

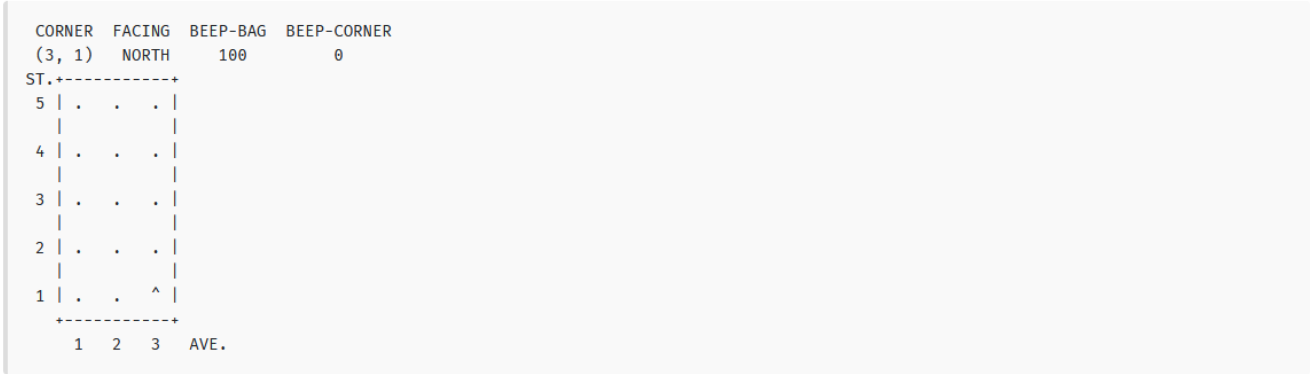
## Task 5: Picture frame

Robot Karel was given the task to frame the picture. This can be achieved by the robot marking all four boundary walls of the world. In addition, after completing the task, Karel moves to the center of the world.

When uploading your program, use in the function `turn_on()`map name `task_5.kw`.

### Initial situation

Robot Karel starts at any position, turned at will, and has a sufficient number of marks in his backpack. The dimensions of the world are always odd, the smallest size of the world is 3x3.



### The end situation

Charles ends in the middle of the world, facing north. The borders of the world are marked.

