Control system lab report

- 1. Obseravation Of Unit Step Response Of First-Order System Using Matlab
- 2. Obseravation Of Unit Ramp Response Of First-Order System Using Matlab
- 3. Obseravation Of Unit Impulse Response Of First-Order System Using Matlab
- 4. Observation Of Unit Step Response Of First-Order System For Different Time Constant Using Matlab
- 5. Observation Of Unit Step Response Of A Second-Order System Using Matlab
- 6. Observation Of Impulse Response Of The System, $G(S) = \frac{1}{S^2 + 0.2S + 1}$ Using Matlab
- 7. Observation Of Unit Step Response For The System

$$\begin{bmatrix} \dot{x_1} \\ \dot{x_2} \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ 6.5 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

8. Observation Of Impulse Response Of The System, $G(S) = \frac{1}{S^2 + 0.2s + 1}$

Using Unit Step Response

- 9. Observation Of Unit Step Response The System ,G(S)= $\frac{25}{s^2+4s+25}$ Using Matlab
- 10. Observation Of Unit Step Response The System ,G(S)= $\frac{25}{s^2+4s+25}$ Using Plot Command
- 11. Observation Of Unit Ramp Response The System ,G(S)= $\frac{2s+1}{s^2+s+1}$ Using Matlab.
- 12. Observation Of Unit Step Response For The System

$$\begin{bmatrix} \dot{x_1} \\ \dot{x_2} \end{bmatrix} = \begin{bmatrix} -1 & 0.5 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$Y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

For input (a)u=unit step input (b) $u=e^{-t}$ using matlab.

13.Root Locus Of The System ,G(S)= $\frac{20}{s(s+1)(s+2)}$ Using Matlab

14. Root Locus Of The System ,G(S)= $\frac{2s+1}{s^2+s+1}$ Using Matlab

15. Root Locus Of The System ,G(S)= $\frac{s(s+1)}{s^2+4s+16}$ Using Matlab