

# Plan

- Dual of a Primal
- Fundamental theorem of Duality
- The complementary slackness Theorem

## Dual of a Primal

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- The LPP(\*) is called a **Primal** problem.

- **Theorem 1:** If  $\mathbf{x} \in \text{Fea}(P)$  and  $\mathbf{y} \in \text{Fea}(D)$ , then  $\mathbf{c}^T \mathbf{x} \leq \mathbf{b}^T \mathbf{y}$ .



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- **Theorem 3:** The Dual of the Dual (D) (of the Primal (P)) is the Primal (P).

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- Hence  $\mathbf{x} = [2, 0]^T$ , is **optimal** for the **Primal (P)** and  $\mathbf{y} = [\frac{5}{3}, 0]^T$  is **optimal** for the **Dual (D)**.



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- Any straight line passing through the origin is a cone.  
Union of a finite number of straight lines passing through the origin is also a cone.
- Also a **cone**  $T$  is said to be a **convex cone** if it is also a **convex subset** of  $\mathbb{R}^n$ .
- **Exercise:** If  $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k$  are all vectors in  $\mathbb{R}^n$  then check that  

$$T = \{\alpha_1 \mathbf{a}_1 + \alpha_2 \mathbf{a}_2 + \dots + \alpha_k \mathbf{a}_k : \alpha_i \geq 0 \text{ for all } i = 1, \dots, k\}$$
is a **convex cone**.
- $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k$  are called **generators** of the **convex cone**  $T$ .

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- **Theorem 4:** (**Farka's Lemma**) Exactly **one** of the following two systems has a solution.

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- **Corollary 4** implies if the **Primal** does **not** have a **feasible solution** then the **dual** does not have an **optimal solution**.

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- If  $\mathbf{x} \in Fea(P)$  and  $\mathbf{y} \in Fea(D)$  then  $\mathbf{c}^T \mathbf{x} \leq \mathbf{b}^T \mathbf{y}$ , hence system (1) has a solution  $\Leftrightarrow$  system (1)'' has a solution:



$$A_{m \times n} \mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq \mathbf{0} \quad (1)''$$

$$A^T \mathbf{y} \geq \mathbf{c}, \mathbf{y} \geq \mathbf{0}$$

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- System (1)'' can be written as:

$$\begin{bmatrix} A_{m \times n} & \mathbf{0}_{m \times m} \\ \mathbf{0}_{n \times n} & -A_{n \times m}^T \\ -\mathbf{c}_{1 \times n}^T & \mathbf{b}_{1 \times m}^T \end{bmatrix} \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} \leq \begin{bmatrix} \mathbf{b} \\ -\mathbf{c} \\ 0 \end{bmatrix}, \quad \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} \geq \begin{bmatrix} \mathbf{0}_{n \times 1} \\ \mathbf{0}_{m \times 1} \end{bmatrix}$$

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- By **corollary 4**, exactly one of the two systems, (1'') (given above) and (2'') (given below) has a solution.

$$\begin{bmatrix} \mathbf{z}_{1 \times m}^T & \mathbf{w}_{1 \times n}^T & a_{1 \times 1} \end{bmatrix} \begin{bmatrix} A_{m \times n} & \mathbf{0}_{m \times m} \\ \mathbf{0}_{n \times n} & -A_{n \times m}^T \\ -\mathbf{c}_{1 \times n}^T & \mathbf{b}_{1 \times m}^T \end{bmatrix} \geq \begin{bmatrix} \mathbf{0}_{1 \times n} & \mathbf{0}_{1 \times m} \end{bmatrix},$$

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 $x_j = 0$  whenever  $(A^T \mathbf{y})_j > c_j, j = 1, 2, \dots, n$  (1)  
 and  
 $y_i = 0$  whenever  $(A\mathbf{x})_i < b_i, i = 1, 2, \dots, m.$  (1\*)

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- Check that  $[\frac{1}{2}, 3, 0]^T \in \text{Opt}(P)$  and  $[1, 1]^T \in \text{Opt}(D)$ .