

Chapter 3.3- Spanning Sets and Linear Independence

Learning Outcomes:

- Write a linear combination of a set of vectors in a vector space V .
- Determine whether a set S of vectors in a vector space V is a spanning set of V .
- Determine whether a set of vectors in a vector space V is linearly independent.

Definition of Linear Combination of Vectors

A vector \mathbf{v} in a vector space V is called a **linear combination** of the vectors $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ in V if \mathbf{v} can be written in the form

$$\mathbf{v} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \cdots + c_k \mathbf{u}_k$$

where c_1, c_2, \dots, c_k are scalars.

Examples:

a. For the set of vectors in \mathbf{R}^3 ,

$$S = \{(\overset{\mathbf{v}_1}{1}, \overset{\mathbf{v}_2}{3}, \overset{\mathbf{v}_3}{1}), (\overset{\mathbf{v}_2}{0}, \overset{\mathbf{v}_2}{1}, \overset{\mathbf{v}_3}{2}), (\overset{\mathbf{v}_3}{1}, \overset{\mathbf{v}_3}{0}, \overset{\mathbf{v}_3}{-5})\},$$

\mathbf{v}_1 is a linear combination of \mathbf{v}_2 and \mathbf{v}_3 since

$$\begin{aligned} \mathbf{v}_1 &= 3\mathbf{v}_2 + \mathbf{v}_3 = 3(0, 1, 2) + (1, 0, -5) \\ &= (1, 3, 1). \end{aligned}$$

Examples:

b. For the set of vectors in $M_{2,2}$,

$$S = \left\{ \overset{\mathbf{v}_1}{\begin{bmatrix} 0 & 8 \\ 2 & 1 \end{bmatrix}}, \overset{\mathbf{v}_2}{\begin{bmatrix} 0 & 2 \\ 1 & 0 \end{bmatrix}}, \overset{\mathbf{v}_3}{\begin{bmatrix} -1 & 3 \\ 1 & 2 \end{bmatrix}}, \overset{\mathbf{v}_4}{\begin{bmatrix} -2 & 0 \\ 1 & 3 \end{bmatrix}} \right\},$$

\mathbf{v}_1 is a linear combination of \mathbf{v}_2 , \mathbf{v}_3 and \mathbf{v}_4

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{v}_2 + 2\mathbf{v}_3 - \mathbf{v}_4 \\ &= \begin{bmatrix} 0 & 2 \\ 1 & 0 \end{bmatrix} + 2\begin{bmatrix} -1 & 3 \\ 1 & 2 \end{bmatrix} - \begin{bmatrix} -2 & 0 \\ 1 & 3 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 8 \\ 2 & 1 \end{bmatrix}. \end{aligned}$$

Finding a Linear Combination

1. Write the vector $\mathbf{w} = (1, 1, 1)$ as a linear combination of vectors in the set S .

$$S = \{(\overset{\mathbf{v}_1}{1}, \overset{\mathbf{v}_2}{2}, \overset{\mathbf{v}_3}{3}), (0, 1, 2), (-1, 0, 1)\}$$

$$\begin{aligned}(1, 1, 1) &= c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-1, 0, 1) \\ &= (c_1 - c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3).\end{aligned}$$

$$c_1 - c_3 = 1$$

$$2c_1 + c_2 = 1$$

$$3c_1 + 2c_2 + c_3 = 1$$

$$c_1 = 1 + t, \quad c_2 = -1 - 2t, \quad c_3 = t.$$

where t is any real number.

Thus, \mathbf{w} can be written as

$$\mathbf{w} = 2\mathbf{v}_1 - 3\mathbf{v}_2 + \mathbf{v}_3.$$

Finding a Linear Combination

2. Write the vector $\mathbf{w} = (1, -2, 2)$ as a linear combination of vectors in the set S .

$$S = \{(\overset{\mathbf{v}_1}{1}, \overset{\mathbf{v}_2}{2}, \overset{\mathbf{v}_3}{3}), (0, 1, 2), (-1, 0, 1)\}$$

$$\begin{aligned}(1, -2, 2) &= c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-1, 0, 1) \\ &= (c_1 - c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3).\end{aligned}$$

$$\begin{aligned}c_1 - c_3 &= 1 \\ 2c_1 + c_2 &= -2 \\ 3c_1 + 2c_2 + c_3 &= 2.\end{aligned}$$

The system has no solution.

Therefore, \mathbf{w} cannot be written as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

Spanning Sets

Definition:

Let $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ be a subset of a vector space V . The set S is called a **spanning set** of V if *every* vector in V can be written as a linear combination of vectors in S . In such cases it is said that S **spans** V .

Examples:

1. The set $S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ spans R^3 since any vector $\mathbf{u} = (u_1, u_2, u_3)$ in R^3 can be written as a linear combination of vectors in S , that is,

$$\mathbf{u} = u_1(1, 0, 0) + u_2(0, 1, 0) + u_3(0, 0, 1) = (u_1, u_2, u_3)$$

Spanning Sets

Examples:

2. The set $S = \{1, x, x^2\}$ spans P_2 (set of polynomials of degree 2 or less).

This is because any polynomial function

$p(x) = a + bx + cx^2$ in P_2 can be written as

$$\begin{aligned} p(x) &= a(1) + b(x) + c(x^2) \\ &= a + bx + cx^2. \end{aligned}$$

Note: The spanning sets in examples 1 and 2 are called the standard spanning sets of R^3 and P_2 , respectively.

More examples:

1. Show that set $S = \{(1, 2, 3), (0, 1, 2), (-2, 0, 1)\}$ spans R^3 .

Solution: Let $\mathbf{u} = (u_1, u_2, u_3)$ be *any* vector in R^3 . For S to span R^3 , there must be scalars c_1, c_2 and c_3 such that

$$(u_1, u_2, u_3) = c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-2, 0, 1)$$

$$= (c_1 - 2c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3).$$

$$c_1 - 2c_3 = u_1$$

$$2c_1 + c_2 = u_2$$

$$3c_1 + 2c_2 + c_3 = u_3.$$

It can be verified that the determinant of the coefficient matrix is nonzero, so the system has a unique solution. Thus, any vector in R^3 can be written as a linear combination of the vectors in S .

Therefore, the set S spans R^3 .

2. Does the set $S = \{(1, 2, 3), (0, 1, 2), (-1, 0, 1)\}$ span R^3 ?

Solution: For S to span R^3 , it must be that for any vector $\mathbf{u} = (u_1, u_2, u_3)$ in R^3 , there must be scalars c_1, c_2 and c_3 such that

$$\begin{aligned}(u_1, u_2, u_3) &= c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-1, 0, 1) \\ &= (c_1 - c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3).\end{aligned}$$

$$\begin{aligned}c_1 - c_3 &= u_1 \\ 2c_1 + c_2 &= u_2 \\ 3c_1 + 2c_2 + c_3 &= u_3.\end{aligned}$$

$\mathbf{w} = (1, 1, 2)$ is in R^3 and cannot be written as a linear combination of the vectors in S .

Therefore, the set S does not span R^3 .

Definition of the Span of a Set

If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is a set of vectors in a vector space V , then the **span of S** is the set of all linear combinations of the vectors in S ,

$$\text{span}(S) = \{c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k \mid c_1, c_2, \dots, c_k \text{ are real numbers}\}$$

The span of S is denoted by

$$\text{span}(S) \text{ or } \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}.$$

If $\text{span}(S) = V$, it is said that V is **spanned** by $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$, or that S **spans** V .

Theorem:

If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is a set of vectors in a vector space V , then $\text{span}(S)$ is a subspace of V . Moreover, $\text{span}(S)$ is the smallest subspace of V that contains S , in the sense that every other subspace of V that contains S must contain $\text{span}(S)$.

Proof:

Note that the zero vector is contained in $\text{span}(S)$, so $\text{span}(S)$ is nonempty. Now, we show that $\text{span}(S)$ is closed under addition and scalar multiplication.

Let \mathbf{u} and \mathbf{v} be in $\text{span}(S)$, that is,

$$\mathbf{u} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_k\mathbf{v}_k$$

$$\mathbf{v} = d_1\mathbf{v}_1 + d_2\mathbf{v}_2 + \cdots + d_k\mathbf{v}_k$$

where c_1, c_2, \dots, c_k and d_1, d_2, \dots, d_k are scalars.

Proof: (continuation)

Then

$$\mathbf{u} + \mathbf{v} = (c_1 + d_1)\mathbf{v}_1 + (c_2 + d_2)\mathbf{v}_2 + \cdots + (c_k + d_k)\mathbf{v}_k$$

and for any scalar c ,

$$c\mathbf{u} = (cc_1)\mathbf{v}_1 + (cc_2)\mathbf{v}_2 + \cdots + (cc_k)\mathbf{v}_k$$

These show that $\mathbf{u} + \mathbf{v}$ and $c\mathbf{u}$ can be written as linear combinations of vectors in S , hence, $\mathbf{u} + \mathbf{v}$ and $c\mathbf{u}$ are in $\text{span}(S)$. Thus, $\text{span}(S)$ is a subspace of V .

Linear Dependence and Linear Independence

Definition:

A set of vectors $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ in a vector space V is called **linearly independent** if the vector equation

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_k \mathbf{v}_k = \mathbf{0}$$

has only the trivial solution, $c_1 = 0, c_2 = 0, \dots, c_k = 0$.

If there are also nontrivial solutions, then S is called **linearly dependent**.

Examples:

- (a) The set $S = \{(1, 2), (2, 4)\}$ in R^2 is linearly dependent because
- $$-2(1, 2) + (2, 4) = (0, 0).$$

Linear Dependence and Linear Independence

Examples:

(b) The set $S = \{(1, 0), (0, 1), (-2, 5)\}$ in R^2 is linearly dependent because

$$2(1, 0) - 5(0, 1) + (-2, 5) = (0, 0).$$

(c) The set $S = \{(0, 0), (1, 2)\}$ in R^2 is linearly dependent because

$$1(0, 0) + 0(1, 2) = (0, 0).$$

Testing for Linear Dependence and Linear Independence

Let $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ be a set of vectors in a vector space V . To determine whether S is linearly independent or linearly dependent, perform the following steps.

1. From the vector equation $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k = \mathbf{0}$ write a homogeneous system of linear equations in the variables c_1, c_2, \dots , and c_k .
2. Use Gaussian elimination to determine whether the system has a unique solution.
3. If the system has only the trivial solution, then the set S is linearly independent. If the system also has nontrivial solutions, then S is linearly dependent.

Examples:

1. Determine whether the set of vectors in R^3 is linearly independent or linearly dependent.

$$\begin{array}{ccc} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \\ S = \{(1, 2, 3), (0, 1, 2), (-2, 0, 1)\} \end{array}$$

Find c_1, c_2 , and c_3 such that

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}.$$

$$c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-2, 0, 1) = (0, 0, 0)$$

$$(c_1 - 2c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3) = (0, 0, 0)$$

$$c_1 - 2c_3 = 0$$

$$2c_1 + c_2 = 0$$

$$3c_1 + 2c_2 + c_3 = 0$$

By Gaussian elimination, we can see that

$$c_1 = c_2 = c_3 = 0.$$

So, S is linearly independent.

Examples:

2. Determine whether the set of vectors in P_2 is linearly independent or linearly dependent.

$$S = \{\overset{\mathbf{v}_1}{1 + x - 2x^2}, \overset{\mathbf{v}_2}{2 + 5x - x^2}, \overset{\mathbf{v}_3}{x + x^2}\}$$

Solution: $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}.$

$$c_1(1 + x - 2x^2) + c_2(2 + 5x - x^2) + c_3(x + x^2) = 0 + 0x + 0x^2$$

$$(c_1 + 2c_2) + (c_1 + 5c_2 + c_3)x + (-2c_1 - c_2 + c_3)x^2 = 0 + 0x + 0x^2$$

$$\begin{array}{rcl} c_1 + 2c_2 & = & 0 \\ c_1 + 5c_2 + c_3 & = & 0 \\ -2c_1 - c_2 + c_3 & = & 0 \end{array} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 1 & 5 & 1 & 0 \\ -2 & -1 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Observe that the system has infinitely many solutions. So, S is linearly dependent.

Examples:

3. Determine whether the set of vectors in $M_{2,2}$ is linearly independent or linearly dependent.

$$S = \left\{ \overset{\mathbf{v}_1}{\begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}}, \overset{\mathbf{v}_2}{\begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix}}, \overset{\mathbf{v}_3}{\begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}} \right\}$$

Solution:

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3 = \mathbf{0}$$

$$c_1 \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} + c_2 \begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix} + c_3 \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{array}{rcl} 2c_1 + 3c_2 + c_3 & = & 0 \\ c_1 & = & 0 \\ 2c_2 + 2c_3 & = & 0 \\ c_1 + c_2 & = & 0 \end{array} \begin{bmatrix} 2 & 3 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 2 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

So, S is linearly independent.

Theorem:

A set $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$, $k \geq 2$, is linearly dependent if and only if at least one of the vectors \mathbf{v}_j can be written as a linear combination of the other vectors in S .

Examples:

$$\begin{array}{ccc} & \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \\ S = \{ & 1 + x - 2x^2, & 2 + 5x - x^2, & x + x^2 \} \end{array}$$
$$\begin{array}{lcl} c_1 + 2c_2 & = & 0 \\ c_1 + 5c_2 + c_3 & = & 0 \\ -2c_1 - c_2 + c_3 & = & 0 \end{array} \quad \Rightarrow \quad \mathbf{v}_2 = 2\mathbf{v}_1 + 3\mathbf{v}_3$$

Corollary:

Two vectors \mathbf{u} and \mathbf{v} in a vector space V are linearly dependent if and only if one is a scalar multiple of the other.

Examples:

1. The set

$$S = \{(1, 2, 0), (-2, 2, 1)\}$$

is linearly independent since \mathbf{v}_1 and \mathbf{v}_2 are not scalar multiples of each other.

2. The set

$$S = \{(4, -4, -2), (-2, 2, 1)\}$$

is linearly dependent since $\mathbf{v}_1 = -2\mathbf{v}_2$.

Assignment

1. Determine whether or not the set $S = \{(1, -2, 0), (0, 0, 1), (-1, 2, 0)\}$ spans R^3 . Justify your answer.
2. Given the matrices $A = \begin{bmatrix} 2 & -3 \\ 4 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 0 & 5 \\ 1 & -2 \end{bmatrix}$. Show that the matrix $C = \begin{bmatrix} 6 & -19 \\ 10 & 7 \end{bmatrix}$ is a linear combination of matrices A and B .
3. For which value/s of t is the set $S = \{(t, 1, 1), (1, 0, 1), (1, 1, 3t)\}$ linearly independent?

