

# Shiv Seetharaman

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## EDUCATION

### HARVEY MUDD COLLEGE

#### BS IN GENERAL ENGINEERING

Expected May 2019 | Claremont, CA

Eng. GPA: 3.6 / 4.0

Dean's List: Fall 2016, Fall 2017, Spring 2018

### COURSEWORK

- Microprocessor Systems and Applications
- Data Structures
- System Identification, Estimation, and Learning
- Autonomous Navigation
- Control Theory and Signal Processing
- Digital Design and Computer Architecture
- Electrical and Magnetic Circuits
- Experimental Engineering (underwater robots)
- Continuum Mechanics

## SKILLS

### PROGRAMMING

Proficient:

C • C++ • MATLAB • Python

• ARM Assembly

Knowledgeable:

Linux • OpenCV • gRPC • Protocol

Buffers • iOS dev/Swift

### ENGINEERING

Proficient:

PCB Design (KiCAD) • System Verilog

• I2C, SPI, UART • Microcontrollers,

FPGAs • Oscilloscopes, Logic Analyzers

• Board Bring-up • SPICE • Lathe/ Mill

Machining

Knowledgeable:

Kalman and Particle Filters • Motion

Planning • Localization • Time Series and

Random Processes • Fiber Optics

• Networking • Telecommunications

## ACTIVITIES

### TEACHING ASSISTANT

Microprocessor Systems (Head TA, F-18)

• Digital Electronics and Computer Architecture (Head TA, S-18)

• Experimental Engineering - Underwater Robots (S-18) • Intro to Signals and Systems (F-17)

## EXPERIENCE

### TECHMATION - FIRMWARE ENGINEER (CLINIC PROGRAM, TEAM OF 5)

Sept 2018 – Present | Claremont, CA

- Programming the embedded software and data-processing pipeline for a millimeter wave radar sensor to detect and track obstacles, in real-time.

### X, THE MOONSHOT FACTORY (GOOGLE X) - SOFTWARE ENGINEERING INTERN: FREE SPACE OPTICAL COMMUNICATIONS (FSOC)

May 2018 – Sept 2018 | Mountain View, CA

- Built and tested an atmospheric channel emulator to characterize FSOC modem performance. Caught critical bugs to assist modem development and validate algorithms. Presented findings to senior engineers and executives.
- Tested an ASIC for a novel modulation scheme to be used in future systems.
- Programmed the data-processing pipeline for a system statistics/performance visualizer to improve and expedite characterization, development, and monitoring. Used Go, gRPC, and Protobufs.

### WET (DESIGN) - HARDWARE ENGINEER (CLINIC PROGRAM, TEAM OF 6)

Jan 2018 – May 2018 | Harvey Mudd College, Claremont, CA

- Worked on a team to design and build 8 autonomous, wireless floating robots to swim in a synchronized pattern with bright, flashing lights.
- Helped design a Bluetooth PCB with the nRF52 BLE chip for multilink UART.
- Designed, assembled and tested a closed-loop current driver PCB for high-power LEDs. Implemented thermal and current management features.
- Programmed, tuned and tested a PID controller in Python for the floating robots to autonomously follow a desired trajectory.

### OPEN DEVICES ENGINEERING LAB - STUDENT RESEARCHER

Jun 2017 – Sept 2017 | Harvey Mudd College, Claremont, CA

- Wrote embedded C, and designed, assembled and tested a PCB to generate sine waves between 10 kHz and 20 MHz to build a low-cost network analyzer prototype. Used a direct digital synthesis (DDS) chip interfacing with an STM32 microcontroller over SPI.
- Explored time interleaving to increase sampling rate without additional costs.

## PROJECTS

### VISION BASED PATH PLANNING AND LOCALIZATION - TEAM OF 2

April 2018 – May 2018 | Claremont, CA

Wrote Python to implement a Particle Filter to localize a wheeled robot using encoders and an overhead camera. Used a motion planner to drive the robot from a start to goal state while avoiding dynamic obstacles. (Website: [bit.ly/2OrxaaJ](http://bit.ly/2OrxaaJ))

### LED MATRIX CONNECT-4 GAME - TEAM OF 2

Oct 2017 – Dec 2017 | Claremont, CA

Wrote System Verilog on an FPGA to implement a custom LED Matrix driver using an NRZ protocol running at 800 kHz and a frame buffer using a dual-port RAM. Wrote embedded C on a Raspberry Pi for the game interface and an LCD display driver.

(Report: [bit.ly/2P8KL6S](http://bit.ly/2P8KL6S))

### AUTONOMOUS WEATHER BOAT - TEAM OF 4

Mar 2017 – May 2017 | Claremont, CA

Used a Hall effect sensor to make a wind speed sensor, sampled using interrupts in C. Programmed a proportional control GPS way-point tracking system for autonomous navigation. Designed OP-AMP circuits for sensor signal conditioning.