

Q1

$$Q \begin{bmatrix} 3 & 4 & 3 \\ 1 & 5 & -1 \\ 6 & 3 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 7 \\ 15 \end{bmatrix} \begin{matrix} -0/3 \\ -0 \times 2 \\ -0 \times 2 \end{matrix}$$

$$\begin{bmatrix} 3 & 4 & 3 \\ 0 & 3.6667 & -2 \\ 0 & -5 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 3.6667 \\ -5 \end{bmatrix} + 0x_3 \frac{5}{3.6667}$$

$$\begin{bmatrix} 3 & 4 & 3 \\ 0 & 3.6667 & -2 \\ 0 & 0 & -1.7222 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 3.6667 \\ 0 \end{bmatrix}$$

$$\begin{matrix} x_3 = 0 \\ x_2 = 1 \\ 3x_1 + 4 = 10 \\ x_1 = 2 \end{matrix} \Rightarrow \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 6 & 3 & 7 \\ 1 & 5 & -1 \\ 3 & 4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 15 \\ 7 \\ 10 \end{bmatrix} \begin{matrix} + -1/6 \cdot 0 \\ + -1/2 \cdot 0 \\ + -1/2 \cdot 0 \end{matrix}$$

$$\begin{bmatrix} 6 & 3 & 7 \\ 0 & 4.5 & -2.6667 \\ 0 & 2.5 & -0.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 15 \\ 4.5 \\ 2.5 \end{bmatrix} \begin{matrix} \\ -2.5/4.5 \cdot 0 \\ -2.5/4.5 \cdot 0 \end{matrix}$$

$$\begin{bmatrix} 6 & 3 & 7 \\ 0 & 4.5 & -2.6667 \\ 0 & 0 & 0.7778 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 15 \\ 4.5 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{matrix} x_3 = 0 \\ x_2 = 1 \\ x_1 = 2 \end{matrix} \Rightarrow \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Q2

```
eps    abs(x1-1)    abs(x2-eps)/eps    cond(A)
6.00e-08    0.00e+00    1.04e+06    1.22e+15
5.00e-07    4.88e-04    9.78e+02    1.60e+13
9.00e-07    2.44e-04    2.72e+02    4.94e+12
9.50e-07    2.44e-04    2.58e+02    4.43e+12
>>
```

Sqrt(eps_much)=10e-8

Conclusion: when eps is really close to sqrt(eps_much), the error for x1 is almost zero, but for x2, the relative error is large than other eps since the eps is too small. Then when eps grow, the error for x1 and relative error for x2 are smaller. From the cond(A) we can see error for x1 and relative error for x2 will grow when conditional number grow.

Matlab code

```
function [ex1,ex2,condA]=test(eps)

A=[1,1+eps;1-eps,1];
B=[1+(1+eps)*eps;1];
sol=inv(A)*B;
```

```

ex1=abs(sol(1,1)-1);
ex2=abs((sol(2,1)-eps)/eps);
condA=cond(A);
end
[e1a,e2a,condAa]=test(6e-8);
[e1b,e2b,condAb]=test(5e-7);
[e1c,e2c,condAc]=test(9e-7);
[e1d,e2d,condAd]=test(9.5e-7);
fprintf("eps  abs(x1-1)  abs(x2-eps)/eps
cond(A)\n %.2e  %.2e  %.2e  %.2e\n %.2e  %.2e  %.2e  %.2e\n
%.2e  %.2e  %.2e  %.2e\n %.2e  %.2e  %.2e  %.2e\n ",6e-
8,e1a,e2a,condAa,5e-7,e1b,e2b,condAb,9e-
7,e1c,e2c,condAc,9.5e-7,e1d,e2d,condAd)

```

Q3

a.

matlab code

```

function B=GE(A)
    S=size(A);
    n=S(1,1);
    B=eye(n);
    for i=1:n-1
        for j=i+1:n
            B(j,i)=A(j,i)/A(i,i);
            for k=i:n
                A(j,k)=A(j,k)-B(j,i)*A(i,k);
            end
        end
    end
    for p=1:n
        for q=p:n
            B(p,q)=A(p,q);
        end
    end
end

function [B,ipivot]=GEPP(A)
    S=size(A);
    n=S(1,1);
    P=eye(n);
    ipivot=zeros(1,n);
    for i=1:n-1
        [x,y]=max(abs(A(i:n,i)));
        %ipivot(1,i)=y+i-1;
    end
end

```

```

        if ((y+i-1)~=i)
            A([i y+i-1],:)=A([y+i-1 i],:);
            P([i y+i-1],:)=P([y+i-1 i],:);
        end
    end
    for i=1:n
        for j=1:n
            if (P(j,i) ==1)
                ipivot(1,i)=j;
            end
        end
    end
    B=GE(A);
end
function x=backward(B,b,ipivot)
    S=size(B);
    n=S(1,1);
    P=zeros(n,n);
    for j=1:n
        P(ipivot(j),j)=1;
    end
    U1=triu(B);
    for i=1:n
        B(i,i)=1;
    end
    L1=tril(B);
    Newb=P*b;
    y=L1\Newb;
    x=U1\y;
end

```

b.

```

n=input("pls");
A=rand(n,n);
x=ones(n,1);
b=A*x;
ipivotGER=1:n;
ipivotGE=ipivotGER.';
output1=GE(A)
[output2,1]=GEPP(A)
GEx=backward(output1,b,ipivotGE);
GEPPx=backward(output2,b,1);

```

```

error1=abs(x-A\b)./x;
error2=abs(x-GE x)./x;
error3=abs(x-GEPPx)./x;
con=cond(A);
fprintf("inv(A)*b  NO PIVOTING  PIVOTING
cond(A)\n %.2e  %.2e  %.2e  %.2e\n
",error1(1,1),error2(1,1),error3(1,1),con)
Here are some sample output

```

output1 =

0.8875	0.0730	0.5092	0.4944
0.5925	0.5366	0.5371	0.0439
0.8924	0.9872	-0.2963	-0.3258
0.2290	0.8880	-0.6141	0.4003

output2 =

0.8875	0.0730	0.5092	0.4944
0.8924	0.5297	0.2339	-0.2825
0.5925	1.0130	0.3002	0.3300
0.2290	0.8996	1.4943	0.4003

l =

1	3	2	4
---	---	---	---

```

inv(A)*b  NO PIVOTING  PIVOTING  cond(A)
8.88e-16  1.22e-15  9.99e-16  2.93e+01

```

output1 =

0.1804	0.4667	0.4304	0.0502	0.3641	0.9277	0.5117
2.6731	-1.0644	-0.2753	0.4310	-0.8552	-1.9377	-0.5155
4.5353	1.8323	-1.1963	-0.2287	0.6053	0.0799	-0.5565
3.3596	0.8123	0.2989	0.2504	0.0746	-1.5575	-0.7283
2.2393	0.3001	0.5762	0.9764	-0.4924	0.0694	0.5125
3.4076	0.7053	0.3266	1.9569	1.8701	1.6393	-0.1195
1.7041	0.5005	0.4880	2.3595	0.2331	2.3592	1.6668

output2 =

0.8180	0.1664	0.2514	0.7888	0.6897	0.7368	0.8196
0.7514	0.7146	0.6930	0.2977	-0.4578	-0.0119	-0.0040
0.5894	0.1191	0.6446	0.0648	-0.2338	0.1093	0.3697
0.3757	0.2800	-0.4291	0.4285	0.3178	0.6319	-0.0202
0.7408	0.8118	0.1800	-0.3193	0.7885	-0.3450	-0.2713
0.2205	0.6017	-0.0652	-0.6968	0.8798	1.5234	0.5821
0.4937	0.9005	-0.8629	-0.5766	0.6862	0.2841	0.3989

l =

6	3	1	5	7	2	4
---	---	---	---	---	---	---

```

inv(A)*b  NO PIVOTING  PIVOTING  cond(A)
3.11e-15  3.11e-15  8.88e-16  3.33e+01

```

```

1.2020  2.0010  0.7391  0.0101  0.3440  1.2402  -1.0883  -1.1807  -0.2411  0.3213
1.5348  1.0616  0.2578  -0.2647  -0.3008  -0.2468  -0.4215  -0.3997  -0.3819  -0.2000
0.0678  0.7663  0.1580  -0.7830  0.2476  0.4756  0.0642  0.0295  0.6053  0.9134
0.7786  0.0824  0.9075  -2.0759  -3.9370  0.1887  0.9935  0.9673  1.4877  3.0822
0.2527  2.3524  0.4097  -3.3927  -3.7838  12.8782  -14.2449  -14.1180  -16.9034  -35.8306
1.6954  -1.6243  -0.0221  -1.5084  -3.9663  0.6596  -0.0542  0.0284  -2.1864  -2.5839
1.7957  -2.2320  -0.0450  2.3099  1.7484  -14.0219  -1.1892  -0.8775  -3.0569  -4.1002
1.3851  -0.5675  0.7203  -1.7372  -4.8107  1.2077  -0.0257  -3.8071  2.8387  -0.3147

output2 =

0.9683  0.0656  0.3497  0.0595  0.4068  0.2353  0.7204  0.9202  0.8870  0.9515
0.6697  0.7717  0.5680  0.1558  0.7217  0.6233  -0.4152  -0.2244  -0.5472  0.1503
0.4336  0.2954  0.4597  0.7000  -0.0739  0.1633  0.1199  0.3962  0.1532  0.4094
0.9442  0.1359  -0.1920  1.0542  -0.3601  0.5282  0.1882  0.1471  -0.5874  -0.7760
0.0377  0.2392  -0.1392  0.2172  0.4891  0.1773  0.7708  0.7532  0.8634  1.1077
0.5569  0.3496  -0.5380  0.5413  0.2541  0.1113  -0.3946  -0.4142  0.8172  0.6727
0.1407  0.7499  -0.5724  1.0189  0.3903  -3.1439  -0.5855  -0.6732  3.6430  3.2060
0.7713  0.3246  0.6754  0.3131  -0.4410  0.1263  -0.6498  -0.1790  3.2051  1.7902
0.8547  0.8351  -0.9057  0.5162  -0.6109  -2.3191  1.0134  -0.2377  0.1969  0.1894
0.5184  0.6066  -0.9659  0.7007  0.0062  -6.2203  3.0074  -0.9612  -9.6479  -1.0241

l =

6 10 2 9 5 3 7 4 1 8

inv(A)*b NO PIVOTING PIVOTING cond(A)
1.95e-14 1.98e-14 8.55e-15 2.81e+03

```

Q4

Problem 4 [4 points] You have to interpolate e^x by a polynomial of degree five using equally spaced points in $[0, 1]$. What error would you expect if you use this polynomial?

Using equally spaced points, what degree polynomial would you use to achieve a maximum error of 10^{-8} ?

$$\begin{aligned}
 n &= 5 & h &= \frac{1}{5} & M &= \max_{x \in [0,1]} |e^x| = e \\
 |f(x) - e^x| &\leq \frac{e}{4 \times 6} \cdot \left(\frac{1}{5}\right)^6 = 7.2487 \times 10^{-6} \\
 \lim_{n \rightarrow \infty} \frac{M}{4(n+1)} \left(\frac{1}{n}\right)^{n+1} &= \frac{e}{4(n+1)n^{n+1}} \leq 10^{-8} \\
 E(6) &= 3.4680 \times 10^{-7} > 10^{-8} \\
 E(7) &= 1.4735 \times 10^{-8} > 10^{-8} \\
 E(8) &= 5.6258 \times 10^{-10} < 10^{-8} \\
 \text{We can achieve error } 10^{-8} &\text{ by degree 8.}
 \end{aligned}$$

Problem 5 [5 points] You are given the data points

Q5

```

approx =
    1.0247    1.0724

M =
   -0.9375

BoundError =
    5.8594e-06

actualerror1 =
    2.4158e-06

actualerror2 =
    1.3607e-06

```

- From the matlab output, we can see approximation for $x=0.05$ is 1.0247 and for $x=0.15$ is 1.0724.
- The bound error is $5.8594e-6$
- The bound error is the max error between $[0,0.3]$. so it is larger than the actual error.
From the matlab output, we can see actual error for $x=0.05$ is $2.4158e-6 < \text{bounderror}$
 $x=0.15$ is $1.3607e-6 < \text{bounderror}$

Matlab code

```

x=[0,0.1,0.2,0.3];
f = @(x) sqrt(x+1);
y=f(x);
p=polyfit(x,y,3)
data=[0.05,0.15];
approx=polyval(p,data)
h=0.1;
n=3;

M=-15/16*1^(-7/2)
BoundError=abs(M/(4*(n+1))*h^(n+1))
actualerror1=abs(f(0.05)-approx(1))
actualerror2=abs(f(0.15)-approx(2))
c.2000*2000

```

Command Window									
0.0999	0.9149	0.9680	0.6164	0.8884	0.6698	0.4455	0.2193	0.5525	0.7201
0.8536	0.9295	0.1613	0.4429	0.3019	0.0062	0.9204	0.1953	0.7575	0.4362
0.3321	0.0975	0.6454	0.2794	0.9183	0.5133	0.3930	0.6047	0.5101	0.4162
0.2786	0.6502	0.5039	0.3973	0.8741	0.7023	0.4308	0.9809	0.7380	0.2407
0.5941	0.1951	0.2294	0.0483	0.0144	0.7324	0.7999	0.4006	0.3181	0.4700
0.7463	0.6068	0.8575	0.5008	0.1767	0.6212	0.5705	0.2348	0.5328	0.3458
0.0193	0.6422	0.0638	0.0107	0.8721	0.9370	0.7193	0.5145	0.5006	0.3225
0.7642	0.2706	0.2591	0.6607	0.0504	0.1197	0.1057	0.9719	0.5371	0.9811
0.3677	0.1886	0.4315	0.5825	0.7596	0.8520	0.5731	0.4985	0.9194	0.2987
0.9191	0.5026	0.6528	0.8936	0.9340	0.6713	0.2630	0.3641	0.1616	0.5509
0.5547	0.9971	0.4025	0.9597	0.8768	0.2417	0.3208	0.2558	0.1421	0.2401
0.8616	0.1558	0.1148	0.4605	0.4859	0.0629	0.2630	0.1993	0.7779	0.7369
0.6661	0.9438	0.7818	0.8672	0.9263	0.1896	0.2748	0.8277	0.1313	0.9105
0.8531	0.4882	0.6358	0.6106	0.7580	0.2374	0.9739	0.0375	0.8882	0.9569
0.6956	0.9759	0.0737	0.4147	0.3656	0.1121	0.1334	0.3769	0.0553	0.1221
0.1047	0.1541	0.9924	0.7140	0.1078	0.8395	0.6564	0.5897	0.8794	0.0662
inv(A)*b NO PIVOTING PIVOTING cond(A)									
5.46e-13	1.74e-11	1.71e-10	1.59e+05						

0.8272	0.5791	0.0645	0.3362	0.6241	0.8615	0.5747	0.9540	0.1601	0.5288
0.5319	0.2283	0.1950	0.9973	0.5671	0.2502	0.1264	0.4234	0.1719	0.5350
0.2665	0.6329	0.0823	0.5934	0.7850	0.2514	0.6052	0.5103	0.2067	0.4471
0.9422	0.0414	0.1276	0.6590	0.2065	0.9228	0.3921	0.7052	0.3057	0.7284
0.7451	0.7870	0.9213	0.4056	0.3248	0.3956	0.5969	0.8574	0.7825	0.4514
0.8033	0.9405	0.1391	0.1342	0.5959	0.7765	0.0848	0.8716	0.4492	0.8162
0.8426	0.9150	0.0831	0.9670	0.9673	0.4791	0.5127	0.8988	0.7508	0.3624
0.3038	0.9388	0.4491	0.2868	0.6685	0.9344	0.9872	0.0132	0.2562	0.2993
0.4424	0.4039	0.0163	0.8567	0.8254	0.7789	0.7824	0.5533	0.5840	0.2831
0.3441	0.8673	0.2988	0.8494	0.5955	0.2262	0.6322	0.1958	0.0136	0.3896
0.7298	0.4202	0.1050	0.0342	0.4971	0.1744	0.6130	0.9507	0.0573	0.5883
0.0698	0.3896	0.5540	0.4350	0.9455	0.5469	0.8629	0.6156	0.9853	0.8775
0.8756	0.1129	0.2698	0.4075	0.7828	0.0846	0.7007	0.5352	0.8405	0.3826
0.4216	0.4629	0.5734	0.8554	0.6604	0.3036	0.6801	0.7077	0.8465	0.4251
0.2009	0.3340	0.6402	0.1386	0.3861	0.5958	0.6220	0.4447	0.2689	0.0438
0.4136	0.4210	0.3815	0.2486	0.5710	0.4944	0.5144	0.7582	0.1459	0.8069
inv(A)*b NO PIVOTING PIVOTING cond(A)									
1.60e-12	3.64e-10	4.36e-10	1.63e+05						

Command Window									
0.2168	0.7534	0.3779	0.5966	0.4757	0.3929	0.3573	0.0557	0.6555	0.5642
0.0629	0.2350	0.1159	0.7535	0.0112	0.5609	0.6375	0.0556	0.6681	0.4291
0.8331	0.5357	0.1519	0.8989	0.2967	0.9439	0.7352	0.8540	0.4775	0.4676
0.0046	0.4709	0.9311	0.9557	0.3461	0.7755	0.4830	0.7089	0.1432	0.3812
0.7437	0.1943	0.2010	0.1391	0.3943	0.9129	0.4017	0.4057	0.6574	0.6686
0.6616	0.8366	0.7151	0.1230	0.9981	0.2777	0.4837	0.4353	0.6362	0.9937
0.9268	0.4402	0.6785	0.8743	0.1410	0.5178	0.0343	0.0288	0.3610	0.1429
0.8403	0.9431	0.3008	0.3656	0.7433	0.9150	0.6439	0.7666	0.6353	0.1344
0.0012	0.7677	0.7264	0.4500	0.2658	0.8871	0.6279	0.3683	0.5124	0.9033
0.9900	0.0106	0.2318	0.0075	0.1660	0.0629	0.3318	0.6095	0.3859	0.2035
0.5210	0.1837	0.4123	0.7027	0.2887	0.8124	0.6534	0.3510	0.4158	0.0612
0.7070	0.6447	0.5907	0.2658	0.1133	0.7274	0.1103	0.8997	0.1962	0.3508
0.4102	0.2214	0.8424	0.6215	0.8775	0.2448	0.7846	0.3366	0.8893	0.5960
0.9595	0.4117	0.0760	0.7337	0.2175	0.8904	0.3128	0.9233	0.6859	0.1519
0.2528	0.2430	0.8446	0.7491	0.7065	0.7384	0.2178	0.6163	0.2612	0.0725
0.7376	0.1890	0.5762	0.9611	0.6976	0.5280	0.6181	0.2859	0.0684	0.3454
inv(A)*b NO PIVOTING PIVOTING cond(A)									
7.31e-13	4.10e-10	2.10e-09	1.55e+05						

0.8179	0.4578	0.7711	0.9248	0.1344	0.1484	0.7717	0.5366	0.5122	0.9284
0.5147	0.1968	0.7180	0.8757	0.9652	0.3290	0.5472	0.6153	0.6232	0.0568
0.4338	0.6111	0.3263	0.2354	0.7452	0.7402	0.1565	0.5140	0.6142	0.3321
0.7569	0.0254	0.9632	0.0199	0.6675	0.6809	0.6290	0.3676	0.8115	0.7104
0.4717	0.9038	0.1449	0.0652	0.1450	0.5911	0.2276	0.8762	0.0891	0.3486
0.0215	0.2105	0.2860	0.2097	0.3956	0.7343	0.0587	0.8791	0.8294	0.7433
0.2081	0.1022	0.2777	0.0828	0.2069	0.1229	0.2917	0.8358	0.4665	0.8295
0.7274	0.1942	0.9009	0.1550	0.4405	0.9594	0.1539	0.9846	0.3904	0.3475
0.6994	0.1760	0.8491	0.2936	0.8114	0.4926	0.8676	0.2482	0.1842	0.4573
0.2473	0.9695	0.9680	0.1877	0.4853	0.0109	0.5232	0.8916	0.1294	0.1063
0.4442	0.1353	0.1336	0.6693	0.8327	0.6821	0.6920	0.3979	0.7899	0.6702
0.3751	0.2783	0.1755	0.6604	0.8877	0.0810	0.5158	0.2764	0.1190	0.4892
0.7419	0.3967	0.8593	0.2652	0.4984	0.7096	0.4377	0.5073	0.2105	0.3594
0.4650	0.4535	0.2089	0.2312	0.7291	0.3122	0.1005	0.6675	0.7334	0.4471
0.6339	0.6480	0.5028	0.9750	0.2055	0.6479	0.9204	0.5420	0.4548	0.8897

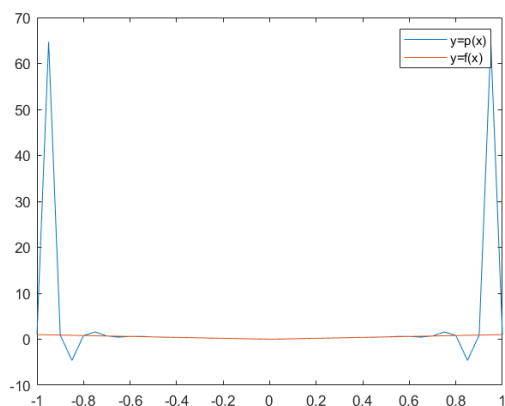
inv(A)*b	NO PIVOTING	PIVOTING	cond(A)
5.28e-11	7.66e-11	2.88e-09	1.34e+06

0.7198	0.2988	0.2497	0.3821	0.0972	0.2579	0.7185	0.3871	0.3590	0.0906
0.0454	0.1861	0.7592	0.6214	0.4627	0.9812	0.4038	0.1050	0.4321	0.1118
0.8246	0.8531	0.1271	0.0126	0.2967	0.5854	0.3898	0.9011	0.9117	0.0982
0.2528	0.0082	0.0663	0.9149	0.9150	0.9783	0.7399	0.7299	0.2489	0.2734
0.8513	0.0228	0.3907	0.4837	0.9009	0.9436	0.2576	0.8457	0.6887	0.1676
0.4669	0.3110	0.0604	0.7792	0.3996	0.3159	0.4468	0.6246	0.8867	0.4357
0.7904	0.7039	0.4003	0.0322	0.0293	0.6644	0.5375	0.4568	0.0887	0.2146
0.4784	0.3345	0.0920	0.1483	0.9565	0.6509	0.2356	0.2305	0.3145	0.5709
0.0118	0.3044	0.9310	0.2747	0.5481	0.1086	0.1327	0.1121	0.7813	0.2582
0.2138	0.8953	0.2503	0.8456	0.3857	0.8060	0.5691	0.7957	0.1860	0.3482
0.7070	0.5977	0.5305	0.1520	0.3315	0.9490	0.5840	0.5730	0.7576	0.1337
0.4195	0.4145	0.5424	0.6945	0.3064	0.1723	0.3355	0.4563	0.2650	0.8625
0.7979	0.8742	0.7678	0.0911	0.7318	0.9383	0.6445	0.3756	0.7395	0.3141
0.0995	0.5359	0.1631	0.7575	0.9394	0.3810	0.7074	0.8456	0.9366	0.7478
0.2274	0.3301	0.8327	0.7942	0.2437	0.8605	0.5274	0.4752	0.7690	0.2642
0.4777	0.5316	0.5665	0.4095	0.9221	0.6024	0.6417	0.0647	0.6850	0.5218

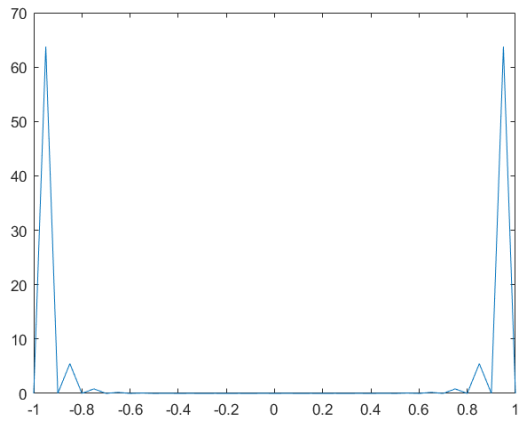
inv(A)*b	NO PIVOTING	PIVOTING	cond(A)
1.36e-10	2.59e-08	1.38e-09	2.86e+08

Q6

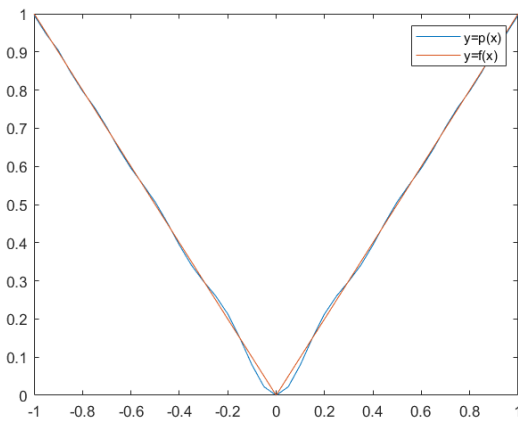
Plot 1: $p(x)$ and $f(x)$



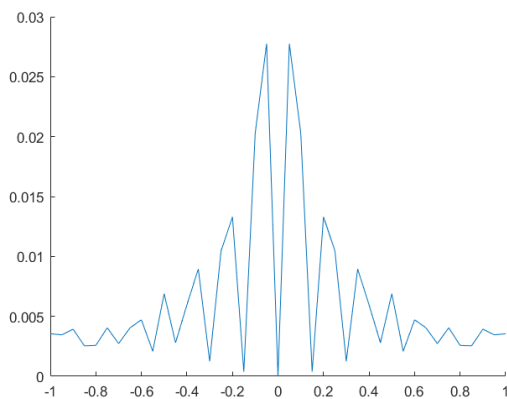
Plot 2: error for linespace



Plot 3: $p(x)$ and $y(x)$ for Chebyshev



Plot of error for Chebyshev



Matlab code

```
x=linspace(-1, 1, 21);
y=abs(x);
```

```

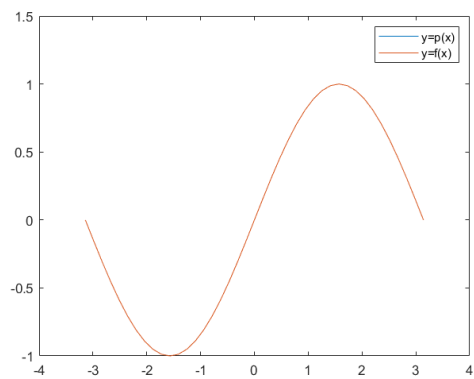
P=polyfit(x,y,20);
f = @(t) abs(t);
xx=linspace(-1,1,41);
yy=polyval(P,xx);
plot(xx,yy)
hold on
y2=f(xx);
plot(xx,y2)
legend('y=p(x)', 'y=f(x)')
%hold off
%error=abs(f(xx)-yy);
%plot(xx,error)

i=0:20;
n=20;
m= @(j) cos((2.*j+1).*pi./(2.*n+2));
x=m(i);
y=abs(x);
P=polyfit(x,y,20);
f = @(t) abs(t);
xx=linspace(-1,1,41);
yy=polyval(P,xx);
%plot(xx,yy)
hold on
y2=f(xx);
%plot(xx,y2)
%legend('y=p(x)', 'y=f(x)')
%hold off
error=abs(f(xx)-yy);
plot(xx,error)

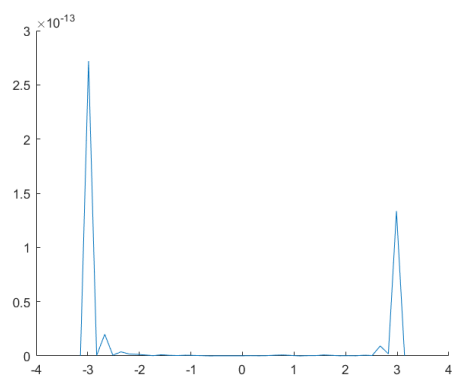
```

Q7

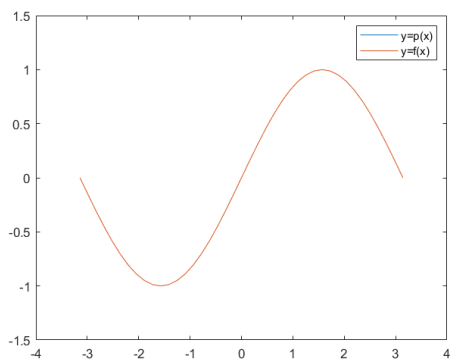
Plot 1: p(x) and f(x)



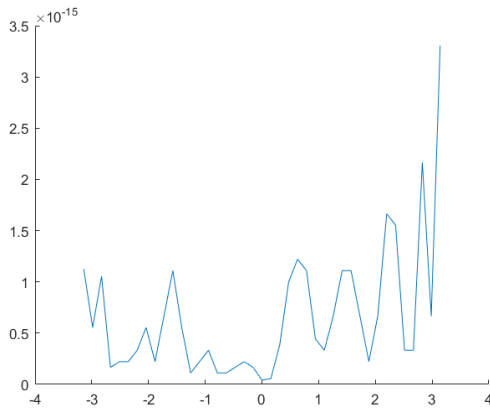
Plot 2: error for linespace



Plot 3: $p(x)$ and $y(x)$ for Chebyshev



Plot of error for Chebyshev



Discussion:

From the plot we can see the error between original function and interpolation for $\sin(x)(10e-15)$ are much smaller than $\text{abs}(x)(10e-2)$. We can also see that Chebyshev nodes are more accurate to present the interpolation. Also, the error for $\text{abs}(x)$ are symmetric about y axis, and for $\sin(x)$ are not.

Matlab code

```
x=linspace(-pi, pi, 21);
y=sin(x);
P=polyfit(x,y,20);
f = @(t) sin(t);
xx=linspace(-pi,pi,41);
yy=polyval(P,xx);
%plot(xx,yy)
hold on
y2=f(xx);
%plot(xx,y2)
%legend('y=p(x)', 'y=f(x)')
%hold off
error=abs(f(xx)-yy);
plot(xx,error)

i=0:20;
n=20;
m = @(j) pi*cos((2.*j+1).*pi./(2.*n+2));
x=m(i);
y=sin(x);
P=polyfit(x,y,20);
f = @(t) sin(t);
xx=linspace(-pi,pi,41);
yy=polyval(P,xx);
%plot(xx,yy)
```

```

hold on
y2=f(xx);
%plot(xx,y2)
%legend('y=p(x)', 'y=f(x)')
%hold off
error=abs(f(xx)-yy);
plot(xx,error)

```

Q8

```

function [p,table]=newton(x,xx,yy,n)
    diff=zeros(n,n);
    for i=1:n
        diff(i,1) =yy(i);
    end
    for j=2:n
        for k=j:n
            diff(k,j)=(diff(k,j-1)-diff(k-1,j-1))/(xx(k)-
xx(k-j+1));
        end
    end
    p=diff(1,1);
    for i=2:n
        mult=1;
        for j=1:i-1
            mult=mult*(x-xx(j));
        end
        p=p+diff(i,i)*mult;
    end
    table=diff;
end

```