

Frequency Response Representation

- Graphical Representation Strategy
- <u>Bode'Plots</u>
- <u>Nyquist Plots</u>



Graphical Representation Tools

Among the many possible ways of graphically representing the frequency response, Bode' and Nyquist plots are the most commonly employed forms.

An important added **advantage** of these **representations** is the possibility of visualizing **the closed loop** behaviour and applicable **control actions**, in a simple & intuitive manner.

Therefore, the **above plots** are also useful **tools** for the **design** of closed loop **control systems**.



Representation with Bode' Plots



Bode' Diagrams

Bode' diagrams show variation of $|G(j\omega)|$ and $\angle G(j\omega)$ on **two separate plots** as ω varies from 0 to ∞ . In these plots, while **dB** is used for **magnitude**, **degree** is used for **phase**.

Both $|G(j\omega)|$ and $\angle G(j\omega)$ plots use a log scale (either octave or decade) for ω , which permits a large frequency scale to be shown together.



Bode' Plot Creation Process

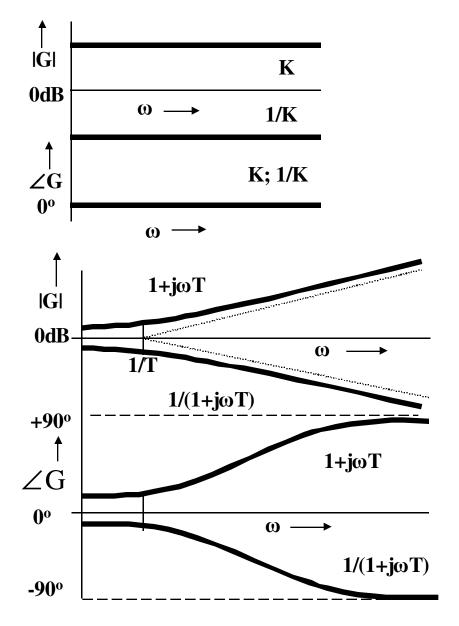
We find that dB scale $(20log_{10})$ converts multiplication/division into addition / subtraction of Log magnitudes of the numerator and denominator factors of G(s).

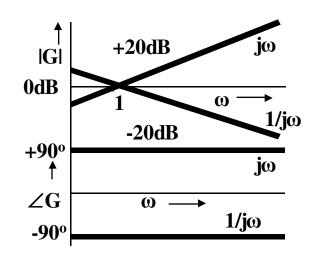
Similarly, **total phase** of the frequency response can also be expressed as **an addition / subtraction** of phase angles of the numerator/ denominator **factors**.

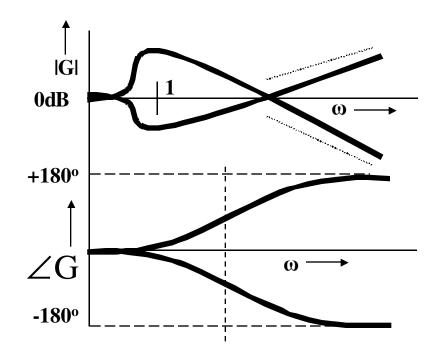
Thus, it is **possible to create** a complex bode' plot through a **building block approach** by synthesizing it using **simple factors**, e.g. pure gain, 1st order and 2nd order.



Bode' Plots of Basic Factors









Basic Features of Plots

We see from the **plots** that all show a specific **pattern** for the **two limiting** frequency points of '0' and ' ∞ '.

This is typically in the form of **low** and **high frequency** asymptotes, which provide DC gain (G(0)) and relative degree (i.e. n - m) of G(s).

We also find that **changes** in the **asymptote angles** occur around **frequencies** that correspond to **poles and zeros**.

Therefore, we can **relate these** features to the plant **transfer function**, G(s).



Transfer Function - Bode' Plot

Poles and zeros are seen as points where slope of magnitude plot changes & are termed corner frequencies.

G(0) & 'k' are seen as intercept which is 20 $\log_{10}K$ & slope, which is -20k dB/decade for ω = 0. (G(s) \approx K/s^k).

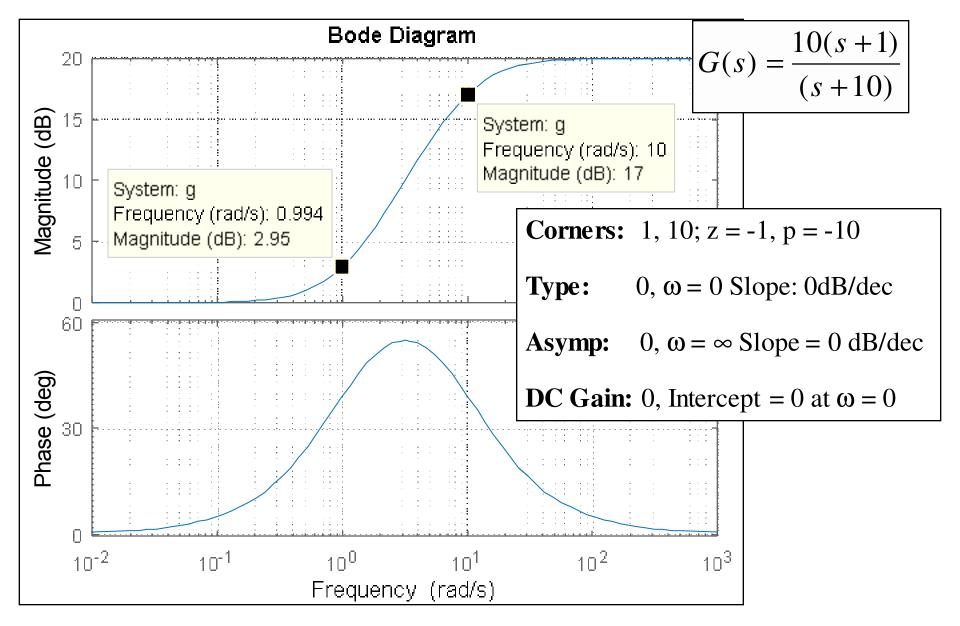
(n-m) is seen as **slope** of curve for $\omega \to \infty$, which is -20(n-m) **dB/decade**. (G(s) $\approx K/s^{(n-m)}$).

Thus it is seen that we can **reconstruct** the complete **transfer function** from its **magnitude** response.

The above logic is used to arrive at phase plots.



Bode' Diagram Example





Summary

Bode' representation, makes the task of creating and interpreting the frequency response simpler.



Bode' Drawback & Nyquist Concept

Bode' plot consists of two graphics, which need to be interpreted together.

However, in **some cases**, there is a need to see **complete frequency response** in a single graphic and **Nyquist plot** addresses this need.

It is a plot of $Imag[G(j\omega)]$ Vs $Re[G(j\omega)]$ in 2-D complex plane as ω varies from $-\infty$ to $+\infty$.

Polar plot is the plot from 0 to ∞ and hence is a subset of the Nyquist plot.



Representation with Nyquist Plots



Nyquist Plot Characteristics

In Nyquist plot, $G(j\omega)$ is treated as a **complex** quantity, and represented **as such** in what is called, ' $G(j\omega)$ – **plane**'.

Here, $G(j\omega)$ is a **vector** from **origin** to a point in the **above plane**, whose **length** is $|G(j\omega)|$ and **angle** with real axis is $\angle G(j\omega)$.

The plot is **locus** of all **terminal points** of these vectors for $\omega = 0$ to ∞ .

In this plot, frequency is a graduation on the locus.



Nyquist Plot Features

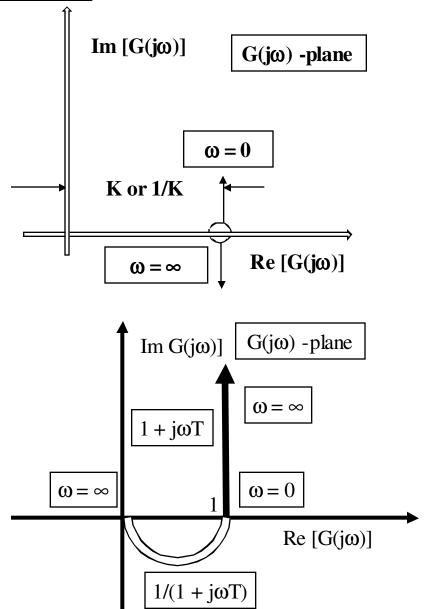
Nyquist plots combine magnitude & phase into one and are therefore, compact.

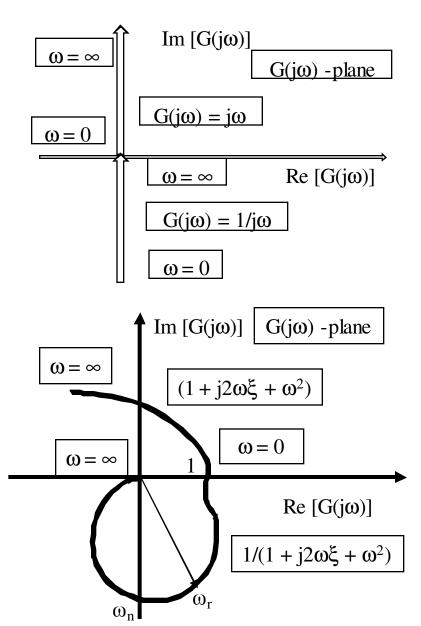
However, **Nyquist plots cannot** clearly indicate **contributions of various factors**, like Bode' plots do.

Even then, factors like, $K^{\pm 1}$, $(j\omega)^{\pm 1}$, $(1+j\omega T)^{\pm 1}$, $(1+2\xi\omega j+(j\omega)^2)^{\pm 1}$ have **certain distinguishing features**, as shown next.



Polar Plots of Basic Factors







Transfer Function - Nyquist Plot

Poles and zeros are not seen in Nyquist plot and for that reason, no corner frequencies are possible.

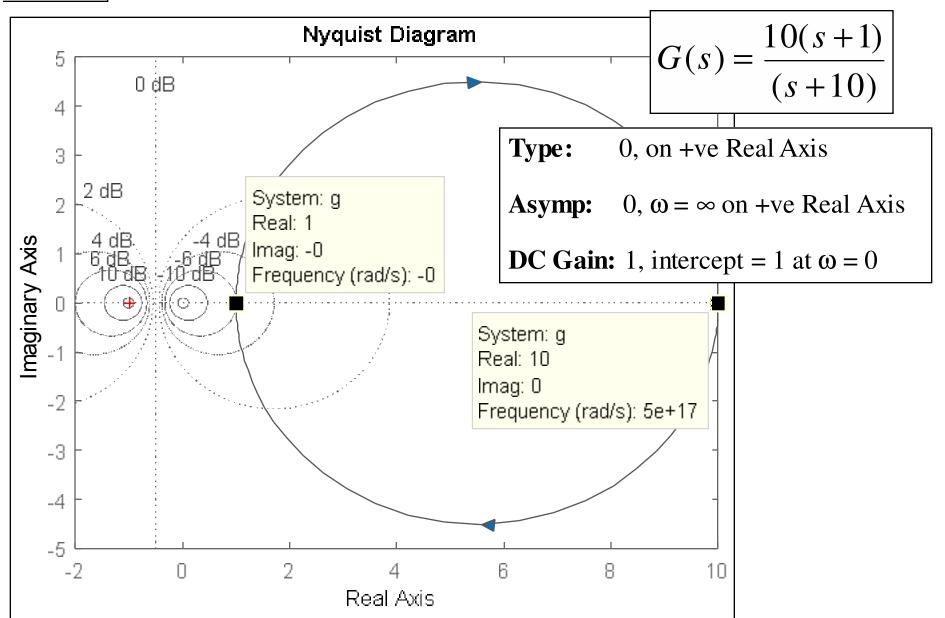
System type is seen in Nyquist plot in terms of the axis from which it start at $\omega = 0$. E.g., type '0' systems start from +ve real axis, type '1' systems start from -ve imaginary axis etc.

(n-m) is seen in terms of the axis close to $\omega = \infty$. E.g. closeness to +ve imaginary axis indicates n-m = 3.

DC gain is seen as **intercept** of plot on **real axis** at ω =0.



Nyquist Plot Example





Summary

Nyquist plots are more **elegant**, but are not very easy to interpret.

However, both **Bode' & Nyquist** representations can be used for interpreting the **transfer function features** through attributes **captured** in these plots.