

Experiment No - 7

Aim \rightarrow Implement 2D Transformation : Translation, Scaling, Rotation, Reflection, shearing.

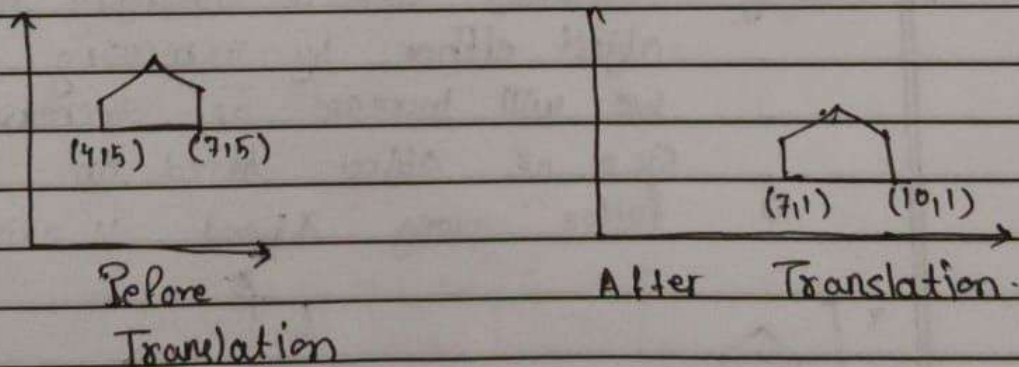
Resources Required \rightarrow Turbo C, Wordpad, ~~notepad~~ pointer

Theory : We have to perform 2D transformation on 2D object. Here we perform transformation on line segment.

The 2D Transformation are \rightarrow

- 1) Translation
- 2) Scaling
- 3) Rotation.

1) Translation \rightarrow Translation is defined as moving object from one position to another position along straight line path.



We can move the object based on translation distances along x and y axis. t_x denotes translation distance along x-axis and t_y denotes translation distance along y-axis.

Translation Distance \rightarrow It is nothing but how much unit we should translate the object from one point to another along x-y axis.

Consider (x, y) are old coordinates of point A. Then the new coordinates of that same point (x', y') can be obtained as follows \rightarrow

$$x' = x + tx$$

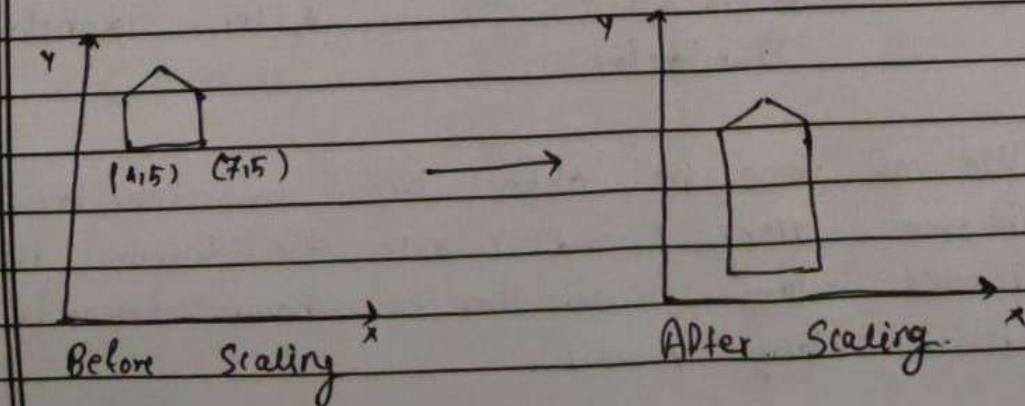
$$y' = y + ty$$

We denote translation transformation as P.

$$P' = P + T$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} tx \\ ty \end{bmatrix}$$

2] Scaling \rightarrow Scaling refer to changing the size of object either by increasing or decreasing we will increase or decrease the size of object based on Scaling factor along x and y axis.



If (x_1, y_1) are old coordinate of object, the new coordinate of object after applying scaling transformation as follows \rightarrow

$$\begin{aligned} X_2 &= X_1 * S_x \\ Y_2 &= Y_1 * S_y \end{aligned} \quad \left\{ \begin{array}{l} S_x \text{ and } S_y \text{ are scaling factors} \\ \text{along } x\text{-axis and } y\text{-axis.} \end{array} \right\}$$

$$\begin{bmatrix} X_2 \\ Y_2 \end{bmatrix} = \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix} \begin{bmatrix} X_1 \\ Y_1 \end{bmatrix}$$

3) ~~Rotation~~ \rightarrow A rotation is defined

3) Rotation \rightarrow It is defined as repositioning of all points of an object in a plane along a circular path plane centred at pivot point. We rotate an object by an angle theta (θ).

New Coordinate after rotation depend on both X and Y .

$$X_2 = X_1 \cos \theta - Y_1 \sin \theta$$

$$Y_2 = X_1 \sin \theta + Y_1 \cos \theta$$

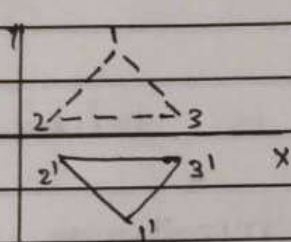
or Matrix form \rightarrow

$$\begin{bmatrix} X_2 \\ Y_2 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} X_1 \\ Y_1 \end{bmatrix}$$

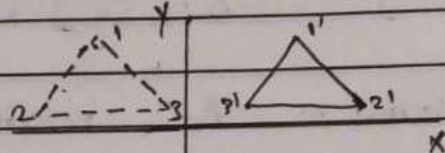
~~Conclusion~~ \rightarrow Implementation for 2D transformation is done for rotation, scaling and translation which helps us move, rotate and change shapes easily.

4) Reflection \rightarrow Reflection is the mirror image of original objects. In other words, we can say that it is a rotation operation with 180° . In reflection transformation, the size of the object does not change.

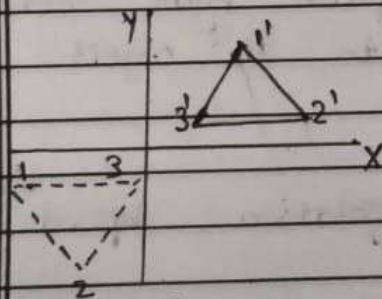
The following figures ~~will~~ show reflection with X and Y axes \rightarrow



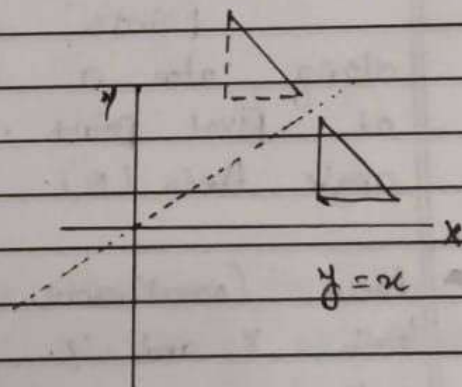
(a)



(b)



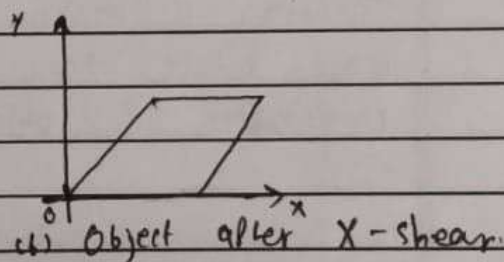
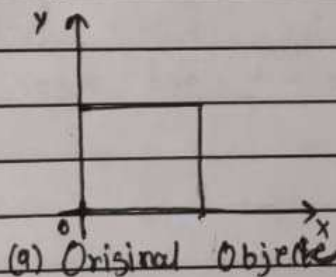
(c)



5) Shear \rightarrow A transformation that slants the shape of an object is called the shear transformation. There are two shear transformation X-Shear and Y shear.

i) Shear \rightarrow A transformation that slants the shape of an object is called the shear transformation. There are two shear transformations X-Shear and Y-Shear. One shifts X coordinates value and other shifts Y coordinate values. However, in both the cases only one coordinate change its coordinates other preserves its values. Shearing is also termed as Skewing.

ii) X-shear preserves the Y coordinate and changes are made to X-coordinates, which causes the vertical lines to tilt right or left as shown in figure

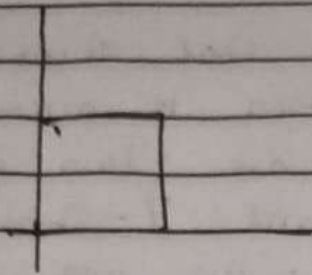


The transformation can be represented as \rightarrow

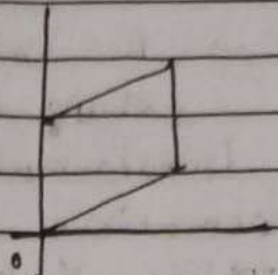
$$X' = X + Shx \cdot Y$$

$$Y' = Y$$

iii) Y-shear preserves the X coordinates and changes the Y coordinates which causes the horizontal lines to transform into lines which slopes up or down as shown in the following figure \rightarrow



a) Original Object



b) Object after Y shear

The Y-Shear can be represented as →

$$Y' = Y + Shy \cdot X$$

$$X' = X$$

Conclusion → Implementation for 2-D transformation is done for ~~total~~ translation, rotation, scaling, reflection and shearing which helps us move, rotate, change shape, reflect and shear the coordinates of object easily.