

# Shixuan Gu

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Github: <https://github.com/ShixuanGu>

## EDUCATION

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- Carnegie Mellon University** Pittsburgh, PA, United States  
*M.S. in Biomedical Engineering and Integrated Study in Computer Science* Sep. 2021 - Present  
**Biomedical Engineering Department Head's Fellowship**
- Shanghai Jiao Tong University** Shanghai, China  
*B.Eng. in Computer Science & Artificial Intelligence, IEEE Honor Class* Sep. 2017 - Jun. 2021  
**Outstanding Graduate of Shanghai Jiao Tong University**

## RESEARCH INTERESTS

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I'm interested in geometric deep learning, especially the interdisciplinary field of 3D computer vision and medical image analysis. Currently, my research focuses on investigating geometric deep learning to tackle problems in biomedical applications, such as electron microscopy imaging (Connectomics) and CT Scans. I'm also interested in robotics and physics.

## PUBLICATIONS

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- Point-Based Rib Segmentation, Labeling, and Centerline Extraction: A Dataset and Baselines**  
Jiancheng Yang\*, **Shixuan Gu\***, Liang Jin\*, Kaiming Kuang, Donglai Wei, Hanspeter Pfister, Bingbing Ni, and Ming Li.  
IEEE Transactions on Medical Imaging (IEEE TMI), 2022, (under review)
- FreNet Frame: A Skeleton-based Frame for Segmentation of Elongated Objects**  
**Shixuan Gu**, Jason Ken Adhinarta, Jiancheng Yang, Hanspeter Pfister, Jeff W. Lichtman, and Donglai Wei.  
IEEE Transactions on Medical Imaging (IEEE TMI), 2022, (manuscript)
- Ribbon: Template Alignment-based Rib Centerline Extraction from CT Scans**  
**Shixuan Gu\***, Jiancheng Yang\*, Donglai Wei, Hanspeter Pfister, and Bingbing Ni.  
International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI), 2023, (manuscript)
- RibSeg Dataset and Strong Point Cloud Baselines for Rib Segmentation from CT Scans**  
Jiancheng Yang\*, **Shixuan Gu\***, Donglai Wei, Hanspeter Pfister, Bingbing Ni  
International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI), 2021  
[\[paper\]](#) [\[code\]](#) [\[dataset\]](#) [\[poster\]](#)

## RESEARCH EXPERIENCE

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### Visual Computing Group - Harvard University Cambridge, MA, United States

- DenSpineEM: 3D Dendritic Spine Instance Segmentation from EM Images**  
*Advisor: Prof. Hanspeter Pfister, Prof. Donglai Wei, Prof. Jeff Lichtman* May. 2022 - Present
  - Explored the topic of human brain and computational neuroscience, and developed 3 dendritic spine segmentation benchmarks, from mouse somatosensory cortex, mouse visual cortex, and human frontal lobe, respectively.
  - Implemented a TEASAR-based baseline method to perform dendritic spine segmentation.
  - Generalized the method to perform intracranial aneurysm segmentation.
- Point-Based Rib Segmentation, Labeling, and Centerline Extraction: A Dataset and Baselines**  
*Advisor: Prof. Hanspeter Pfister, Prof. Donglai Wei, Prof. Bingbing Ni* Jun. 2021 - Jul. 2022
  - Enlarged RibSeg dataset by adding 170 cases with labeled rib segmentation and providing the annotations of anatomical centerlines for the total 660 cases, which is the first large public benchmark for this topic.
  - Proposed a point-based deep learning method for end-to-end rib segmentation, labeling, and centerline extraction, with multiple metrics for comprehensive method evaluation.
  - Explored key challenges and clinical significances in this topic, which are valuable to guide rib-related studies.

### Biorobotics Lab - Carnegie Mellon University Pittsburgh, PA, United States

- Robotic Ventilator: Patient Care Technologies for Permanent Ambulatory Artificial Lung Support**  
*Advisor: Prof. Howie Choset, Prof. Keith Cook* Sep. 2021 - Present
  - Designed and built a portable O<sub>2</sub> concentrator for ICU ventilation.
  - Designed and built a clinical ventilation sensor for breathing data collection and interaction with online database.

- Developed a deep learning-based alarming system for lung-related disease and built a online database for breathing data.

## Bingbing Ni's Lab - Shanghai Jiao Tong University

Shanghai, China

- **RibSeg Dataset and Strong Point Cloud Baselines for Rib Segmentation from CT Scans**

*Advisor: Prof. Bingbing Ni, Prof. Hanspeter Pfister*

*Oct. 2020 - Jun. 2021*

- Developed RibSeg, the first public large-scale dataset, including 490 CT scans (11,719 individual ribs), for rib segmentation and centerline extraction to enable downstream applications and method comparison.
- Proposed an efficient point cloud-based model to segment ribs, which converts dense CT volume into sparse point clouds via thresholding and random downsampling, and produces high-quality and robust rib segmentation (**Dice 95%**) with significant efficiency (**40× faster than prior arts**).

## PROJECTS

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- **Simulated evaluation of automatic control methods for vehicles:** implemented control methods, including PID, MPC, FLC, and evaluated their performance for intelligent vehicles through simulations on CyberTorcs.
- **Batch QR code scanning for mobile devices:** built a complimentary system to enable batch QR code scanning on mobile devices, with online CNN-based method and offline DIP-based method.
- **Machine learning-based vehicle localization and mapping:** developed machine learning-based methods for vehicle localization and mapping under complex environments.

## AWARDS

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- **2019 VEX U Skills Challenge World Champion, VEX U Division Champion, and World Finalist**  
2019 VEX U Robotics World Championship, Robotics Education & Competition Foundation
- **2018 Create Award, Robot Skills Finalist, Silver Award**  
2018 12th Asia-Pacific Robotics Championship, Asian Robotics League
- **2018 Nomination for Excellence Award, Amaze Award, Tournament Semifinalists**  
2018 China National VEX Robotics Competition
- **2018 Student Ambassador, Excellent Student Presentation Award**  
2018 Student Learning Festival of C9+1 Symposium, The University of Hong Kong
- **2016 First Prize, Best Con in Shanghai International Young Physicists' Tournament (IYPT Shanghai)**  
Shanghai Physical Society, China

## TECHNICAL STRENGTHS

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- **Programming:** Python (scikit-learn, NumPy, Pandas, SciPy, PyTorch), C++, MATLAB, Javascript, HTML
- **Robotics:** Proficient in VEX robot design, RobotC, SolidWorks
- **Tools:** Anaconda, TensorFlow, CyberTorcs, MySQL
- **Teaching:** UCLA Extension - Artificial Intelligence and Data Science (COM SCI - 960.01: Aug'21), Research Methodologies (ENGL 902: Aug'21), Academic Writing (ENGL 901: Aug'21)