

- a. Jacob Olson
- b. <https://github.com/Shivlocin/eece.7120.robotics>
- c. Shivlocin
- d. Shivlocin
- e. Shivlocin

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```
Setting VEHICLE_NAME to default
root@977fe0a43eaa:/home/software# rostopic list
/default/anti_instagram_node/transform
/default/camera_node/camera_info
/default/car_cmd
/default/corrected_image/compressed
/default/ground_projection/lineseglist_out
/default/inverse_kinematics_node/actuator_limits
/default/inverse_kinematics_node/actuator_limits_received
/default/lane_controller_node/actuator_limits_received
/default/lane_controller_node/car_cmd
/default/lane_controller_node/fsm_mode
/default/lane_controller_node/intersection_navigation_pose
/default/lane_controller_node/obstacle_avoidance_pose
/default/lane_controller_node/obstacle_detected
/default/lane_controller_node/radius_limit
/default/lane_controller_node/stop_line_reading
/default/lane_controller_node/switch
/default/lane_filter_node/belief_img
/default/lane_filter_node/change_params
/default/lane_filter_node/entropy
/default/lane_filter_node/fsm_mode
/default/lane_filter_node/in_lane
/default/lane_filter_node/lane_pose
/default/lane_filter_node/ml_img
/default/lane_filter_node/switch
/default/line_detector_node/colorSegment
/default/line_detector_node/edge
/default/line_detector_node/fsm_mode
/default/line_detector_node/image_with_lines
/default/line_detector_node/segment_list
/default/line_detector_node/switch
/default/wheels_driver_node/wheels_cmd
/default/wheels_driver_node/wheels_cmd_executed
/random/topic
/rosout
/rosout_agg
root@977fe0a43eaa:/home/software#
```