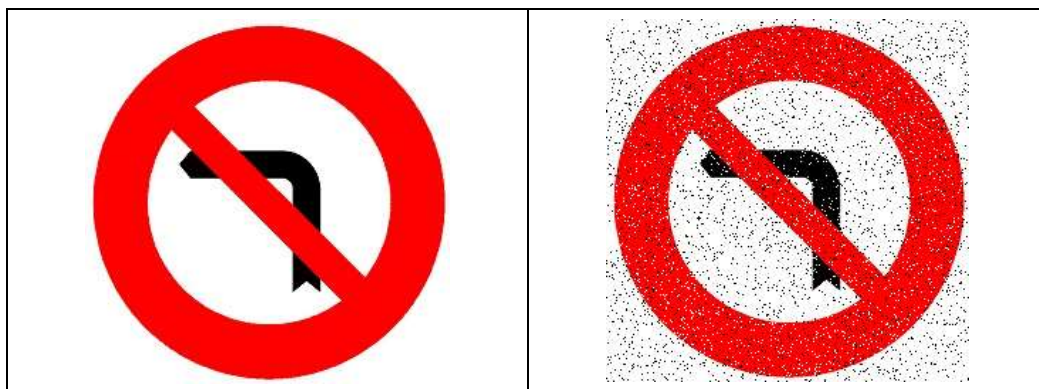
				 岔路					
差異度	0.013	差異度	199	差異度	718	差異度	990	差異度	1233

實際執行程式畫面



示意圖

程式執行結果:左圖為輸入影像，右圖為輸入雜訊，下圖為前五名圖片。



				
差異度 248	差異度 347	差異度 475	差異度 1064	差異度 1303

實際執行程式畫面



示意圖

程式執行結果:左圖為輸入影像,右圖為平均值濾波,下圖為前五名圖片。




									
									
差異度	43	差異度	272	差異度	293	差異度	1164	差異度	1294

實際執行程式畫面



示意圖

程式執行結果:左圖為輸入影像，右圖為偏色影像，下圖為前五名圖片。

									
									
差異度	1275	差異度	3251	差異度	3335	差異度	3382	差異度	3509

實際執行程式畫面

