```
Stacking_Classifier_Submission1.ipynb - Colaboratory
#importing libraries
import matplotlib
import matplotlib.pyplot as plt
import random
import pandas as pd
import numpy as np
from tqdm import tqdm
from sklearn.decomposition import PCA
from sklearn.manifold import TSNE
from sklearn.model_selection import train_test_split
import pickle
!curl --header 'Host: doc-0k-3c-docs.googleusercontent.com' --user-agent 'Mozilla/5.0 (X11; Linux x86_64; rv:81.0) Gecko/20100101 Firefox/81.0' --header 'Accept: text/html,appli
!curl --header 'Host: doc-0k-3c-docs.googleusercontent.com' --user-agent 'Mozilla/5.0 (X11; Linux x86 64; rv:81.0) Gecko/20100101 Firefox/81.0' --header 'Accept: text/html,appli
!curl --header 'Host: doc-08-3c-docs.googleusercontent.com' --user-agent 'Mozilla/5.0 (X11; Linux x86 64; rv:81.0) Gecko/20100101 Firefox/81.0' --header 'Accept: text/html,appli
!unzip /content/falls.zip
!pip install seaborn --upgrade
import seaborn as sns
print(sns.__version__)
                                                                     Time Current
      % Total
                % Received % Xferd Average Speed
                                                    Time
                                                            Time
                                     Dload Upload
                                                    Total
                                                            Spent
                                                                     Left Speed
    100 20021 100 20021
                           0
                                 0 93120
                                                                   --:-- 93120
                                               0 --:--:--
      % Total
                % Received % Xferd Average Speed
                                                   Time
                                                            Time
                                                                     Time Current
                                     Dload Upload
                                                            Spent
                                                                     Left Speed
                                                    Total
    100 6100 100 6100
                           0
                                                0 --:--:-- 28240
                                 0 28240
                                                                     Time Current
      % Total
                % Received % Xferd Average Speed Time
                                                            Time
                                                            Spent
                                    Dload Upload Total
                                                                     Left Speed
    100 21.3M
                0 21.3M
                           0
                                  0 12.2M
                                               0 --:--: 0:00:01 --:-- 12.2M
    Archive: /content/falls.zip
       creating: falls/
      inflating: falls/equip_failures_test_set.csv
      inflating: falls/equip failures training set.csv
    Requirement already up-to-date: seaborn in /usr/local/lib/python3.6/dist-packages (0.11.0)
    Requirement already satisfied, skipping upgrade: matplotlib>=2.2 in /usr/local/lib/python3.6/dist-packages (from seaborn) (3.2.2)
    Requirement already satisfied, skipping upgrade: pandas>=0.23 in /usr/local/lib/python3.6/dist-packages (from seaborn) (1.1.2)
    Requirement already satisfied, skipping upgrade: scipy>=1.0 in /usr/local/lib/python3.6/dist-packages (from seaborn) (1.4.1)
    Requirement already satisfied, skipping upgrade: numpy>=1.15 in /usr/local/lib/python3.6/dist-packages (from seaborn) (1.18.5)
    Requirement already satisfied, skipping upgrade: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.2->seaborn) (2.4.7)
    Requirement already satisfied, skipping upgrade: kiwisolver>=1.0.1 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.2->seaborn) (1.2.0)
    Requirement already satisfied, skipping upgrade: python-dateutil>=2.1 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.2->seaborn) (2.8.1)
    Requirement already satisfied, skipping upgrade: cycler>=0.10 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.2->seaborn) (0.10.0)
    Requirement already satisfied, skipping upgrade: pytz>=2017.2 in /usr/local/lib/python3.6/dist-packages (from pandas>=0.23->seaborn) (2018.9)
    Requirement already satisfied, skipping upgrade: six>=1.5 in /usr/local/lib/python3.6/dist-packages (from python-dateutil>=2.1->matplotlib>=2.2->seaborn) (1.15.0)
    0.11.0
#Loading Scaler
filename = '/content/scalar.pkl'
```

Loading scaler

```
with open(filename, 'rb') as f:
    scaler = pickle.load(f)
print(scaler)
 StandardScaler(copy=True, with mean=True, with std=True)
```

Loading varriables

```
#Loading varriables
filename = '/content/varriables.pickle'
with open(filename, 'rb') as f:
         high_nan_features, median, time_based_sensor, bottom_n_features, useless_features = pickle.load(f)
print("high_nan_features = ",high_nan_features)
print("median = ",median)
print("time_based_sensor = ",time_based_sensor)
print("bottom_n_features = ",bottom_n_features)
print("useless_features = ",useless_features)
  righ_nan_features = ['sensor2_measure', 'sensor38_measure', 'sensor39_measure', 'sensor40_measure', 'sensor41_measure', 'sensor42_measure', 'sensor43_measure', 'sensor68_r
           median = sensor1_measure
           sensor3 measure
                                                                                           152.0
           sensor4_measure
                                                                                           126.0
           sensor5 measure
                                                                                               0.0
           sensor6_measure
                                                                                               0.0
           sensor105_histogram_bin7_nan
                                                                                               0.0
           sensor105_histogram_bin8_nan
                                                                                               0.0
           sensor105 histogram bin9 nan
                                                                                               0.0
           sensor106_measure_nan
                                                                                               0.0
           sensor107 measure nan
                                                                                               0.0
           Length: 332, dtype: float64
           time based sensor = [['sensor7 histogram bin0', 'sensor7 histogram bin1', 'sensor7 histogram bin2', 'sensor7 histogram bin3', 'sensor7 histogram bin4', 'sensor8 histogram bin
           bottom_n_features = {'sensor25_histogram_bin9': 0.000404517327265069, 'sensor4_measure': -0.0005747918610703464, 'sensor56_measure': -0.0005748712717671971, 'sensor5_measure'
           useless_features = ['sensor7_histogram_bin5', 'sensor7_histogram_bin6', 'sensor8_measure', 'sensor12_measure', 'sensor14_measure', 'sensor15_measure', 'sensor16_measure',
```

Loading dataframe

```
#Loading dataframe
df = pd.read_csv("/content/falls/equip_failures_training_set.csv")
```

₽		id	target	sensor1_measure	sensor2_measure	sensor3_measure	sensor4_measure	sensor5_measure	sensor6_measure	sensor7_histogram_bin0	sensor7_histogram_bin1 sensor7_h
	0	1	0	76698	na	2130706438	280	0	0	0	0
	1	2	0	33058	na	0	na	0	0	0	0
	2	3	0	41040	na	228	100	0	0	0	0
	3	4	0	12	0	70	66	0	10	0	0
	4	5	0	60874	na	1368	458	0	0	0	0
	5 rov	NS X	172 colum	ins							

▼ Replace na with np.nan

"""Instead of nan value we have na, so we will replace na with np.nan"""

```
df = df.replace('na', np.NaN)
df.head()
```

₽		id	target	sensor1_measure	sensor2_measure	sensor3_measure	sensor4_measure	sensor5_measure	sensor6_measure	sensor7_histogram_bin0	sensor7_histogram_bin1	sensor7_h
	0	1	0	76698	NaN	2130706438	280	0	0	0	0	
	1	2	0	33058	NaN	0	NaN	0	0	0	0	
	2	3	0	41040	NaN	228	100	0	0	0	0	
	3	4	0	12	0	70	66	0	10	0	0	
	4	5	0	60874	NaN	1368	458	0	0	0	0	
	5 rov	NS ×	172 colum	nns								

▼ Change data-type of dataframe

"We could see that few coloumns are of int type, and other are of object type, So for using data we need to make them float data type"

```
df = df.astype("float32")
df.dtypes
[→ id
                                 float32
    target
                                 float32
    sensor1_measure
                                 float32
    sensor2_measure
                                 float32
    sensor3_measure
                                 float32
                                 . . .
    sensor105_histogram_bin7
                                 float32
    sensor105_histogram_bin8
                                 float32
    sensor105_histogram_bin9
                                 float32
                                 float32
    sensor106_measure
```

▼ Drop useless coloumn from feature

Length: 172, dtype: object

sensor107_measure

5 rows × 171 columns

```
"""id coloumn is just index, we don't need it , so we will drop it"""
df = df.drop(["id"],axis=1)
df.head()
```

float32

target	sensor1_measure	sensor2_measure	sensor3_measure	sensor4_measure	sensor5_measure	sensor6_measure	sensor7_histogram_bin0	sensor7_histogram_bin1	sensor7_histo
0.0	76698.0	NaN	2.130706e+09	280.0	0.0	0.0	0.0	0.0	
0.0	33058.0	NaN	0.000000e+00	NaN	0.0	0.0	0.0	0.0	
0.0	41040.0	NaN	2.280000e+02	100.0	0.0	0.0	0.0	0.0	
0.0	12.0	0.0	7.000000e+01	66.0	0.0	10.0	0.0	0.0	
0.0	60874.0	NaN	1.368000e+03	458.0	0.0	0.0	0.0	0.0	
	0.0 0.0 0.0 0.0	0.0 76698.0 0.0 33058.0 0.0 41040.0 0.0 12.0	0.0 76698.0 NaN 0.0 33058.0 NaN 0.0 41040.0 NaN 0.0 12.0 0.0	0.0 76698.0 NaN 2.130706e+09 0.0 33058.0 NaN 0.000000e+00 0.0 41040.0 NaN 2.280000e+02 0.0 12.0 0.0 7.000000e+01	0.0 76698.0 NaN 2.130706e+09 280.0 0.0 33058.0 NaN 0.000000e+00 NaN 0.0 41040.0 NaN 2.280000e+02 100.0 0.0 12.0 0.0 7.000000e+01 66.0	0.0 76698.0 NaN 2.130706e+09 280.0 0.0 0.0 33058.0 NaN 0.000000e+00 NaN 0.0 0.0 41040.0 NaN 2.280000e+02 100.0 0.0 0.0 12.0 0.0 7.000000e+01 66.0 0.0	0.0 76698.0 NaN 2.130706e+09 280.0 0.0 0.0 0.0 33058.0 NaN 0.000000e+00 NaN 0.0 0.0 0.0 41040.0 NaN 2.280000e+02 100.0 0.0 0.0 0.0 12.0 0.0 7.000000e+01 66.0 0.0 10.0	0.0 76698.0 NaN 2.130706e+09 280.0 0.0 0.0 0.0 0.0 0.0 33058.0 NaN 0.000000e+00 NaN 0.0 0.0 0.0 0.0 41040.0 NaN 2.280000e+02 100.0 0.0 0.0 0.0 0.0 12.0 0.0 7.000000e+01 66.0 0.0 10.0 10.0 0.0	0.0 33058.0 NaN 0.000000e+00 NaN 0.0 0.0 0.0 0.0 0.0 41040.0 NaN 2.280000e+02 100.0 0.0 0.0 0.0 0.0 0.0 0.0 12.0 0.0 7.000000e+01 66.0 0.0 10.0 0.0 0.0 0.0

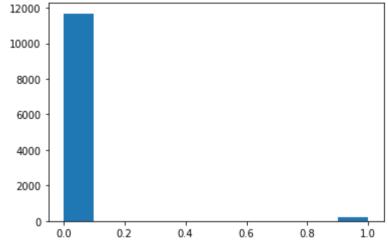
Train(D1), validation(D2) and test(D_test) split

```
<a list of 10 Patch objects>)
6000 -
5000 -
4000 -
2000 -
1000 -
```

plt.hist(y_test)

0.0

0.2



For each feature create new feature, that tells presence of nan, because nan values also contains some

information

```
coloumns = D1.columns
#Train
for coloumn in tqdm(coloumns):
    D1[coloumn + "_nan"] = [1.0 if np.isnan(x) else 0.0 for x in D1[coloumn]]
#Validation
for coloumn in tqdm(coloumns):
    D2[coloumn + "_nan"] = [1.0 if np.isnan(x) else 0.0 for x in D2[coloumn]]
#Test
for coloumn in tqdm(coloumns):
    D_test[coloumn + "_nan"] = [1.0 if np.isnan(x) else 0.0 for x in D_test[coloumn]]
                      | 0/170 [00:00<?, ?it/s]/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:5: SettingWithCopyWarning:
     A value is trying to be set on a copy of a slice from a DataFrame.
     Try using .loc[row_indexer,col_indexer] = value instead
     See the caveats in the documentation: <a href="https://pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy">https://pandas.pydata.org/pandas.pydata.org/pandas-docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy</a>
     100%|
                       | 170/170 [00:11<00:00, 14.81it/s]
                        170/170 [00:01<00:00, 89.26it/s]
     100%|
                      [| 170/170 [00:03<00:00, 50.33it/s]
```

▼ Drop features with more than 50% nan values

```
#Train
D1 = D1.drop(high_nan_features,axis=1)

#Validation
D2 = D2.drop(high_nan_features,axis=1)

#Test
D_test = D_test.drop(high_nan_features,axis=1)

D1.head()

D1.head()
```

```
nan with mean is not sensible at all
```

```
#Train
D1 = D1.fillna(median)
#Validation
D2 = D2.fillna(median)
                                                                                 #Here we are filling test nan values with, train median
#Test
                                                                                 #Here we are filling test nan values with, train median
D_test = D_test.fillna(median)
```

D test.head()

₽		sensor1_measure	sensor3_measure	sensor4_measure	sensor5_measure	sensor6_measure	sensor7_histogram_bin0	sensor7_histogram_bin1	sensor7_histogram_bin2	sensor7_h:	
	39062	40868.0	2.080000e+02	170.0	0.0	0.0	0.0	0.0	0.0		
	20915	46282.0	2.130706e+09	2500.0	0.0	0.0	20614.0	96250.0	174206.0		
	30989	39552.0	0.000000e+00	126.0	0.0	0.0	0.0	0.0	0.0		
	6964	1436.0	6.800000e+01	66.0	0.0	0.0	0.0	0.0	0.0		
	44837	33342.0	3.240000e+02	304.0	0.0	0.0	0.0	0.0	0.0		
ļ	5 rows × 332 columns										

https://colab.research.google.com/drive/1WNYDVia984vZFibC2FoullOrMzV2Euq7#scrollTo=3q2kci9Xlsi7&printMode=truewardsites and the second of the control of t

We have 100 simple sensor, and 7 time based sensor. Here we will extract min, max and mean from those time

```
based sensors
def mean(a,b,c,d,e,f,g,h,i,j):
    list = [a,b,c,d,e,f,g,h,i,j]
    return np.mean(list_)
def min (a,b,c,d,e,f,g,h,i,j):
    list = [a,b,c,d,e,f,g,h,i,j]
    return min(list_)
def max (a,b,c,d,e,f,g,h,i,j):
    list_{=} = [a,b,c,d,e,f,g,h,i,j]
    return max(list_)
#Train
for i in tqdm(range(0,len(time_based_sensor))):
    D1[time_based_sensor[i][0].split("_")[0] + "_mean"] = D1.apply(lambda row : mean(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time based sensor[i][3]] , row[time based sensor[i][4]] , row[time based sensor[i][5]] ,
                                                                                     row[time based sensor[i][6]] , row[time based sensor[i][7]] , row[time based sensor[i][8]] ,
                                                                                     row[time_based_sensor[i][9]] ) , axis = 1)
    D1[time_based_sensor[i][0].split("_")[0] + "_min"] = D1.apply(lambda row : min_(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                                                                     row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
                                                                                     row[time based sensor[i][9]] ) , axis = 1)
    D1[time_based_sensor[i][0].split("_")[0] + "_max"] = D1.apply(lambda row : max_(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                                                                     row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
                                                                                     row[time based sensor[i][9]] ) , axis = 1)
#Validation
for i in tqdm(range(0,len(time_based_sensor))):
    D2[time_based_sensor[i][0].split("_")[0] + "_mean"] = D2.apply(lambda row : mean(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                                                                     row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
                                                                                     row[time_based_sensor[i][9]] ) , axis = 1)
    D2[time_based_sensor[i][0].split("_")[0] + "_min"] = D2.apply(lambda row : min_(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                                                                     row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
                                                                                     row[time_based_sensor[i][9]] ) , axis = 1)
    D2[time_based_sensor[i][0].split("_")[0] + "_max"] = D2.apply(lambda row : max_(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][2]] ,
                                                                                     row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                                                                     row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
                                                                                     row[time_based_sensor[i][9]] ) , axis = 1)
#Test
for i in tqdm(range(0,len(time_based_sensor))):
```

```
row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] ,
                                          row[time_based_sensor[i][6]] , row[time_based_sensor[i][7]] , row[time_based_sensor[i][8]] ,
```

D_test[time_based_sensor[i][0].split("_")[0] + "_mean"] = D_test.apply(lambda row : mean(row[time_based_sensor[i][0]] , row[time_based_sensor[i][1]] , row[time_based_sensor[i][0]] .

row[time based sensor[i][9]]) , axis = 1)

row[time_based_sensor[i][9]]) , axis = 1)

row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] , row[time based sensor[i][6]] , row[time based sensor[i][7]] , row[time based sensor[i][8]] ,

row[time_based_sensor[i][3]] , row[time_based_sensor[i][4]] , row[time_based_sensor[i][5]] , row[time based sensor[i][6]] , row[time based sensor[i][7]] , row[time based sensor[i][8]] , D test.head()

С→	100%	7/7	[00:43<00:00,	6.28s/it]
_	100%	7/7	[00:06<00:00,	1.08it/s]
	100%	7/7	[00:12<00:00,	1.78s/it]

	sensor1_measure	sensor3_measure	sensor4_measure	sensor5_measure	sensor6_measure	sensor7_histogram_bin0	sensor7_histogram_bin1	sensor7_histogram_bin2	sensor7_h:
39062	40868.0	2.080000e+02	170.0	0.0	0.0	0.0	0.0	0.0	
20915	46282.0	2.130706e+09	2500.0	0.0	0.0	20614.0	96250.0	174206.0	
30989	39552.0	0.000000e+00	126.0	0.0	0.0	0.0	0.0	0.0	
6964	1436.0	6.800000e+01	66.0	0.0	0.0	0.0	0.0	0.0	
44837	33342.0	3.240000e+02	304.0	0.0	0.0	0.0	0.0	0.0	

5 rows × 353 columns

▼ Removing all the features which are least correlated to our target

```
#Train
D1 = D1.drop(bottom_n_features.keys(),axis=1)

#Validation
D2 = D2.drop(bottom_n_features.keys(),axis=1)

#test
D_test = D_test.drop(bottom_n_features.keys(),axis=1)
```

Removing all the intercorrelated features

```
#Train
D1 = D1.drop(useless_features , axis=1)

#Validation
D2 = D2.drop(useless_features , axis=1)

#Test
D_test = D_test.drop(useless_features , axis=1)

print("train_size = ",D1.shape)
print("validation_size = ",D2.shape)
print("test_size = ",D_test.shape)

C> train_size = (42000, 232)
    validation_size = (6120, 232)
    test_size = (11880, 232)
```

▼ Feature Scaling

```
#Train
D1 = scaler.transform(D1)

#Train
D2 = scaler.transform(D2)

#Test
D_test = scaler.transform(D_test)
```

▼ We will over sample our minority(down hole equip fail) using RandomOverSampler

```
from imblearn.over_sampling import RandomOverSampler
from collections import Counter

oversample = RandomOverSampler(sampling_strategy='minority')

# fit and apply the transform
D1_over , y_1_over = oversample.fit_resample(D1, y_1)
```

/usr/local/lib/python3.6/dist-packages/sklearn/externals/six.py:31: FutureWarning: The module is deprecated in version 0.21 and will be removed in version 0.23 since we've "(https://pypi.org/project/six/).", FutureWarning)
/usr/local/lib/python3.6/dist-packages/sklearn/utils/deprecation.py:144: FutureWarning: The sklearn.neighbors.base module is deprecated in version 0.22 and will be removed

warnings.warn(message, FutureWarning)
/usr/local/lib/python3.6/dist-packages/sklearn/utils/deprecation.py:87: FutureWarning: Function safe_indexing is deprecated; safe_indexing is deprecated in version 0.22 and warnings.warn(msg, category=FutureWarning)

```
# summarize class distribution
print("distribution before oversampling = ",Counter(y_1))
print("distribution after oversampling = ",Counter(y_1_over))
print("-"*50)
print("shape of X_train = ", D1.shape)
print("shape of y_train = ", len(y_1))
print("-"*50)
print("-"*50)
print("shape of X_train_over = ", D1_over.shape)
print("shape of y_train_over = ", y_1_over.shape)
```

 \Box

```
distribution before oversampling = Counter({0.0: 41300, 1.0: 700})
distribution after oversampling = Counter({0.0: 41300, 1.0: 41300})
```

Making 3 dataset(Da,Db,Dc) for 3 models

```
def make sample(data=D1 over ,label = y 1 over , size = 42000):
    random index = np.random.randint(0 , len(data) , size)
    sampled_data = []
    sampled_label = []
    for random in random index:
       sampled data.append(data[random])
       sampled_label.append(label[random])
    return np.array(sampled_data),np.array(sampled_label)
Da,ya = make sample(data=D1 over ,label = y 1 over , size = 90000)
Db,yb = make_sample(data=D1_over ,label = y_1_over , size = 90000)
Dc,yc = make_sample(data=D1_over ,label = y_1_over , size = 90000)
print("*Distributon of data*")
print("ya = ",Counter(ya))
print("yb = ",Counter(yb))
print("yc = ",Counter(yc))
 r→ *Distributon of data*
    ya = Counter(\{1.0: 45216, 0.0: 44784\})
    yb = Counter(\{0.0: 45067, 1.0: 44933\})
    yc = Counter(\{1.0: 45096, 0.0: 44904\})
```

→ Making 3 models

▼ Decision Tree

```
from sklearn.metrics import f1_score
from sklearn.metrics import roc_curve
from sklearn.metrics import auc
from sklearn.metrics import precision_score
from sklearn.metrics import recall_score
from sklearn.metrics import confusion_matrix
import seaborn as sns
from sklearn.tree import DecisionTreeClassifier
def plot_confusion_matrix(test_y, predict_y,lables):
    C = confusion_matrix(test_y, predict_y)
    print("Number of misclassified points ",(len(test_y)-np.trace(C))/len(test_y)*100)
    \# C = 9,9 matrix, each cell (i,j) represents number of points of class i are predicted class j
    A = (((C.T)/(C.sum(axis=1))).T)
    #divid each element of the confusion matrix with the sum of elements in that column
    \# C = [[1, 2],
         [3, 4]]
    # C.T = [[1, 3],
             [2, 4]]
    # C.sum(axis = 1) axis=0 corresponds to columns and axis=1 corresponds to rows in two diamensional array
    \# C.sum(axix = 1) = [[3, 7]]
    \# ((C.T)/(C.sum(axis=1))) = [[1/3, 3/7]
                               [2/3, 4/7]]
    \# ((C.T)/(C.sum(axis=1))).T = [[1/3, 2/3]
                                [3/7, 4/7]
    \# sum of row elements = 1
    B = (C/C.sum(axis=0))
    #divid each element of the confusion matrix with the sum of elements in that row
    \# C = [[1, 2],
          [3, 4]]
    # C.sum(axis = 0) axis=0 corresonds to columns and axis=1 corresponds to rows in two diamensional array
    \# C.sum(axix = 0) = [[4, 6]]
    \# (C/C.sum(axis=0)) = [[1/4, 2/6],
                          [3/4, 4/6]]
    labels = lables
    cmap=sns.light_palette("green")
    # representing A in heatmap format
    print("-"*50, "Confusion matrix", "-"*50)
    plt.figure(figsize=(10,5))
    sns.heatmap(C, annot=True, cmap=cmap, fmt=".3f", xticklabels=labels, yticklabels=labels)
    plt.xlabel('Predicted Class')
    plt.ylabel('Original Class')
    plt.show()
    print("-"*50, "Precision matrix", "-"*50)
    plt.figure(figsize=(10,5))
    sns.heatmap(B, annot=True, cmap=cmap, fmt=".3f", xticklabels=labels, yticklabels=labels)
    plt.xlabel('Predicted Class')
    plt.ylabel('Original Class')
    plt.show()
    print("Sum of columns in precision matrix", B.sum(axis=0))
    # representing B in heatmap format
    plt.figure(figsize=(10,5))
    sns.heatmap(A, annot=True, cmap=cmap, fmt=".3f", xticklabels=labels, yticklabels=labels)
    plt.xlabel('Predicted Class')
    plt.ylabel('Original Class')
    plt.show()
    print("Sum of rows in precision matrix", A.sum(axis=1))
```

```
DT best = DecisionTreeClassifier(class weight="balanced" , max depth=30 , min samples split = 30)
  DT_best.fit(Da,ya)
  print("Train F1 Score = ",f1_score(ya , DT_best.predict(Da)))
  print("Validation F1 Score = ",f1_score(y_2 , DT_best.predict(D2)))
   Train F1 Score = 0.9975291210730673
       Validation F1 Score = 0.5949820788530467
▼ Gradient_Boost_1
  import xgboost as xgb
  GB1 = xgb.XGBClassifier(max_depth=100,learning_rate=0.12,n_estimators=2000,colsample_bytree=0.4,subsample=0.4)
  GB1.fit(Db,yb)
  print("Train F1 Score = ",f1_score(yb , GB1.predict(Db)))
  print("Validation F1 Score = ",f1_score(y_2 , GB1.predict(D2)))
   r→ Train F1 Score = 1.0
       Validation F1 Score = 0.7631578947368423
▼ Gradient_Boost_2
  GB2 = xgb.XGBClassifier(max_depth=60,learning_rate=0.1,n_estimators=3000,colsample_bytree=0.7,subsample=0.7)
  GB2.fit(Dc,yc)
  print("Train F1 Score = ",f1_score(yc , GB2.predict(Dc)))
  print("Validation F1 Score = ",f1_score(y_2 , GB2.predict(D2)))
   Train F1 Score = 1.0
       Validation F1 Score = 0.7911111111111111

▼ Stacking Classifier

  y_1 = np.array(y_1)
  y_2 = np.array(y_2)
  from sklearn.linear_model import LogisticRegression
  from mlxtend.classifier import StackingCVClassifier
  GB = xgb.XGBClassifier(max_depth=50,learning_rate=0.1,n_estimators=3000,colsample_bytree=0.7,subsample=0.7)
  SC = StackingCVClassifier(classifiers=[DT_best,GB1,GB2],
                              use_probas=False,
                              use_features_in_secondary=True,
                              meta_classifier=GB)
  SC.fit(D1,y_1)
  print("Train F1 Score = ",f1_score(y_1 , SC.predict(D1)))
  print("Validation F1 Score = ",f1_score(y_2 , SC.predict(D2)))
   Train F1 Score = 1.0
       Validation F1 Score = 0.8125
  print("Test F1 Score = ",f1_score(y_test , SC.predict(D_test)))
   Test F1 Score = 0.8222811671087533
▼ AUC Score
  train fpr, train tpr, tr thresholds = roc curve(y 1, SC.predict(D1))
  test_fpr, test_tpr, te_thresholds = roc_curve(y_test , SC.predict(D_test))
  plt.plot(train_fpr, train_tpr, label="train AUC ="+str(auc(train_fpr, train_tpr)))
  plt.plot(test_fpr, test_tpr, label="test AUC ="+str(auc(test_fpr, test_tpr)))
  plt.legend()
  plt.xlabel("FPR")
  plt.ylabel("TPR")
  plt.title("ROC curve")
  plt.grid()
  plt.show()
   \Box
                            ROC curve
         1.0
         0.8
         0.6
         0.4
         0.2
                               train AUC =1.0
                               test AUC = 0.8903869200479371
         0.0
                    0.2
                                   0.6
                                                 1.0
                               FPR
Precision
  print("Train precision Score = ",precision_score(y_1 , SC.predict(D1)))
  print("Test precision Score = ",precision_score(y_test , SC.predict(D_test)))
```

Stacking_Classifier_Submission1.ipynb - Colaboratory

▼ Recall

 \Box

06/10/2020

Train precision Score = 1.0

Test precision Scare - A 265021727780/072

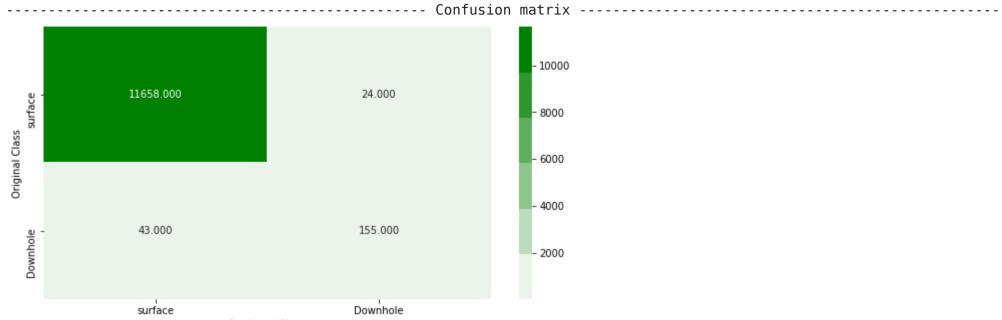
```
print("Train recall Score = ",recall_score(y_1 , SC.predict(D1)))
print("Test recall Score = ",recall_score(y_test , SC.predict(D_test)))

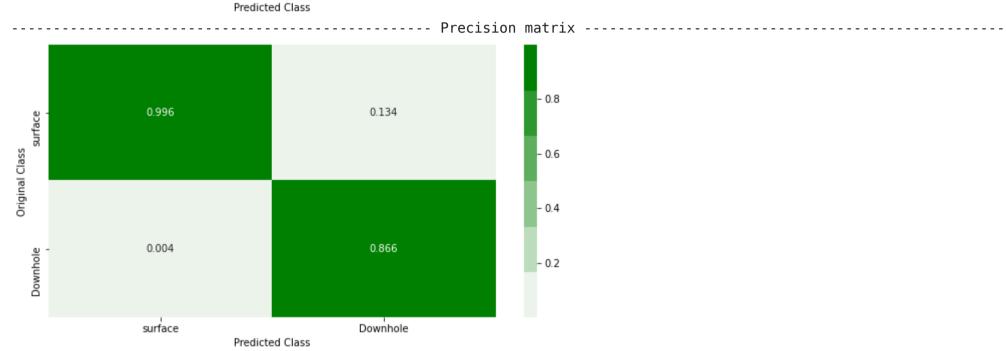
Train recall Score = 1.0
Test recall Score = 0.78282828282829
```

▼ Confusion matrix test

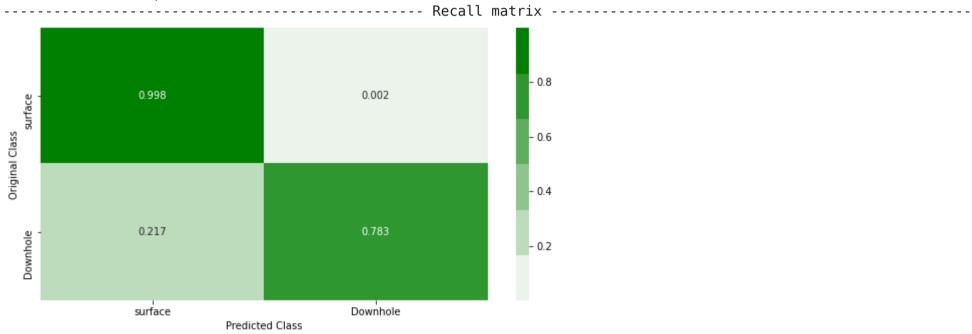
```
lables = ["surface" , "Downhole"]
plot_confusion_matrix(y_test, SC.predict(D_test) , lables)
```

Number of misclassified points 0.563973063973064





Sum of columns in precision matrix [1. 1.]



Sum of rows in precision matrix $[1. \ 1.]$

→ Result

• Just using 70% of total data, we mannaged to get F1 score of 0.82. Which is pretty good