# SHIVEN TRIPATHI

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**Educational Qualifications** 

| Year                         | Degree     | $\operatorname{Institution}(\operatorname{Board})$ | CGPA/%    |
|------------------------------|------------|--|-----------|
| July'19 – June'23 (expected) | B.Tech, EE | Indian Institute of Technology, Kanpur             | 9.2/10.0  |
| 2019                         | CBSE – XII | Delhi Public School, Greater Noida                 | 93.8%     |
| 2017                         | CBSE – X   | Delhi Public School, Greater Noida                 | 10.0/10.0 |

#### Scholastic Achievements

- Top 0.5%, JEE-Advanced (amongst 160,000 candidates)
- All India Rank 208, *JEE-Main* (amongst 1.3 million candidates)
- All India Rank 6, UPSEE (amongst 200,000 candidates)
- NTSE Scholar, 2017, Top 0.07% to be awarded scholarship by NCERT (from 1 million candidates)
- KVPY-SX Fellow, 2019, Top 1% to be awarded fellowship by DST, India (from 100,000 candidates)
- Top 1%, National Standard Examination in Physics, 2019

# Research Experience

### Object Detection and SLAM in UGV

Under Prof. Nishchal K. Verma

Research Project
Dec. 2020 - Present

- Working with Senior Researchers in IDEA Lab, on a project sponsored by DRDO for unmanned ground vehicle.
- Conducted a literature review on various SLAM methods using various sensors like Camera, LIDAR, IMU etc., benchmarking the results on KITTI datasets for Husky Bot.
- Currently working on implementing fusion (Camera+LiDAR) pipeline for object detection with SLAM, using Deep Learning methods.

#### Team ERA-IITK

Science and Technology Council

 $Software\ Team$ 

March 2020 - Present

Team ERA-IITK competes in **IEEE ICRA DJI Robomaster Challenge**, building autonomous ground robots.

- Implemented object detection and tracking modules for the armoured bot using traditional CV based techniques and DL methods like YOLO.
- Tested out RL using DQN agents on pygames as a proxy to the training of the bot to target and attack enemy bots.

Code at: ShivenTripathi/Deep-RL

 Currently working on integrating RL Agents and Behavior Trees for optimal decision making under threat and advantage.

#### Swachta Mitra

Research Project

Under Prof. Ashutosh Modi

at 2020 Descent

- Working in a team with CSE Senior Year Students to stop littering by building **DL** garbage detection and localisation pipelines.
- Created and annotated dataset of over 10k images relevant to littering in Indian landscapes.
- Currently working on establishing baseline performances using standard architectures like R-CNN.

#### Team Humanoid-IITK

Science and Technology Council Nov 2019 - May 2020

Team Humanoid-IITK competes in **FIRA RoboWorld Cup**, building humanoid robots capable of archery, wrestling etc.

- Implemented obstacle detection modules for the Humanoid Robot using potential field mapping. ShivenTripathi/humanoid\_ws
- Worked with OpenCV and ROS to build efficient nodes solving CV tasks like detection, tracking and depth mapping, used to solve the problem statement of archery.

#### Relevant Coursework

Fundamentals of Programming (A) Data Structures and Algorithm Complex Analysis and PDEs (A) Computational Cognitive Science (i) Deep Learning (@)

Real Analysis (A) Linear Algebra and ODEs (A) Introduction to Economics Probability and Statistics (i) Reinforcement Learning (@)

A: Grade for excellent performance, i: In progress, @: Coursera

### **Projects**

Fashion Intelligence Systems ShivenTripathi/GRiD-Software Flipkart GRiD 2.0 July 2020 - Sep. 2020

Finished in National Top 3 (from over 9k teams) Implemented Machine Learning model to identify trends in Fashion items and generate actionable insights on trendiness of products to build a portfolio.

- Used open sourced MMFashion models to **identify** attributes and get features representative of styles.
- Built Fashion Vectors using a priority list obtained from the modified output MMFashion model to get individual trend ranks.
- Applied dimensionality reduction techniques like tSNE and then did clustering using kMeans to obtain visually distinct style clusters.

Conversational Robot

Shiven Tripathi/Conversational Robot

Robotics CLub, IIT Kanpur

May 2020 - July 2020 ral Language

- Studied various preliminaries for Natural Language Processing and implemented GloVe model for generating embeddings for text.
- Experimented with different ASR methods and implemented DeepSpeech 2 trained on a limited but augmented dataset consisting of audiobooks.
- Built hybrid pipelines for response generation using pattern recognising AIML along with Topic Aware Seq2Seq Deep Learning model.

# PETCat, Biomimetics

ShivenTripathi/PETcat\_vision
May 2020 - July 2020

Robotics CLub, IIT Kanpur
• Implemented Face and l

- Implemented Face and Emotion Recognition modules using classic CV approaches combined with CNN architectures.
- Integrated individual modules into ROS nodes for easy deployment and functionality for the robot.

# Positions of Responsibility

- Secretary, Special Interest Group in Machine Learning (SIGML)
  - Conducted sessions aimed at Student and Faculty Researchers in Machine Learning for discussion of their research problems and cross-pollination of ideas.
- Coordinator, Debating Society, competed as part of Institute Debate Team and trained peers in this activity.

# Skills

Programming Languages: C++, Python, C
Data Science: Tensorflow, Keras, Scikit, MATLAB
Robotics: ROS, OpenCV, Arduino, Gazebo, Gym
Utilities: LaTeX, Git, Bash, Processing