TKalmanFilter

- m_type
- m_linearKalman
- m_initialPoints
- m_initialRects
- m_lastPointResult
- m_lastRectResult
- m_lastRect
- m_initialized
- m_deltaTime
- m_accelNoiseMag
- MIN_INIT_VALS

+ TKalmanFilter()
+ TKalmanFilter()
+ ~TKalmanFilter()
+ GetPointPrediction()
+ Update()
+ GetRectPrediction()
+ Update()
- CreateLinear()
- CreateLinear()