

A P STANT INSTRIPTIND OF TROCENOLOGY (Approved by AICTE New Delhi & Govt. of Maharashtra, Affiliated to University of Mumbai) (Religious Jain Minority)



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Program -

Class : TE (Div-C)

Subject: AI LAB(CSL 605)

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namika M Batch: C2

Experiment 5

```
def heuristic(n):
H dist = {
'A': 10,
'B': 8,
'C': 8,
'D': 7,
'E': 3,
'F': 6,
'G': 5,
'H': 3,
'I': 1,
'J': 0
return H_dist[n]
Graph nodes = {
'A': [('B', 6), ('F', 3)],
'B': [('A', 6), ('C', 3), ('D', 2)],
'C': [('B', 3), ('D', 1), ('E', 5)],
'D': [('B', 2), ('C', 1), ('E', 8)],
'E': [('C', 5), ('D', 8), ('I', 5), ('J', 5)],
'F': [('A', 3), ('G', 1), ('H', 7)],
'G': [('F', 1), ('I', 3)],
'H': [('F', 7), ('I', 2)],
'I': [('E', 5), ('G', 3), ('H', 2), ('J', 3)]
}
def aStarAlgo(start node, stop node):
open set = set(start node)
```

```
closed set = set()
g = \{\}
parents = \{\}
g[start node] = 0
parents[start node] = start node
while len(open set) > 0:
n = None
for v in open set:
if n == None \text{ or } g[v] + heuristic(v) < g[n] + heuristic(n):
n = v
if n == stop node or Graph nodes[n] == None:
pass
else:
for (m, weight) in Graph nodes[n]:
if m not in open_set and m not in closed_set:
open set.add(m)
parents[m] = n
g[m] = g[n] + weight
else:
if g[m] > g[n] + weight:
g[m] = g[n] + weight
parents[m] = n
if m in closed set:
closed_set.remove(m)
open set.add(m)
if n == None:
print("Path does not exist!")
return None
if n == stop_node:
path = []
while parents[n] != n:
path.append(n)
n = parents[n]
path.append(start_node)
path.reverse()
print(f"Path found: {path}")
```

```
return path
open_set.remove(n)
closed_set.add(n)
print("Path does not exist!")
return None
aStarAlgo('A', 'J')
      ···return None
     aStarAlgo('A', 'J')
  Path found: ['A', 'F', 'G', 'I', 'J']
['A', 'F', 'G', 'I', 'J']
```