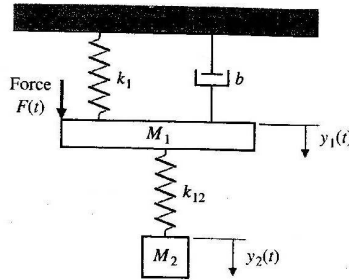


1 Obtain the applicable differential equation relating output ' $y_1$ ' and input ' $F(t)$ ', for the dynamic vibration absorber given below. (Hint: use  $d/dt \equiv D$  along with algebraic manipulations to find the equation) (2)



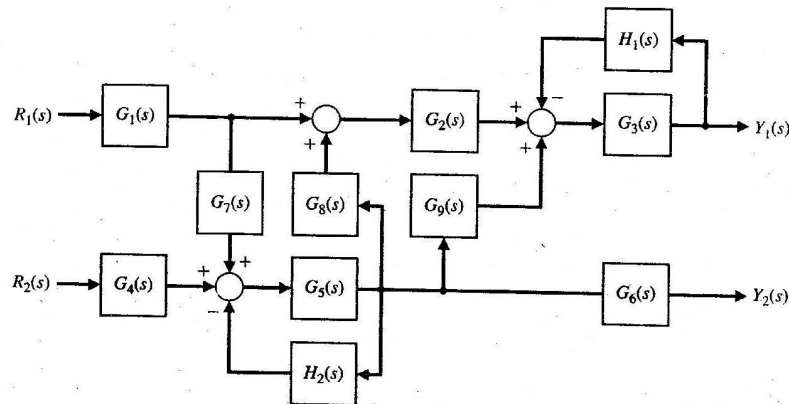
$$\text{Mass } M_1: M_1 \ddot{y}_1 + b \dot{y}_1 + k_1 y_1 + k_{12} (y_1 - y_2) = F; \quad \text{Mass } M_2: M_2 \ddot{y}_2 + k_{12} (y_2 - y_1) = 0$$

$$y_2 = -\left(\frac{k_{12}}{M_2 D^2 + k_{12}}\right) y_1; \quad (M_1 D^2 + bD + k_1 + k_{12}) y_1 + \left(\frac{k_{12}^2}{M_2 D^2 + k_{12}}\right) y_1 = F$$

$$\left[ (M_1 D^2 + bD + k_1 + k_{12}) \times (M_2 D^2 + k_{12}) + k_{12}^2 \right] y_1 = (M_2 D^2 + k_{12}) F$$

$$M_1 M_2 \ddot{\ddot{y}}_1 + M_2 b \ddot{\ddot{y}}_1 + (M_1 k_{12} + M_2 \{k_1 + k_{12}\}) \ddot{y}_1 + b k_{12} \dot{y}_1 + (k_1 k_{12} + 2k_{12}^2) y_1 = M_2 \ddot{F} + k_{12} F$$

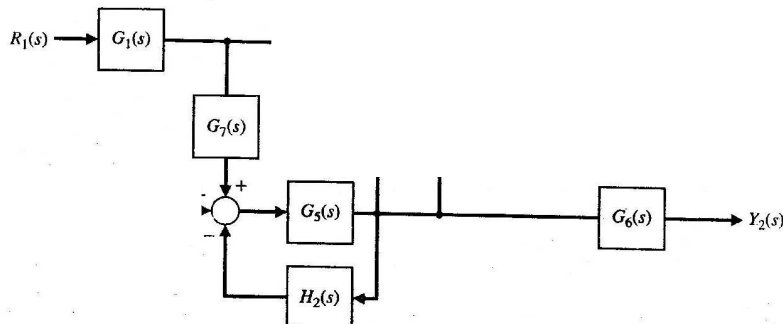
2. Reduce following block diagram and obtain  $Y_2/R_1$ . (Hint: Assume  $R_2 = 0$ ). (2)



Step-1:  $R_2 = 0$ , remove  $G_4$  branch from the summing junction.

Step-2: Split the summing junction of step-1 & reduce the block formed by  $G_5$  &  $H_2$ .

Step-3: Reduce the block containing  $G_1$ ,  $G_7$ ,  $G_5/(1+G_5H_2)$  &  $G_6$ .



$$\frac{Y_2}{R_1} = \frac{G_1 G_5 G_6 G_7}{1 + G_5 H_2}$$

3. Obtain  $y(t)$  of the following 2<sup>nd</sup> order system, using convolution integral, for given initial conditions. (2)

$$\ddot{y} + 4y = 3u(t), \quad u(t) = 1(t); \quad y(0) = 0; \quad \dot{y}(0) = 1$$

Hint:  $y(t) = y(0) + \int_0^t g(t-\tau)u(\tau)d\tau$ ;  $g(t) = \frac{1}{m\omega_d} e^{-\sigma t} \sin \omega_d t \rightarrow$  Unit Impulse Response;  $1(t) \rightarrow$  Unit Step

$2\sigma = \frac{c}{m}$ ;  $\omega_n^2 = \frac{k}{m}$ ; Interpret  $m, c, k, \omega_d$  as per their standard meaning for a 2<sup>nd</sup> order LTI system.

$$\ddot{y} + 4y = 3u(t), \quad m = 1; \quad c = 0; \quad k = 4 \rightarrow \sigma = 0; \quad \omega_d = \omega_n = 2; \quad g(t) = \frac{1}{m\omega_d} e^{-\sigma t} \sin \omega_d t = \frac{1}{2} \sin 2t$$

$$y_h(t) = g(t) = \frac{1}{2} \sin 2t \quad \{g(t) = g(0+) \text{ as unit impulse same as unit velocity as initial condition}\}$$

$$y(t) = y_h(t) + \frac{1}{2} \int_0^t \sin 2(t-\tau) \times 3d\tau; \quad y(t) = \frac{1}{2} \sin 2t + \frac{3}{2} \int_0^t (\sin 2t \cos 2\tau - \cos 2t \sin 2\tau) d\tau$$

$$y(t) = \frac{1}{2} \sin 2t + \frac{3}{2} \sin 2t \int_0^t \cos 2\tau d\tau - \frac{3}{2} \cos 2t \int_0^t \sin 2\tau d\tau$$

$$y(t) = \frac{1}{2} \sin 2t + \frac{3}{2} \sin 2t \times \left[ \frac{1}{2} \sin 2\tau \right]_0^t - \frac{3}{2} \cos 2t \times \left[ -\frac{1}{2} \cos 2\tau \right]_0^t$$

$$y(t) = \frac{1}{2} \sin 2t + \frac{3}{4} \sin^2 2t + \frac{3}{4} \cos 2t \times (\cos 2t - 1) = \frac{3}{4} + \frac{1}{2} \sin 2t - \frac{3}{4} \cos 2t$$

4. Consider the system transfer function given below. (3)

$$G(s) = \frac{24}{s^3 + 9s^2 + 26s + 24}$$

Obtain the unit step response  $y(t)$  using the partial fractions decomposition approach. (Hint: Use the following rules as applicable).

$$A_i = \left[ (s - p_i) Y(s) \right]_{s=p_i}; \quad L^{-1} \left[ \frac{A_i}{s + p_i} \right] = A_i e^{-p_i t}; \quad \text{One of the roots is -3.}$$

$$Y(s) = U(s)G(s) = \frac{24}{s(s^3 + 9s^2 + 26s + 24)}$$

$$Y(s) = \frac{24}{s(s+3)(s^2 + as + b)} = \frac{24}{s(s+3)(s^2 + 6s + 8)} = \frac{24}{s(s+3)(s+2)(s+4)}$$

$$Y(s) = \frac{A_1}{s} + \frac{A_2}{s+2} + \frac{A_3}{s+3} + \frac{A_4}{s+4}; \quad A_1 = 1; \quad A_2 = -6; \quad A_3 = 8; \quad A_4 = -3$$

$$y(t) = L^{-1}(Y(s)) = 1 - 6e^{-2t} + 8e^{-3t} - 3e^{-4t}$$

5. Obtain the expressions for magnitude and phase (in degrees) of the following system, subjected to the sinusoidal input and give their values for  $\omega = 1.99, 2.01$ . (1)

$$G(s) = \frac{4}{s^2 + 4}; \quad u(t) = 2 \sin \omega t; \quad s = j\omega$$

$$G(s) = \frac{4}{s^2 + 4}; \quad G(j\omega) = \frac{4}{(j\omega)^2 + 4} = \frac{4}{4 - \omega^2}$$

$$|G(j\omega)| = \left| \frac{4}{4 - \omega^2} \right| = \frac{4}{|4 - \omega^2|}; \quad |G(j1.99)| = 100.25; \quad |G(j2.01)| = 99.75$$

$$\angle G(j\omega) = \angle \frac{4}{4 - \omega^2} = \tan^{-1} \frac{0}{4} \times (4 - \omega^2); \quad \angle G(j1.99) = \tan^{-1} \frac{0}{4} \times 0.04 = 0^\circ$$

$$\angle G(j2.01) = \tan^{-1} \frac{0}{4} \times (-0.04) = 180^\circ$$

PAPER ENDS