Department of Computer Science and Engineering

Shivanirudh S G, 185001146, Semester VII

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UCS1712 - Graphics and Multimedia Lab

Exercise 8: 3-Dimensional Transformations in C++ using OpenGL

Aim:

Perform basic 3D Transformations on any 3D Object.

Code:

```
1 #ifndef LOPENGL_H
2 #define LOPENGL_H
3
4 #include <GL/freeglut.h>
5 #include <GL/gl.h>
6 #include <GL/glu.h>
7 #include <math.h>
8 #include <stdio.h>
9 #include <stdib.h>
10 #include <iostream>
11 #include <vector>
12 #include <ctime>
13 #include <tuple>
14 #include <unistd.h>
15 using namespace std;
16
17 #endif
```

```
1 #ifndef LUTIL_H
2 #define LUTIL_H
4 #include "Headers.h"
6 //Screen Constants
7 const int SCREEN_WIDTH = 1362;
8 const int SCREEN_HEIGHT = 750;
9 const int SCREEN_FPS = 60;
10 const int POINT_SIZE=3;
12 typedef float MatrixDim [4][4];
13 MatrixDim transformation_matrix;
15 static GLfloat input[8][3]={
      \{40,40,-50\},\{90,40,-50\},\{90,90,-50\},\{40,90,-50\},
      {30,30,0},{80,30,0},{80,80,0},{30,80,0}
17
18
19 };
20
21 float output[8][3];
22 float tx,ty,tz;
23 float sx,sy,sz;
24 float angle;
25
26 int choice, choiceRot;
27
28 void init();
30 void render();
32 void setIdentityM(MatrixDim m);
34 void translate(int tx, int ty, int tz);
35
36 void scale(int sx, int sy, int sz);
37
38 void RotateX(float angle);
39
40 void RotateY(float angle);
41
42 void RotateZ(float angle);
44 void multiplyMatrices();
46 void Axes(void);
48 void draw(float a[8][3]);
49
50 #endif
#include "Signatures.h"
3 void init(){
      glClearColor(0.0,0.0,0.0,1.0);
      glOrtho(-454.0,454.0,-250.0,250.0,-250.0,250.0);
      glEnable(GL_DEPTH_TEST);
6
7 }
```

```
9 void render(){
10
11
       while(true){
12
            glClear(GL_COLOR_BUFFER_BIT|GL_DEPTH_BUFFER_BIT);
13
14
            Axes();
           glColor3f(1.0,0.0,0.0);
15
            draw(input);
           setIdentityM(transformation_matrix);
17
18
           cout << "Choose transformation: " << endl;</pre>
19
           cout << "1 for Translation" << end1 << "2 for Rotation" << end1;</pre>
20
           cout << "3 for Scaling" << endl << "0 to Exit" << endl;</pre>
21
           cout << "Enter your choice: ";cin >> choice;
22
23
           cout << "transformation: "<<choice << endl;</pre>
24
25
26
           if(choice == 1){
                cout << "Enter the translation factor for X, Y and Z: ";</pre>
27
28
                cin>>tx >> ty >> tz;
           }
29
            else if(choice == 2){
30
31
                cout << "Enter the rotation angle: ";</pre>
                cin>>angle;
32
33
                cout << "Choose axis to rotate around: " << endl;</pre>
34
                cout<<"1 for around X axis"<<endl<<"2 for around Y axis</pre>
35
       "<<endl;
                cout << "3 for around Z axis" << endl;</pre>
36
37
                cout << "Enter your choice: ";cin>>choiceRot;
38
39
            else if(choice == 3){
40
                cout << "Enter the scaling factor for X, Y and Z: ";</pre>
41
42
                cin>>sx >> sy >> sz;
           }
43
44
            else if(choice){
                cout << "Invalid option" << endl;</pre>
45
46
            }
47
            else;
48
           switch(choice){
49
                case 1:
50
                     translate(tx,ty,tz);
51
                     break;
52
                case 2:
53
                     switch (choiceRot) {
54
                          case 1:
55
                              RotateX(angle);
56
57
                              break:
                          case 2:
58
59
                              RotateY(angle);
                              break;
60
61
                          case 3:
                              RotateZ(angle);
62
63
                              break;
```

```
default:
64
65
                              break;
66
                     multiplyMatrices();
67
                     for (int i = 0; i < 8;i++){</pre>
68
                         for (int j = 0; j < 3; j++) {
69
                              cout << output[i][j] << " ";</pre>
70
71
72
                         cout << endl;</pre>
                     }
73
                     break;
74
75
                 case 3:
                     scale(sx,sy,sz);
76
77
                     multiplyMatrices();
                     break;
78
            }
79
80
            draw(output);
81
82
            glFlush();
       }
83
84 }
85
86 void setIdentityM(MatrixDim m){
87 for(int i=0;i<4;i++)
       for(int j=0; j<4; j++)</pre>
88
89
            m[i][j]=(i==j);
90 }
91
92 void translate(int tx,int ty,int tz){
93
94
        for(int i=0;i<8;i++){</pre>
            output[i][0]=input[i][0]+tx;
95
            output[i][1]=input[i][1]+ty;
96
            output[i][2]=input[i][2]+tz;
97
98
99 }
100
101 void scale(int sx,int sy,int sz){
       transformation_matrix[0][0]=sx;
102
103
        transformation_matrix[1][1]=sy;
        transformation_matrix[2][2]=sz;
104
105 }
106
107 void RotateX(float angle){
        cout << angle << endl;</pre>
108
        angle = angle * 3.1416 / 180;
109
        cout << angle << endl;</pre>
       transformation_matrix[1][1] = cos(angle);
111
        transformation_matrix[1][2] = -sin(angle);
112
113
        transformation_matrix[2][1] = sin(angle);
        transformation_matrix[2][2] = cos(angle);
114
115 }
116
void RotateY(float angle){
        angle = angle *3.1416/180;
118
       transformation_matrix[0][0] = cos(angle);
119
120
        transformation_matrix[0][2] = -sin(angle);
```

```
transformation_matrix[2][0] = sin(angle);
121
122
        transformation_matrix[2][2] = cos(angle);
123
124 }
125
126 void RotateZ(float angle){
127
       angle = angle *3.1416/180;
       transformation_matrix[0][0] = cos(angle);
128
       transformation_matrix[0][1] = sin(angle);
129
130
       transformation_matrix[1][0] = -sin(angle);
        transformation_matrix[1][1] = cos(angle);
131
132 }
133
134 void multiplyMatrices(){
       for (int i=0; i < 8; i++) {</pre>
135
            for(int j=0;j<3;j++){</pre>
136
137
                output[i][j]=0;
                for(int k=0;k<3;k++){</pre>
138
139
                     output[i][j]+=(input[i][k]*transformation_matrix[k
       ][j]);
            }
141
       }
142
143
144 }
145 void Axes(void){
       glColor3f (1.0, 1.0, 1.0);
146
       glBegin(GL_LINES);
147
            glVertex2s(-1000 ,0);
148
            glVertex2s( 1000 ,0);
149
150
        glEnd();
        glBegin(GL_LINES);
151
            glVertex2s(0,-1000);
152
            glVertex2s(0 , 1000);
       glEnd();
154
155 }
156 void draw(float a[8][3]){
157
        glBegin(GL_QUADS);
            glColor3f(0.7,0.4,0.5); //behind
158
159
            glVertex3fv(a[0]);
            glVertex3fv(a[1]);
            glVertex3fv(a[2]);
161
162
            glVertex3fv(a[3]);
163
            glColor3f(0.8,0.2,0.4); //bottom
164
            glVertex3fv(a[0]);
            glVertex3fv(a[1]);
166
167
            glVertex3fv(a[5]);
            glVertex3fv(a[4]);
168
169
            glColor3f(0.3,0.6,0.7); //left
            glVertex3fv(a[0]);
172
            glVertex3fv(a[4]);
            glVertex3fv(a[7]);
173
174
            glVertex3fv(a[3]);
175
176
            glColor3f(0.2,0.8,0.2); //right
```

```
glVertex3fv(a[1]);
177
178
           glVertex3fv(a[2]);
           glVertex3fv(a[6]);
179
           glVertex3fv(a[5]);
180
181
           glColor3f(0.7,0.7,0.2); //up
182
           glVertex3fv(a[2]);
183
           glVertex3fv(a[3]);
184
185
           glVertex3fv(a[7]);
           glVertex3fv(a[6]);
186
187
           glColor3f(1.0,0.1,0.1);
188
           glVertex3fv(a[4]);
189
           glVertex3fv(a[5]);
190
           glVertex3fv(a[6]);
191
           glVertex3fv(a[7]);
192
193
       glEnd();
194
195 }
 1 #include "Helpers.h"
 3 int main( int argc, char* args[] ){
       glutInit(&argc,args);
 5
       glutInitDisplayMode(GLUT_SINGLE|GLUT_RGB|GLUT_DEPTH);
       glutInitWindowSize(1362,750);
       glutInitWindowPosition(0,0);
       glutCreateWindow( "OpenGL" );
 9
10
11
       init();
12
13
       glutDisplayFunc(render);
14
15
       glutMainLoop();
16
       return 0;
17
18 }
```

Output:

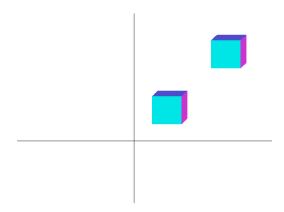
Translation:

 ${\bf Choose\ transformation:}$

- 1 for Translation
- 2 for Rotation
- 3 for Scaling
- 0 to Exit

Enter your choice: 1

Enter the translation factor for X, Y and Z: 100 100 100



Rotation - X axis:

Choose transformation:

1 for Translation

2 for Rotation

3 for Scaling

0 to Exit

Enter your choice: 2

Enter the rotation angle: 45

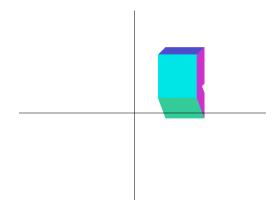
Choose axis to rotate around:

1 for around X axis

2 for around Y axis

3 for around Z axis

Enter your choice: 1



Rotation - Y axis:

Choose transformation:

1 for Translation

2 for Rotation

3 for Scaling

0 to Exit

Enter your choice: 2

Enter the rotation angle: 45

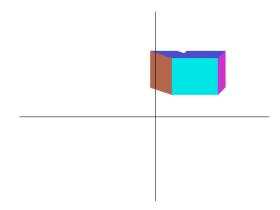
Choose axis to rotate around:

1 for around X axis

2 for around Y axis

3 for around Z axis

Enter your choice: 2



Rotation - Z axis:

Choose transformation:

1 for Translation

2 for Rotation

3 for Scaling

0 to Exit

Enter your choice: 2

Enter the rotation angle: 45

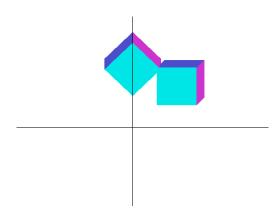
Choose axis to rotate around:

1 for around X axis

2 for around Y axis

3 for around Z axis

Enter your choice: 3



Scaling:

Choose transformation:

1 for Translation

2 for Rotation

3 for Scaling

0 to Exit

Enter your choice: 3 Enter the translation factor for X, Y and Z: 2 2 2 $\,$

