

$$\frac{C(s)}{R(s)} = \frac{16}{s^2 + (0.8 + 16k)s + 16} \rightarrow \omega_n = 4$$

(2)

$$\rightarrow 2\eta\omega_n = 2 \times 0.5 \times 4 = 0.8 + 16k \rightarrow k = 0.2$$

$$t_r = \frac{\pi - \beta}{\omega_d}, \beta = \tan^{-1}\left(\frac{\omega_d}{\eta\omega_n}\right), \omega_d = \omega_n \sqrt{1 - \eta^2} = 3.46$$

$$\rightarrow \beta = 1.047 \rightarrow t_r = 0.605 \text{ sec}$$

$$t_p = \frac{\pi}{\omega_d} = \frac{\pi}{3.46} = 0.907 \text{ sec}$$

$$M_p = \exp\left(\frac{-\pi\eta}{\sqrt{1-\eta^2}}\right) \rightarrow M_p = \exp\left(\frac{-0.5 \times \pi}{\sqrt{1-0.25}}\right) = 0.163$$

$$t_s = \frac{4}{\eta\omega_n} = \frac{4}{0.5 \times 4} = 2 \text{ sec}$$

$$1 - \frac{e^{-2t} (\sin(2\sqrt{3}t) + \sqrt{3} \cos(2\sqrt{3}t))}{\sqrt{3}}$$

پاسخ به مودی مله :

$$G(s) = \frac{16}{s^2 + 3s + 16} \rightarrow \omega_n = 4, 2\eta \times 4 = 3 \rightarrow \eta = 0.375$$

(ب) ⑤

$$t_s = \frac{4}{\eta \omega_n} = 2.667, \quad t_p = \frac{\pi}{\omega_d} = 0.8472$$

$$\%OS = \exp\left(-\frac{\pi \eta}{\sqrt{1-\eta^2}}\right) = 0.28, \quad t_r = \frac{\pi - \beta}{\omega_d} = 0.356$$

$$G(s) = \frac{0.04}{s^2 + 0.02s + 0.04} \rightarrow \omega_n = 0.2, \eta = 0.05$$

(ج)

$$t_s = 400, \quad t_p = 15.73, \quad \%OS = 85.45\%, \quad t_r = 5.26s$$

$$G(s) = \frac{1.05 \times 10^7}{s^2 + 1.6 \times 10^3 s + 1.05 \times 10^7} \rightarrow \eta = 0.247, \omega_n = 3240$$

(د)

$$t_s = 0.05, \quad t_p = 0.01, \quad \%OS = 44.92\%, \quad t_r = 3.88 \times 10^{-4} \text{ sec}$$

$$t_p = \frac{\pi}{\omega_d} = 0.01$$

$$\%P = \exp\left(\frac{-\pi \eta}{\sqrt{1-\eta^2}}\right) \rightarrow \eta = 0.4 \quad \left\{ \begin{array}{l} \omega_d = \omega_n \sqrt{1-\eta^2} = 100\pi \\ \rightarrow 0.91\omega_n = 100\pi \rightarrow \omega_n = \frac{100\pi}{0.91} \\ \rightarrow \omega_n = 345.22 \end{array} \right.$$

⑥

$$\rightarrow G(s) = \frac{1.19 \times 10^5}{s^2 + 276.18s + 1.19 \times 10^5}$$

$$\ddot{y} + 3\dot{y} + 2y = 0, \quad y(0) = 0.1, \quad \dot{y}(0) = 0.05$$

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$$\xrightarrow{\text{Laplace}} s^2 y(s) - s y(0) - \dot{y}(0) + 3(s y(s) - y(0)) + 2 y(s) = 0$$

$$\longrightarrow y(s) (s^2 + 3s + 2) = 0.1s + 0.35 \longrightarrow y(s) = \frac{0.1s + 0.35}{s^2 + 3s + 2}$$

$$= \frac{0.25}{s+1} + \frac{-0.15}{s+2} \xrightarrow{\text{inverse Laplace}} y(t) = 0.25e^{-t} - 0.15e^{-2t}$$

$$a) C(s) = \frac{5}{s(s+5)} = \frac{1}{s} - \frac{1}{s+5} \longrightarrow C(t) = 1 - e^{-5t}$$

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$$T = \frac{1}{5}, \quad t_r = \frac{2.2}{5} = 0.44, \quad t_s = \frac{4}{5} = 0.8$$

$$b) C(s) = \frac{20}{s(s+20)} = \frac{1}{s} - \frac{1}{s+20} \longrightarrow C(t) = 1 - e^{-20t}, \quad T = \frac{1}{20}$$

$$t_r = \frac{2.2}{20} = 0.11, \quad t_s = \frac{4}{20} = 0.2$$

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$$\sigma_s = 0.05 \longrightarrow \exp\left(\frac{-\pi \eta}{\sqrt{1-\eta^2}}\right) = 0.05 \longrightarrow \eta = 0.69$$

$$t_s = 2 \longrightarrow \frac{4}{\eta \omega_n} = 2 \longrightarrow \eta \omega_n = 2 \longrightarrow \omega_n = \frac{2}{0.69} = 2.90$$

$$a) \frac{5}{(s+3)(s+6)} \rightarrow \text{poles: } -3, -6, c(t) = A + B e^{-3t} + C e^{-6t}$$

(3)

$$b) \frac{10(s+7)}{(s+10)(s+20)} \rightarrow \text{poles: } -10, -20, \text{zero: } -7, c(t) = A + B e^{-10t} + C e^{-20t}$$

$$c) \frac{20}{s^2 + 6s + 144} \rightarrow \text{poles: } -3 \pm j3\sqrt{15}, c(t) = A + B e^{-3t} \cos(3\sqrt{15}t + \theta)$$

$$d) \frac{s+5}{(s+10)^2} \rightarrow \text{poles: } -10, \text{zero: } -5, c(t) = A + B e^{-10t} + C t e^{-10t}$$

(7)

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -1 & -1 \\ 6.5 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$$\begin{cases} \dot{x}_1 = -x_1 - x_2 + u_1 + u_2 \\ \dot{x}_2 = 6.5x_1 + u_1 \\ y_1 = x_1 \\ y_2 = x_2 \end{cases} \rightarrow \begin{cases} s X_1(s) = -X_1(s) - X_2(s) + U_1(s) + U_2(s) \\ s X_2(s) = 6.5 X_1(s) + U_1(s) \\ Y_1(s) = X_1(s) \\ Y_2(s) = X_2(s) \end{cases} \quad \begin{matrix} (1) \\ (2) \end{matrix}$$

$$\rightarrow (s+1) X_1(s) = \frac{-6.5}{s} X_1(s) - \frac{U_1(s)}{s} + U_1(s) + U_2(s)$$

$$\rightarrow X_1(s) (s^2 + s + 6.5) = (s-1) U_1(s) + U_2(s)$$

$$\rightarrow Y_1(s) = X_1(s) = \frac{s-1}{s^2 + s + 6.5} U_1(s) + \frac{5}{s^2 + s + 6.5} U_2(s)$$

$$(2) \rightarrow Y_2(s) = X_2(s) = \frac{s+7.5}{s^2+s+6.5} U_1(s) + \frac{32.5}{s(s^2+s+6.5)}$$

$$\rightarrow \omega_n = \sqrt{6.5}, \quad \zeta = \frac{1}{2\sqrt{6.5}}$$