# **SPRINT 1 DOCUMENT**

# PROJECT TITLE: SPACE TRAFFIC DENSITY PREDICTION

#### **Team Members:**

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#### 1. SPRINT OBJECTIVE

To perform exploratory data analysis (EDA), pre-processing, and feature engineering to gain insights into the dataset and set the groundwork for predictive modeling of space traffic density.

#### 2. SPRINT OVERVIEW

Duration: 7-Nov-24 to 18-Nov-24

#### **Focus Areas:**

- Understanding the problem statement.
- Gaining insights into the dataset.
- Conducting exploratory data analysis (EDA).

#### 3. DELIVERABLES

#### 3.1 Problem Statement

- Addressed the need for a reliable space traffic density prediction system for collision avoidance and mission planning.
- Identified key factors influencing traffic density: orbital location, object type, and time of day.
- Developed a foundational understanding of project expectations and objectives.

# **Expected Outcomes Delivered:**

- Clear understanding of the problem.
- Established scope and requirements for predictive modeling.

# 3.2 Dataset Exploration

- Attributes analyzed:
  - **Timestamp:** Traffic recording time.
  - Location: Orbital zones like Lagrange Points, Low Earth Orbit, Mars Transfer Orbit.
  - Object\_Type:Categories like Space Stations, Satellites, Probes, and Space Debris, Manned Spacecraft and Asteroid Mining Ship.

- Traffic\_Density: Numerical representation of space traffic volume.
- o Peak\_Time: Hourly peak traffic observations.
- Dataset summary and insights:
  - No missing values.
  - Nearly symmetric Traffic\_Density distribution (skewness = 0.092).
  - Data types: Numerical and categorical attributes.

#### 3.3 Exploratory Data Analysis (EDA)

### **Data Insights:**

#### 1. Univariate Analysis:

- Distribution and characteristics of individual features.
- Visualizations: Histograms, Box Plots, and Violin Plots for Traffic\_Density.

#### 2. Bivariate Analysis:

- Examined Traffic\_Density trends across locations and object types using box and violin plots.
- No significant association between object type and location (Chi-square p-value = 0.3583).

## 3. Time Series Analysis:

Observed traffic density trends over time.

# 4. Additional Analysis:

- o Identified high-risk zones and bottlenecks for specific object types.
- Highlighted peak traffic patterns by object type and location.

#### 4. KEY METRICS

Metric	Value
Total Records in Dataset	1000
Skewness of Traffic_Density	0.092 (Nearly symmetric)
ANOVA Test (p-values for Object_Type and Location)	0.464, 0.339 (Not significant)
Chi-Square Test (Object_Type vs Location)	p-value = 0.3583

#### 5. KEY LEARNINGS

- Gained a deeper understanding of orbital dynamics and traffic patterns.
- Learned advanced visualization techniques to uncover patterns in data.
- Importance of robust feature engineering for categorical variables.

#### **6. NEXT STEPS**

- Refine feature engineering techniques for predictive modeling.
- Design and implement machine learning models for space traffic prediction.
- Explore advanced time series forecasting methods for real-time prediction.

#### 7. VISUALIZATIONS

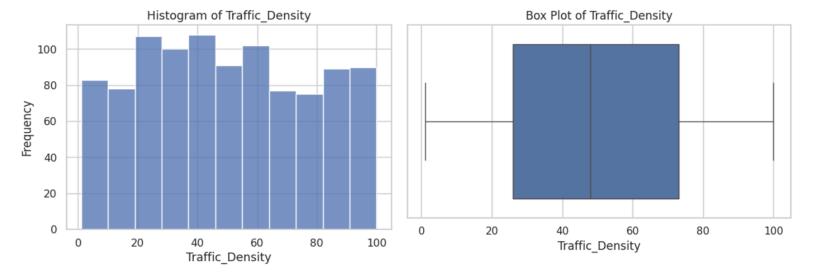


Fig 8.1 Histogram of Traffic Density

Fig 8.2 Box Plot of Traffic Density

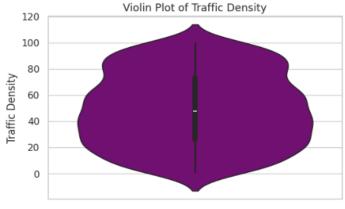


Fig 8.3 Violin plot of Traffic density

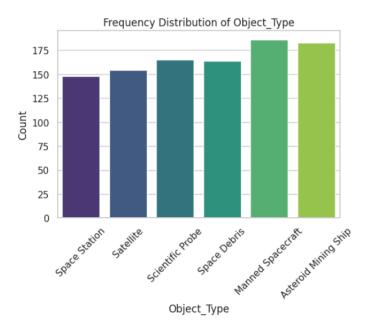


Fig 8.4 Frequency distribution of Object\_Type

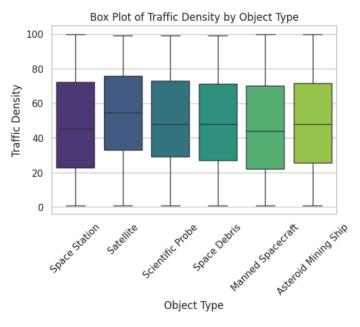


Fig 8.6 Box Plot of Traffic density by Object\_Type

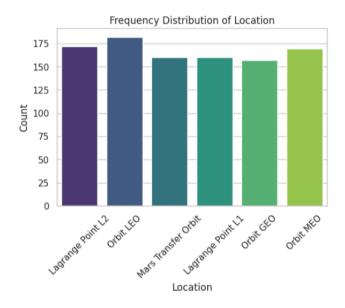


Fig 8.5 Frequency Distribution of Location

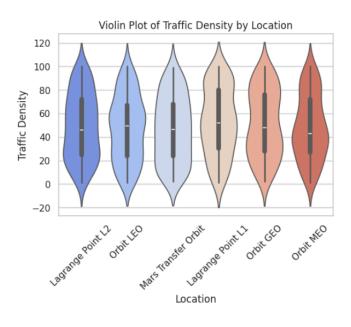


Fig 8.7 Box Plot of Traffic Density by Location

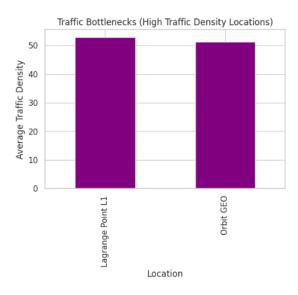


Fig 8.8 High Traffic Density Locations

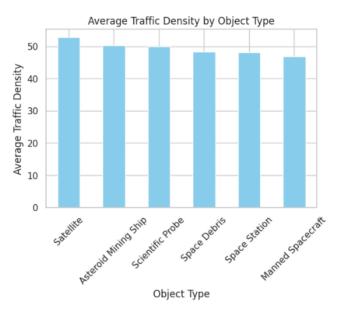


Fig 8.9 Average Traffic Density by Object\_type

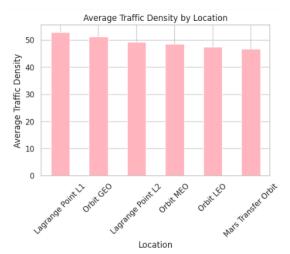


Fig 8.10 Average Traffic Density by location

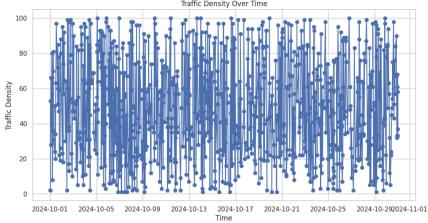


Fig 8.11 Traffic Density over time

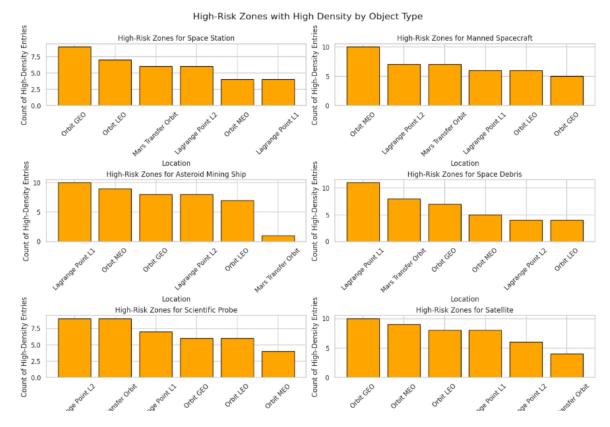


Fig 8.12 High Risk Zones with High Density by Object\_type

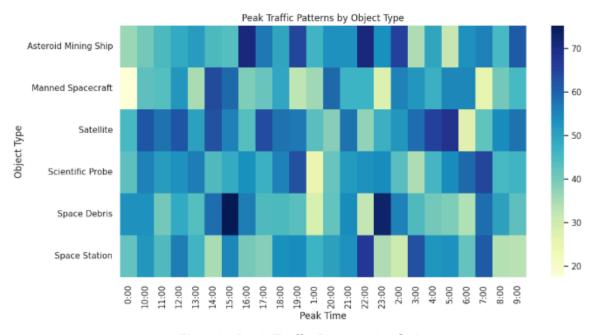


Fig 8.13 Peak Traffic Patterns by Object type

# 8. CONCLUSION

The first sprint successfully laid the foundation for predicting space traffic density. By gaining a comprehensive understanding of the dataset and exploring key traffic patterns, the project is well-positioned to transition into the model development phase in subsequent sprints.