

```

import random

def cost(state):
    """Calculate the number of attacking pairs of queens in the current state."""
    attacking_pairs = 0
    n = len(state)
    for i in range(n):
        for j in range(i + 1, n):
            if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
                attacking_pairs += 1
    return attacking_pairs

def print_board(state):
    """Represent the state as a 4x4 board."""
    n = len(state)
    board = [['.' for _ in range(n)] for _ in range(n)]
    for i in range(n):
        board[state[i]][i] = 'Q'

    for row in board:
        print(" ".join(row))

def get_neighbors(state):
    """Generate all possible neighbors by swapping two queens."""
    neighbors = []
    n = len(state)
    for i in range(n):
        for j in range(i + 1, n):
            neighbor = list(state)
            neighbor[i], neighbor[j] = neighbor[j], neighbor[i] # Swap queens
            neighbors.append(tuple(neighbor))
    return neighbors

def hill_climbing(initial_state):
    """Hill climbing algorithm to solve the N-Queens problem."""
    current = initial_state
    print(f"Initial state:")
    print_board(current)
    print(f"Cost: {cost(current)}")
    print('-' * 20)

    while True:
        neighbors = get_neighbors(current)
        # Select the neighbor with the lowest cost
        next_state = min(neighbors, key=lambda x: cost(x))

```

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    print(f"Next state:")
    print_board(next_state)
    print(f"Cost: {cost(next_state)}")
    print('-' * 20)

    if cost(next_state) >= cost(current):
        # If no better state is found, return the current state as
the solution
        print(f"Solution found:")
        print_board(current)
        print(f"Cost: {cost(current)}")
        return current
    current = next_state

if __name__ == "__main__":
    # Initial state for 4-Queens, random placement
    initial_state = (3, 1, 2, 0) # Example initial state, where each
index represents a column

    # Run Hill Climbing algorithm
    solution = hill_climbing(initial_state)

```

→ Hill Climbing Search Algorithm

function Hill Climbing (problem) returns a
State that is a local maximum cost ← MakeNode
(problem.Initial-State)

loop do

 neighbor ← a highest-valued successor of
 curr if neighbor value > curr value
 then

 return curr.State

 curr ← neighbor

• $x_0 = 3, x_1 = 1, x_2 = 2, x_3 = 0$

cost = 2

			9
	9		
9		9	

• $x_0 = 1, x_1 = 0, x_2 = 3, x_3 = 2$

cost = 2 + 1 + 1 = 4

	9		
9			
		9	9

• $x_0 = 1, x_1 = 3, x_2 = 0, x_3 = 2$


C = 0

	9		
9			9
		9	

• $x_0 = 3, x_1 = 2, x_2 = 0, x_3 = 1$

C = 2

		9	9
		9	
9	9		

 Hill Climbing Algorithm 1BM23CS316.ipynb ☆

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initial_state = (3, 1, 2, 0) # Example initial state, where each index represents a column

# Run Hill Climbing algorithm
solution = hill_climbing(initial_state)
```

↔

```
Initial state:
. . . Q
. Q . .
. . Q .
Q . . .
Cost: 2
-----
Next state:
. . . Q
Q . . .
. . Q .
. Q . .
Cost: 1
-----
Next state:
. . Q .
Q . . .
. . . Q
. Q . .
Cost: 0
-----
Next state:
. . Q .
. Q . .
. . . Q
Q . . .
Cost: 1
-----
Solution found:
. . Q .
Q . . .
. . . Q
. Q . .
Cost: 0
```