For office use only	Team Control Number	For office use only
T1	2012050	F1
T2	Problem Chosen	F2
T3	1 foblem Chosen	F3
T4	$oldsymbol{A}$	F4
	* *	

### 2020 MCM/ICM Summary Sheet

# An MCM Paper Made by Team 2012050

Here is the abstract of your paper. Firstly, that is ...
Secondly, that is ...
Thirdly, that is ...
Finally, that is ...

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## 1 Introduction

## 1.1 Problem Background

Here is the problem background [1] ...

Two major problems are discussed in this paper, which are:

- Doing the first thing.
- Doing the second thing.

### 1.2 Literature Review

A literatrue say something about this problem ...

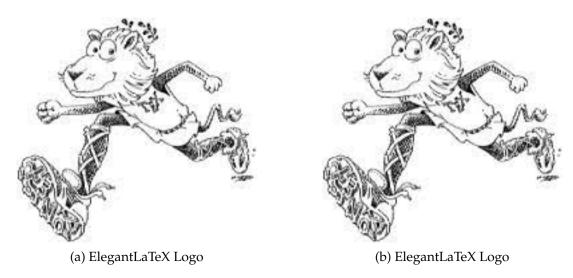


Figure 1: ElegantLaTeX Logo

Figure 1 is the logo of the Tex.



Figure 2: logo

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### 1.3 Our work

We do such things [2] ...

- **1.** We do ...
- **2.** We do ...
- **3.** We do ...

# 2 Preparation of the Models

## 2.1 Assumptions

### 2.2 Notations

The primary notations used in this paper are listed in **Table 1**.

Table 1: Notations

Symbol	Definition	Unit
A	the first one	cm
b	the second one	cm
$\alpha$	the last one	cm

## 3 The Models

### 3.1 Model 1

### 3.1.1 Detail 1 about Model 1

$$e^{i\theta} = \cos\theta + i\sin\theta. \tag{1}$$

$$\iiint_D \mathrm{d}f = \max_D g \tag{2}$$

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```
Algorithm 1: GF(4) 3D reconstruction
     Input: \mathcal{X} \in \mathbb{R}^{l_1 \times l_2 \times l_3}, K_c, K_p, R, T
      Output: Coord_{i,i}
 1 Initialize all G\tilde{F}^{(i,j)}s
 2 for each X_{i_j}^k(N_0 \le i \le N_1, M_0 \le j \le M_1, k \in (r, g, b)) do 3 d = \max(|\sum_{i=-\epsilon}^{\epsilon} I(x^k + i, y^k) - \sum_{j=-\epsilon}^{\epsilon} I(x^k, y^k + j)|);
             if d > t then
  4
                 C_{ij} = -1
  5
             else
  6
                  Candidate_{ij} = -3
 s for each Candidate_{i,i}^k(N_0 \leq i \leq N_1, M_0 \leq j \leq M_1) do
             \begin{array}{c} \overline{\textbf{if } Candidate_{ij} == -1 \textbf{ then}} \\ \rho_C = \frac{n \sum_{i=1}^n M_{Ci} M_{Ci'} - \sum_{i=1}^n M_{Ci} \sum_{i=1}^n M_{Ci'}}{\sqrt{n \sum_{i=1}^n M_{Ci}^2 - (\sum_{i=1}^n M_{Ci})^2} \sqrt{n \sum_{i=1}^n M_{Ci'}^2 - (\sum_{i=1}^n M_{Ci'})^2}}; \end{array} 
10
                    if \rho_C > t then
11
                      \boxed{GridPoint_{ij} = -1}
12
13 for each GridPoint_{i,i}^k(N_0 \leq i \leq N_1, M_0 \leq j \leq M_1) do
             FeaturePoint_{i,j} = BFS(GridPoint_{i,j}, FLAG);
14
            \begin{array}{l} \textbf{if} \ \underline{FeaturePoint_{i,j} == -1} \ \textbf{then} \\ | \ \underline{\textbf{if}} \ \underline{\sum_{i=-\epsilon}^{\epsilon} I(x^k+i,y^k) - \sum_{j=-\epsilon}^{\epsilon} I(x^k,y^k+j) > 0} \ \textbf{then} \\ | \ \underline{FeaturePoint_{i,j} = -1} \end{array}
15
16
17
                    else
18
                       FeaturePoint_{i,j} = -2
19
20 for each FeaturePoint_{i}^{k}(N_{0} \leq i \leq N_{1}, M_{0} \leq j \leq M_{1}) do
             if FeaturePoint_{i,j} \neq -1 and FeaturePoint_{i,j} \neq -2 then
                    s = \sqrt{1 - \frac{rg + gb + rb}{r^2 + g^2 + b^2}};
h_r = \frac{2r - g - b}{2\sqrt{(r - g)^2 + (r - b)(g - b)}};
h_g = \frac{2g - r - b}{2\sqrt{(g - r)^2 + (g - b)(r - b)}};
h_b = \frac{2b - g - r}{2\sqrt{(b - g)^2 + (b - r)(g - r)}};
22
23
24
25
                    k = s - \sqrt{1 - \max(h_r, h_g, h_b)} if k < 0.2 then
                      FeaturePoint_{i,j} = 0
27
                    else
28
                          FeaturePoint_{i,j} = \max(r, g, b)
     for each FeaturePoint_{i_i}^k(N_0 \le i \le N_1, M_0 \le j \le M_1) do
             if FeaturePoint_{i,j} == -1 or FeaturePoint_{i,j} == -2 then
31
                    (u_1 m_{31}^1 - m_{11}^1) X_W + (u_1 m_{32}^1 - m_{12}^1) Y_W + (u_1 m_{33}^1 - m_{13}^1) Z_W = m_{14}^1 - u_1 m_{34}^1;
32
                     (v_1 m_{31}^1 - m_{21}^1) X_W + (v_1 m_{32}^1 - m_{22}^1) Y_W + (v_1 m_{33}^1 - m_{23}^1) Z_W = m_{24}^1 - v_1 m_{34}^1; 
 (u_1 m_{31}^2 - m_{11}^2) X_W + (u_1 m_{32}^2 - m_{12}^2) Y_W + (u_1 m_{33}^2 - m_{13}^2) Z_W = m_{14}^2 - u_1 m_{34}^2; 
33
34
```

 $Coord_{i,j} = (X_W, Y_W, Z_W)$ 

35

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## 4 Strengths and Weaknesses

## 4.1 Strengths

- First one...
- Second one ...

### 4.2 Weaknesses

• Only one ...

# References

- [1] Zhan Song and Chi Kit Ronald Chung. Determining both surface position and orientation in structured-light-based sensing. <u>IEEE Transactions on Pattern Analysis</u> & Machine Intelligence, 32(10):1770–1780, 2010.
- [2] Haibo Lin, Lei Nie, and Zhan Song. A single-shot structured light means by encoding both color and geometrical features. Pattern Recognition, 54:178–189.

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## Apendix: The source codes

This MATLAB program is used to calculate the value of variable a.

#### Program 1: temp.m

```
1  a = 0;
2  for i = 1:5
3     a = a + 1;
4  end
```

This LINGO program is used to search the optimize solution of 0-1 problem.

#### Program 2: temp.lg4

```
1 model:
2 sets:
3 WP/1..12/: M, W, X;
4 endsets
5 data:
6 M = 2 5 18 3 2 5 10 4 11 7 14 6;
7 W = 5 10 13 4 3 11 13 10 8 16 7 4;
8 enddata
9 max = @sum(WP:W*X);
10 @sum(WP: M * X) <= 46;
11 @for(WP: @bin(X));
12 end</pre>
```

#### Program 3: temp.py

```
1 employees = []
2 for id in employee_ids:
3    employee = fetch_employee(id)
4 if employee:
5    employees.append(employee)
```