

Why are seat belts firm instead of stretchy?

Chapter 11 – Impulse and Momentum

- Momentum, impulse

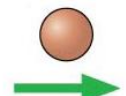
$$\vec{p} = m\vec{v} \quad \rightarrow \quad \vec{J} = \Delta\vec{p}$$

- When is momentum conserved?
- Collisions and explosions
- Rockets



The wall delivers an impulse to the ball.

Before:

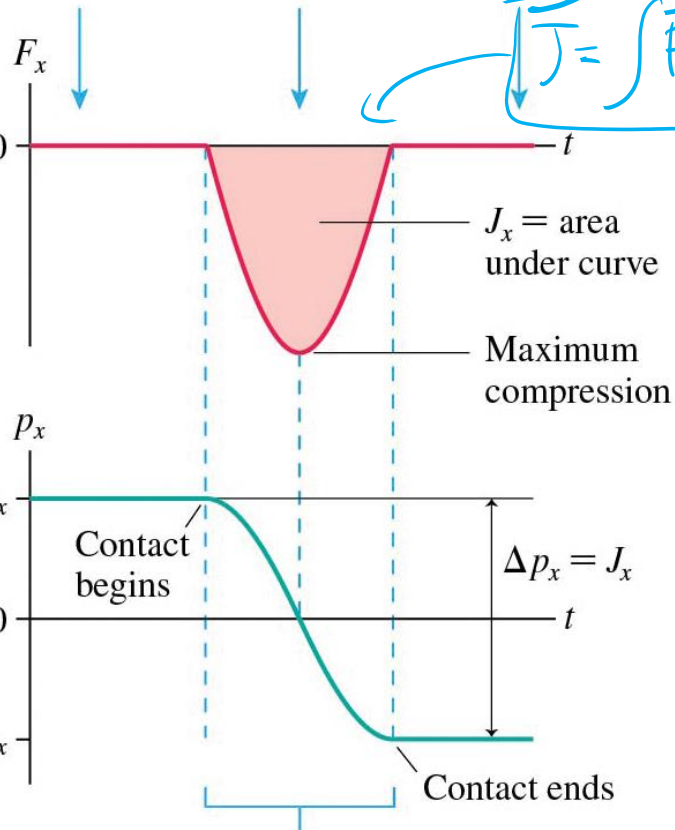


$$v_{ix} > 0$$

After:



$$v_{fx} < 0$$



Initially the ball is moving to the right.



Then it's hit to the left.



+



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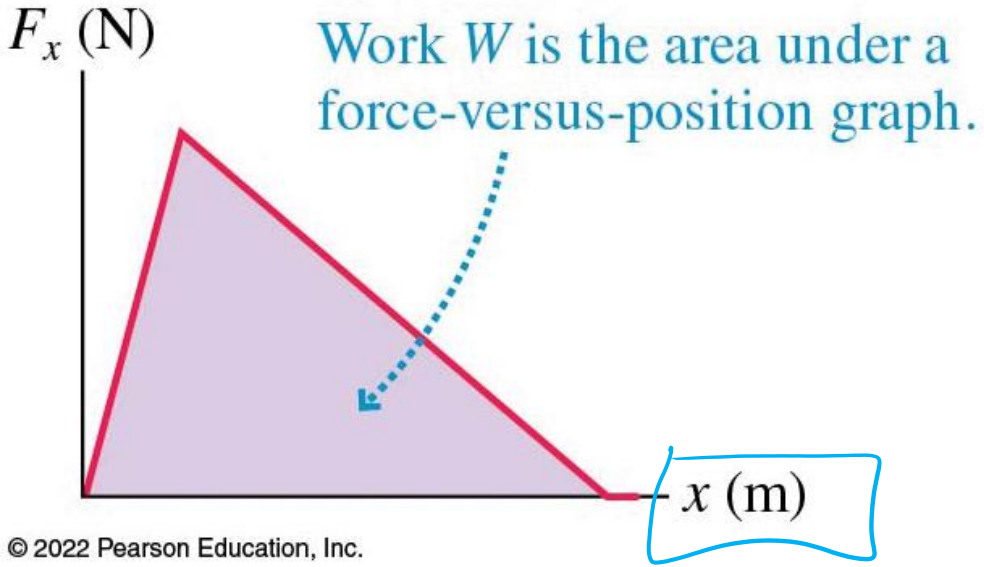


It rebounds to the left with no loss of speed.

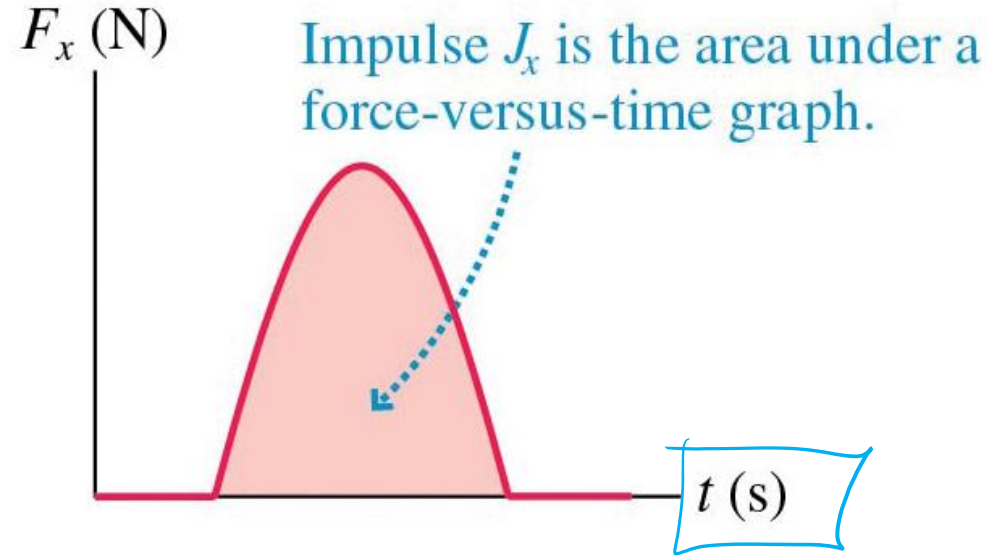
$$p_{ix} + J_x = p_{fx}$$

The impulse changes the ball's momentum.

Work versus Impulse



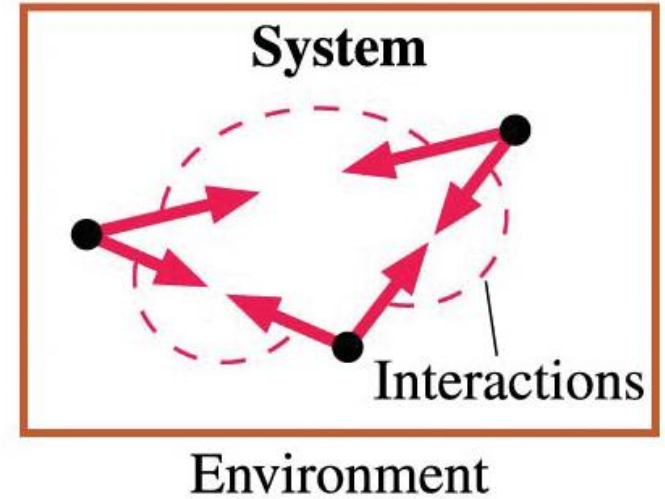
$$W = \int \vec{F}_{\text{ext}} \cdot d\vec{x}$$



$$\vec{J} = \int \vec{F}_{\text{ext}} dt = \Delta \vec{p}$$

Is momentum conserved?

The total momentum of an **isolated system** is conserved. The particles of an isolated system interact with each other but not with the environment. Regardless of how intense the interactions are, **the final momentum equals the initial momentum.**



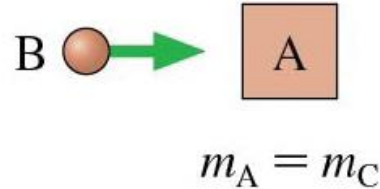
◀◀ **LOOKING BACK** Section 10.4 Energy conservation

Team Up Questions

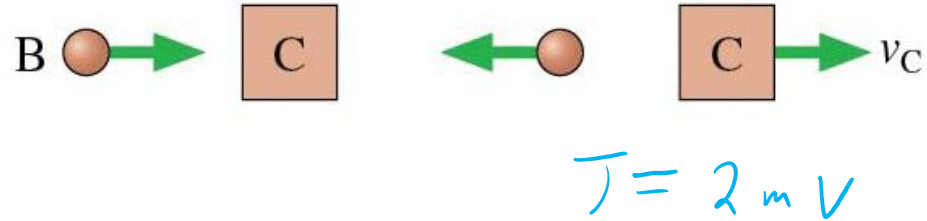
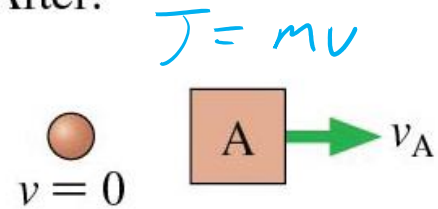
STOP TO THINK 11.3 Objects A and C are made of different materials, with different “springiness,” but they have the same mass and are initially at rest. When ball B collides with object A, the ball ends up at rest. When ball B is thrown with the same speed and collides with object C, the ball rebounds to the left. Compare the speeds of A and C after the collisions. Is v_A ~~greater than~~, ~~equal~~ to, or less than v_C ?

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Before:



After:



C: $J = \Delta p = \vec{p}_f - \vec{p}_i$

$\vec{p}_i = \text{right}$
 $\vec{p}_f = \text{left}$

Team Up Questions

② Wood cart (1 kg) versus metal cart (4 kg)

$$\int F dx = \text{same}$$

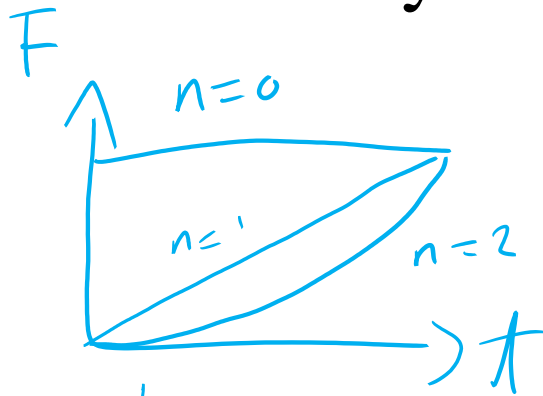
③

$$\int F dx = \text{same}$$

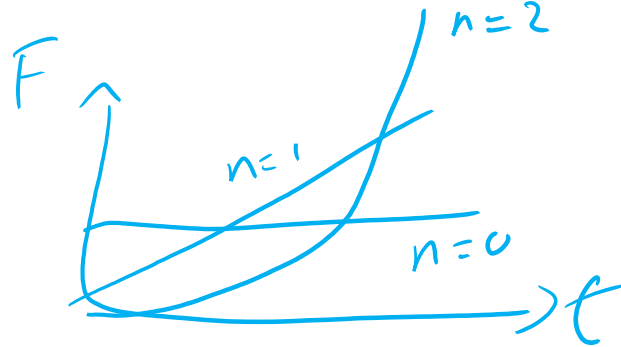
$$K = \frac{1}{2} m v^2 = \frac{p^2}{2m}$$

We want minimum F_{\max}

Why are seat belts firm instead of stretchy?



bad
areas \neq each other



$$\vec{F}(t) = \vec{A} t^n \quad A \text{ is unknown (so eliminate)}$$

$$\vec{J} = \text{constant} = 0 - \vec{p}_i = -m\vec{v}_i$$

$$\vec{J} = \int \vec{F}(t) dt = \int_0^T \vec{A} t^n dt = \vec{A} \frac{1}{n+1} T^{n+1}$$

$$\vec{J} = (\vec{A} T^n) \frac{T}{n+1} = (\vec{F}_{\max}) \frac{T}{n+1}$$

$$\vec{F}_{\max} = \frac{-m\vec{v}_i}{T} (n+1)$$

$$F(t) = F_{\max}$$

$n=0$ is best!