

Sequential Circuits

Equivalence of State Machines

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CS-230: Digital Logic Design & Computer Architecture



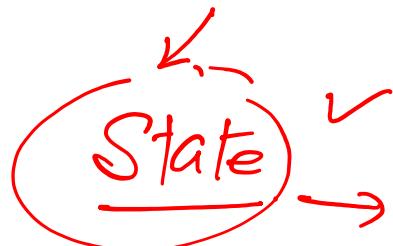
Lecture 19 (17 February 2022)

CADSL

State machine

↳ temporal. behaviour.

Finite State Machine (FSM)



STG (State Transition Graph)
↓

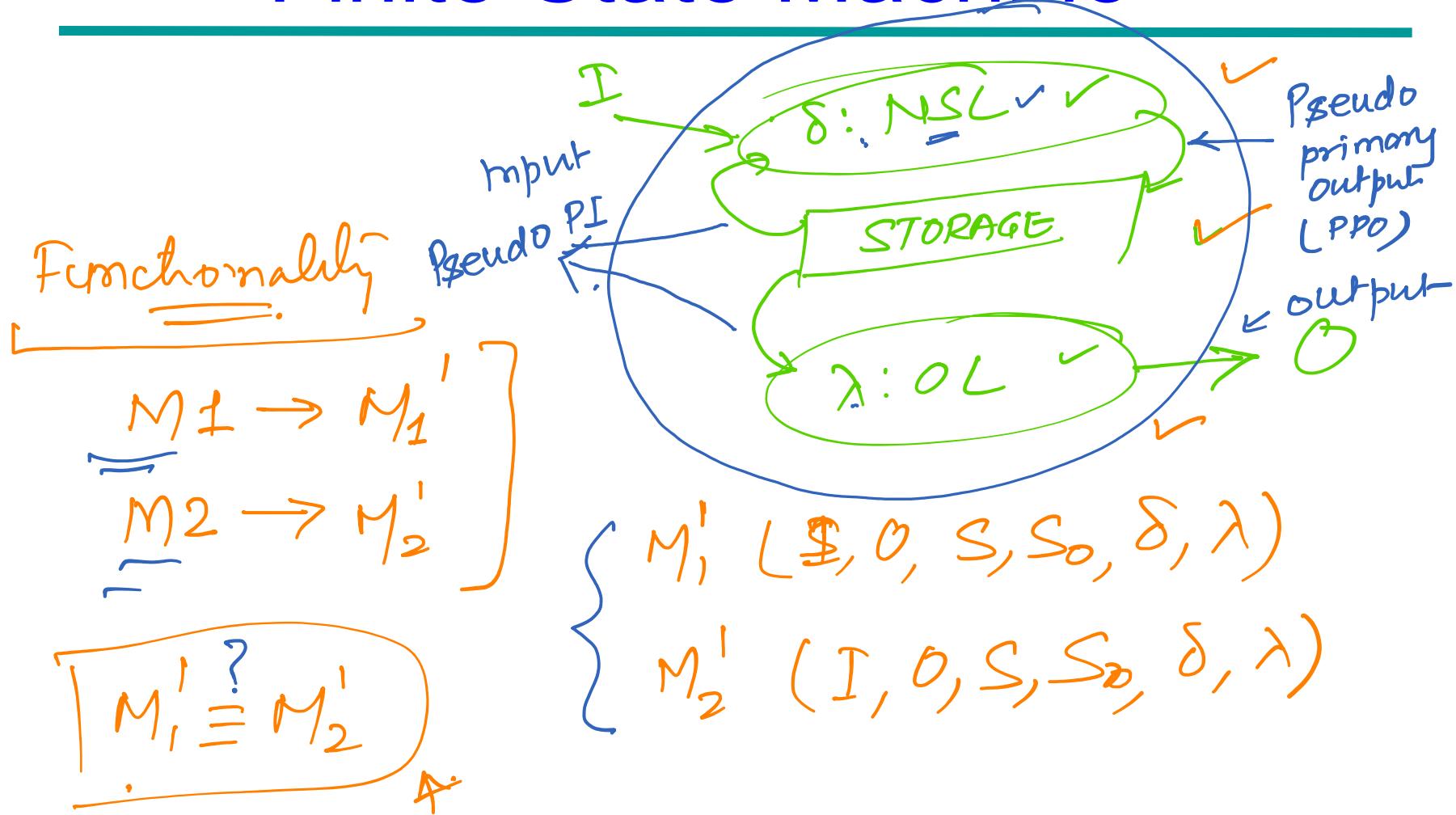
minimization (automatic)

↓
Equivalence checking

↓
minimized State machine.



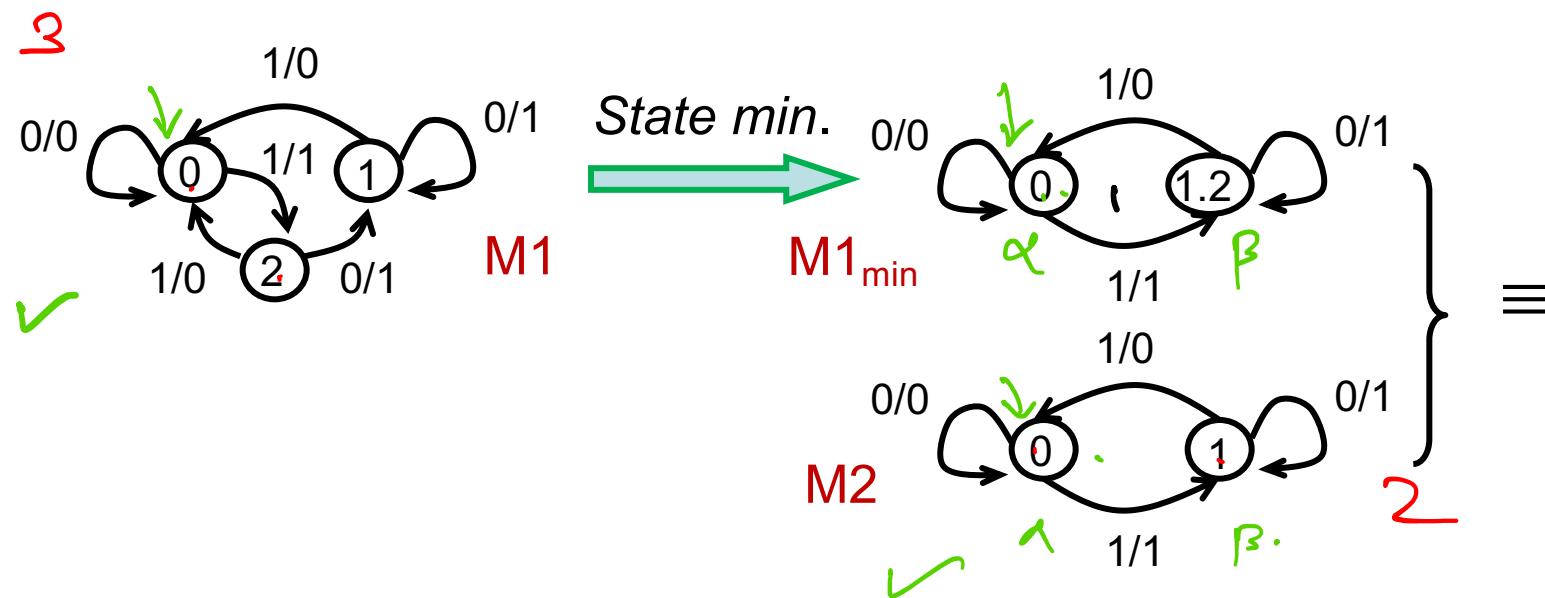
Finite State Machine



Sequential Verification

- Approach 1: Based on isomorphism of state transition graphs
 - two machines M_1, M_2 are *equivalent* if their state transition graphs (STGs) are *isomorphic*
 - perform state minimization of each machine
 - check if $\text{STG}(M_1)$ and $\text{STG}(M_2)$ are isomorphic

M'_1 M'_2



Machine Equivalence

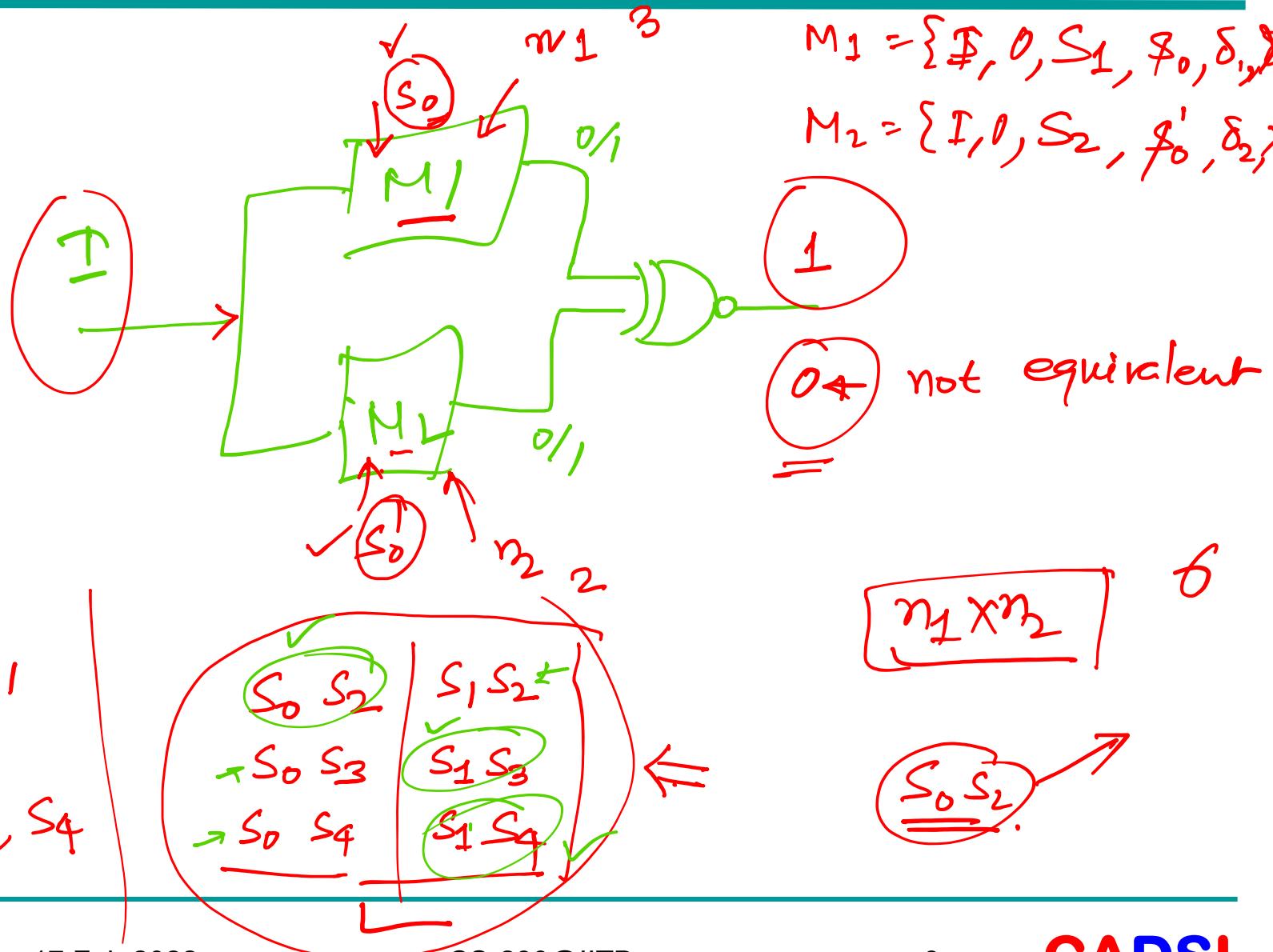
- Two machines M_1, M_2 are said to be equivalent if and only if, for every state in M_1 , there is corresponding equivalent state in M_2
- If one machine can be obtained from the other by relabeling its states they are said to be isomorphic to each other



Finite State Machine

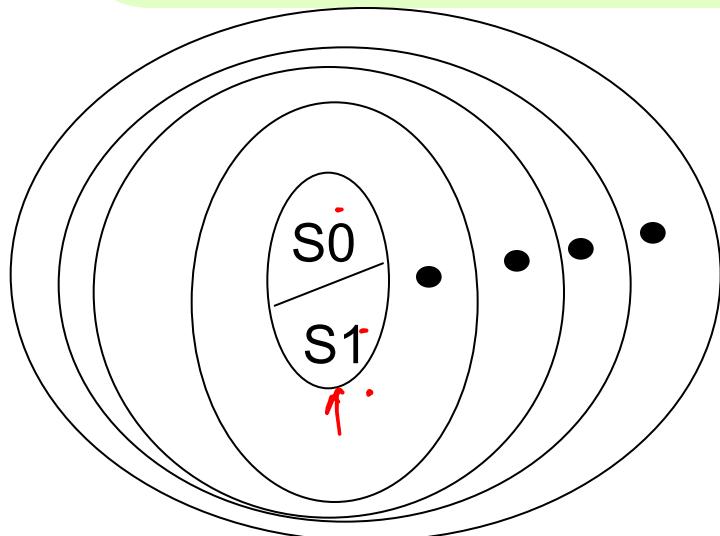
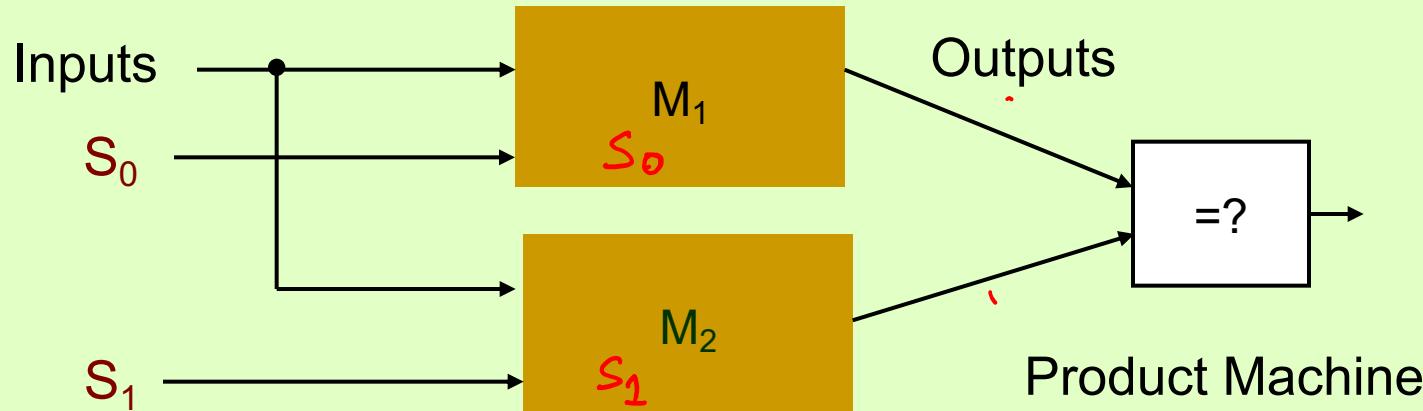
(D)

$$\frac{10}{1024}$$



Reachability-Based Equivalence Checking

Approach 2: Symbolic Traversal Based Reachability Analysis ✓



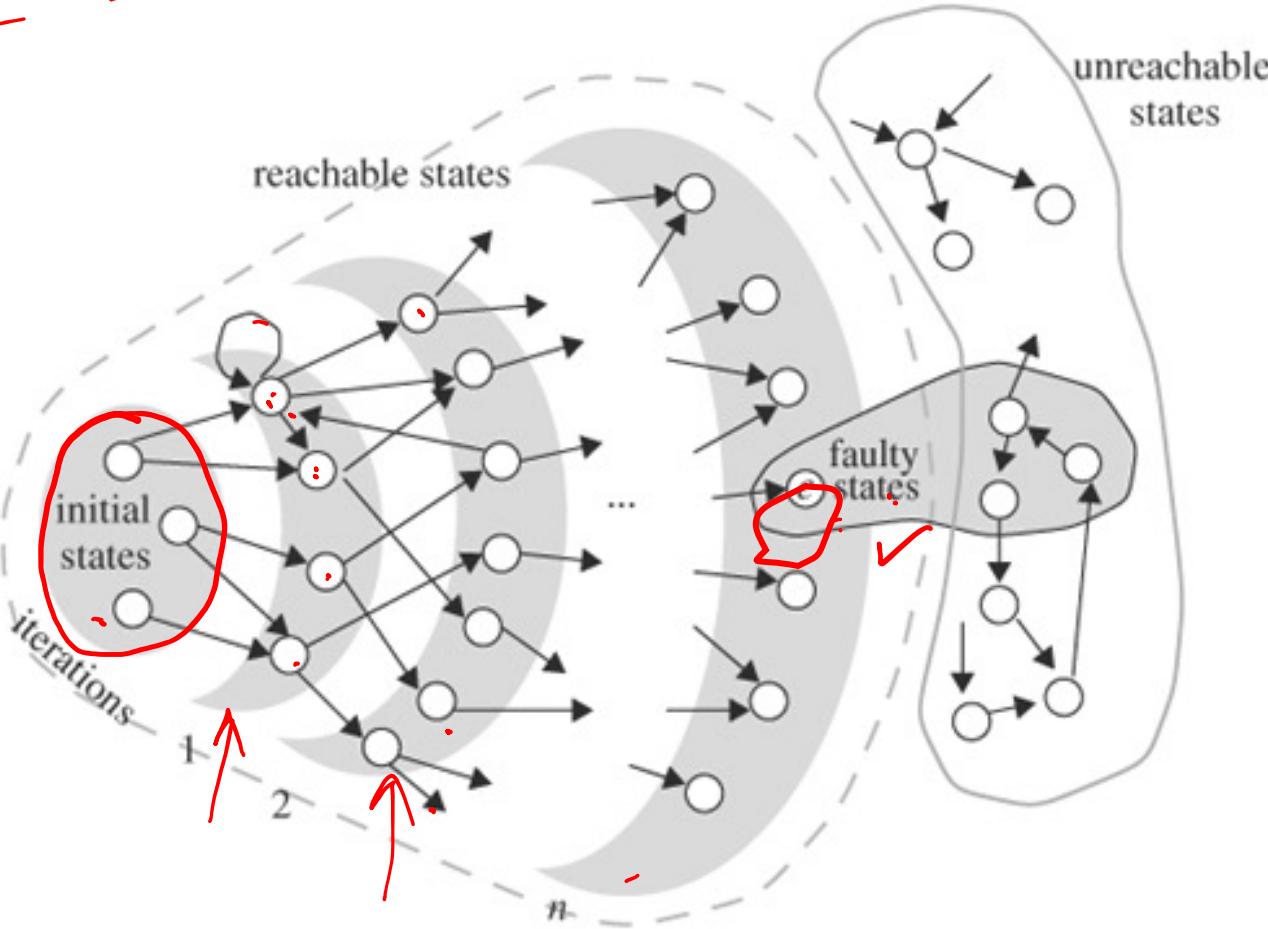
- Build product machine of M_1 and M_2
- Traverse state-space of product machine starting from reset states S_0, S_1
- Test equivalence of outputs in each state
- Can use any state-space traversal technique

$$M \cong M_1 \times M_2$$



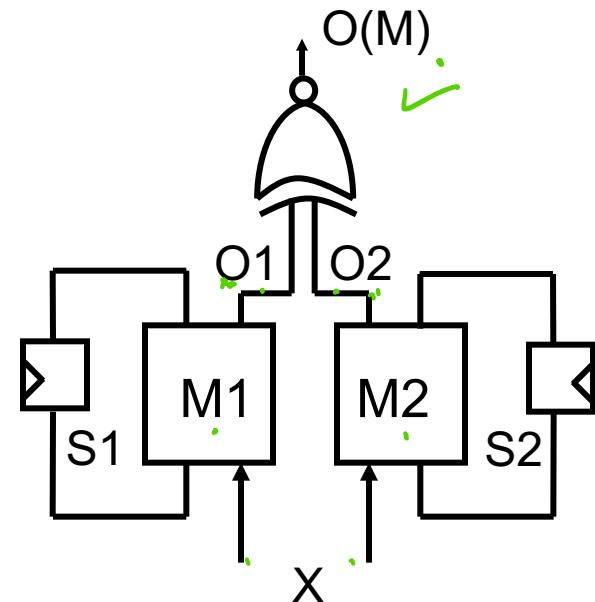
Forward Reachability

Counter example



Sequential Verification

- Symbolic FSM traversal of the product machine
- Given two FSMs: $M_1(X, S_1, \delta_1, \lambda_1, O_1)$, $M_2(X, S_2, \delta_2, \lambda_2, O_2)$
- Create a product FSM: $M = M_1 \times M_2$
 - traverse the states of M and check its output for each transition
 - the output $O(M) = 1$, if outputs $O_1 = O_2$
 - if all outputs of M are 1, M_1 and M_2 are equivalent
 - otherwise, an error state is reached
 - error trace is produced to show: $M_1 \neq M_2$



Product Machine - Construction

- Define the product machine $M(X, S, S^0, \delta, \lambda, O)$ $|S| = |S_1| \times |S_2|$

– states,

$$S = S_1 \times S_2$$

– next state function, $\delta(s, x) : (S_1 \times S_2) \times X \rightarrow (S_1 \times S_2)$

– output function, $\lambda(s, x) : (S_1 \times S_2) \times X \rightarrow \{0, 1\}$

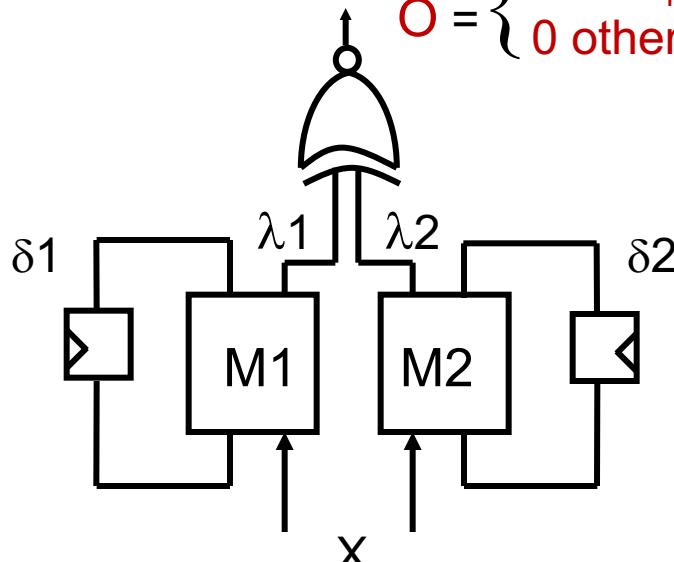
$$\lambda(s_1, x) = \lambda_1(s_1, x)$$
$$\lambda(s_2, x)$$

$$\lambda(s, x) = \lambda_1(s_1, x) \oplus \lambda_2(s_2, x)$$

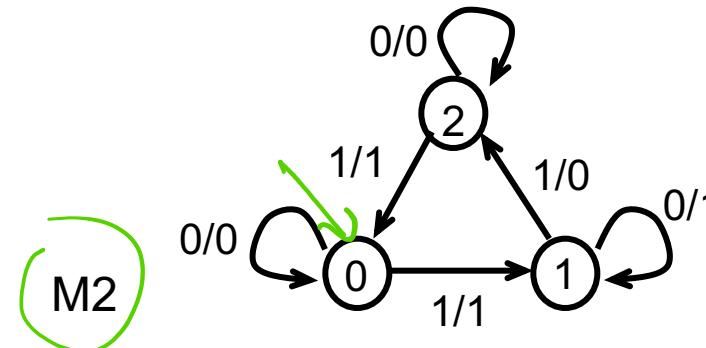
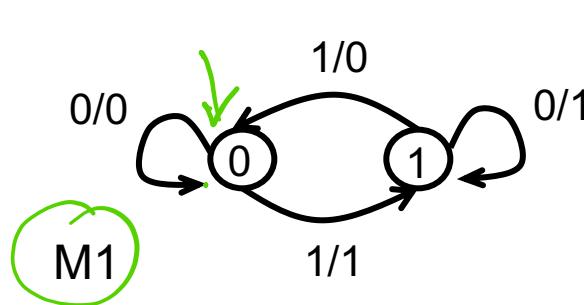
$$O = \begin{cases} 1 & \text{if } O_1 = O_2 \\ 0 & \text{otherwise} \end{cases}$$

- Error trace (*distinguishing sequence*) that leads to an error state

- sequence of inputs which produces 1 at the output of M
- produces a state in M for which M_1 and M_2 give different outputs



FSM Traversal in Action

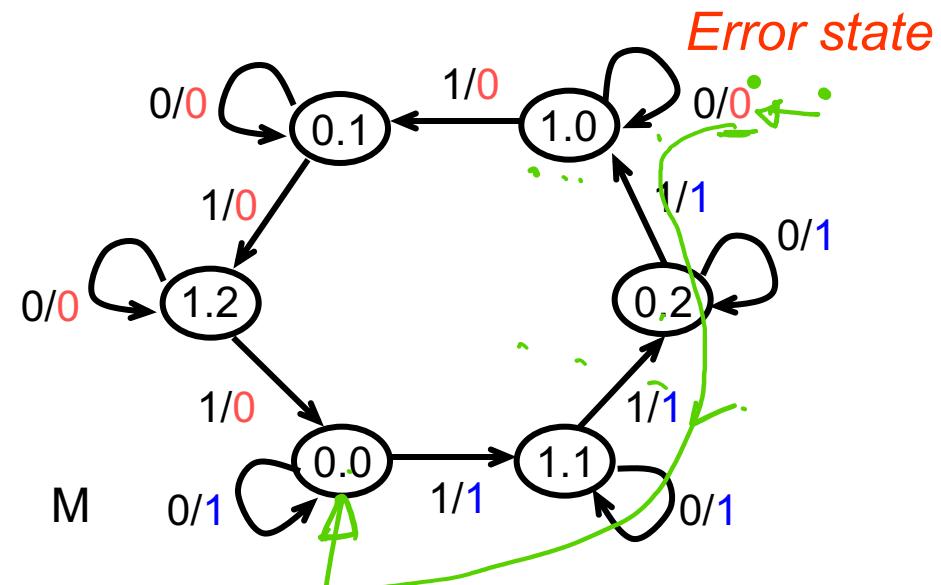


Initial states: $s_1=0, s_2=0, s=(0.0)$

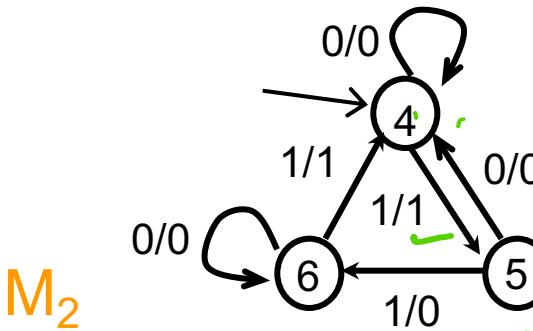
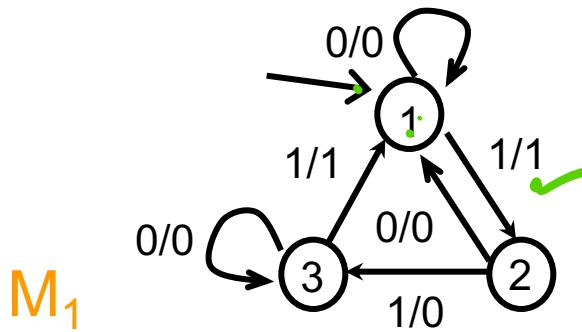
	$Out(M)$
State reached	$x=0 \ x=1$

- New $^0 = (0.0) \quad 1 \quad 1$
- New $^1 = (1.1) \quad 1 \quad 1$
- New $^2 = (0.2) \quad 1 \quad 1$
- New $^3 = (1.0) \quad 0 \quad 0$

- STOP - backtrack to initial state to get error trace: $x=\{1,1,1,0\}$



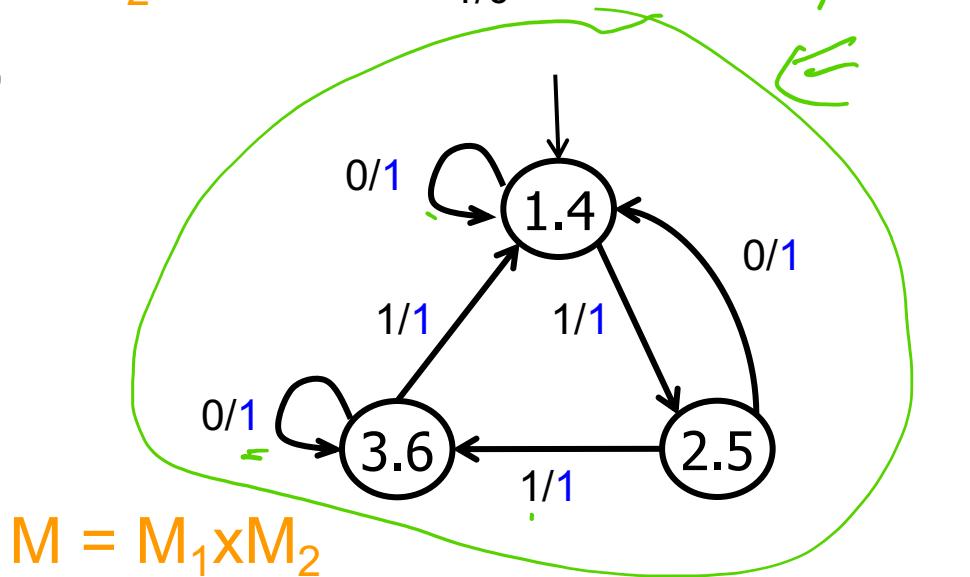
FSM Traversal in Action



Initial states: $s_1=1$, $s_2=4$, $s=(1.4)$

	$Out(M)$
State reached	$x=0 \quad x=1$

- $New^0 = (1.4) \quad 1 \quad 1$
- $New^1 = (2.5) \quad 1 \quad 1$
- $New^2 = (3.6) \quad 1 \quad 1$

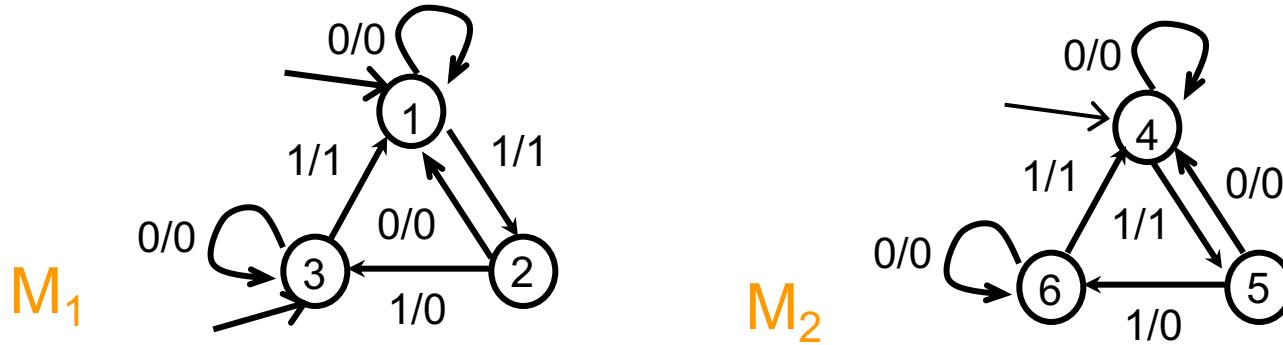


$$M = M_1 \times M_2$$

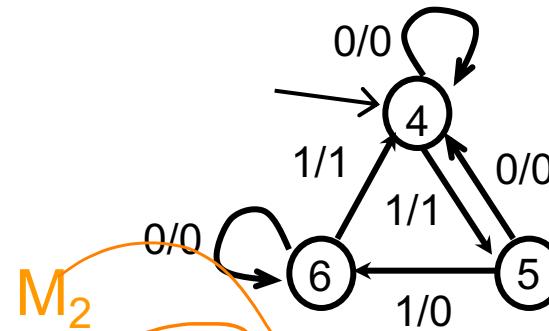
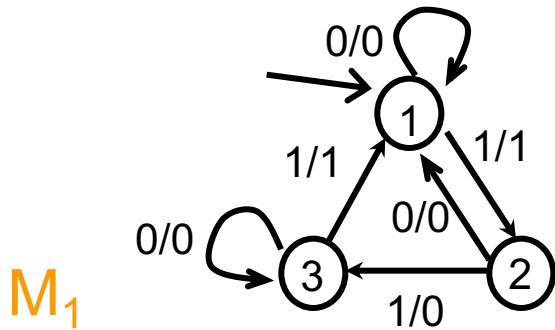
$$M_1 \equiv M_2$$



FSM Traversal in Action



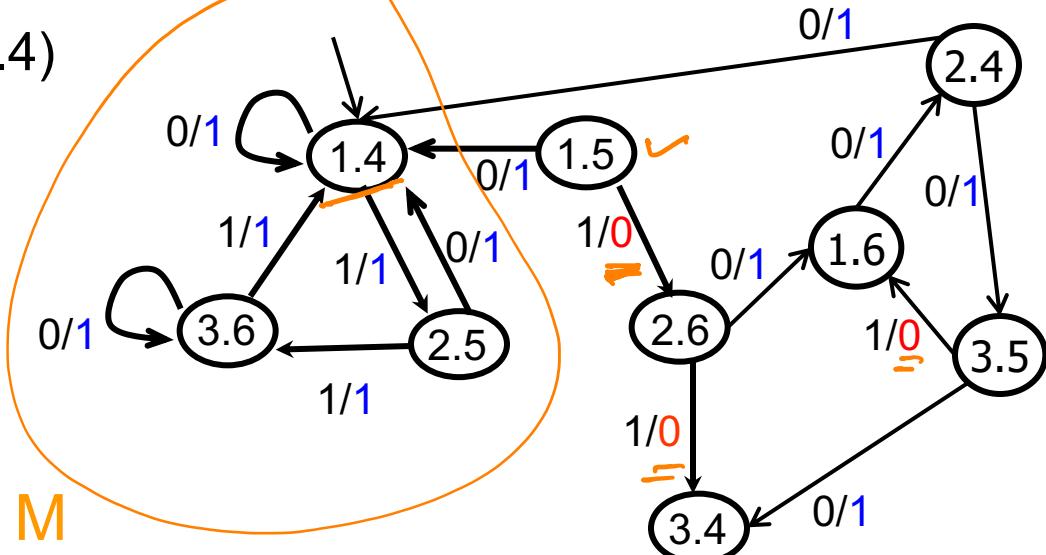
FSM Traversal in Action



Initial states: $s_1=1$, $s_2=4$, $s=(1,4)$

	$Out(M)$
State reached	$x=0 \quad x=1$

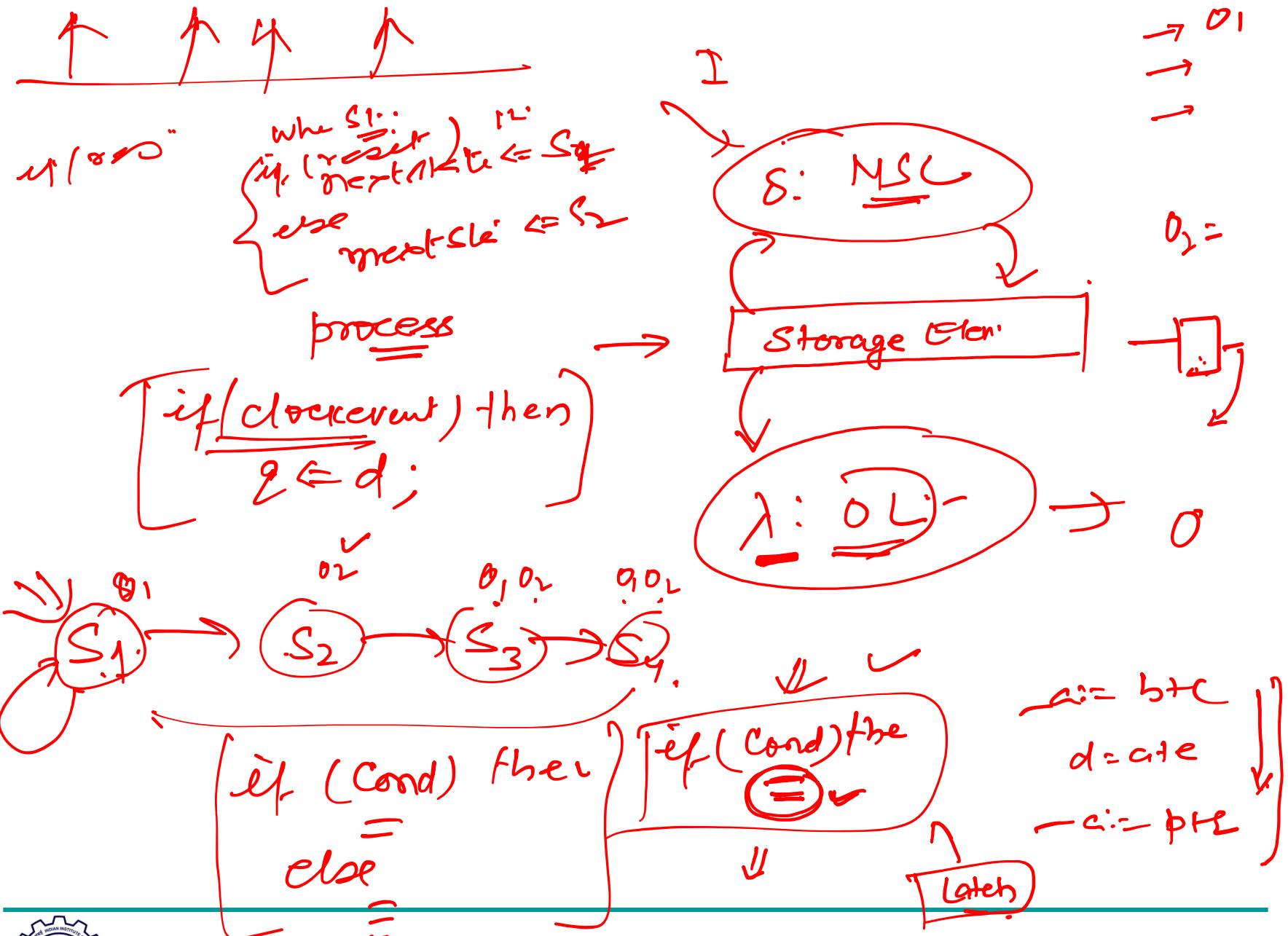
- $New^0 = (1,4) \quad 1 \quad 1$
- $New^1 = (2,5) \quad 1 \quad 1$
- $New^2 = (3,6) \quad 1 \quad 1$



- Erroneous states are not reachable

$$M \models \Gamma, D, S, S_0, \delta, \lambda$$

$$M_1 \equiv M_2$$



FSM Traversal - Algorithm

- Traverse the product machine $M(X, S, \delta, \lambda, O)$
 - start at an initial state S_0
 - iteratively compute symbolic image $\text{Img}(S_0, R)$ (set of *next states*):

$$\text{Img}(S_0, R) = \exists_x \exists_s S_0(s).R(x, s, t)$$

$$R = \prod_i R_i = \prod_i (t_i \equiv \delta_i(s, x))$$

until an *error state* is reached

- transition relation R_i for each next state variable t_i can be computed as $t_i = (t \otimes \delta(s, x))$
(this is an alternative way to compute transition relation, when design is specified at gate level)



Thank You



17 Feb 2022

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17

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