Chapter 3.4 - Basis and Dimension



Learning Outcomes:

- Recognize bases in the vector spaces \mathbb{R}^n , \mathbb{R}_n , and $\mathbb{R}_{m,n}$.
- Find the dimension of a vector space.



Definition of Basis

A set of vectors $S = \{\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_n\}$ in a vector space V is called a **basis** for V if the following conditions are true: i. S spans V.

ii. S is linearly independent.

Standard Basis for *n*-space

The vectors

$$\mathbf{e}_1 = (1, 0, \dots, 0)$$
 $\mathbf{e}_2 = (0, 1, \dots, 0)$
 \vdots
 $\mathbf{e}_n = (0, 0, \dots, 1)$

form a basis for \mathbb{R}^n called the **standard basis** for \mathbb{R}^n .



Standard Basis for P_n

$$S = \{1, x, x^2, \dots, x^n\}$$

Standard Basis for vector space M_{mn}

-consists of the mn distinct $m \times n$ matrices having a single 1 and all the other entries equal to zero.



Examples:

1. Show that the following set is a basis for \mathbb{R}^3 .

$$S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$$

i. Since any vector in \mathbb{R}^3 can be written as a linear combination of vectors in S, that is,

$$\mathbf{u} = u_1(1, 0, 0) + u_2(0, 1, 0) + u_3(0, 0, 1) = (u_1, u_2, u_3).$$

Then, S spans R^3 .

ii. The vector equation

$$c_1(1,0,0) + c_2(0,1,0) + c_3(0,0,1) = (0,0,0)$$

has only the trivial solution $c_1 = c_2 = c_3 = 0$.

Thus, S is linearly independent.

Therefore, S is a basis for R^3 , and is called the standard basis for R^3 .



Examples:

2. Show that the set

$$S = \{(1, 1), (1, -1)\}$$

is a basis for \mathbb{R}^2 .

i. Show that S spans R^2 .

Let $\mathbf{x} = (x_1, x_2)$ be an arbitrary vector in \mathbb{R}^2 .

Show that \mathbf{x} can be written as a linear combination of \mathbf{v}_1 and \mathbf{v}_2 .

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 = \mathbf{x}$$

$$c_1(1, 1) + c_2(1, -1) = (x_1, x_2)$$

$$(c_1 + c_2, c_1 - c_2) = (x_1, x_2)$$

$$c_1 + c_2 = x_1$$

$$c_1 - c_2 = x_2$$

Since the system has nonzero determinant, then it has a unique solution. Hence, S spans \mathbb{R}^2 .



Examples:

ii. Show that S is linearly independent.

$$c_{1}\mathbf{v}_{1} + c_{2}\mathbf{v}_{2} = \mathbf{0}$$

$$c_{1}(1, 1) + c_{2}(1, -1) = (0, 0)$$

$$(c_{1} + c_{2}, c_{1} - c_{2}) = (0, 0).$$

$$c_{1} = c_{2} = 0$$

$$c_{1} + c_{2} = 0$$

Thus, S is linearly independent.

Therefore, S is a basis for R^2 .

3. The set

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

is a basis for $M_{2,2}$ and is called the **standard basis** for $M_{2,2}$.



Theorem: (Uniqueness of Basis Representation)

If $S = \{\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_n\}$ is a basis for a vector space V, then every vector in V can be written in one and only one way as a linear combination of vectors in S.

Example:

Let $\mathbf{u} = (u_1, u_2, u_3)$ be any vector in R^3 . Show that the equation $\mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3$ has a unique solution for the basis $S = {\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3} = {(1, 2, 3), (0, 1, 2), (-2, 0, 1)}$

Solution:

$$(u_1, u_2, u_3) = c_1(1, 2, 3) + c_2(0, 1, 2) + c_3(-2, 0, 1)$$

$$= (c_1 - 2c_3, 2c_1 + c_2, 3c_1 + 2c_2 + c_3),$$

$$c_1 - 2c_3 = u_1$$

$$2c_1 + c_2 = u_2$$

$$3c_1 + 2c_2 + c_3 = u_3$$



Theorem: (Bases and Linear Dependence)

If $S = \{\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_n\}$ is a basis for a vector space V, then every set containing more than n vectors in V is linearly dependent.

Theorem: (Number of Vectors in a Basis)

If a vector space V has one basis with n vectors, then every basis for V has n vectors.

Examples:

- (a) The set $S_1 = \{(3, 2, 1), (7, -1, 4)\}$ is not a basis for \mathbb{R}^3 .
- (b) The set

$$S_2 = \{x + 2, x^2, x^3 - 1, 3x + 1, x^2 - 2x + 3\}$$

is not a basis for P_3 .



Definition of Dimension of a Vector Space

If a vector space V has a basis consisting of n vectors, then the number n is called the **dimension** of V, denoted by $\dim(V) = n$. If V consists of the zero vector alone, the dimension of V is defined as zero.

- 1. The dimension of \mathbb{R}^n with the standard operations is n.
- 2. The dimension of P_n with the standard operations is n+1.
- 3. The dimension of $M_{m,n}$ with the standard operations is mn.



Note:

If W is a subspace of an n-dimensional vector space, then it can be shown that W is finite dimensional and the dimension of W is less than or equal to n.

Determining of the dimension of W is done by finding a set of linearly independent vectors that spans the subspace. This set is a basis for the subspace, and the dimension of the subspace is the number of vectors in the basis.



Finding the Dimension of a Subspace Examples:

- 1. Determine the dimension of each subspace of \mathbb{R}^3 .
 - (a) $W = \{(d, c-d, c) \mid c \text{ and } d \text{ are real numbers}\}$
 - (b) $W = \{(2b, b, 0) \mid b \text{ is a real number}\}$
- 2. Find the dimension of the subspace W of \mathbb{R}^4 spanned by \mathbf{v}_1 \mathbf{v}_2 \mathbf{v}_3

$$S = \{(-1, 2, 5, 0), (3, 0, 1, -2), (-5, 4, 9, 2)\}$$

3. Let W be the subspace of all symmetric matrices in $M_{2,2}$. What is the dimension of W?



Theorem: (Basis Tests in an n-Dimensional Space)

Let V be a vector space of dimension n.

- 1. If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a linearly independent set of vectors in V, then S is a basis for V.
- 2. If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ spans V, then S is a basis for V.

Example: Show that the set of vectors is a basis for $M_{5,1}$.

$$S = \left\{ \begin{bmatrix} 1\\2\\-1\\3\\4 \end{bmatrix}, \begin{bmatrix} 0\\1\\3\\-2\\3 \end{bmatrix}, \begin{bmatrix} 0\\0\\2\\-1\\5 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\0\\-2 \end{bmatrix} \right\}$$



Exercise:

- 1. Show whether $S = \{x^3 1, 2x^2, x + 3, 5 2x + 2x^2 + x^3\}$ is a basis for P_3 .
- 2. Find a basis for the vector space of all symmetric 3×3 matrices. What is the dimension of this vector space?