

# Microprocessors

## Organization & ISA

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*EE-309: Microprocessors*



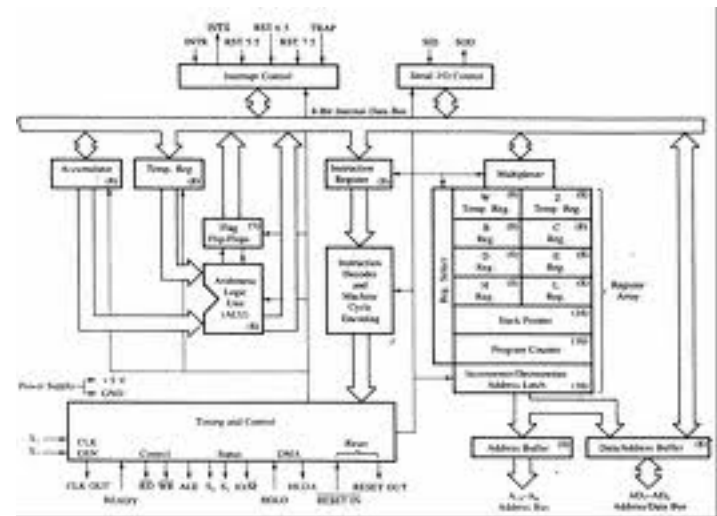
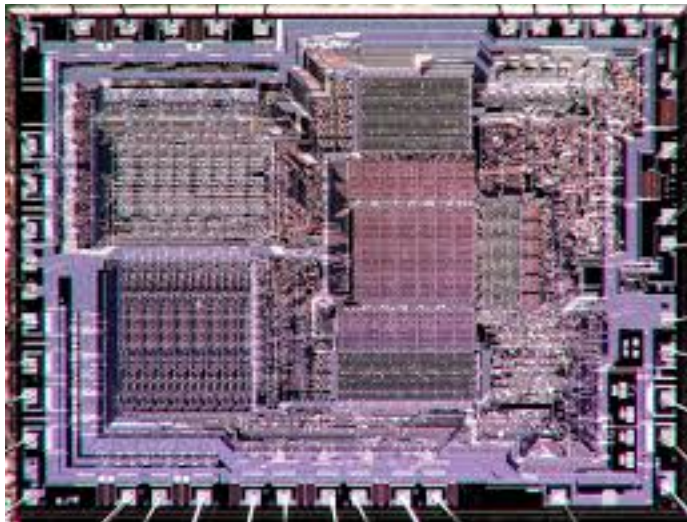
Lecture 3 (25 July 2015)

**CADSL**

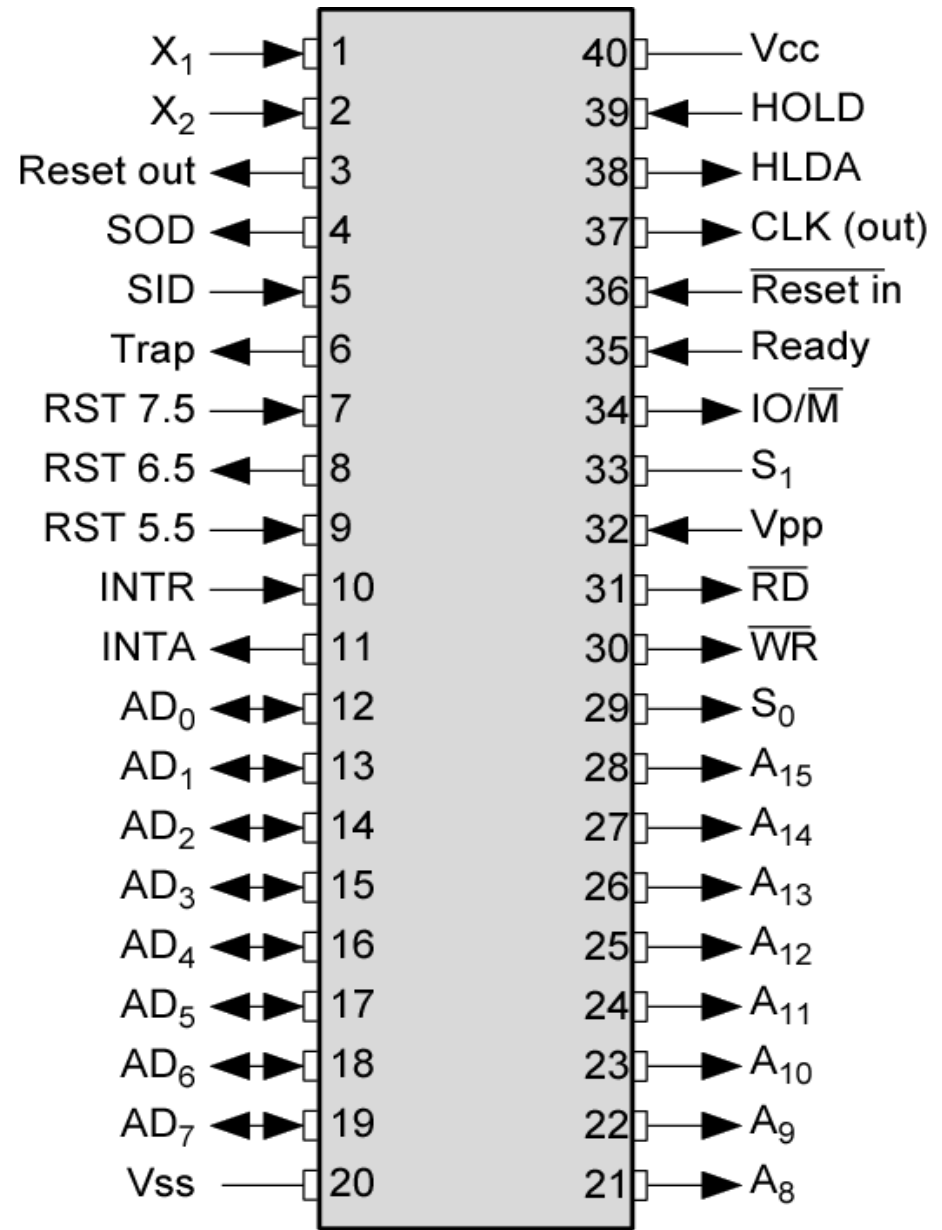
# MICROPROCESSOR

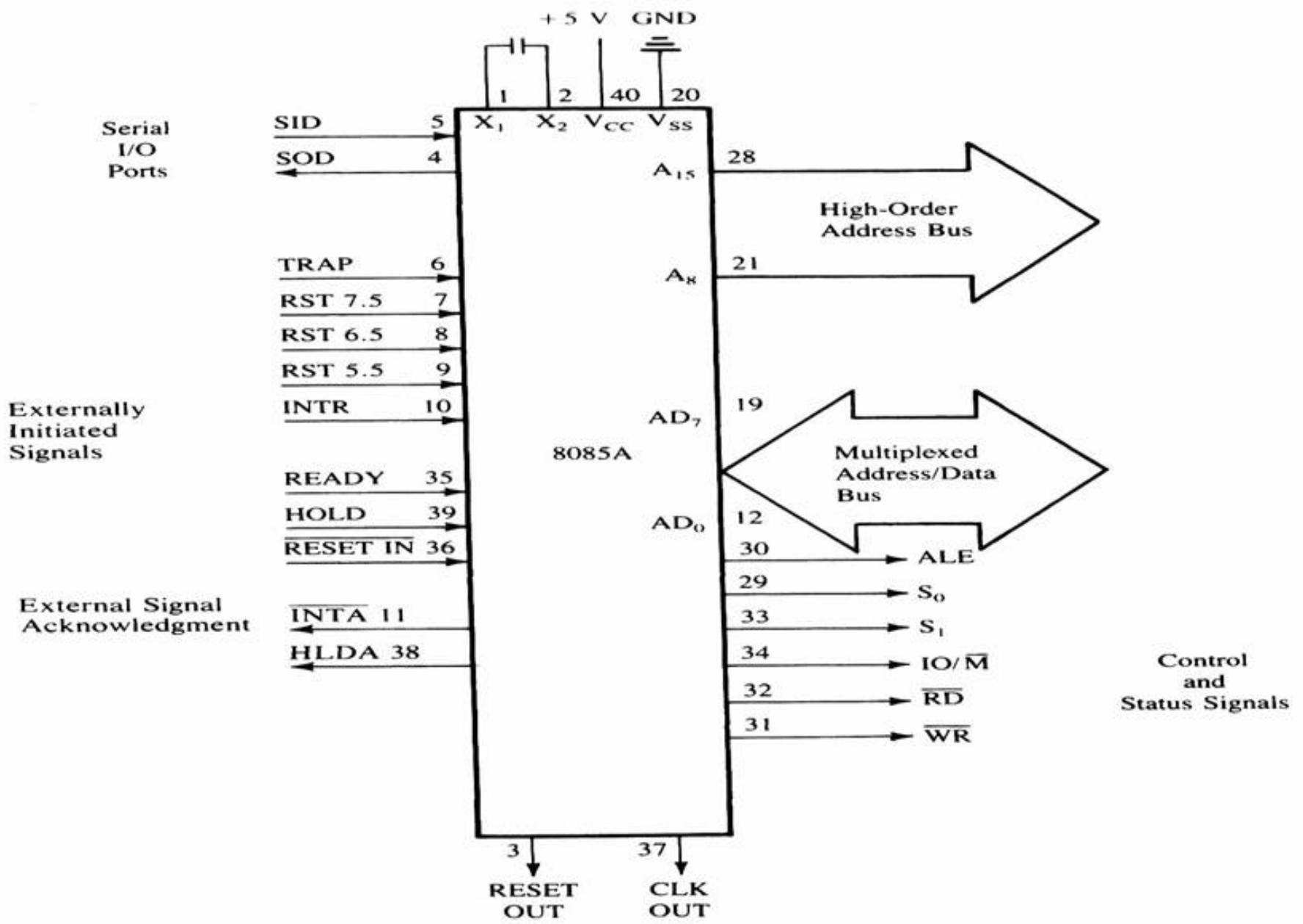
# 8085





# Intel 8085 Pin Configuration

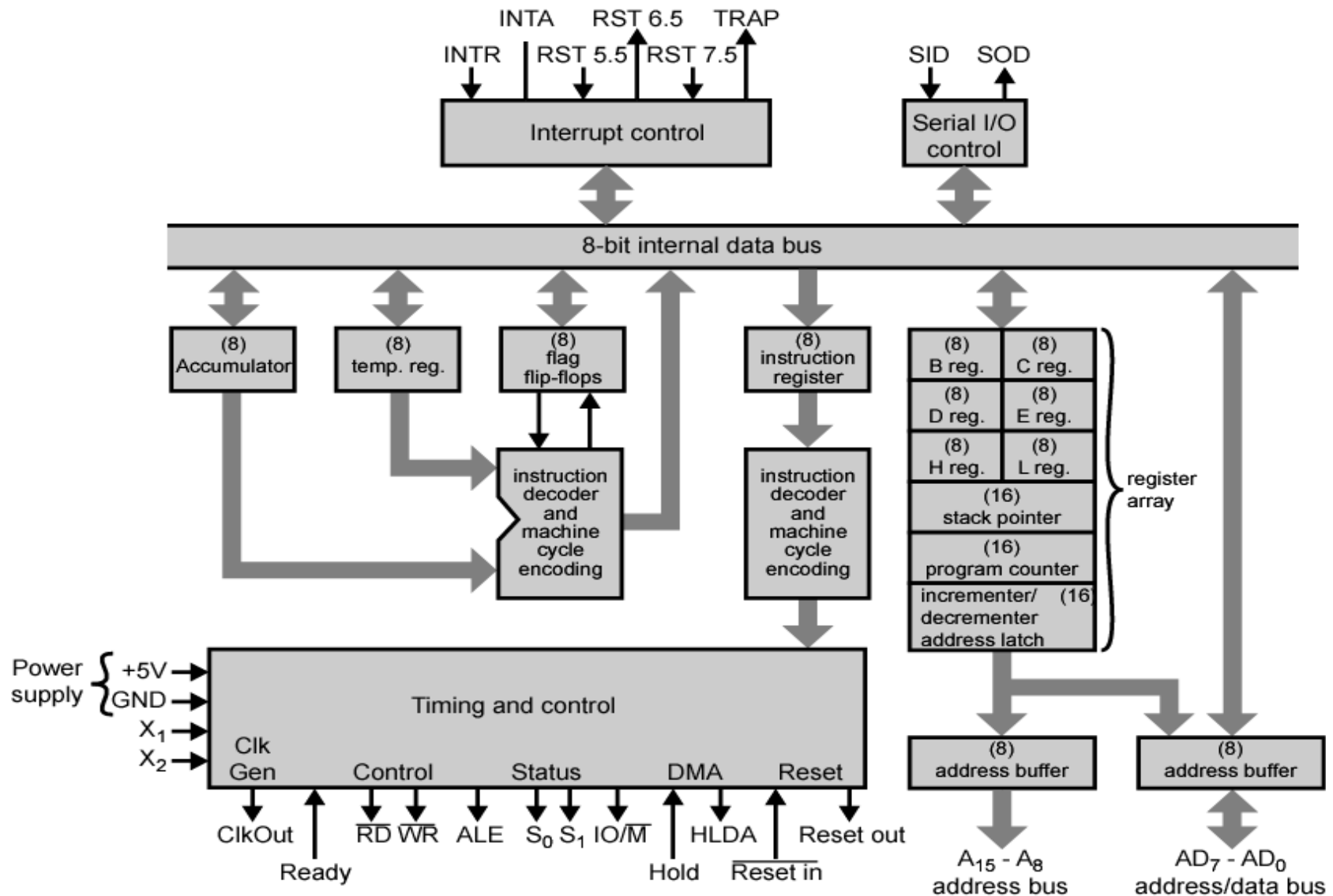




## Signals and I/O Pins



# Intel 8085 CPU Block Diagram



# The 8085 and Its Buses

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- 8-bit general purpose microprocessor that can address 64K Byte of memory.
- 40 pins and uses +5V for power. It can run at a maximum frequency of 3 MHz.
  - The pins on the chip can be grouped into 6 groups
    - Address Bus.
    - Data Bus.
    - Control and Status Signals.
    - Power supply and frequency.
    - Externally Initiated Signals.
    - Serial I/O ports.



# The Address and Data Bus Systems

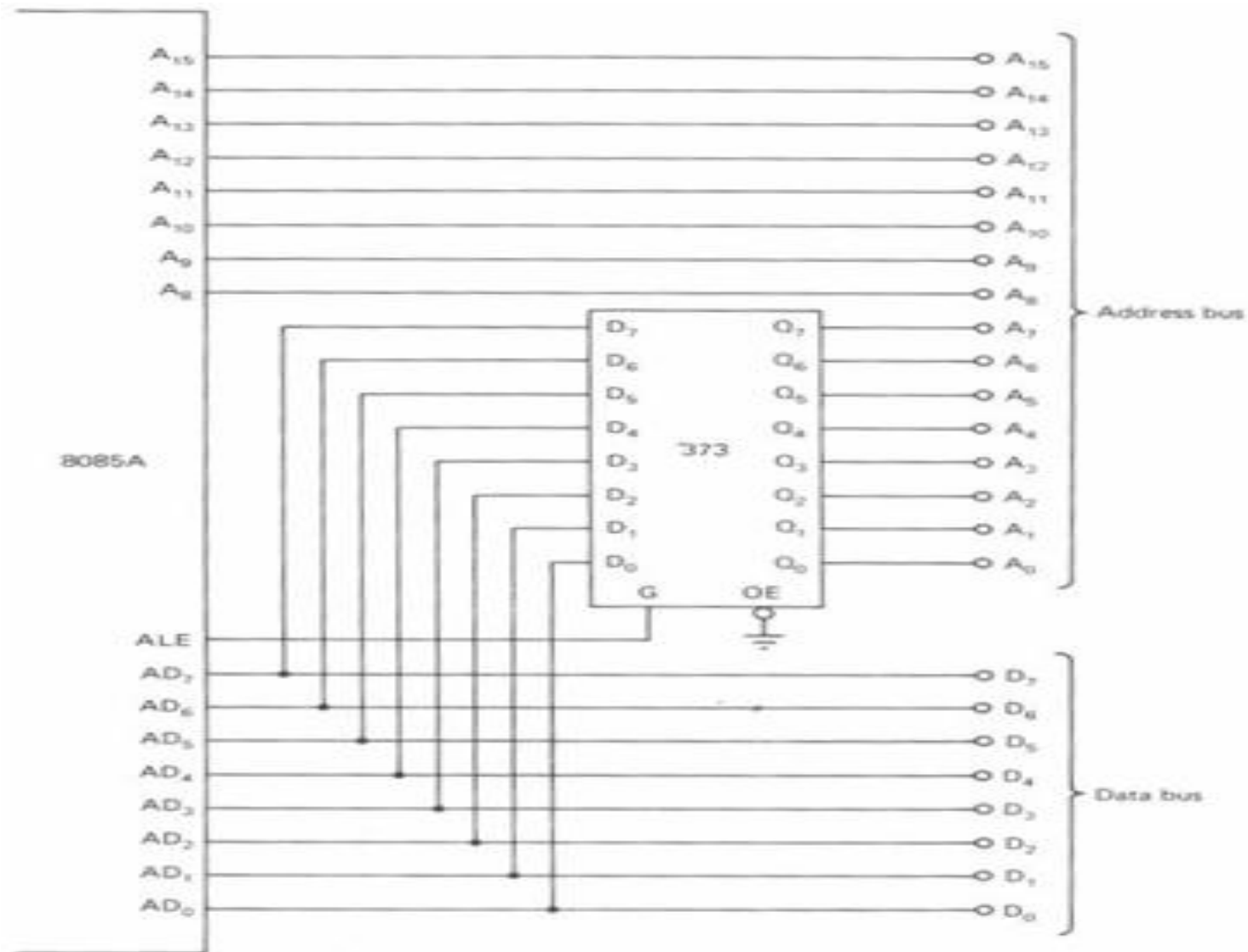
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- The address bus has 8 signal lines **A8 – A15** which are **unidirectional**.
- The other 8 address bits are **multiplexed** (time shared) **with the 8 data bits**.
  - So, the bits **AD0 – AD7** are **bi-directional** and serve as **A0 – A7** and **D0 – D7** at the same time.
    - During the execution of the instruction, these lines carry the address bits during the early part, then during the late parts of the execution, they carry the 8 data bits.
  - In order to separate the address from the data, we can use a **latch** to save the value before the function of the bits changes.





# Demultiplexing of Address/Data Bus



# The Control and Status Signals

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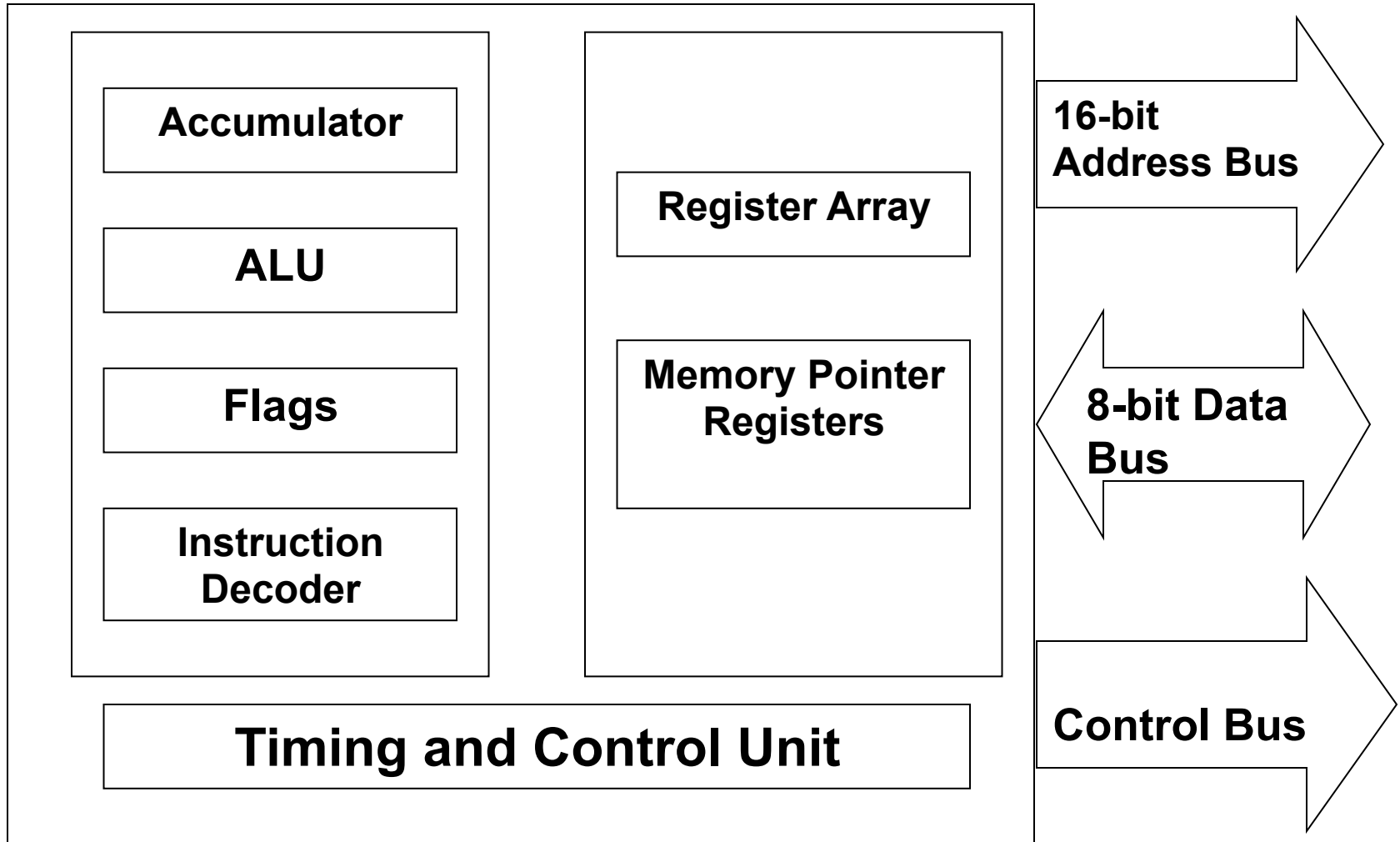
- 4 main control and status signals.
  - ALE: Address Latch Enable. This signal is a pulse that become 1 when the AD0 – AD7 lines have an address on them. It becomes 0 after that. This signal can be used to enable a latch to save the address bits from the AD lines.
  - RD: Read. Active low.
  - WR: Write. Active low.
  - IO/M: This signal specifies whether the operation is a memory operation (IO/M=0) or an I/O operation (IO/M=1).
  - S1 and S0 : Status signals to specify the kind of operation being performed. Usually not used in small systems.



# INSTRUCTION SET OF 8085



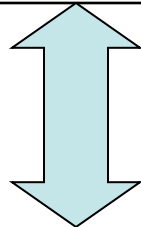
# Programming model of 8085



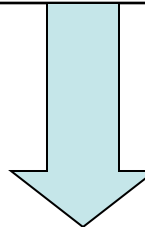
# Programming model of 8085

A Accumulator (8-bit)	Flag Register (8-bit)							
	S	Z		AC		P		CY
B (8-bit)	C (8-bit)							
D (8-bit)	E (8-bit)							
H (8-bit)	L (8-bit)							
Stack Pointer (SP) (16-bit)								
Program Counter (PC) (16-bit)								

8- Lines  
Bidirectional



16- Lines  
Unidirectional



# Instruction Set of 8085

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## ➤ Instructions

- 74 operation codes, e.g. **ADD**
- 246 Instructions, e.g. **ADD B**

## ➤ **8085** instructions can be classified as

- 1. Data Transfer (Copy)**
- 2. Arithmetic**
- 3. Logical and Bit manipulation**
- 4. Branch**
- 5. Machine Control**



# Addressing Modes of 8085

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- The various formats of specifying operands are called addressing modes
- Addressing modes of 8085
  - Register Addressing
  - Immediate Addressing
  - Memory Addressing
  - Input/Output Addressing



# Data movement instructions for the 8085 microprocessor

Instruction	Operation
NOP	No operation
MOV $r1, r2$	$r1 = r2$
MOV $r, M$	$r = M[HL]$
MOV $M, r$	$M[HL] = r$
MVI $r, n$	$r = n$
MVI $M, n$	$M[HL] = n$
LXI $rp, \Gamma$	$rp = \Gamma$
LDA $\Gamma$	$A = M[\Gamma]$
STA $\Gamma$	$M[\Gamma] = A$
LHLD $\Gamma$	$HL = M[\Gamma], M[\Gamma+1]$
SHDL $\Gamma$	$M[\Gamma], M[\Gamma+1] = HL$

Instruction	Operation
LDAX $rp$	$A = M[rp]$ ( $rp = BC, DE$ )
STAX $rp$	$M[rp] = A$ ( $rp = BC, DE$ )
XCHG	$DE \leftrightarrow HL$
PUSH $rp$	Stack = $rp$ ( $rp \neq SP$ )
PUSH PSW	Stack = A, flag register
POP $rp$	$rp = \text{Stack}$ ( $rp \neq SP$ )
POP PSW	A, flag register = Stack
XTHL	$HL \leftrightarrow \text{Stack}$
SPHL	$SP = HL$
IN $n$	$A = \text{input port } n$
OUT $n$	output port $n = A$





# Data Operation instructions for the 8085 microprocessor

Instruction	Operation	Flags
ADD <i>r</i>	$A = A + r$	All
ADD <i>M</i>	$A = A + M[HL]$	All
ADI <i>n</i>	$A = A + n$	All
ADC <i>r</i>	$A = A + r + CY$	All
ADC <i>M</i>	$A = A + M[HL] + CY$	All
ACI <i>n</i>	$A = A + n + CY$	All
SUB <i>r</i>	$A = A - r$	All
SUB <i>M</i>	$A = A - M[HL]$	All
SUI <i>n</i>	$A = A - n$	All
SBB <i>r</i>	$A = A - r - CY$	All
SBB <i>M</i>	$A = A - M[HL] - CY$	All
SBI <i>n</i>	$A = A - n - CY$	All
INR <i>r</i>	$r = r + 1$	Not CY
INR <i>M</i>	$M[HL] = M[HL] + 1$	Not CY
DCR <i>n</i>	$r = r - 1$	Not CY
DCR <i>M</i>	$M[HL] = M[HL] - 1$	Not CY
INX <i>rp</i>	$rp = rp + 1$	None
DCX <i>rp</i>	$rp = rp - 1$	None
DAD <i>rp</i>	$HL = HL + rp$	CY
DAA	Decimal adjust	All

Instruction	Operation	Flags
ANA <i>r</i>	$A = A \wedge r$	All
ANA <i>M</i>	$A = A \wedge M[HL]$	All
ANI <i>n</i>	$A = A \wedge n$	All
ORA <i>r</i>	$A = A \vee r$	All
ORA <i>M</i>	$A = A \vee M[HL]$	All
ORI <i>n</i>	$A = A \vee n$	All
XRA <i>r</i>	$A = A \oplus r$	All
XRA <i>M</i>	$A = A \oplus M[HL]$	All
XRI <i>n</i>	$A = A \oplus n$	All
CMP <i>r</i>	Compare <i>A</i> and <i>r</i>	All
CMP <i>M</i>	Compare <i>A</i> and <i>M[HL]</i>	All
CPI <i>n</i>	Compare <i>A</i> and <i>n</i>	All
RLC	$CY = A_7, A = A_{6-0}, A_7$	CY
RRC	$CY = A_0, A = A_0, A_{7-1}$	CY
RAL	$CY, A = A, CY$	CY
RAR	$A, CY = CY, A$	CY
CMA	$A = A'$	None
CMC	$CY = CY'$	CY
STC	$CY = 1$	CY



# Program Control instructions for the 8085 microprocessor

Instruction	Operation
JUMP $\Gamma$	GOTO $\Gamma$
<i>Jcond</i> $\Gamma$	If condition is true then GOTO $\Gamma$
PCHL	GOTO address in <i>HL</i>
CALL $\Gamma$	Call subroutine at $\Gamma$
<i>Ccond</i> $\Gamma$	If condition is true then call subroutine at $\Gamma$
RET	Return from subroutine
<i>Rcond</i>	If condition is true then return from subroutine
RSTn	Call subroutine at $8*n$ ( $n = 5.5, 6.5, 7.5$ )
RIM	$A = IM$
SIM	$IM = A$
DI	Disable interrupts
EI	Enable interrupts
HLT	Halt the CPU



# Register Addressing

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- Operands are one of the internal registers of 8085
- Examples-

**MOV A, B**

**ADD C**



# Immediate Addressing

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- Value of the operand is given in the instruction itself
- Example-

**MVI A, 20H**

**LXI H, 2050H**

**ADI 30H**

**SUI 10H**



# Memory Addressing

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- One of the operands is a memory location
- Depending on how address of memory location is specified, **memory** addressing is of two types
  - **Direct** addressing
  - **Indirect** addressing



# Direct Addressing

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- 16-bit Address of the memory location is specified in the instruction directly
- Examples-

**LDA 2050H**

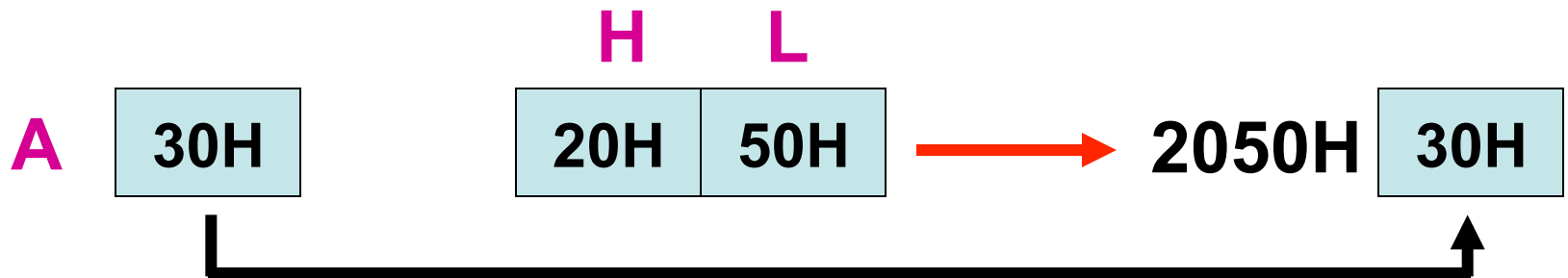
**STA 3050H**



# Indirect Addressing

- A **memory pointer** register is used to store the address of the memory location
- Example-

**MOV M, A** ;copy register A to memory location whose address is stored in register pair HL



# Input/Output Addressing

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- 8-bit address of the port is directly specified in the instruction
- Examples-

**IN 07H**

**OUT 21H**





# Instruction & Data Formats

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Instruction classification according to size

- 1-byte Instructions
- 2-byte Instructions
- 3-byte Instructions



# One-byte Instructions

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- Includes Opcode and Operand in the same byte
- Examples-

Opcode	Operand	Binary Code	Hex Code
<b>MOV</b>	<b>C, A</b>	0100 1111	<b>4FH</b>
<b>ADD</b>	<b>B</b>	1000 0000	<b>80H</b>
<b>HLT</b>		0111 0110	<b>76H</b>



# Two-byte Instructions

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- First byte specifies Operation Code
- Second byte specifies Operand

Opcode	Operand	Binary Code	Hex Code
<b>MVI</b>	<b>A, 32H</b>	0011 1110	<b>3EH</b>
		0011 0010	<b>32H</b>
<b>MVI</b>	<b>B, F2H</b>	0000 0110	<b>06H</b>
		1111 0010	<b>F2H</b>



# Three-byte Instructions

- First byte specifies Operation Code
- Second & Third byte specifies Operand

Opcode	Operand	Binary Code	Hex Code
<b>LXI</b>	<b>H, 2050H</b>	0010 0001 0101 0000 0010 0000	<b>21H</b> <b>50H</b> <b>20H</b>
<b>LDA</b>	<b>3070H</b>	0011 1010 0111 0000 0011 0000	<b>3AH</b> <b>70H</b> <b>30H</b>



# Data Transfer (Copy) Operations

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1. **Load** a 8-bit number in a Register
2. **Copy** from Register to Register
3. **Copy** between Register and Memory
4. **Copy** between Input/Output Port and Accumulator
5. **Load** a 16-bit number in a Register pair
6. **Copy** between Register pair and Stack memory



# Example Data Transfer (Copy) Operations / Instructions

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1. **Load** a 8-bit number 4F in register **B**
2. **Copy** from Register **B** to Register **A**
3. **Load** a 16-bit number 2050 in Register pair **HL**
4. **Copy** from Register **B** to **Memory** Address 2050
5. **Copy** between **Input/Output** Port and **Accumulator**

**MVI B, 4FH**

**MOV A,B**

**LXI H, 2050H**

**MOV M,B**

**OUT 01H**

**IN 07H**



# Arithmetic Operations

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1. **Addition** of two 8-bit numbers
2. **Subtraction** of two 8-bit numbers
3. **Increment/ Decrement** a 8-bit number



# Example Arithmetic Operations / Instructions

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- |  |                |
|--|----------------|
| 1. <b>Add</b> a 8-bit number 32H to<br>Accumulator                   | <b>ADI 32H</b> |
| 2. <b>Add</b> contents of Register <b>B</b> to<br>Accumulator        | <b>ADD B</b>   |
| 3. <b>Subtract</b> a 8-bit number 32H from<br>Accumulator            | <b>SUI 32H</b> |
| 4. <b>Subtract</b> contents of Register <b>C</b><br>from Accumulator | <b>SUB C</b>   |
| 5. <b>Increment</b> the contents of Register<br><b>D</b> by 1        | <b>INR D</b>   |
| 6. <b>Decrement</b> the contents of<br>Register <b>E</b> by 1        | <b>DCR E</b>   |





# Logical & Bit Manipulation Operations

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- **AND** two 8-bit numbers
- **OR** two 8-bit numbers
- **Exclusive-OR** two 8-bit numbers
- **Compare** two 8-bit numbers
- **Complement**
- **Rotate** Left/Right Accumulator bits



# Example Logical & Bit Manipulation Operations / Instructions

○ Logically <b>AND</b> Register <b>H</b> with <b>A</b> ccumulator	<b>ANA H</b>
○ Logically <b>OR</b> Register <b>L</b> with <b>A</b> ccumulator	<b>ORA L</b>
○ Logically <b>XOR</b> Register <b>B</b> with <b>A</b> ccumulator	<b>XRA B</b>
○ <b>Compare</b> contents of Register <b>C</b> with <b>A</b> ccumulator	<b>CMP C</b>
○ <b>Complement</b> <b>A</b> ccumulator	<b>CMA</b>
○ <b>Rotate</b> <b>A</b> ccumulator Left	<b>RAL</b>



# Branching Operations

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➤ control the flow of program execution

## – Jumps

- Conditional jumps
- Unconditional jumps

## – Call & Return

- Conditional Call & Return
- Unconditional Call & Return



# Example Branching Operations / Instructions

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- |   |                   |
|---|-------------------|
| 1. <b>Jump</b> to a 16-bit Address 2080H if Carry flag is <b>SET</b>              | <b>JC 2080H</b>   |
| 2. Unconditional <b>Jump</b>  | <b>JMP 2050H</b>  |
| 3. <b>Call</b> a subroutine with its 16-bit Address                               | <b>CALL 3050H</b> |
| 4. <b>Return back</b> from the Call   | <b>RET</b>        |
| 5. <b>Call</b> a subroutine with its 16-bit Address if Carry flag is <b>RESET</b> | <b>CNC 3050H</b>  |
| 6. <b>Return</b> if Zero flag is <b>SET</b>                                       | <b>RZ</b>         |



# Machine Control Instructions

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- Affect the operation of the processor

**HLT**                      Stop program execution

**NOP**                      Do not perform any operation



# Writing a Assembly Language Program

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Steps to write a program

- Analyze the problem
- Develop algorithm
- Draw a flowchart
- Convert flowchart to Assembly language by picking appropriate 8085 instructions



# Example 1

---

- Add two numbers
- Copy 8-bit result in A to C
- If CARRY is generated
  - Handle it
- Result is in register pair BC



# Algorithm Development

1. Load two numbers in registers D, E
3. Add them
5. Store 8 bit result in C
7. Check CARRY flag
8. If CARRY flag is SET
  - Store CARRY in register B
9. Stop

- Load registers D, E

- Copy register D to A
- Add register E to A
- Copy A to register C

- Use Conditional Jump instructions

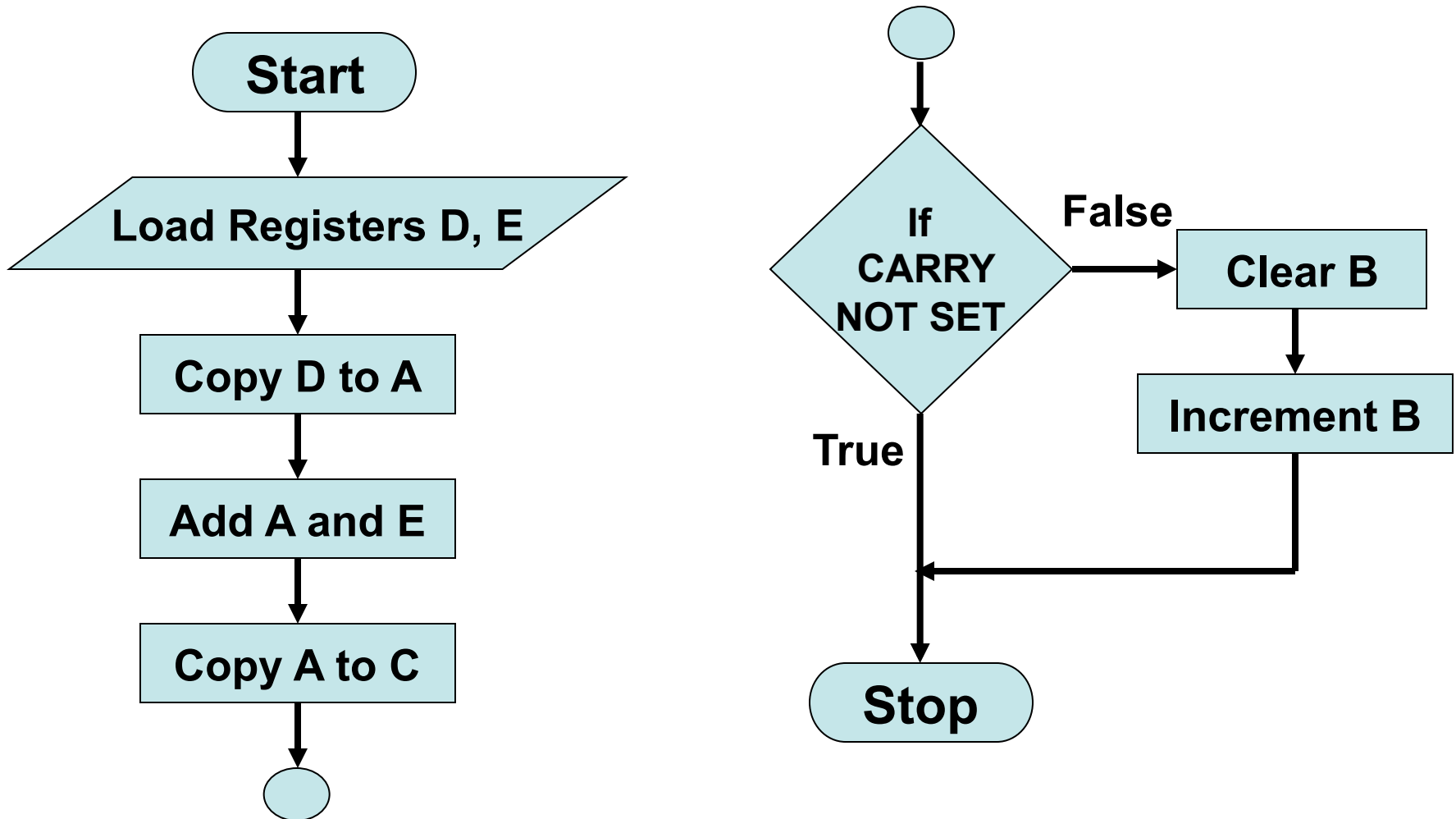
- Clear register B
- Increment B

- Stop processing





# Flowchart



# Assembly Language Program

- Load registers D, E
- Copy register D to A
- Add register E to A
- Copy A to register C
- Use Conditional Jump instructions
- Clear register B
- Increment B
- Stop processing

```
MVI D, 2H
MVI E, 3H
MOV A, D
ADD E
MOV C, A
JNC END
MVI B, 0H
INR B
END: HLT
```



# Example 2: Sum of Natural Numbers

## The Algorithm of the program

1:	total = 0, i = 0	}	$n + (n - 1) + \dots + 1$
2:	i = i + 1		
3:	total = total + i		
4:	IF I /= n THEN GOTO 2		

## The 8085 coding of the program

LDA n	}	i = n
MOV B, A		
XRA A	}	sum = A XOR A = 0
Loop: ADD B	}	sum = sum + i
DCR B	}	i = i - 1
JNZ Loop	}	IF I /= 0 THEN GOTO Loop
STA total	}	total = sum



# MICROCONTROLLER

# 8051



# Three criteria in Choosing a Microcontroller

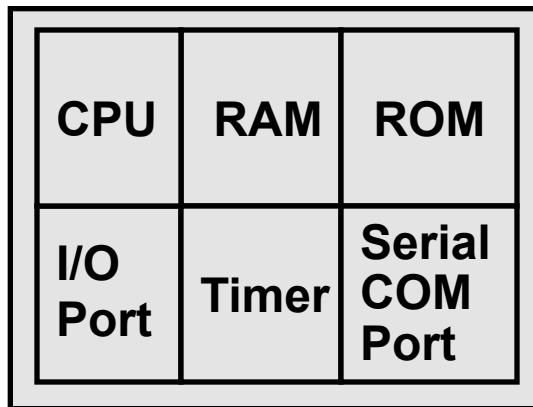
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- meeting the computing needs of the task efficiently and cost effectively
  - speed, the amount of ROM and RAM, the number of I/O ports and timers, size, packaging, power consumption
  - easy to upgrade
  - cost per unit
- availability of software development tools
  - assemblers, debuggers, C compilers, emulator, simulator, technical support
- wide availability and reliable sources of the microcontrollers



# 8051 Basic Component

- 4K bytes internal **ROM**
- 128 bytes internal **RAM**
- Four 8-bit **I/O ports** (P0 - P3).
- Two 16-bit **timers**/counters
- One **serial** interface

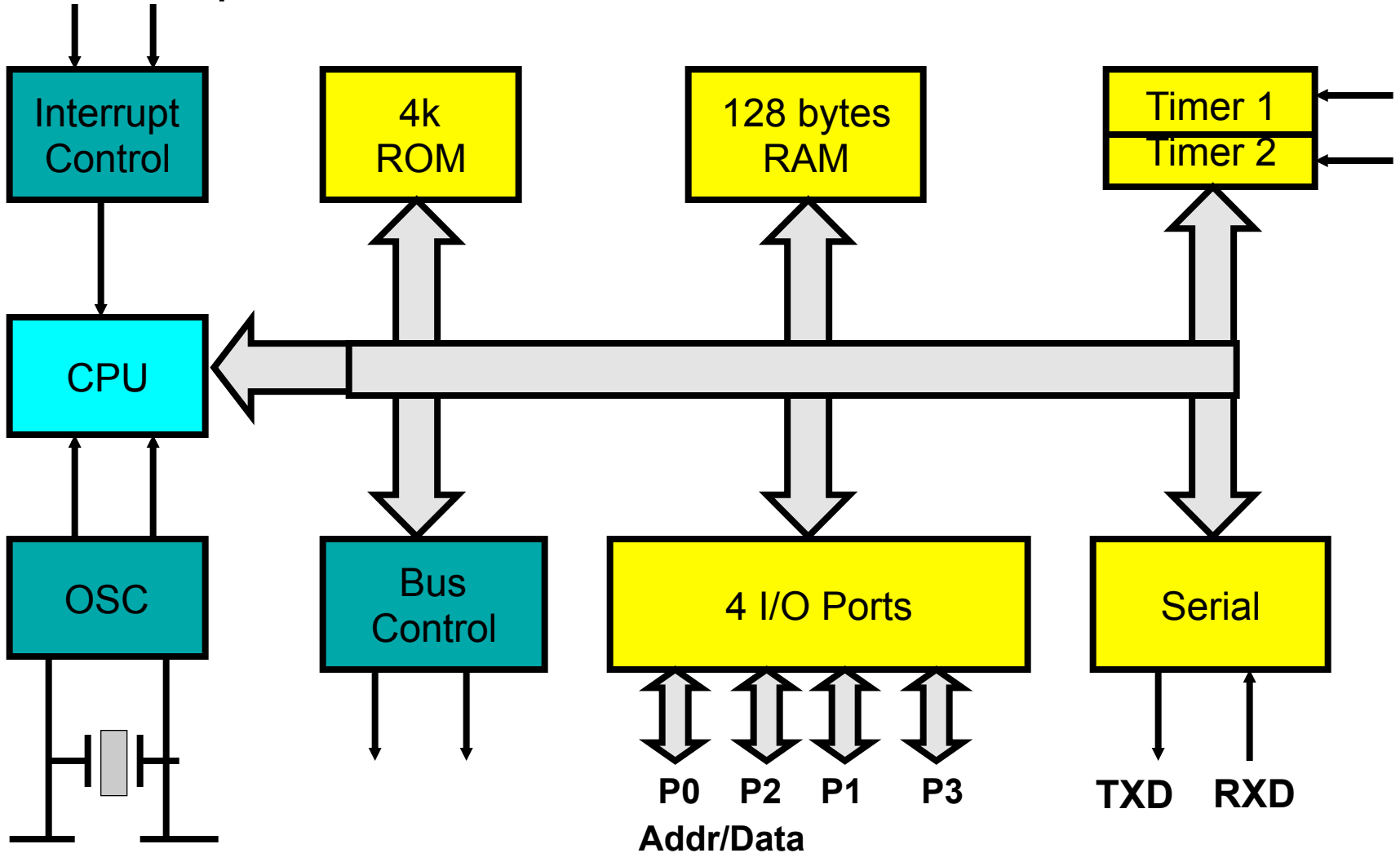


← A single chip  
Microcontroller

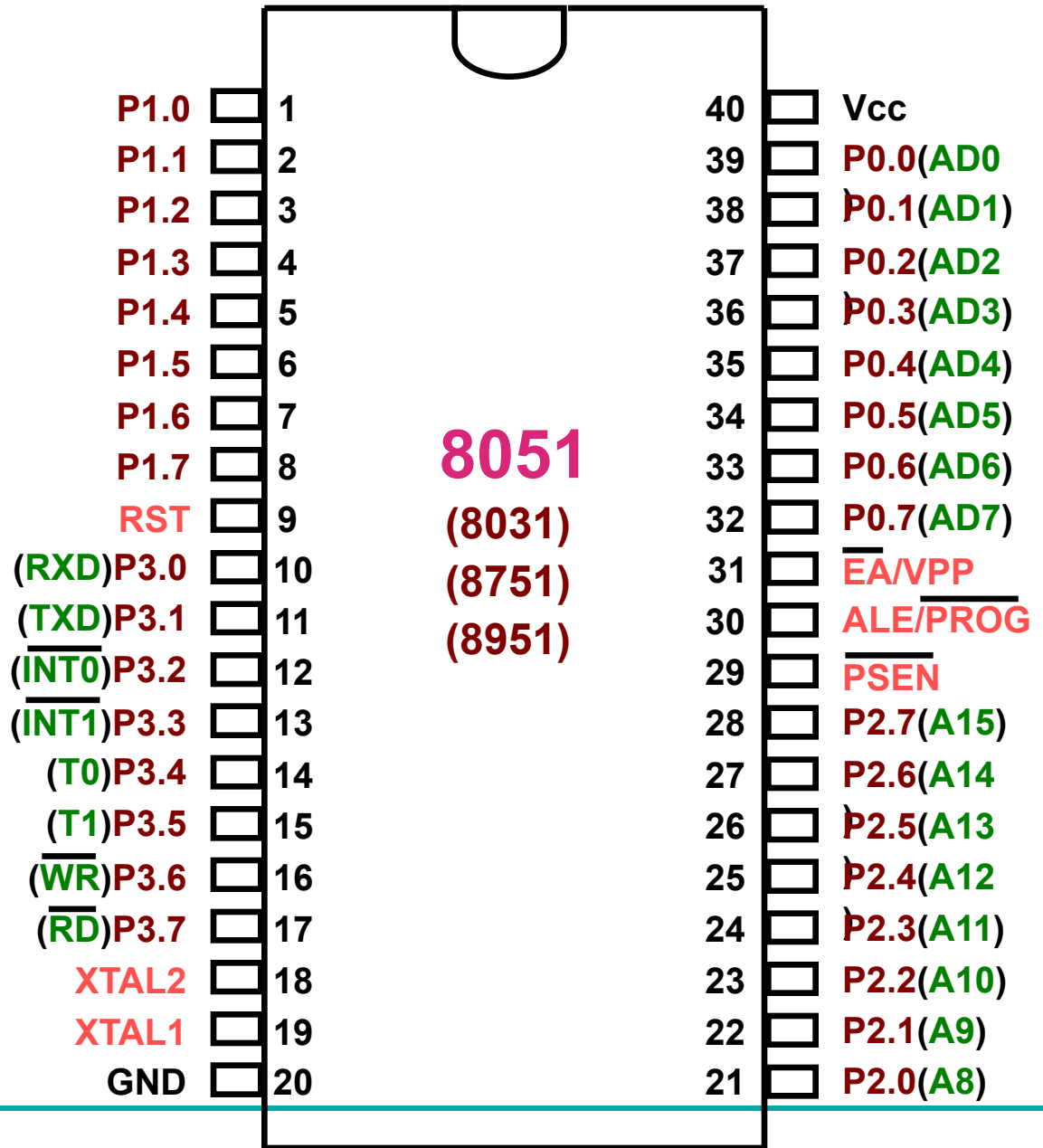


# Block Diagram

External Interrupts



# 8051 Foot Print





# Thank You

