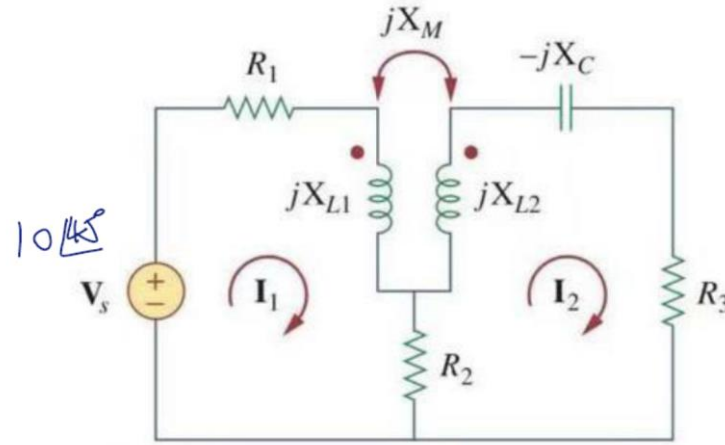


# Q1 All RMS



$$\begin{cases} V_s = (R_1 + jX_{L1} + R_2)I_1 - R_2I_2 - jX_M I_2 \\ (jX_{L2} - jX_C + R_3 + R_2)I_2 - R_2I_1 - jX_M I_1 = 0 \end{cases}$$

$$\begin{cases} V_s = (10 + j15)I_1 - (5 + j2)I_2 \\ (j19.5 + 15)I_2 - (5 + j2)I_1 = 0 \end{cases}$$

$$I_2 = \frac{5 + j2}{15 + j19.5} I_1$$

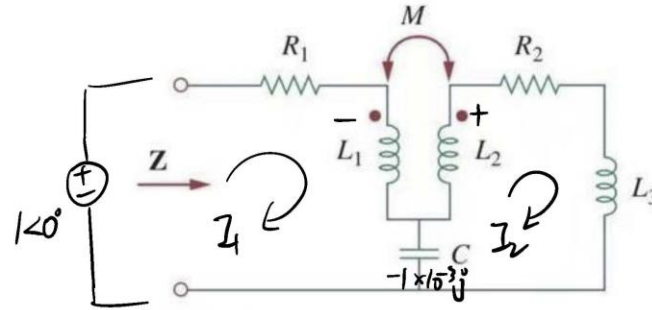
$$I_1 = (0.0286 - j0.0492)V_s = 0.569 \angle -14.83^\circ$$

$$I_2 = (-9.372 \times 10^{-5} - j0.0125)V_s = 0.125 \angle -45.43^\circ$$

## Q2 All RMS

\*correction

$\omega = 10\text{k rad/s}$ , not Hz.



$$\text{Mesh: } \begin{cases} -1 + I_1(R_1 + j\omega L_1) + \frac{1}{j\omega C}(I_1 - I_2) - j\omega M I_2 = 0 \\ (I_2 - I_1) \cdot \frac{1}{j\omega C} + I_2(j\omega L_2 + R_2 + j\omega L_3) - j\omega M I_1 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} -1 + (5k + 100k \cdot j) I_1 - 10^{-3} j (I_1 - I_2) - 200k j I_2 = 0 \\ -10^{-3} j (I_2 - I_1) + (5k + 150k j) I_2 - 200k j I_1 = 0 \end{cases}$$

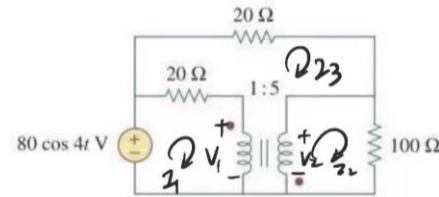
$$\Rightarrow I_2 = (1.33 + 0.044j) I_1$$

$$\Rightarrow (13879 - 166370.7j) I_1 = 1$$

$$\Rightarrow I_1 = 5.99 \times 10^{-6} \angle -85.23^\circ \text{ A}$$

$$\Rightarrow Z = \frac{1\angle 0^\circ}{I_1} = 1.67 \times 10^3 \angle -85.23^\circ \Omega$$

Q3



Mesh :

$$\textcircled{1} \quad -80 + 20(I_1 - I_3) + V_1 = 0$$

$$\textcircled{2} \quad V_2 = 100I_2$$

$$\textcircled{3} \quad 40I_3 - 20I_1 + V_2 - V_1 = 0$$

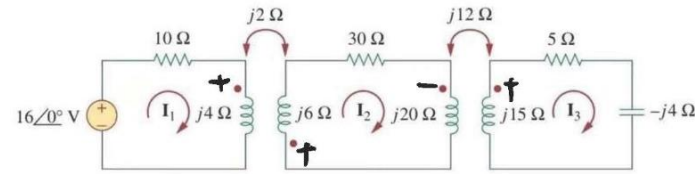
For transformers :

$$\begin{cases} V_2 = -5V_1 \\ I_1 - I_3 = -5(I_2 - I_3) \end{cases}$$

$$\Rightarrow \begin{cases} I_1 = 5.94 \\ I_2 = 0.52 \\ I_3 = 1.42 \end{cases}$$

$$\Rightarrow \begin{cases} \text{top R: } P = 20.15 \text{ W} \\ \text{Left R: } P = 203.95 \text{ W} \\ \text{right R: } P = 13.3 \text{ W} \end{cases}$$

# Q4 All RMS



Mesh:

$$\begin{cases} 16 = (10 + j4)I_1 + j2I_2 \\ 0 = j2I_1 + (30 + j26)I_2 - j12I_3 \\ 0 = -j12I_2 + (5 + j11)I_3 \end{cases}$$

$$\Rightarrow \begin{cases} I_1 = 1.475 \angle -21.91^\circ \text{ A} \\ I_2 = 77.5 \angle -134.85^\circ \text{ mA} \\ I_3 = 77 \angle -110.49^\circ \text{ mA} \end{cases}$$