



## ***P – Control with Root Locus***

Consider the **plant** given below.

$$G(s) = \frac{K(s+4)}{(s+2)(s-1)}$$

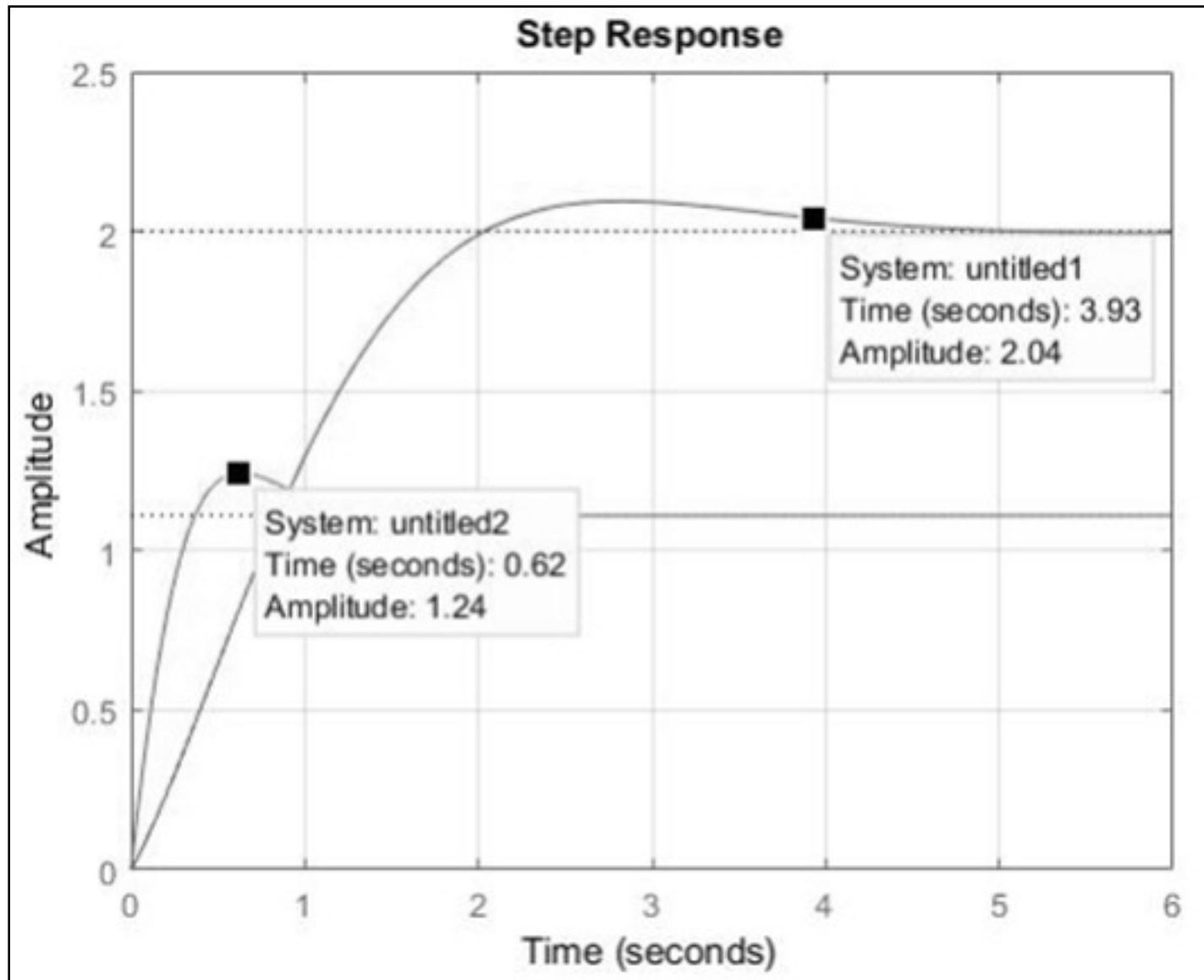
Determine '**K**' using root locus so that  $\zeta = 0.707$  and  $T_s$  (2%) < 4sec.

$$\sigma = \frac{4}{T_s} = 1; \quad \omega_n = \frac{\sigma}{\zeta} = 1.414; \quad \omega_d = 1; \quad s_{1,2} = -1 \pm j1$$





# *Design Verification*





## ***P – Control with Bode Plot***

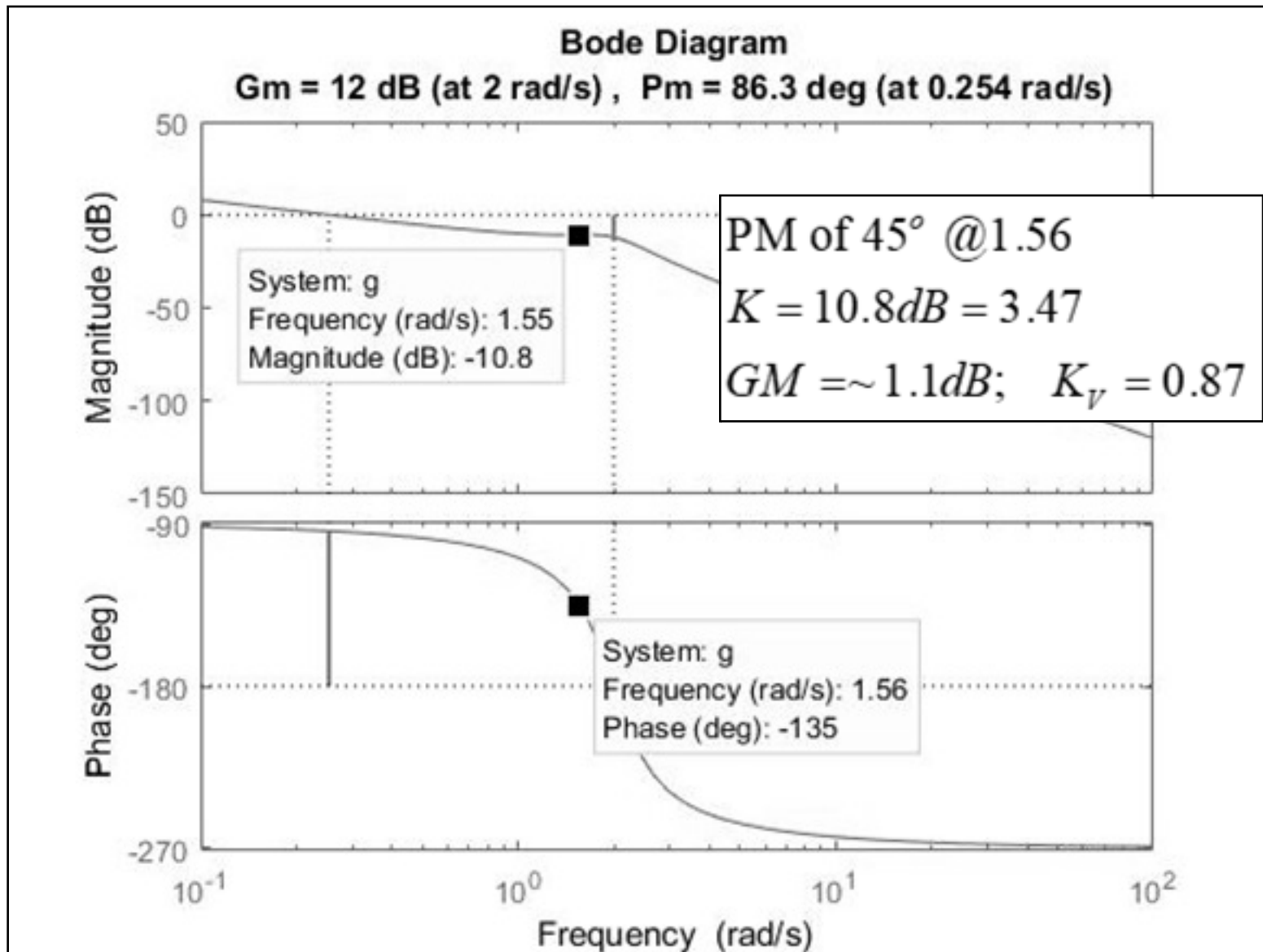
Consider the **plant** given below.

$$G(s) = \frac{K}{s(s^2 + s + 4)}$$

Determine '**K**', for which the system will have a **phase margin** of  $45^\circ$ . Also, determine the **gain margin** for this value of '**K**' as well as **ramp** error constant.



# *Design with Bode Plot*





# *Design Verification*

