SHIVAM DUGGAL

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RESEARCH INTEREST

My research interests lie at the intersection of computer vision, computer graphics and robotics. I am particularly interested in topics such as self-supervised learning, 3D perception, 3D reconstruction, 2D/3D simulation, with applications relating to augmented/virtual reality and robot learning.

EDUCATION

Carnegie Mellon University

Aug 2021 - Present Pittsburgh, USA

Masters of Science in Robotics (MSR)

– Advisor: Prof. Deepak Pathak

- **CGPA: 4.16/4** (till 2nd semester*)

- Awards: Siebel Scholar (1/5 CMU students, only masters student)

Delhi Technological University (DTU, formerly DCE)

Aug 2013 - Aug 2017

Delhi, India

Bachelor in Technology, Computer Science (B. Tech)

- Aggregate: 83.7%, **CGPA: 9.12/10**

RESEARCH EXPERIENCE

Carnegie Mellon University Graduate Student Researcher

Aug 2021 - Present

Pittsburgh, USA

- Advisors: Prof. Deepak Pathak, Prof. Ioannis Gkioulekas

Brown University

May 2021 - Aug 2021

Research Intern

Remote

– Advisor: Prof. Srinath Sridhar

Uber Advanced Technology Group

Nov 2019 - Feb 2021

Research Scientist I

Toronto, Canada

- Advisors: Prof. Raquel Urtasun, Prof. Shenlong Wang

Uber Advanced Technology Group

Aug 2018 - Nov 2019

AI Resident (3 AI residents selected world-wide)

Toronto, Canada

- Advisors: Prof. Raquel Urtasun, Prof. Shenlong Wang

Awards & Honors

*	Denotes	All	India	National	rank	l
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	Siebel Scholarship (\$35000 USD)	2023
Top 4.2%	Outstanding Reviewer ECCV	2022
$\mathbf{Top} 0.2\%$	GeoSim nominated as Best Paper Candidate CVPR	2021
Rank $1/70$	Marketplace Hackathon, Amazon	2017
Rank $20/7937^*$	Codechef June Long Challenge	2017
Rank $10/1885^*$	Hackerearth Collegiate Programming Contest	2016
Rank 28 *	ACM ICPC India Finals	2016

Rank $29/2609^*$	ACM ICPC Amritapuri Regionals	2016
Rank $29/867^*$	ACM ICPC Chennai Preliminary Round	2016
Rank $12/5693^*$	Codechef October Long Challenge	2016
Rank $1/130$ Interns	Flipkart Hackathon JUGAAD	2016
Rank 6 *	IEEEXtreme Programming Competition	2015
Rank 8*	IEEEXtreme Programming Competition	2014

SELECTED PUBLICATIONS & PREPRINTS

[* Denotes equal contribution]

- [1] Shivam Duggal, Deepak Pathak. "Topologically-Aware Deformation Fields for Single-View 3D Reconstruction." (CVPR 2022) [Link]
- [2] Trevor Houchens, Cheng-You Lu, <u>Shivam Duggal</u>, Rao Fu, Srinath Sridhar. "NeuralODF: Learning Omnidirectional Distance Fields for 3D Shape Representation." [Link]
- [3] Shivam Duggal*, Zihao Wang*, Wei-Chiu Ma, Sivabalan Manivasagam, Justin Liang, Shenlong Wang, Raquel Urtasun. "Mending Neural Implicit Modeling for 3D Reconstruction in the Wild." (WACV 2022) [Link]
- [4] Yun Chen*, Frieda Rong*, Shivam Duggal*, Shenlong Wang, Xinchen Yan, Sivabalan Manivasagam, Shangjie Xue, Ersin Yumer, Raquel Urtasun. "GeoSim: Realistic Video Simulation via Geometry-Aware Composition for Self-Driving." (CVPR 2021) [Link]
 Nominated for Best Paper Award!
- [5] <u>Shivam Duggal</u>, Shenlong Wang, Wei-Chiu Ma, Rui Hu, Raquel Urtasun. "Deeppruner: <u>Learning efficient stereo matching via differentiable patchmatch." (ICCV 2019) [Link]</u>
- [6] Shamit Lal*, Shivam Duggal*, Indu Sreedevi. "Online video summarization: Predicting future to better summarize present." (WACV 2019) [Link]

Industry Experience

Amazon, Hyderabad, India	(Software Eng.)	Aug 2017 - Jul 2018
Flipkart, Bangalore, India	(Software Eng. Intern)	Jun 2016 - Aug 2016
Parallel Dots, Delhi, India	(Machine Learning Intern)	Dec 2015 - Jan 2016

Conference Reviewing

CVPR 2023 / WACV 2023 / 3DV 2022 / ECCV 2022 / CVPR 2022 / WACV 2022 / IJCV WACV 2021 / ICRA 2021 / IROS 2021 / SIGGRAPH Asia 2021

Course Work

Computational Photography / Physics-Based Rendering (A+) / Computer Vision (A+) Convex Optimization (A) / Math for Robotics (A)

SKILLS

Languages / Tools & Frameworks: Python, C/C++, LATEX, Pytorch, Git, AWS

PATENTS

- [1] Shivam Duggal, Shenlong Wang, Wei-Chiu Ma, Raquel Urtasun. "Depth Estimation for Autonomous Devices." US Patent App. 16/826,924
- [2] Frieda Rong, Yun Chen, Shivam Duggal, Shenlong Wang, Xinchen Yan, Sivabalan Manivasagam, Ersin Yumer, Raquel Urtasun. "Photorealistic Image Simulation with Geometry-Aware Composition." US Patent App. 17/150,989

OTHER PROJECTS

Non-Exponential Radiative Transfer for Light Transport

CMU, Pittsburgh

- Studied the Radiative Transfer Framework (RTE) which governs the physics of light transport through a participating medium.
- Classical RTE models light transmittance (as an exponential function) only through spatially-uncorrelated participating mediums. We explored the affect of spatially-correlated participating mediums on RTE, by modeling light transmittance as non-exponential functions.

Poisson Solver for Depth Completion

Uber ATG, Toronto

- Casted the problem of monocular depth completion using single camera image and sparse Lidar points, to a boundary value problem.
- Instead of directly predicting depth value per pixel, we developed an approach to first predict relative-depth estimates per pixel and then integrate them to predict the final depth value.

Emotion Recognition on speech signals

DTU, India

- Implemented ensemble approaches and compared various algorithms for emotion recognition in speech signals using MFCC and energy as features.
- Publication: Emotion recognition on speech signals using machine learning, ICBDACI (2017)
 [Link]