

# Chapter 8 – Dynamics in 2D

- Uniform/Nonuniform Circular Motion
- Centrifugal (fictitious) force



# General Principles

## Newton's Second Law

Expressed in x- and y-component form:

$$(F_{\text{net}})_x = \sum F_x = ma_x$$

$$(F_{\text{net}})_y = \sum F_y = ma_y$$

Expressed in  $rtz$ -component form:

$$(F_{\text{net}})_r = \sum F_r = ma_r = \frac{mv_t^2}{r} = m\omega^2 r$$

$$(F_{\text{net}})_t = \sum F_t = \begin{cases} 0 & \text{uniform circular motion} \\ ma_t & \text{nonuniform circular motion} \end{cases}$$

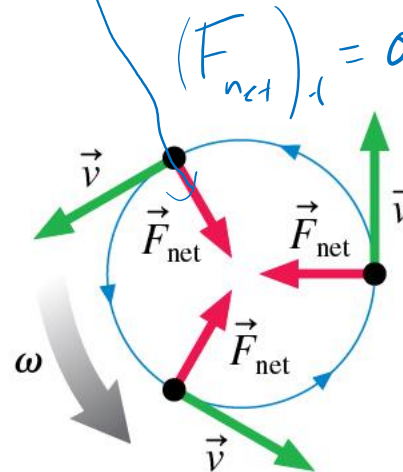
$$(F_{\text{net}})_z = \sum F_z = 0$$

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## Uniform Circular Motion

- Speed is constant.
- $\vec{F}_{\text{net}}$  points toward the center of the circle.
- The **centripetal acceleration**  $\vec{a}$  points toward the center of the circle. It changes the particle's direction but not its speed.

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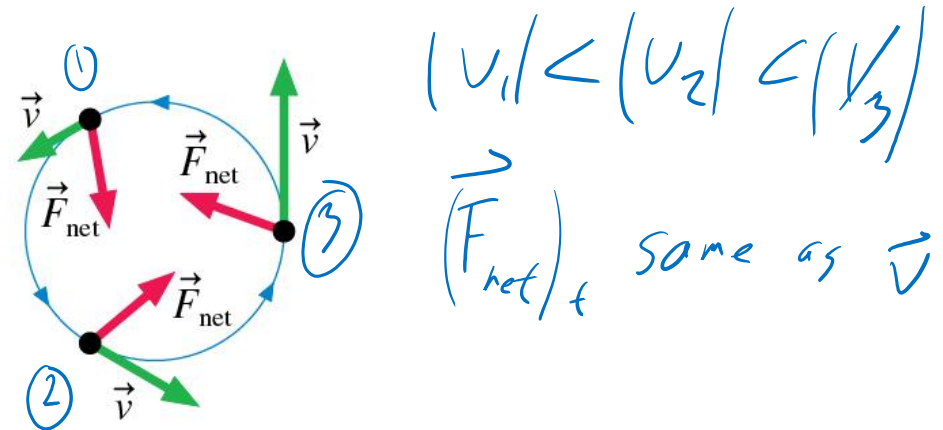
$$(F_{\text{net}})_z = \sum F_z = 0$$

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## Nonuniform Circular Motion

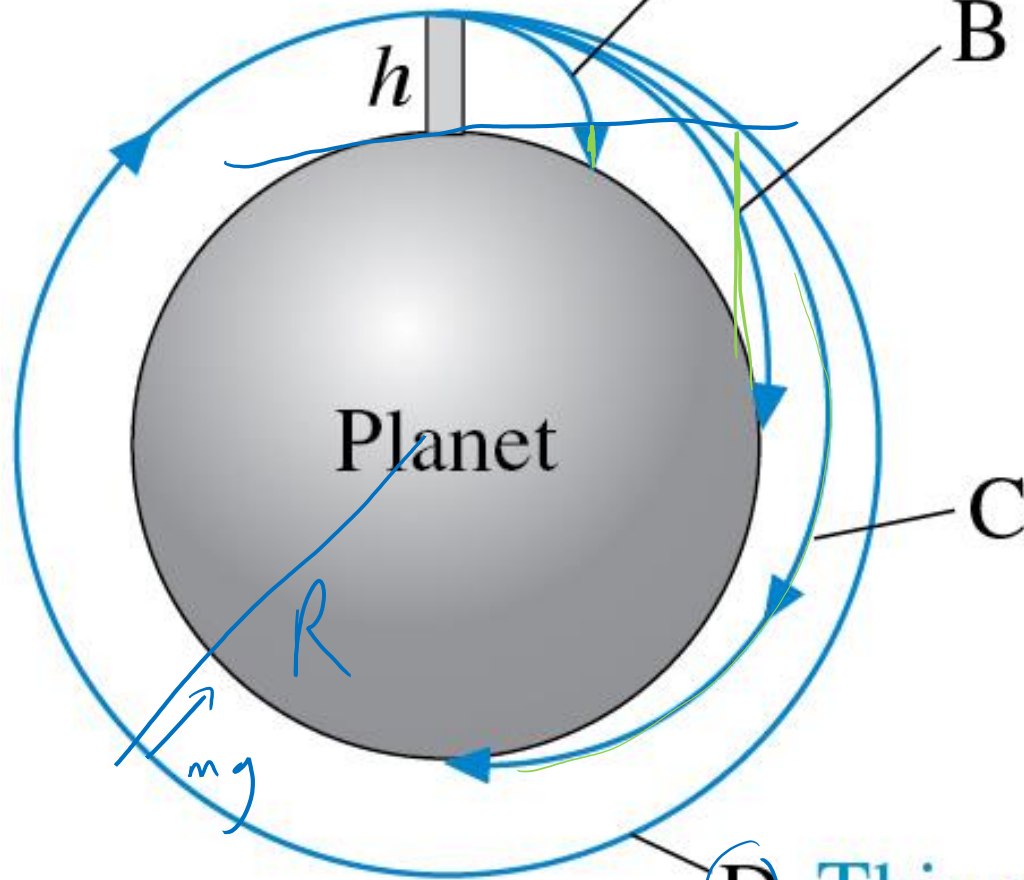
- Speed changes.
- $\vec{F}_{\text{net}}$  and  $\vec{a}$  have both radial and tangential components.
- The radial component changes the particle's direction.
- The tangential component changes the particle's speed.

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**A** Projectile motion

**B** The ground is curving away from the projectile.



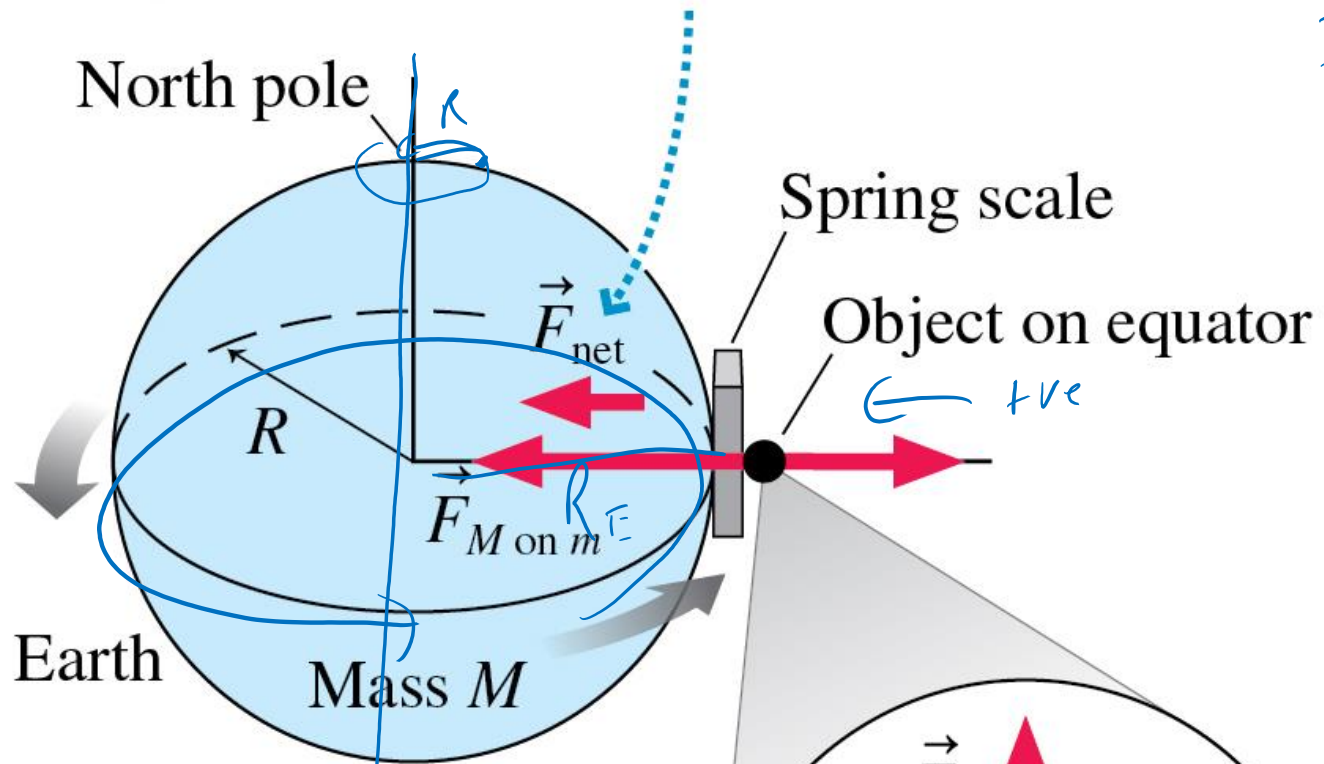
**D** This projectile “falls” all the way around the planet because the curvature of its trajectory matches the planet’s curvature.

$$m \frac{v^2}{R} = mg$$
$$v^2 = gR$$

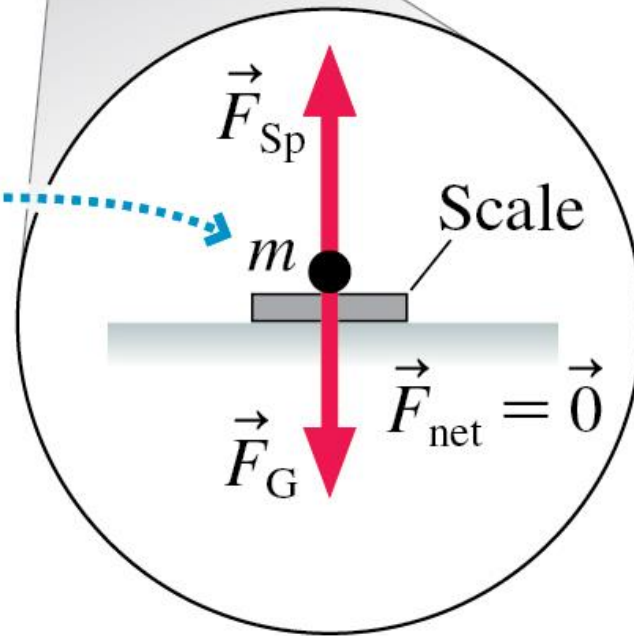
$$v \sim 8 \frac{\text{km}}{\text{s}}$$



The object is in circular motion on a rotating earth, so there is a net force toward the center.



The object is in equilibrium in our reference frame on the rotating earth.



$$\rightarrow 0.03 \text{ m/s}^2$$

$$F_{\text{net}} = mg - n = \underbrace{m\omega^2 R_E}_{\text{ma or centrifugal force}}$$

$$n = mg - m\omega^2 R_E$$

