



Block Diagram Representation

- *I/O Form of Dynamical Systems*
- *Block Diagram Representation*
- *Algebraic Manipulations of Block Diagrams*



I/O Form and Block Diagrams



Input – Output Representations

Mathematical models are **commonly written** in forms that describe **variation** of output with respect to input, as below.

$$y(t) = gu(t); \quad g = \frac{y(t)}{u(t)}$$

Here, **u(t)** is input, **y(t)** is output and ‘**g**’ is the **relation** between ‘y’ and ‘u’ that ‘**transforms**’ ‘u’ into ‘y’. E.g. spring-mass-damper model **can be rewritten**, as follows.

$$m \frac{d^2 y}{dt^2} + b \frac{dy}{dt} + ky = b \frac{du}{dt} + ku$$
$$y(t) = gu(t), \quad g = \frac{b \left(\frac{d}{dt} \right) + k}{m \left(\frac{d^2}{dt^2} \right) + b \left(\frac{d}{dt} \right) + k}$$



Block Diagram as System Form

Block diagrams are an extension of the **I/O form** and are pictorial **representation** of the model of the **system**.

Typical **block** is the basic unit **represented** as follows.

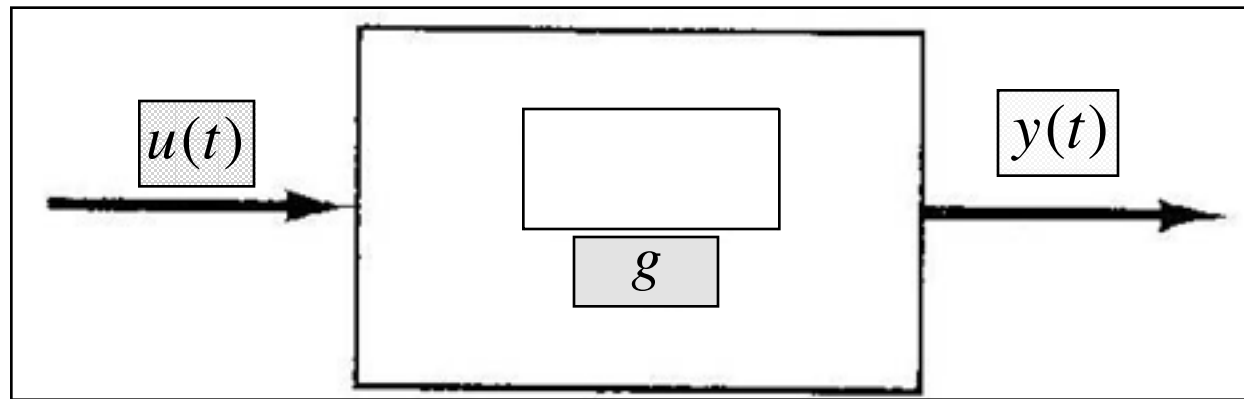
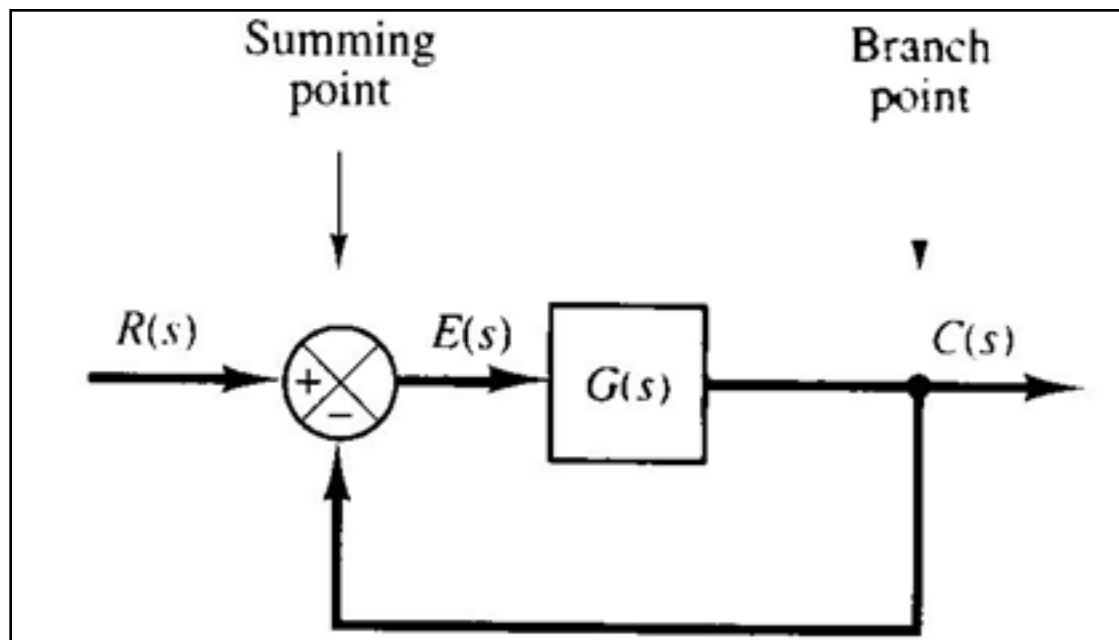


Diagram contains algebraic **operations** e.g. multiplication / division, addition/ subtraction, **consistent** with the model **description**.



Block Diagram as Dynamical Tool

Block diagrams are also tools for **analysis and design** as these can be **manipulated** like algebraic entities, using the applicable **relations**. A typical **diagram** is shown below.



Summing point defines the algebraic **equation** in terms of inputs & output.

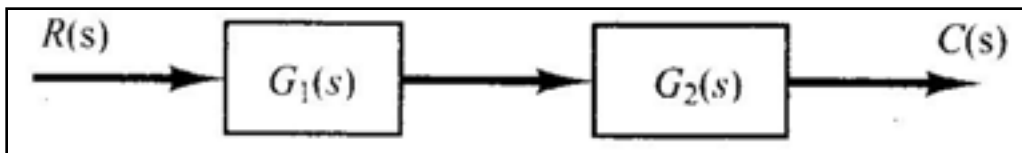
Branch point provides **signal to other** blocks or summing points.

Block represents the **process**.

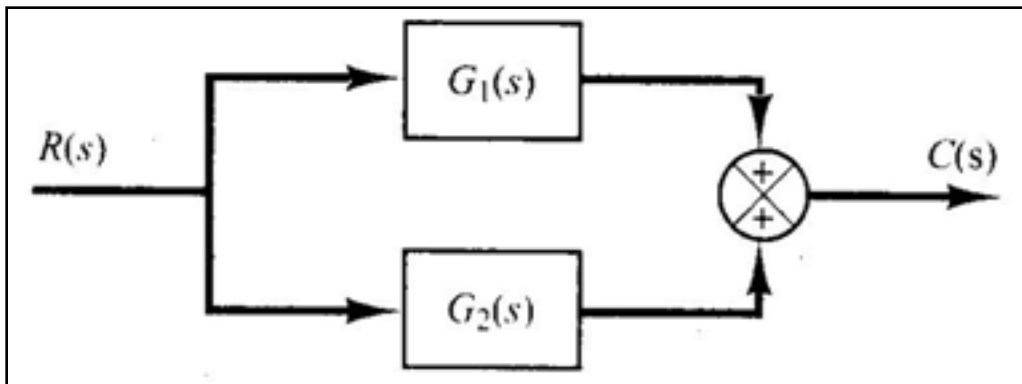


Block Diagram Algebra Concept

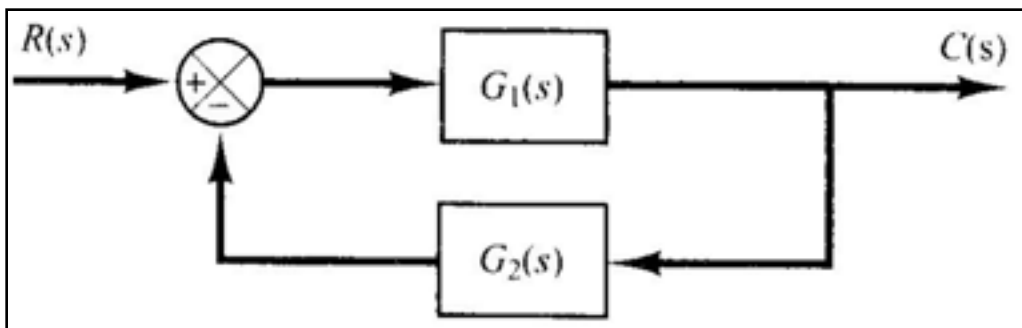
Block diagram algebra is a **discipline** that helps us to **manipulate** diagrams, as algebraic entities.



$$\frac{C(s)}{R(s)} = G_1(s) \cdot G_2(s)$$



$$\frac{C(s)}{R(s)} = G_1(s) + G_2(s)$$

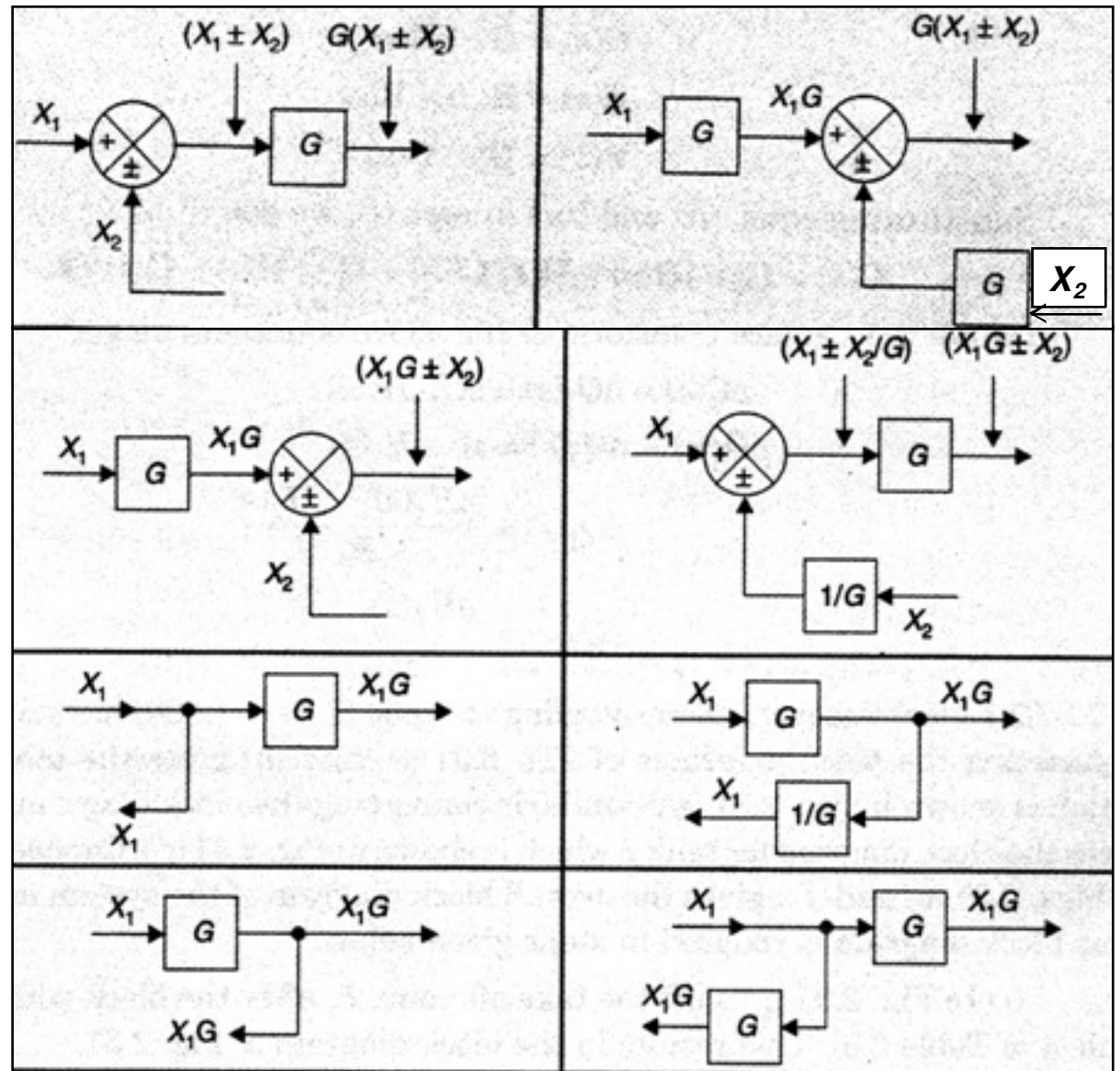


$$\frac{C(s)}{R(s)} = \frac{G_1(s)}{1 + G_1(s) \cdot G_2(s)}$$



Rules for Block Diagram Algebra

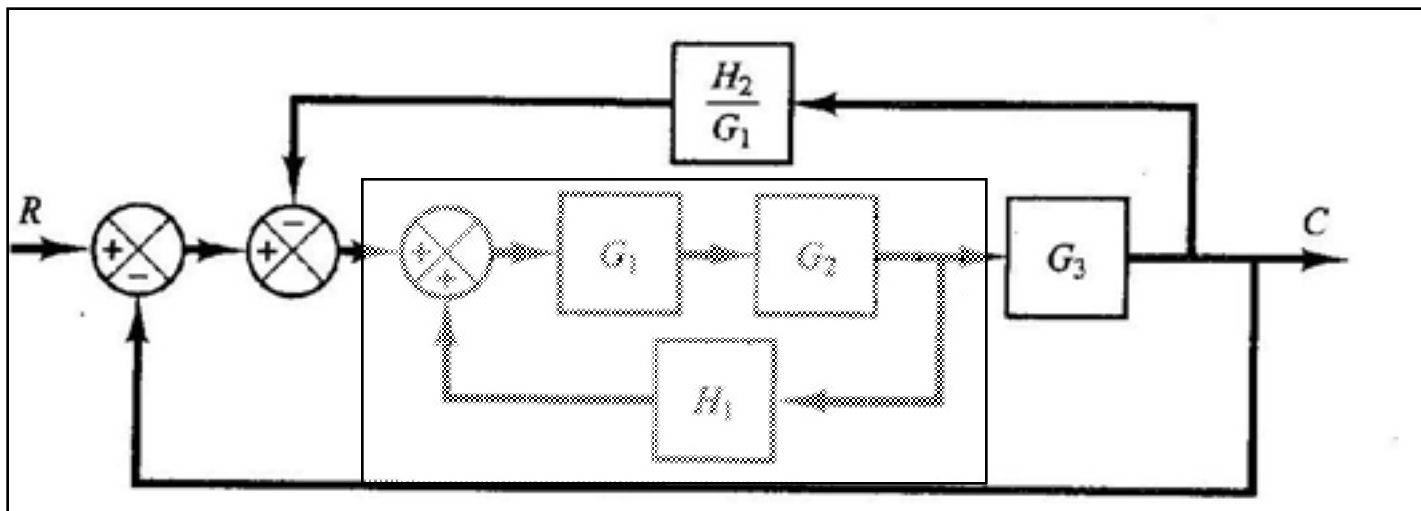
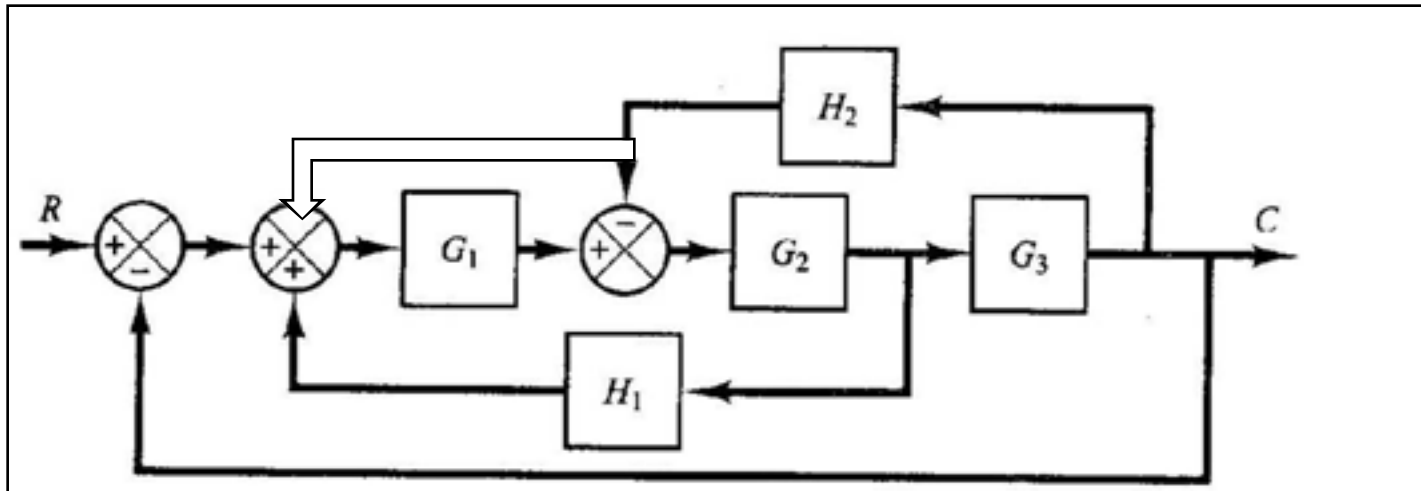
Given along side are **some** of the **rules** that we can use to **manipulate** / simplify system description.





Block Diagram Algebra Example

Consider the following **block diagram**.





Summary

Block diagrams are the most common and **convenient representations** for dynamical systems, which can be manipulated like **algebraic entities**.