Shixuan Gu

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EDUCATION

• Carnegie Mellon University

M.S. in Biomedical Engineering - Research

Biomedical Engineering Department Head's Fellowship

· Shanghai Jiao Tong University

B.Eng. in Information Engineering - Artificial Intelligence, IEEE Honor Class

Outstanding Graduate of Shanghai Jiao Tong University

Pittsburgh, PA, United States Sep. 2021 - Present

Shanghai, China

Sep. 2017 - Jun. 2021

Research Interests

My research interest lies in geometric deep learning with applications in biomedical image analysis. My latest research focuses on 3D registration and reconstruction in electron microscopy imaging (Connectomics) and CT imaging (rib analysis). I also build robots for competition events and medical usage.

Publications

- RibSeg v2: A Large-scale Benchmark for Rib Labeling and Anatomical Centerline Extraction Liang Jin*, Shixuan Gu*, Donglai Wei, Kaiming Kuang, Hanspeter Pfister, Bingbing Ni, Jiancheng Yang, and Ming Li IEEE Transactions on Medical Imaging (IEEE TMI), 2022 (under review) [preprint]
- Modeling Neuron Growth Process Using Physics-informed Convolutional Neural Network Kuanren Qian, Ashlee Liao, Shixuan Gu, Victoria Webster-Wood, Jessica Zhang Scientific Reports, 2022 (in submission)
- RibSeg Dataset and Strong Point Cloud Baselines for Rib Segmentation from CT Scans Jiancheng Yang*, **Shixuan Gu***, Donglai Wei, Hanspeter Pfister, Bingbing Ni International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI), 2021 [paper] [code] [dataset] [poster]

Research Experience

Visual Computing Group - Harvard University

Cambridge, MA, United States

• DenSpineEM: 3D Dendritic Spine Instance Segmentation from EM Images

Advisor: Prof. Hanspeter Pfister, Prof. Donglai Wei, Prof. Jeff Lichtman

May. 2022 - Present

- o Developed the first dendritic spine segmentation benchmark with EM images of mouse somatosensory cortex, mouse visual cortex, and human frontal lobe, respectively.
- \circ Implemented a skeleton-based baseline method to perform dendritic spine segmentation (Dice $\approx 91\%$).
- · Working on geometric transformation to facilitate deep learning for elongated and curvy objects, such as neurites and blood vessels.
- Paper FreNet for Segmentation Along Generalized Cylinders is targeted for IEEE TMI 2022.
- RibSeq v2: Benchmark for Rib Labeling and Anatomical Centerline Extraction

Advisor: Prof. Hanspeter Pfister, Prof. Donglai Wei, Prof. Bingbing Ni

Jun. 2021 - Jul. 2022

- Extended RibSeg dataset and developed the first large public benchmark for rib labeling and anatomical centerline extraction, including 660 CT cases.
- Proposed 1) a point-based deep learning method for end-to-end rib labeling, 2) a TEASAR-based method for rib anatomical centerline extraction, and 3) various metrics for each task to perform comprehensive evaluations.
- o Paper RibSeg v2: A Large-scale Benchmark for Rib Labeling and Anatomical Centerline Extraction submitted to IEEE TMI 2022 is under review.
- Proposed a polyline template alignment-based deep learning method for robust rib anatomical centerline extraction, including Global Affine and Differentiable Upsampling Deformation blocks.
- Paper Ribbon: Template Alignment-based Rib Anatomical Centerline Extraction from CT Scans is targeted for MICCAI 2023.

Computational Bio-Modeling Lab - Carnegie Mellon University

Pittsburgh, PA, United States

- Study on the Pathogenesis of Alzheimer's Disease and Vascular Cognitive Impairment Using Mouse Models

 Advisor: Prof. Jessica Zhang, Prof. Kanekiyo Takahisa

 Oct. 2022 Present
 - o Collaborated with Mayo Clinic to study the differences in brain vascular structure using CT images.
 - o Tested VesSAP on CT images of mouse brain to perform brain segmentation and reconstitution of vasculature.
 - Implementing transfer learning-based method to generalize VesSAP to data from Mayo Clinic.
 - Computing vessel density, length, and size from the segmented CT images to compare brain vascular structures between several mouse groups such as male vs. female mice, and young vs. aged mice.

• Neutron Growth Simulation

Advisor: Prof. Jessica Zhang, Prof. Victoria Webster-Wood

Sep. 2022 - Present

- Implemented a physics-informed (PDE) neural network to speed up the simulation of the growth of neurons.
- Paper Modeling Neuron Growth Process Using Physics-informed Convolutional Neural Network is targeted for Scientific Reports 2022.
- Developing learning-based methods to detect elongated neurite tracers for rat hippocamapal neuron morphogenesis analysis.

Biorobotics Lab - Carnegie Mellon University

Pittsburgh, PA, United States

- Robotic Ventilator: Patient Care Technologies for Permanent Ambulatory Artificial Lung Support

 Advisor: Prof. Howie Choset, Prof. Keith E. Cook, Prof. Jason J. Rose

 Sep. 2021 Aug. 2022
 - Collaborated with UPMC to design and build a portable O₂ concentrator for ICU ventilation.
 - Designed and built a clinical ventilation sensor for breathing data collection and interaction with an online database.
 - o Drafted phase 2 of the research proposal focusing on machine learning-based alarm system for STTR program at NSF.
 - o Developed a deep learning-based alarming system for lung-related disease such as hyperinflation, and built an online database for breathing data.

Vision and Learning Lab - Shanghai Jiao Tong University

Shanghai, China

 RibSeg Dataset and Strong Point Cloud Baselines for Rib Segmentation from CT Scans

Advisor: Prof. Bingbing Ni, Prof. Donglai Wei, Prof. Hanspeter Pfister

Oct. 2020 - Jun. 2021

- Developed *RibSeg*, the first public large-scale dataset, including 490 CT scans (11,719 individual ribs), for rib segmentation to enable downstream applications and method comparison.
- \circ Proposed a point cloud-based method to segment ribs from CT scans, which achieves high accuracy (Dice $\approx 95\%$) and efficiency (40× faster than prior arts).
- Paper RibSeg Dataset and Strong Point Cloud Baselines for Rib Segmentation from CT Scans is accepted by MICCAI 2021.

Intelligent Robot Lab - Shanghai Jiao Tong University

Shanghai, China

• VEX Robotics Project: VEX U Robotics World Tournaments

Advisor: Prof. Chuntao Leng

Sep. 2018 - May. 2020

- Co-founded the SJTU VEX Lab, won the first VEX robotics world championship for SJTU.
- Designed and built the ejection structure crossbow, trebuchet, and flywheel for three prototypes, respectively.
- Designed the scoring path and programmed control codes for the automation stage of the competition.

AWARDS

- [2019] VEX U Skills Challenge World Champion, VEX U Division Champion, and World Finalist 2019 VEX U Robotics World Championship, Robotics Education & Competition Foundation
- [2018] Create Award, Robot Skills Finalist, Silver Award 2018 12th Asia-Pacific Robotics Championship, Asian Robotics League
- [2018] Nomination for Excellence Award, Amaze Award, Tournament Semifinalists 2018 China National VEX Robotics Competition
- [2018] Student Ambassador, Excellent Student Presentation Award 2018 Student Learning Festival of C9+1 Symposium, The University of Hong Kong
- [2016] First Prize, Best Con in Shanghai International Young Physicists' Tournament (IYPT Shanghai) Shanghai Physical Society, China

MISCELLANEOUS

- Programming: Python (PyTorch, scikit-learn, NumPy, Pandas), C++, Javascript, HTML, MATLAB.
- Robotics: Proficient in VEX robot design, RobotC, SolidWorks.
- Tools: ITK, MySQL, CyberTorcs, Neuroglancer.
- Teaching Assistant: UCLA Extension (Shanghai Pinghe) Artificial Intelligence and Data Science (COM SCI 960.01: Aug'21), Research Methodologies (ENGL 902: Aug'21), Academic Writing (ENGL 901: Aug'21).