## Minimum Phase Root Locus

Generate **straight line** root locus of following **plant** and determine the **approximate** value of 'K' for which the **closed loop** system has all **poles** to the left of **-0.5**.

$$G(s) = \frac{K}{(s+1)^4}$$

Poles: -1, -1, -1, -1; n = 4; m = 0; n - m = 4

Real axis: No root on real axis as (n+m) = 0 on both sides.

Asymptotes: 
$$\phi = \frac{\pm (2k+1)180}{n-m} = \pm 45; \pm 135; \quad \sigma = -1$$

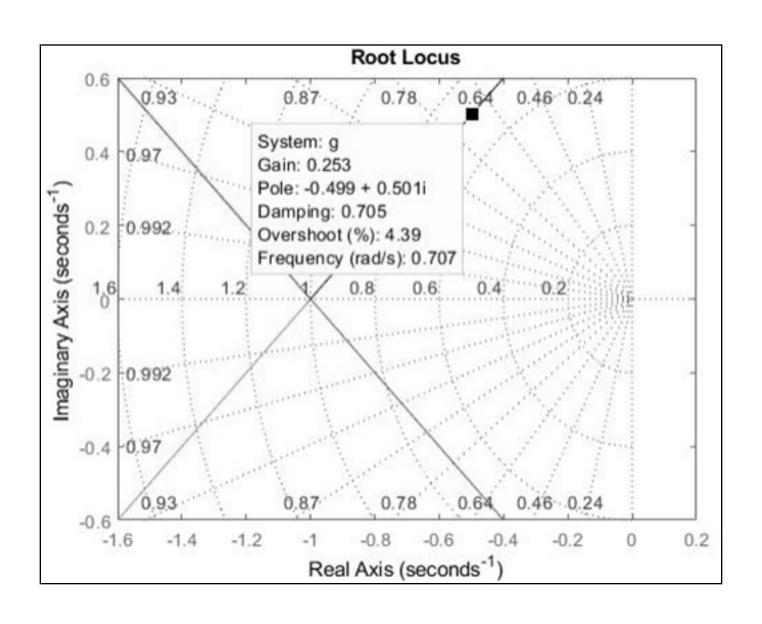
Break-away: 
$$K(s) = -(s+1)^4 \to \frac{dK}{ds} = -4(s+1)^3 = 0 \to s = -1$$

Imaginary axis: 
$$s^4 + 4s^3 + 6s^2 + 4s + (K+1) = 0 \rightarrow K = 4$$
;  $s = \pm j1$ 

Dominant Poles:  $s = -0.5 \pm j0.5$ ;  $K = -(0.5 + j0.5)^4 = 0.25$ 



## Verification with MATLAB



## Non-minimum Phase Root Locus

Generate and **sketch** the asymptotic root locus **plot** for the following **system** and compare it with the case when there is **no time delay**. (Use 1<sup>st</sup> order Pade' approximation).

$$G(s) = \frac{4e^{-2s}}{(s+1)^3}$$

$$G(s) = \frac{4(1-s)}{(s+1)^4}$$
; Poles: -1,-1,-1, Zero: 1;  $n-m=3$ 

Real axis: RL between +1 &  $\infty$ ; Asymptotes:  $\phi = \pm 120, +360$ 

$$\sigma = -2/3$$
; BA:  $s = -1$ ; +5/3; Imag axis:  $K = 0.475$ ;  $\omega = 0.73$ 

$$G(s) = \frac{4}{(s+1)^3}$$
; Poles: -1,-1,-1;  $n-m=3$ 

Real axis: No RL; Asymptotes:  $\phi = \pm 60,180$ ;  $\sigma = -1$ 

BA: 
$$s = -1$$
; Imag axis:  $K = 2$ ;  $s = -\sqrt{3}$ 



## Verification with MATLAB

