

ECE 47300 Assignment 6 Exercise

Your Name: Owen Semeter

Objective: Build an RNN model to predict the next character in a sequence of text data from Shakespeare's plays.

✓ Exercise 1: Data Preprocessing (30 points)

In this part, you will implement some preprocessing functions. Run the following code to load the text data from the given file "shakespeare.txt". Do not change the random seed.

```
In [2]: import numpy as np
! pip install unicode
import unicode
import string
import time
import torch
import pdb

import torch.nn as nn
from torch.autograd import Variable

all_characters = string.printable
print(all_characters)
```

Collecting unicode

Downloading Unicode-1.3.8-py3-none-any.whl.metadata (13 kB)

Downloading Unicode-1.3.8-py3-none-any.whl (235 kB)

```

0.0/235.5 kB ? eta -:--:--
225.3/235.5 kB 8.7 MB/s eta 0:00:01
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```

Installing collected packages: unicode

Successfully installed unicode-1.3.8

0123456789abcdefghijklmnopqrstuvwxyzABCDEFGHIJKLMNOPQRSTUVWXYZ!"#\$%&'()*+,-./:;<=>?@
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📄

Exercise 1: Data Preprocessing (30 points)

Follow the step on the instructions and mount your google drive on Colab which allows to access the .txt file uploaded on your drive that was included with this assignment.

```
In [3]: ! pip install google
from google.colab import drive
drive.mount('/content/drive')
```

Requirement already satisfied: google in /usr/local/lib/python3.11/dist-packages (2.0.3)
 Requirement already satisfied: beautifulsoup4 in /usr/local/lib/python3.11/dist-packages (from google) (4.13.3)
 Requirement already satisfied: soupsieve>1.2 in /usr/local/lib/python3.11/dist-packages (from beautifulsoup4->google) (2.6)
 Requirement already satisfied: typing-extensions>=4.0.0 in /usr/local/lib/python3.11/dist-packages (from beautifulsoup4->google) (4.12.2)
 Mounted at /content/drive

```
In [4]: def read_file(filename):
        file = unicode.decode(open(filename).read())
        return file

        dir_root = '.'      # Your assignment dir
        file_path = dir_root + '/shakespeare.txt'
        file = read_file(file_path)
        file_len = len(file)
        print(f"file length: {file_len}")
        print(file[:100])
```

file length: 1115394
 First Citizen:
 Before we proceed any further, hear me speak.

All:
 Speak, speak.

First Citizen:
 You

✓ Task 1: Implement function to get a random chunk of Shakespeare text (15 points)

The `get_random_chunk` function is a helper function that generates a random chunk of **input text data** and **output text data** (which is one character shifted from the input) from the Shakespeare dataset. Specifically, the `chunk_len` argument specifies the size of the input and output sequences. For example, if `chunk_len=4`, then a valid return value would be the two chunks: ('Befo', 'efor') or ('proc', 'roce'). This function is useful in generating diverse sets of input data for training the RNN model in the assignment.

Hints:

- Start from a random index of the file (but note that the max index must be small enough so that a full chunk can be extracted).
- Based on this random start index, extract `chunk_len` characters for the input sequence and `chunk_len` characters for the output sequence (shifted one character to the right).

```
In [5]: def get_random_chunk(file, rng, chunk_len = 100):
        ##### Your Code Here #####
        assert(len(file) > chunk_len + 1)
        max_idx = len(file) - (chunk_len + 1)
        idx = rng.randint(0, max_idx)
        return (file[idx:idx + chunk_len], file[idx+1:idx + chunk_len + 1])
        ##### End of your code #####

        rng = np.random.RandomState(123) # use this if you need to generate a random sample
        curr_chunk, next_chunk = get_random_chunk(file='Hello world!', rng=rng, chunk_len=1)
        print(f"curr_chunk => {curr_chunk}\n next_chunk=> {next_chunk}")
```

```
print(f"Is curr_chunk and next_chunk same length: {len(curr_chunk) == len(next_chunk)}")
print(f"Is next chunk shifted by one: {curr_chunk[1:] == next_chunk[:-1]}")
```

```
curr_chunk =>Hello worl
next_chunk=> ello world
Is curr_chunk and next_chunk same length: True
Is next chunk shifted by one: True
```

✓ Task 2: Implement function to convert to tensors (15 points)

Define a function `to_tensor(string)` that takes a string of characters as input and return torch tensor as output, similar to in the demo in class. Specifically,

1. Create an empty tensor of shape `(len(string), 1, len(all_characters))` using the PyTorch `torch.zeros` function, where `len(string)` is the length of the input string, 1 is the batch size, and `len(all_characters)` is the total number of unique characters in the text data.
2. Loop through each character in the input string and convert it to a one-hot encoded vector.

```
In [6]: def to_tensor(string):
##### Your Code Here #####
    tensor = torch.zeros(len(string), 1, len(all_characters))
    for ci, character in enumerate(string):
        tensor[ci][0][all_characters.find(character)] = 1
    return tensor
##### End of your code #####

def get_one_hot_tensors(input, output):
    return to_tensor(input), to_tensor(output)

rng = np.random.RandomState(123) # use this if you need to generate a random sample
input, output = get_random_chunk(file, rng, 50)
print(input.replace('\n', ' '))
print(output.replace('\n', ' '))
input_tensor, output_tensor = get_one_hot_tensors(input, output)
print(f"input shape: {input_tensor.shape}")
print(f"output shape: {output_tensor.shape}")
```

```
g's, which Florizel I now name to you; and with sp
's, which Florizel I now name to you; and with spe
input shape: torch.Size([50, 1, 100])
output shape: torch.Size([50, 1, 100])
```

✓ Exercise 2: Build the RNN model (30 points)

In this part, you will build the RNN model using PyTorch.

- nn.GRU is used to implement the GRU algorithm for processing sequential input data.
 - <https://pytorch.org/docs/stable/generated/torch.nn.GRU.html>
- The decoder layer is a fully connected neural network layer that maps the output of the GRU layer to the desired output size.
- As we are only implementing a single layer RNN, the model is not powerful enough to learn long-term dependencies in the text data. So don't be surprised if the output sentences are not very meaningful. We are providing you loss plots (`gru_loss_ex2.png`) to help you check if your code is working correctly.

Code instruction:

- init function:
 1. Set `self.rnn_cell` to a `nn.GRU`
 2. Define a linear decoder layer that maps from the hidden size to the output size
- forward function:
 1. Reshape the input to `(1, 1, -1)` and pass it to the GRU layer
 2. Reshape the `rnn_cell` output to `(1, -1)` and pass it to the decoder layer

```
In [7]: import torch
import torch.nn as nn
from torch.autograd import Variable

class RNN(nn.Module):
    def __init__(self, input_size, hidden_size, output_size, n_layers=1):
        super(RNN, self).__init__()

        self.input_size = input_size
        self.hidden_size = hidden_size
        self.output_size = output_size
        self.n_layers = n_layers

        # Define modules of RNN
        ##### Your Code Here #####
        self.rnn_cell = nn.GRU(input_size, hidden_size, n_layers)
        self.linear_decoder = nn.Linear(hidden_size, output_size)
        ##### End of your code #####

    def forward(self, input, hidden):
        ##### Your Code Here #####
        input = input.view(1, 1, -1)
        input, hidden = self.rnn_cell(input, hidden)
        output = input.view(1, -1)
        output = self.linear_decoder(output)
        ##### End of your code #####
        return output, hidden

    def init_hidden(self):
        return Variable(torch.zeros(self.n_layers, 1, self.hidden_size))
```

```
In [8]: def train(inp, target, decoder):
    hidden = decoder.init_hidden()
    decoder.zero_grad()
    loss = 0

    input_tensor, target_tensor = get_one_hot_tensors(inp, target)
    for c in range(len(inp)):
        output, hidden = decoder(input_tensor[c], hidden)
        loss += criterion(output, torch.argmax(target_tensor[c]).unsqueeze(0))

    loss.backward()
    decoder_optimizer.step()
    return loss.item() / max_length
```

```
In [9]: def evaluate(decoder, prime_str='A', predict_len=100, temperature=0.8):
    hidden = decoder.init_hidden()
    prime_input = to_tensor(prime_str)
    predicted = prime_str

    # Use priming string to "build up" hidden state
    for p in range(len(prime_str) - 1):
        out, hidden = decoder(prime_input[p], hidden)
    inp = prime_input[-1]
    for p in range(predict_len):
        output, hidden = decoder(inp, hidden)

    # Sample from the network as a multinomial distribution
    output_dist = output.data.view(-1).div(temperature).exp()
    top_i = torch.multinomial(output_dist, 1)[0]

    # Add predicted character to string and use as next input
    predicted_char = all_characters[top_i]
    predicted += predicted_char
    inp = to_tensor(predicted_char)

    return predicted
```

```
In [10]: n_epochs = 2000
print_every = 100
plot_every = 10
hidden_size = 100
n_layers = 1
lr = 0.005
max_length = len(all_characters)

decoder = RNN(max_length, hidden_size, max_length)
decoder_optimizer = torch.optim.Adam(decoder.parameters(), lr=lr)
criterion = nn.CrossEntropyLoss()

start = time.time()
all_losses = []
loss_avg = 0
rng = np.random.RandomState(123) # use this if you need to generate a random sample

for epoch in range(1, n_epochs + 1):
    loss = train(*get_random_chunk(file, rng), decoder)
    loss_avg += loss

    if epoch % print_every == 0:
        print(f"[{epoch} {epoch / n_epochs * 100}%] {loss}")
        print(evaluate(decoder, 'Wh', 100), '\n')

    if epoch % plot_every == 0:
        all_losses.append(loss_avg / plot_every)
        loss_avg = 0

print(f"_____")
print(evaluate(decoder, 'Th', 200, temperature=0.2))
```

```
import matplotlib.pyplot as plt
plt.plot(all_losses)
plt.title("GRU Loss: Loss vs Epoch")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.show()
```

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✓ Exercise 3: Implement an LSTM model (30 points)

Using the equations from the slides in class, write your own LSTM cell module. The code below will use this instead of the GRU cell module and train the model.

Notes:

- Note that for LSTM the hidden state is really both the h_t and C_t so we just unpack the passed hidden state into these two variables at the beginning, and pack them into a tuple for returning.
- We apply a single linear layer to compute all the linear parts of the model that operate on h'_{t-1} and then unpack these using `chunk(4)` into the four separate parts. This is equivalent to having 4 separate linear layers.
- As we are only implementing a single layer RNN, the model is not powerful enough to learn long-term dependencies in the text data. So don't be surprised if the output sentences are not very meaningful. We are providing you loss plots (`lstm_loss_ex3.png`) to help you check if your code is working correctly.

Code instruction:

- forward function:
 1. Apply activation functions to get gates and new cell state information
 2. Calculate the new cell state (c_new)
 3. Calculate the new hidden state (h_new)

```
In [11]: class LSTMCell(nn.Module):
    def __init__(self, input_size, hidden_size, bias=True):
        super(LSTMCell, self).__init__()
        self.input_size = input_size
        self.hidden_size = hidden_size
        self.bias = bias

        self.xh = nn.Linear(input_size, hidden_size * 4, bias=bias)
        self.hh = nn.Linear(hidden_size, hidden_size * 4, bias=bias)
        self.reset_parameters()

    def reset_parameters(self):
        std = 1.0 / np.sqrt(self.hidden_size)
        for w in self.parameters():
            w.data.uniform_(-std, std)

    def forward(self, input, hidden=None):
        # Unpack hidden state and cell state
        hx, cx = hidden

        # Apply Linear Layers to input and hidden state
        linear = self.xh(input) + self.hh(hx)

        # Get outputs of applying a linear transform for each part of the LSTM
        input_linear, forget_linear, cell_linear, output_linear = linear.reshape(-1, self.hidden_size)

        ##### Your Code Here #####
        f_gate = torch.sigmoid(forget_linear)
        i_gate = torch.sigmoid(input_linear)
        o_gate = torch.sigmoid(output_linear)
        c_state = torch.tanh(cell_linear)

        c_new = f_gate * cx + i_gate * c_state
        h_new = o_gate * torch.tanh(c_new)
        ##### End of your code #####

        # Pack cell state $C_t$ and hidden state $h_t$ into a single hidden state $t$
        output = h_new # For LSTM the output is just the hidden state
        hidden = (h_new, c_new) # Packed h and C
        return output, hidden
```

```
In [12]: lr = 0.001
class LSTM_RNN(RNN):
    def __init__(self, *args, **kwargs):
        super().__init__(*args, **kwargs)
        # Replace the gru cell with LSTM cell
```

```

        self.rnn_cell = LSTMCell(max_length, hidden_size, max_length)

    def init_hidden(self):
        # LSTM cells need two hidden variables in a tuple of (h_t, C_t)
        return (Variable(torch.zeros(1, 1, self.hidden_size)), Variable(torch.zeros(1, 1, self.hidden_size)))

decoder = LSTM_RNN(max_length, hidden_size, max_length)
decoder_optimizer = torch.optim.Adam(decoder.parameters(), lr=lr)

all_losses = []
loss_avg = 0
rng = np.random.RandomState(123) # use this if you need to generate a random sample

for epoch in range(1, n_epochs + 1):
    loss = train(*get_random_chunk(file, rng), decoder)
    loss_avg += loss

    if epoch % print_every == 0:
        print(f"({epoch} {epoch / n_epochs * 100}%) {loss}")
        print(evaluate(decoder, 'Wh', 100), '\n')

    if epoch % plot_every == 0:
        all_losses.append(loss_avg / plot_every)
        loss_avg = 0

print(f"_____")
print(evaluate(decoder, 'Th', 200, temperature=0.2))

plt.plot(all_losses)
plt.title("LSTM Loss: Loss vs Epoch")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.show()

```

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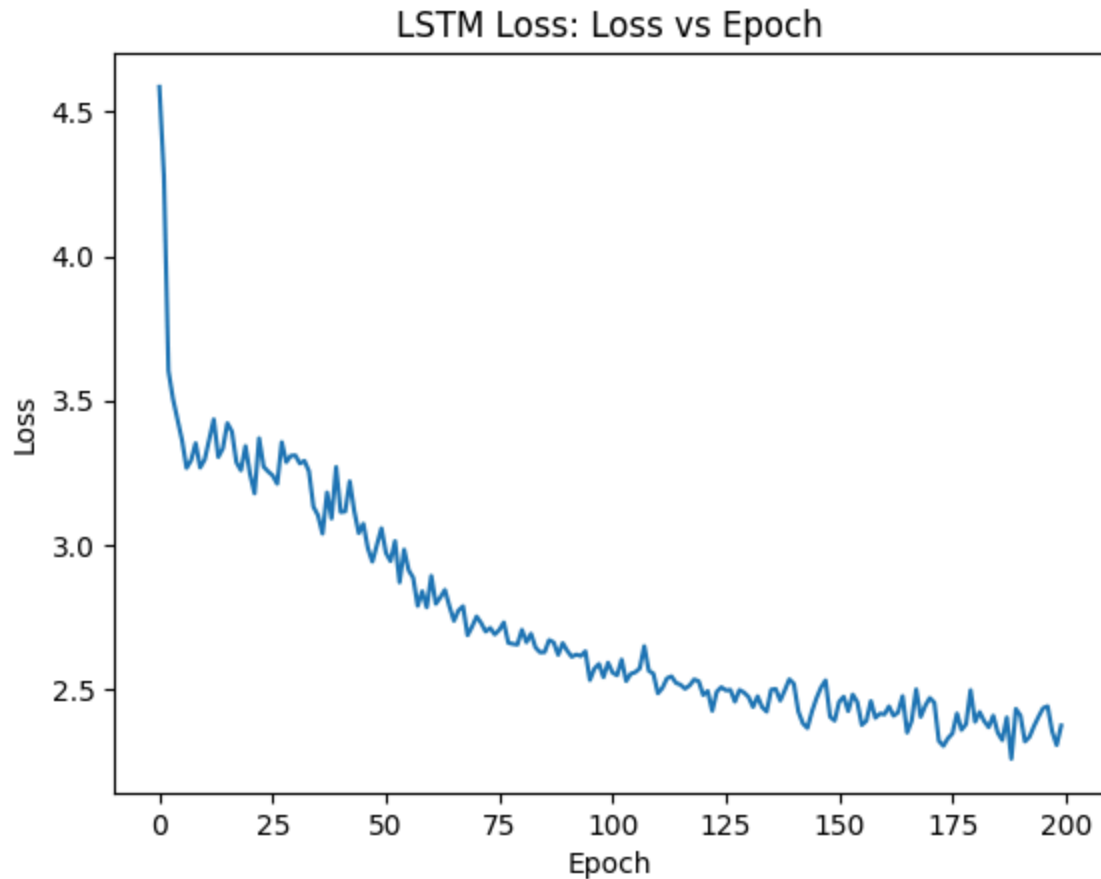
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✓ Exercise 4: Implement your own GRU (10 points)

Same as above but implement a GRU instead of an LSTM module. An example of GRU architecture can be found from the lecture slide:

<https://www.davidinouye.com/course/ece57000-fall-2023/lectures/recurrent-neural-networks.pdf>

Your output loss plot should be similar in Exercise 2.

✓ Code instruction:

• forward function:

1. Concatenate hidden and input to get h_{prime} (see torch.cat)
2. Use self.h2z to calculate z_t
3. Use self.h2r to calculate r_t
4. Use Hadamard product of r_t and h_x and concatenate with input
5. Then use h2h to calculate new hidden information h_{tbar}
6. Update h_t with z_t , h_x , and h_{tbar}

```
In [13]: class GRUCell(nn.Module):
def __init__(self, input_size, hidden_size, bias=True):
    super(GRUCell, self).__init__()
    self.input_size = input_size
    self.hidden_size = hidden_size
    self.bias = bias

    self.h2z = nn.Linear(input_size + hidden_size, hidden_size)
    self.h2r = nn.Linear(input_size + hidden_size, hidden_size)
    self.h2h = nn.Linear(input_size + hidden_size, hidden_size)
```

```

self.reset_parameters()

def reset_parameters(self):
    std = 1.0 / np.sqrt(self.hidden_size)
    for w in self.parameters():
        w.data.uniform_(-std, std)

def forward(self, input, hx=None):
    # Inputs:
    #     input: of shape (batch_size, input_size)
    #     hx: of shape (batch_size, hidden_size)
    # Output:
    #     h_t, h_t: h_t is of shape (batch_size, hidden_size)

    if hx is None:
        hx = Variable(input.new_zeros(input.size(0), self.hidden_size))

    ##### Your Code Here #####
    h_prime = torch.cat((hx, input), 2)
    z_gate = torch.sigmoid(self.h2z(h_prime))
    r_gate = torch.sigmoid(self.h2r(h_prime))
    h_state = torch.tanh(self.h2h(torch.cat((r_gate * hx, input), 2)))
    h_t = (1 - z_gate) * hx + z_gate * h_state
    ##### End of your code #####

    # Reshape h_t match input size
    h_t = h_t.reshape(1, 1, -1)

    return h_t, h_t  # Output and hidden are both h_t

```

```

In [14]: n_epochs = 2000
print_every = 100
plot_every = 10
hidden_size = 100
n_layers = 1
lr = 0.005
max_length = len(all_characters)

# Replace the RNN module with your implemented GRUCell
class GRU_RNN(RNN):
    def __init__(self, *args, **kwargs):
        super().__init__(*args, **kwargs)
        # Replace with your gru cell
        self.rnn_cell = GRUCell(max_length, hidden_size, max_length)

decoder = GRU_RNN(max_length, hidden_size, max_length)
decoder_optimizer = torch.optim.Adam(decoder.parameters(), lr=lr)

all_losses = []
loss_avg = 0
rng = np.random.RandomState(123) # use this if you need to generate a random sample

for epoch in range(1, n_epochs + 1):
    loss = train(*get_random_chunk(file, rng), decoder)

```

```
loss_avg += loss

if epoch % print_every == 0:
    print(f"({epoch} {epoch / n_epochs * 100}%) {loss}")
    print(evaluate(decoder, 'Wh', 100), '\n')

if epoch % plot_every == 0:
    all_losses.append(loss_avg / plot_every)
    loss_avg = 0

print(f"_____")
print(evaluate(decoder, 'Th', 200, temperature=0.2))

plt.plot(all_losses)
plt.title("GRU Loss: Loss vs Epoch")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.show()
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[(1500 75.0%) 2.0188636779785156]

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[(1700 85.0%) 1.8519338989257812]

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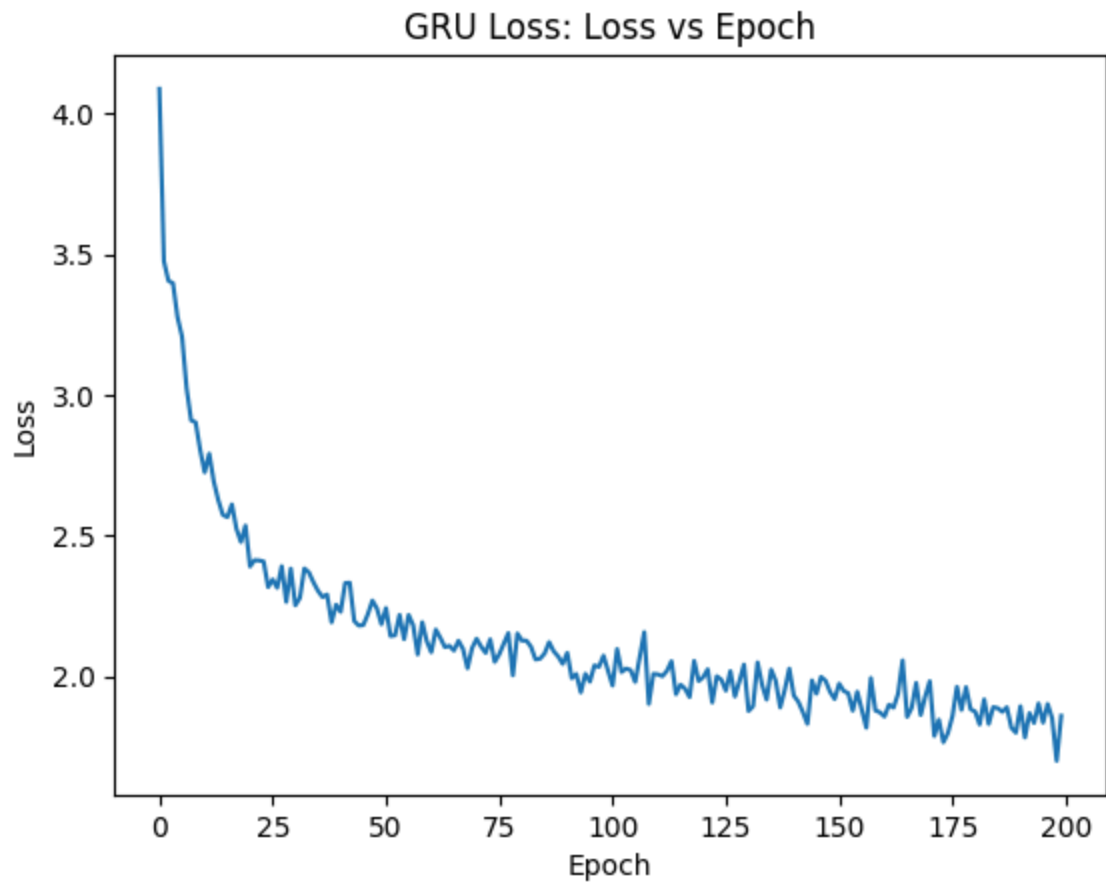
[(2000 100.0%) 1.575778045654297]

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