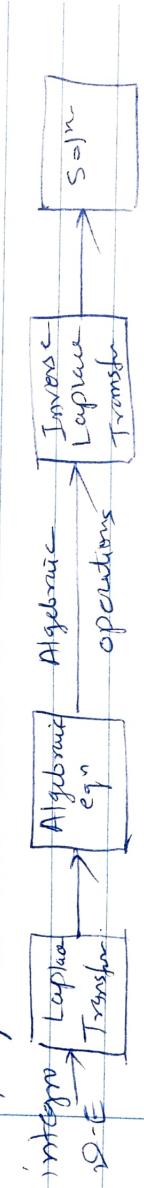


4. Analysis of Transient Response in Circuit using Laplace Transform

Equations describing behaviour of m/w consisting of element like resistances, inductances & capacitances are always of integro-differential type. In earlier chapter we have seen classical methods for solving such eqns. It has been realized that the method of obtaining soln of D.E. is little bit complicated. But using transform methods it becomes simpler. Here we are going to discuss Laplace Transform method which transforms the time domain differential eqns to freq. domain.

The Laplace Transform method provides very simple way of solving complicated integro-differential time domain eqns, by converting them into simple algebraic eqns in the freq. domain.



Laplace Transform Method.

Laplace Transform.

If $f(t)$ is the time domain function, then its L.T. is denoted by $F(s)$ and is defined by the eqn,

$$L[f(t)] = F(s) = \int_0^\infty f(t) e^{-st} dt.$$

where s is the complex freq. variable and is given by

$$s = \sigma + j\omega$$

The real part σ is called attenuation constant or damping factor and ω which is imaginary part of s is the angular freq.

To take into account the possibility that $f(t)$ may be an impulse or one of its higher derivatives, the lower limit of integration is taken as 0^- . This includes time just before the instant $t = 0$.

In the case when no impulses or its higher order derivatives are involved, i.e. for continuous functions, $f(0^-) = f(0^+)$, then the integration can be effectively taken from 0^- to ∞

$$L[f(t)] = F(s) = \int_0^\infty f(t) e^{-st} dt. \quad \text{--- when } f(t) \text{ is cont. man.}$$

The function $f(t)$ possesses a L-T. only if it satisfies the condition given by,

$$\int_{-\infty}^{\infty} |f(t)| e^{-st} dt < \infty \quad \text{for real, positive } s$$

Similar to the L-T, the inverse L-T giving time domain function from freq. domain is defined as,

$$f(t) = L^{-1}[F(s)]$$

$$= \frac{1}{2\pi j} \int_{\sigma_1 - j\infty}^{\sigma_1 + j\infty} F(s) e^{st} ds$$

For real, positive,

Properties of L-T.

1. Linearity

$$L\{f_1(t) + f_2(t) + \dots + f_n(t)\} = F_1(s) + F_2(s) + \dots + F_n(s)$$

it can be further extended as,

$$L\{a_1f_1(t) + a_2f_2(t) + \dots + a_nf_n(t)\} = a_1F_1(s) + a_2F_2(s) + \dots + a_nF_n(s)$$

where a_1, a_2, \dots are constant.

2. Scaling

$$L\{Kf(t)\} = K F(s)$$

3. Real differentiation

$$L\left\{\frac{df(t)}{dt}\right\} = sF(s) - f(0^-)$$

where $f(0^-)$ indicates value of $f(t)$ at $t = 0^-$

The theorem can be extended for n^{th} order derivative as,

$$L\left\{\frac{d^n f(t)}{dt^n}\right\} = s^n F(s) - s^{n-1} f(0^-) - s^{n-2} f'(0^-) - \dots - f^{(n-1)}(0^-)$$

$$f_0, n=2$$

$$L\left\{\frac{d^2 f(t)}{dt^2}\right\} = s^2 F(s) - s \cdot f(0^-) - f'(0^-)$$

$$\text{for } n=3$$

$$L\left\{\frac{d^3 f(t)}{dt^3}\right\} = s^3 F(s) - s^2 f(0^-) - s \cdot f'(0^-) - f''(0^-)$$

4. Real integration

$$\mathcal{L} \left\{ \int_0^t f(t) dt \right\} = \frac{F(s)}{s}$$

for multiple integrals, it can be extended as,

$$\mathcal{L} \left\{ \int_0^{t_1} \int_0^{t_2} \dots \int_0^{t_n} f(t_1) dt_1 dt_2 \dots dt_n \right\} = \frac{F(s)}{s^n}$$

5. Differentiation by s

If $F(s)$ is L-T. of $f(t)$ then the differentiation by s in the complex freq. domain corresponds to the multiplication by t in the time domain

$$\mathcal{L} \left\{ t f(t) \right\} = \frac{-F(s)}{ds}$$

6. Complex - Translation

$$\mathcal{L} \left\{ e^{at} f(t) \right\} = F(s-a)$$

$$\mathcal{L} \left\{ e^{-at} f(t) \right\} = F(s+a)$$

where a is a complex no.

7. Real translation (shifting theorem)

it is useful to obtain L-T. of the shifted or delayed function of time.

If $F(s)$ is the L-T. of $f(t)$ then the L-T. of the function delayed by time T is,

$$\mathcal{L}\{f(t-T)\} = e^{-Ts} F(s)$$

8. Initial value theorem

it is useful to find the initial value of the time function $f(t)$. Thus if $F(s)$ is the L.T. of $f(t)$ then,

$$f(0^+) = \lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} sF(s)$$

only restriction that $f(t)$ must be continuous or at the most, a step discontinuity at $t=0$.

9. Final value theorem.

it is useful to find the final value of the time function $f(t)$

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$$

Table of L.T.

$F(t)$

1

Constant K

t

t^n

e^{-at}

e^{at}

$e^{-at} t^n$

$\sin wt$

$\cos wt$

$e^{-at} \sin wt$

$e^{-at} \cos wt$

$\sinh wt$

$\cosh wt$

$t \cdot e^{-at}$

$1 - e^{-at}$

$F(s)$

$1/s$

K/s

$1/s^2$

$\frac{n!}{s^{n+1}}$

$\frac{1}{s+a}$

$\frac{1}{s-a}$

$\frac{n!}{(s+a)^{n+1}}$

$\frac{\omega}{s^2 + \omega^2}$

$\frac{s}{s^2 + \omega^2}$

$\frac{\omega}{(s+a)^2 + \omega^2}$

$\frac{s+a}{(s+a)^2 + \omega^2}$

$\frac{\omega}{s^2 - \omega^2}$

$\frac{s}{s^2 - \omega^2}$

$\frac{1}{(s+a)^2}$

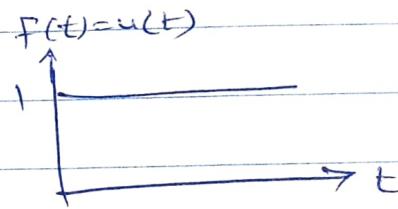
$\frac{a}{s(s+a)}$

L.T. of standard functions.

1. Step function.

Unit step fun is,

$$\begin{aligned} u(t) &= 1 \text{ for } t \geq 0 \\ &= 0 \text{ for } t < 0 \end{aligned}$$



$$\mathcal{L}\{u(t)\} = \frac{1}{s}$$

- If the step is of amplitude A,

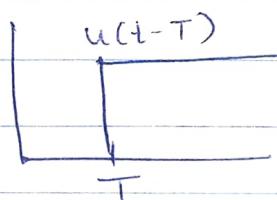
$$\mathcal{L}\{A u(t)\} = \frac{A}{s}$$

- If the unit step is delayed by T instant

$$f(t) = u(t-T)$$

using shifting theorem,

$$\mathcal{L}\{f(t-T)\} = e^{-Ts} F(s)$$



$$\therefore \mathcal{L}\{u(t-T)\} = e^{-Ts} \cdot \frac{1}{s}$$

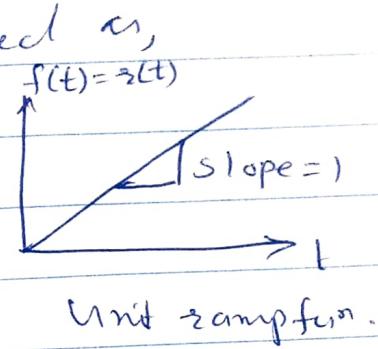
$$= \frac{e^{-Ts}}{s}$$

- The step fun is analogous to the switch which closes at $t=0$

2. Ramp function

The ramp function is defined as,

$$r(t) = t \quad \text{for } t \geq 0 \\ = 0 \quad \text{for } t < 0$$



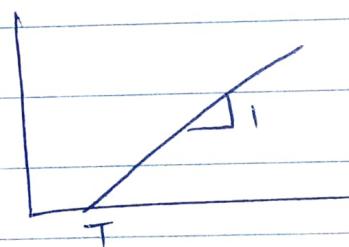
$$\mathcal{L}\{t u(t)\} = \frac{1}{s^2}$$

- For ramp having slope, A,

$$\mathcal{L}\{A t u(t)\} = \frac{A}{s^2}$$

- If the ramp is shifted by T,

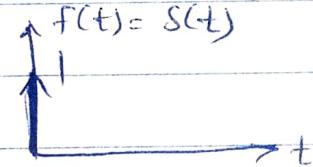
$$\mathcal{L}\{r(t-T)\} = \frac{e^{-Ts}}{s^2}$$



3. Impulse function.

Unit impulse function is $\delta(t)$ and defined as,

$$\delta(t) = 0 \quad \text{for } t = 0 \\ = 0 \quad \text{for } t \neq 0$$

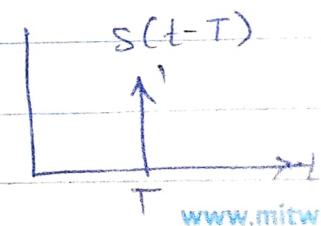


$$\mathcal{L}\{\delta(t)\} = 1$$

If there is delayed impulse, then,

function is $\delta(t-T)$

$$\therefore \mathcal{L}\{\delta(t-T)\} = e^{-Ts}$$



Convolution theorem

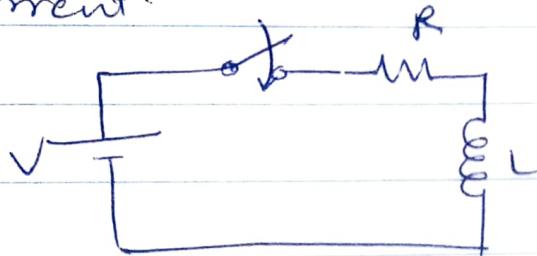
$$\mathcal{L}\{f_1(t) * f_2(t)\} = F_1(s) \cdot F_2(s)$$

$f_1(t) * f_2(t)$ indicates convolution of
 $F_1(s) & F_2(s).$

Inverse Laplace transform.

by using partial fraction method.

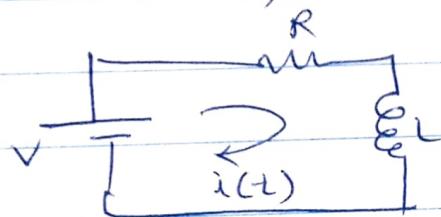
- Ques
- In the ckt. shown, the switch is closed at $t=0$. Find expression for the resulting current.



Before closing switch,
there is no current.

$$\therefore i(0^-) = 0 = i_L(0^-)$$

at $t > 0$, the new is,



Applying KVL,

$$-i(t)R - L \frac{di(t)}{dt} + V = 0$$

$$\therefore V = i(t)R + L \frac{di(t)}{dt} \quad \text{--- } V \text{ is const.}$$

Taking L.T. of above eqn,

$$I(s) \cdot R + L [s \cdot I(s) - i(0^-)] = \frac{V}{s}$$

$$I(s) [R + sL] = \frac{V}{s} \quad \text{as } i(0^-) = 0$$

$$\therefore I(s) = \frac{V}{s(sL + R)} = \frac{V/L}{s(s + R/L)}$$

using partial fraction,

$$I(s) = \frac{A}{s} + \frac{B}{s+R/L}$$

where, ; after solving

$$I(s) = A(s+R/L) + B/s$$

at $s=0$,

$$\frac{V/L}{R/L} = A = V/R$$

at $s=-R/L$

$$B = I(s) \left(s + \frac{R}{L} \right) \quad \text{at } s = -R/L.$$

$$= \frac{V/L}{-R/L} = -V/R$$

$$\therefore I(s) = \frac{V/R}{s} - \frac{V/R}{s+R/L}$$

Taking inverse L-T,

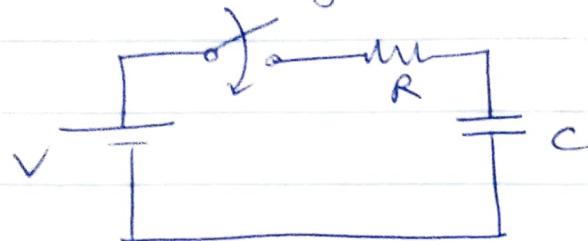
$$i(t) = L^{-1}[I(s)]$$

$$= L^{-1} \left[\frac{V/R}{s} - \frac{V/R}{s+R/L} \right]$$

$$= \frac{V}{R} - \frac{V}{R} \cdot e^{-\frac{R}{L}t}$$

$$= \frac{V}{R} \left(1 - e^{-\frac{R}{L}t} \right)$$

2. In the R-C ckt shown below, the switch is closed at $t=0$. Obtain expression for current using L.T.



$$V_C(0^-) = 0V$$

for $t \geq 0$, KVL eqn is,



$$-i(t)R - \frac{1}{C} \int_{-\infty}^t i(u) du + V = 0$$

$$\therefore i(t)R + \frac{1}{C} \int_0^t i(u) du = V \quad \text{as } \int_{-\infty}^0 i(u) du = 0 \\ \Rightarrow V_C(t) = \frac{1}{C} \int_0^t i(u) du = \frac{1}{C} \int_0^t R \frac{V}{R+1/C} du = \frac{1}{C} \cdot \frac{1}{R+1/C} \cdot V t = \frac{Vt}{R+1/C}$$

Taking L.T. on both sides.

$$I(s)R + \frac{I(s)}{sC} + \frac{V_C(0^-)}{s} = \frac{V}{s}$$

$$\therefore I(s) \left[R + \frac{1}{sC} \right] = \frac{V}{s}$$

$$\therefore I(s) = \frac{\frac{V}{s} \cdot sC}{s[1 + sRC]} = \frac{VC}{1 + sRC} = \frac{VC}{RC[s + \frac{1}{RC}]}$$

$$\therefore I(s) = \frac{V/R}{s + 1/RC}$$

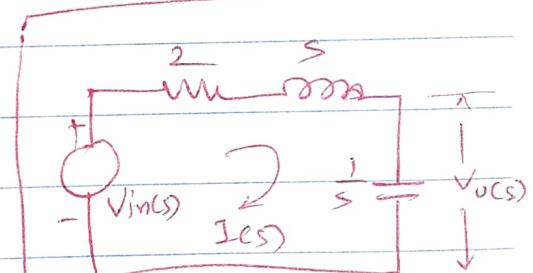
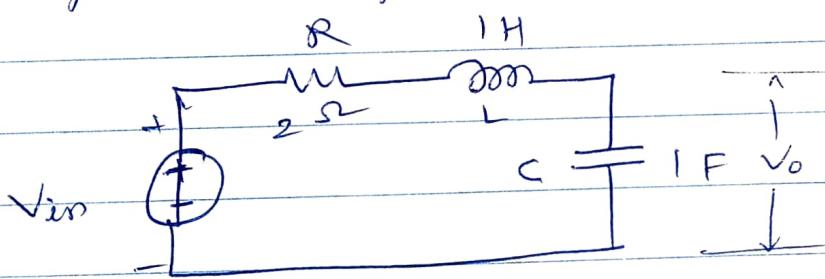
Taking inverse L-T.,

$$i(t) = L^{-1} [I(s)]$$

$$= L^{-1} \left[\frac{V/R}{s + \frac{1}{RC}} \right]$$

$$i(t) = \frac{V}{R} \cdot e^{-t/RC} \text{ A}$$

3. In series RLC ckt. shown below determine the response in time domain for unit impulse input.



Also Assuming initial conditions zero,

KVL eqn can be written as,

$$-2I(s) - sI(s) - \frac{1}{s}I(s) + Vin(s) = 0$$

$$\therefore I(s) \left(2 + s + \frac{1}{s} \right) = Vin(s) \quad \text{--- (1)}$$

while ~~Vo(s)~~ $= I(s) \cdot \frac{1}{s}$ \rightarrow Vltg. across capacitor

$$\therefore I(s) = s \cdot Vo(s)$$

Substituting this in eqn (1),

$$5. V_o(s) \frac{(s^2 + 2s + 1)}{s} = V_{in}(s)$$

$$\frac{V_o(s)}{V_{in}(s)} = \frac{1}{s^2 + 2s + 1} = \frac{1}{(s+1)^2}$$

Input is impulse function.

$V_{in}(t) = \delta(t)$ = unit impulse.

$$V_{in}(s) = L\{\delta(t)\} = 1$$

$$\frac{V_o(s)}{1} = \frac{1}{(s+1)^2}$$

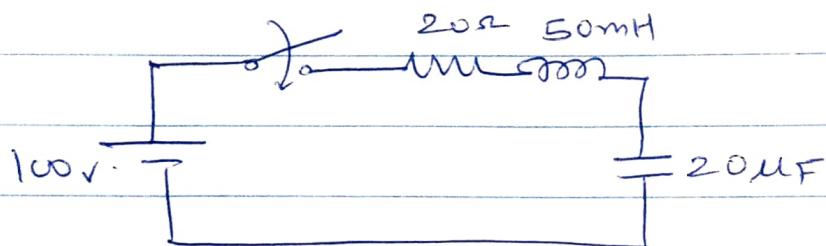
$$\therefore V_o(t) = L^{-1}[V_o(s)]$$

$$\therefore L^{-1}\left[\frac{1}{(s+1)^2}\right]$$

$$\therefore \boxed{V_o(t) = t e^{-t}} \quad \text{as } L[t e^{-at}] = \frac{1}{(s+a)^2}$$

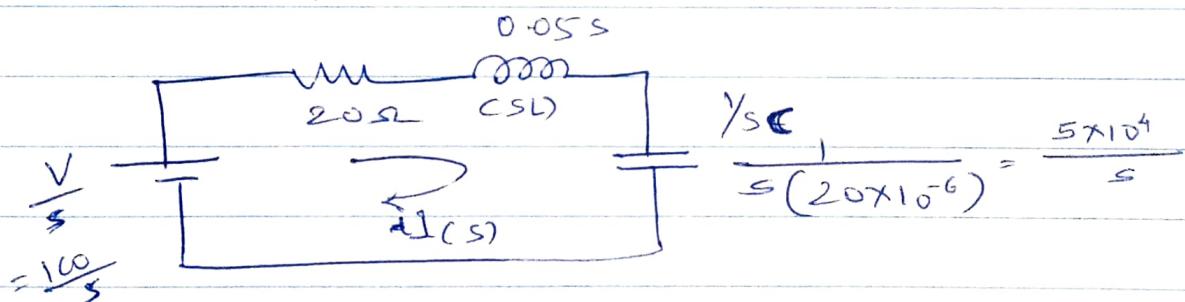
This is the reqd. impulse response of given RLC circuit.

3. The switch is closed at $t=0$. Assuming switch was open for long time before closing, determine current i for $t>0$. Also find voltage across inductor V_L for $t>0$.



Soln.

Network in ~~time~~ freq. domain can be drawn as,



By Ohm's law, $V = IR$

$$\frac{100}{s} = I(s) \left[20 + 0.05s + \frac{5 \times 10^4}{s} \right]$$

$$I(s) = \frac{\frac{100}{s}}{20 + 0.05s + \frac{5 \times 10^4}{s}}$$

$$= \frac{100}{0.05s^2 + 20s + (5 \times 10^4)}$$

$$= \frac{2000}{s^2 + 400s + 10^6}$$

$$I(s) = \frac{2000}{(s+2\omega)^2 + (979.79)^2}$$

$$\therefore e^{-at} \sin \omega t = \frac{\omega}{(s+a)^2 + \omega^2}$$

$$= \frac{2000}{979.79} \cdot \frac{979.79}{(s+200)^2 + (979.79)^2}$$

Taking inverse Laplace,

$$i(t) = 2.04 e^{-200t} \sin(979.79t)$$

Voltage across inductor,

$$V_L(s) = I(s) \cdot L s$$

$$= \frac{2000}{(s+2\omega)^2 + (979.79)^2} \times 0.05 s$$

$$= \frac{100s}{(s+200)^2 + (979.79)^2}$$

$$\therefore e^{-at} \cos \omega t = \frac{s+a}{(s+a)^2 + \omega^2}$$

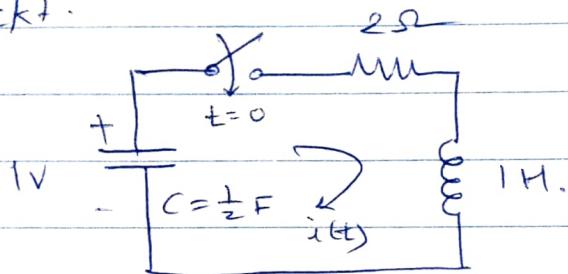
$$V_L(s) = \frac{100(s+200) - 20000}{(s+200)^2 + (979.79)^2}$$

$$= \frac{100(s+2\omega)}{(s+2\omega)^2 + (979.79)^2} - \frac{20000}{(s+2\omega)^2 + (979.79)^2}$$

$$= \frac{10\omega(s+2\omega)}{(s+2\omega)^2 + (979.79)^2} - \frac{20000}{979.79} \cdot \frac{979.79}{(s+200)^2 + (979.79)^2}$$

$$V_L(t) = 10\omega e^{-200t} \cos(979.79t) - 2041 e^{-200t} \sin(979.79t)$$

4 In the given nw capacitor is initially charged to 1V. Find current $i(t)$ and draw the s-domain representation of the ckt.



Solⁿ.

Writing KVL egn.

$$-L \frac{di(t)}{dt} + V_c(0^+) - \frac{1}{C} \int i(t) dt - R i(t) = 0$$

$$L \frac{di(t)}{dt} - V_c(0^+) + \frac{1}{C} \int i(t) dt + R i(t) = 0$$

Taking L.T. of above egn.

$$L [sI(s) - i(0^+)] - \frac{V_c(0^+)}{s} + \frac{1}{C} I(s) + RI(s) = 0$$

Put values, $L = 1 H$

$$R = 2 \Omega$$

$$V_c(0^+) = 1 V$$

$$C = 0.5 F$$

$i(0^+) = 0$... inductor behaves as O.C.

$$sI(s) - \frac{1}{s} + \frac{2}{s} I(s) + 2 I(s) = 0$$

$$\therefore I(s) \left[s + \frac{2}{s} + 2 \right] = \frac{1}{s}$$

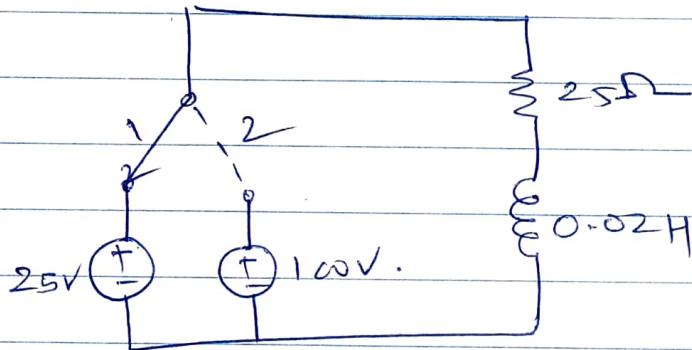
$$\therefore I(s) = \frac{1}{s^2 + 2s + 2}$$

$$= \frac{1}{(s+1)^2 + 1}$$

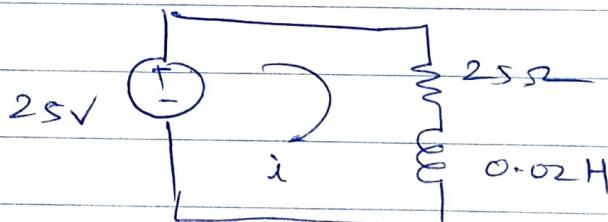
Taking inverse L-T., we get

$$i(t) = e^{-t} \sin t$$

5. In the R-L circuit shown below, the switch is in position 1 for long time enough to establish a steady state condn. At $t=0$, the switch is thrown to position 2. Find the expression for the resulting current.



~~Soln.~~: at position 1 of switch, the ckt. will be



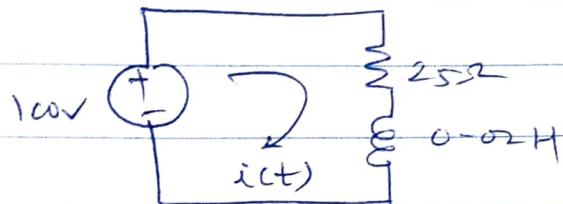
Under steady state condn, the inductor acts as s.c.

$$\therefore i = \frac{25}{25} = 1A$$

This is initial current through ckt.

$$\therefore i(0^-) = 1A$$

When the switch is thrown to position 2,
the ckt. will be



Applying KVL,

$$100 - 25i(t) - 0.02 \frac{di(t)}{dt} = 0$$

$$\therefore 0.02 \frac{di(t)}{dt} + 25 = 100$$

Taking L.T.,

$$0.02 s I(s) - 0.02 i(0^-) + 25 I(s) = \frac{100}{s}$$

$$\therefore 0.02 s I(s) - 0.02 (1) + 25 I(s) = \frac{100}{s}$$

$$\therefore I(s) [0.02s + 25] = \frac{100}{s} + 0.02$$

$$\therefore I(s) = \frac{100 + 0.02s}{s(25 + 0.02s)}$$

$$= \frac{0.02(s + 5000)}{0.02s(s + 1250)}$$

$$= \frac{s + 5000}{s(s + 1250)}$$

Let,

$$\frac{s+5000}{s(s+1250)} = \frac{A}{s} + \frac{B}{s+1250}$$

at $s=0$, $A = 4$

at $s=-1250$, $B = -3$

$$\therefore I(s) = \frac{4}{s} - \frac{3}{s+1250}$$

Taking inverse L-T.,

$$i(t) = L^{-1}[I(s)]$$

$$i(t) = 4 - 3 e^{-1250t} A$$