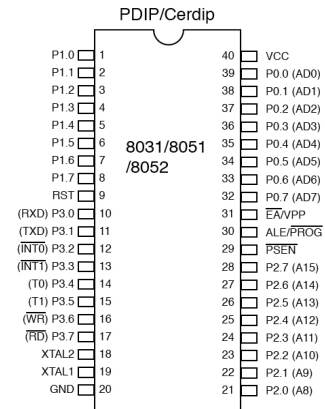


# 8051 Microcontroller: Serial Communication



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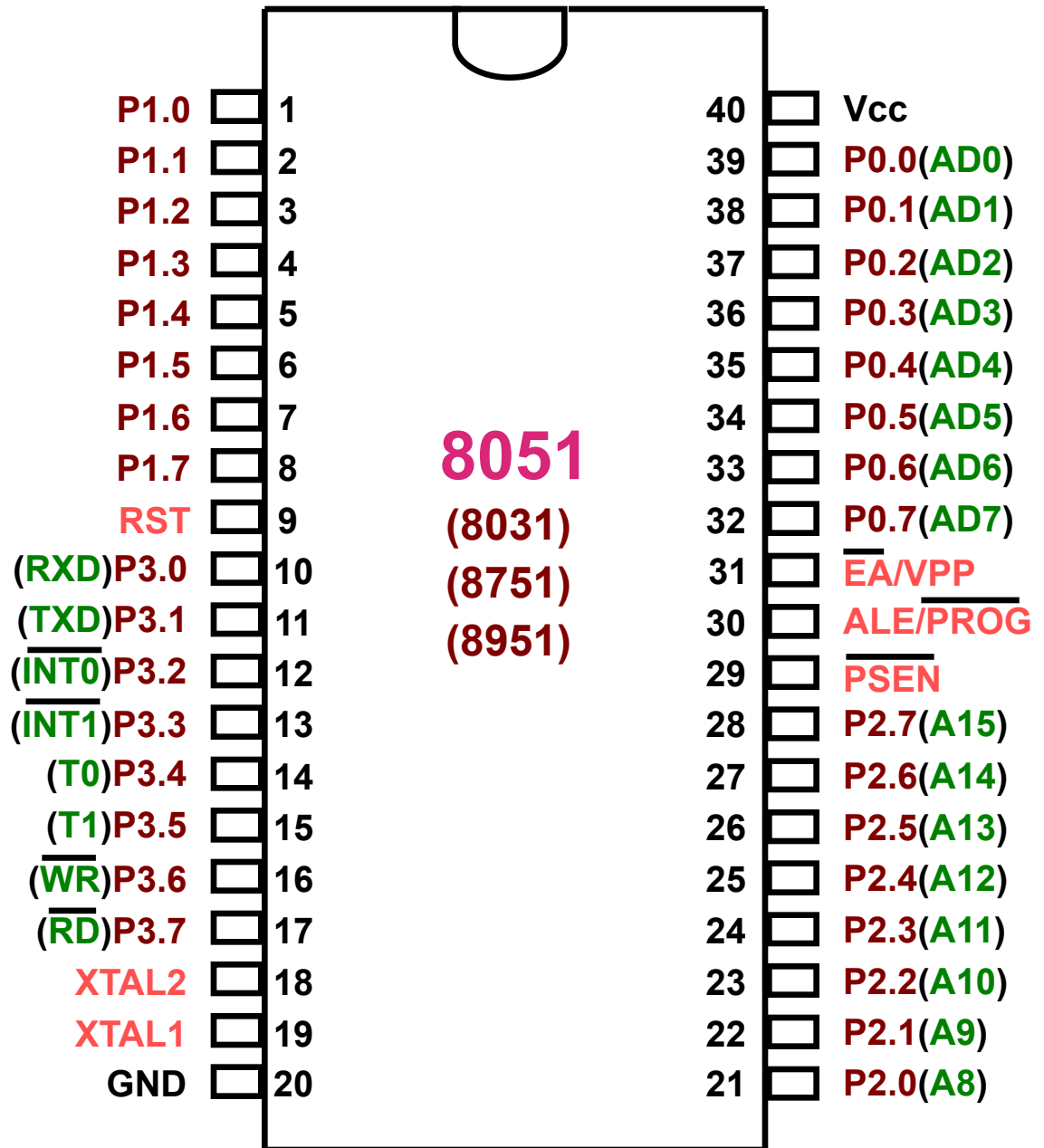
*EE-309: Microprocessors*



Lecture 15 (20 Aug 2015)

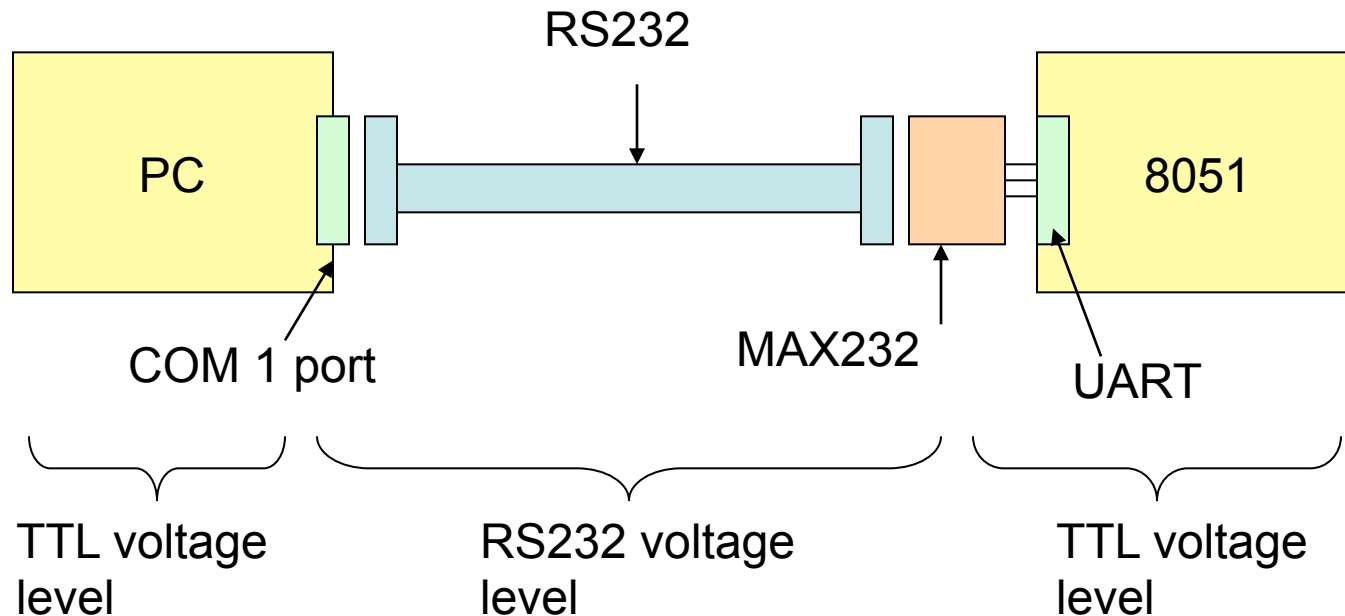
**CADSL**

# 8051 Pin Diagram

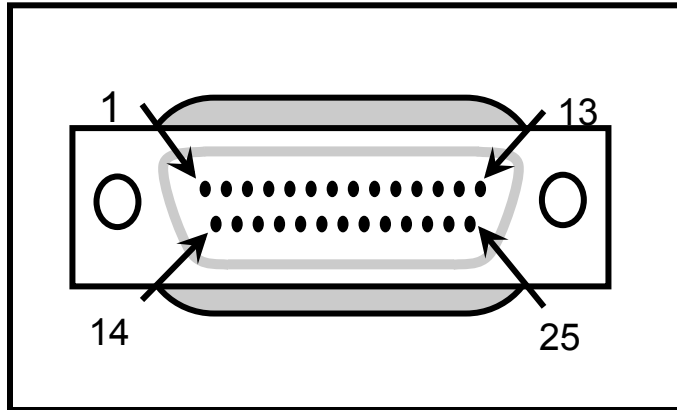


# MAX232

- MAX232 IC chips are commonly referred to as **line drivers**.

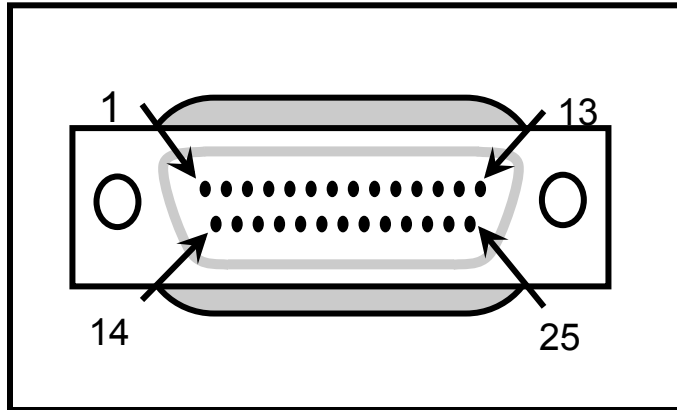


# RS232 Pins for DTE



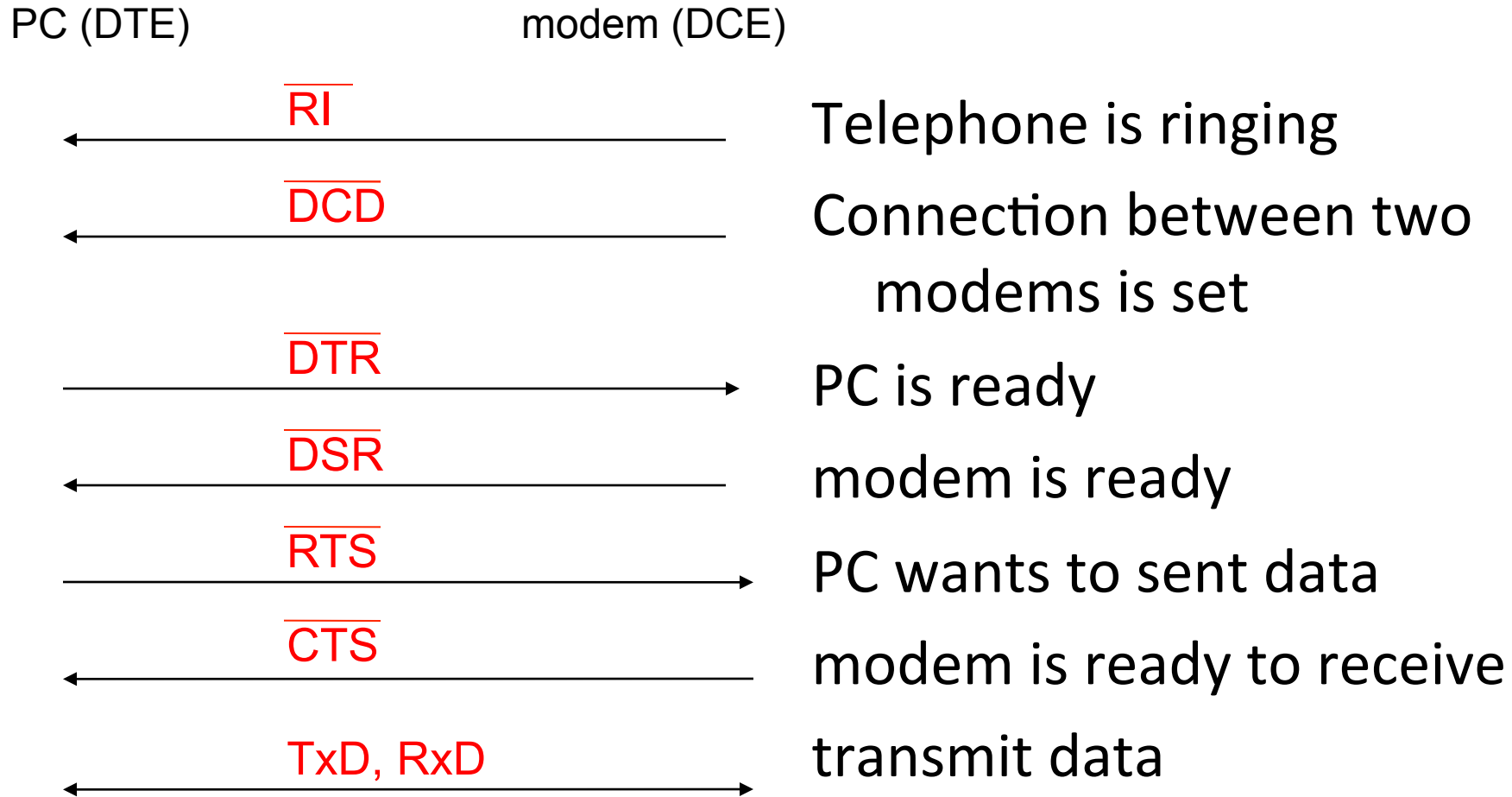
Pin	Description
1	Protective ground
2	Transmitted data (TxD)
3	Received data (RxD)
4	Request to send (RTS)
5	Clear to send (CTS)
6	Data set ready (DSR)
7	Signal ground (GND)
8	Data carrier detect (DCD)
9/10	Reserved for data testing
11	Unassigned
12	Secondary data carrier detect
13	Secondary clear to send

# RS232 Pins for DTE



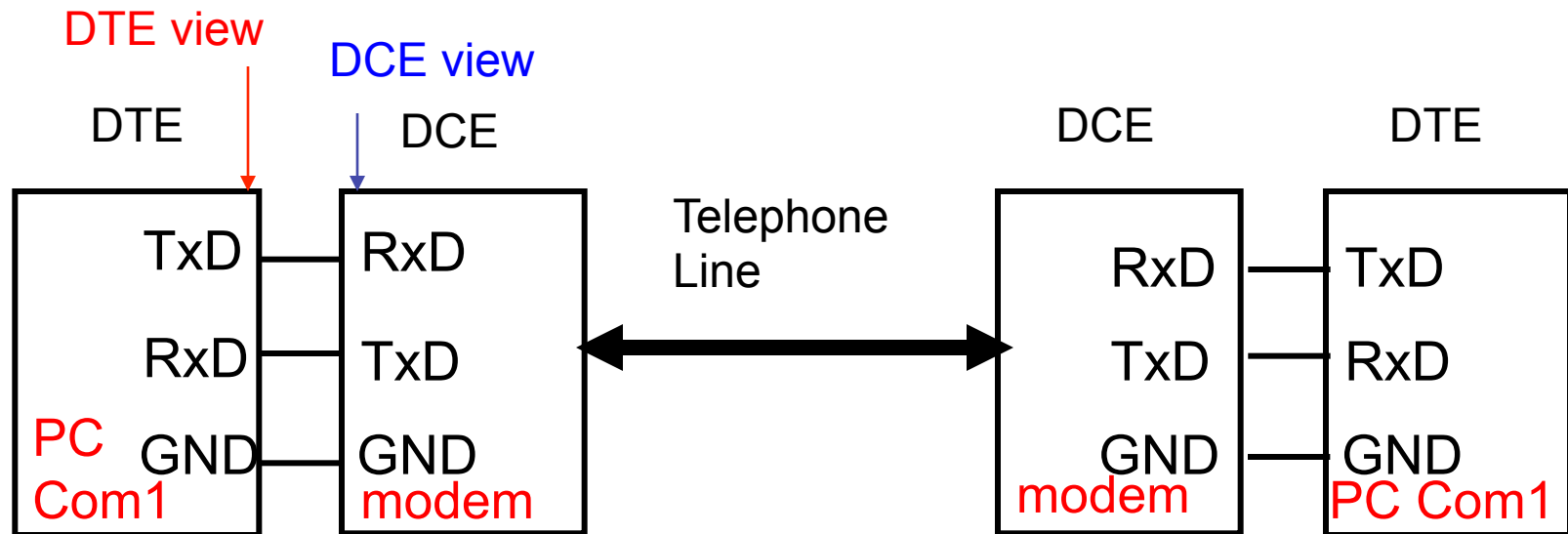
Pin	Description
14	Secondary transmitted data
15	Transmit signal element timing
16	Secondary received data
17	Receive signal element timing
18	Unassigned
19	Secondary request to sent
20	Data terminal ready (DTR)
21	Signal quality detector
22	Ring indicator
23	Data signal rate select
24	Transmit signal element timing
25	Unassigned

# Communication Flow



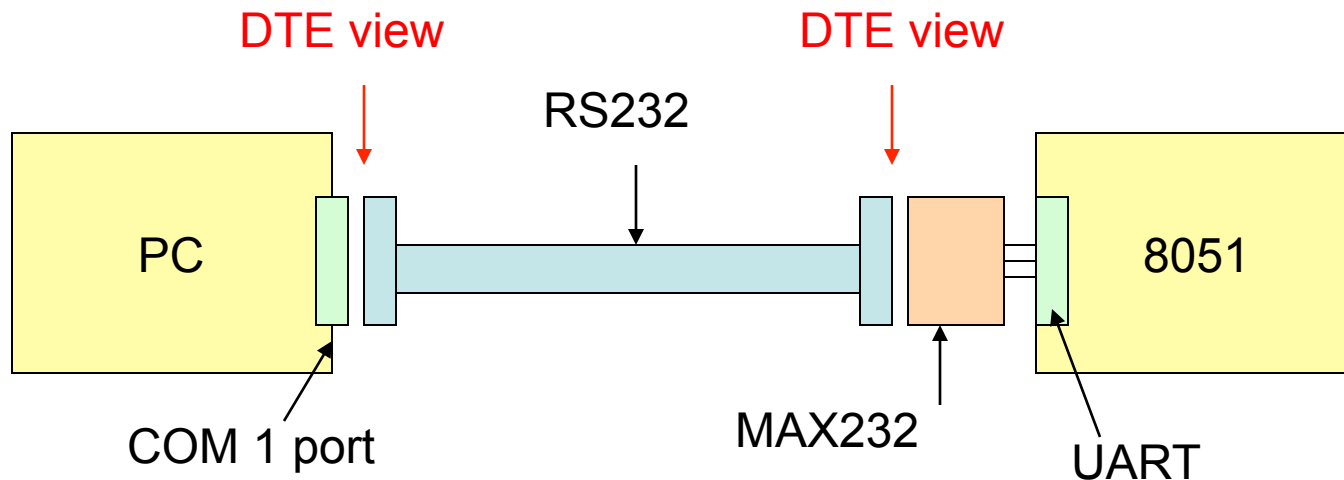
# DTE and DCE

- Communication Equipments are classified as
  - DTE (data terminal equipment)
    - Terminals and computers that send and receive data
  - DCE (data communication equipment)
    - Communication equipment (only for transfer data), modem



# IBM PC/compatible COM ports

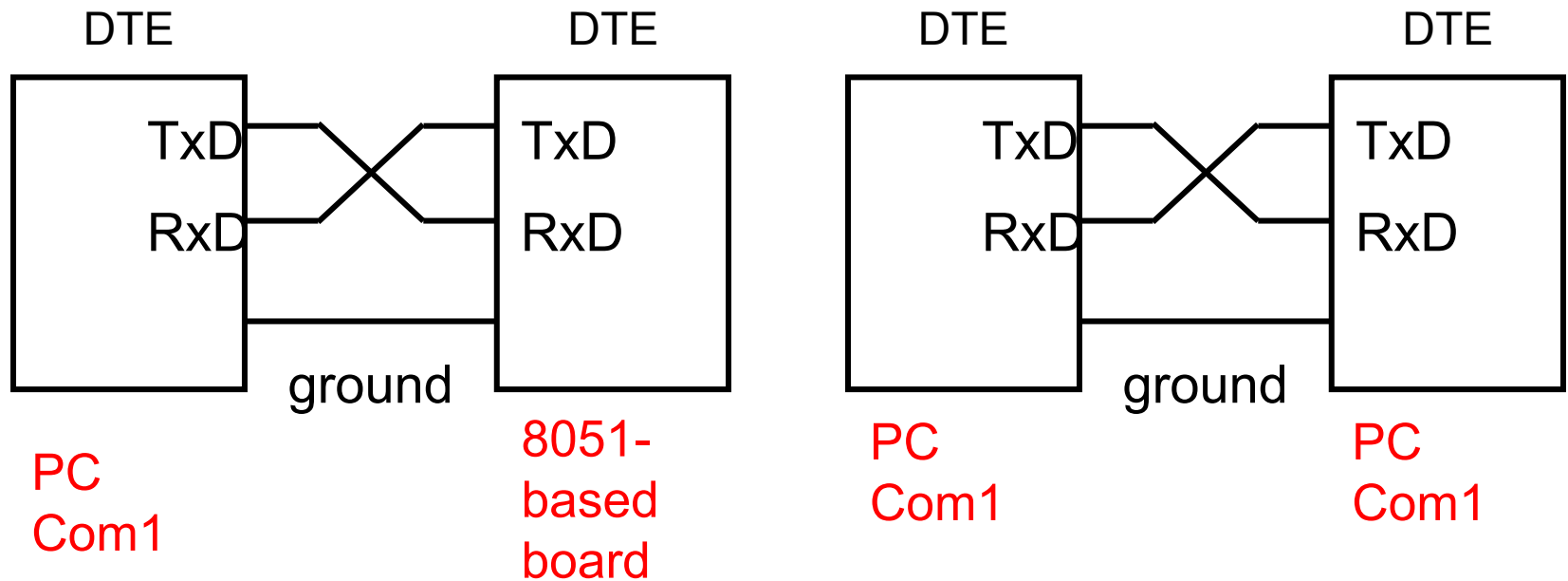
- IBM PC had 2 COM ports.
  - Both COM ports have RS232-type connectors.
  - For mouse, modem





# Null Modem Connection

- The simplest connection between a PC and microcontroller requires a minimum of three pins, TxD, RxD, and GND.
  - null modem connection



# RS422 & RS485

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- By using RS232, the limit distance between two PCs is about 15m.
- It works well even the distance=30m.
- If you want to transfer data with long distance (ex: 300m), you can use RS422 or RS485.



# TxD and RxD pins in the 8051

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- In 8051, the data is received from or transmitted to
  - RxD: received data (Pin 10, P3.0)
  - TxD: transmitted data (Pin 11, P3.1)
- TxD and RxD of the 8051 are TTL compatible.
- The 8051 requires a line driver to make them RS232 compatible.
  - One such line driver is the MAX232 chip.



# PC Baud Rates

- PC supports several baud rates.
    - You can use netterm, terminal.exe, stty, pty to send/receive data.
  - Hyperterminal supports baud rates much higher than the ones list in the Table.
- |                |
|----------------|
| 110 bps        |
| 150            |
| 300            |
| 600            |
| 1200           |
| 2400           |
| 4800           |
| 9600 (default) |
| 19200          |

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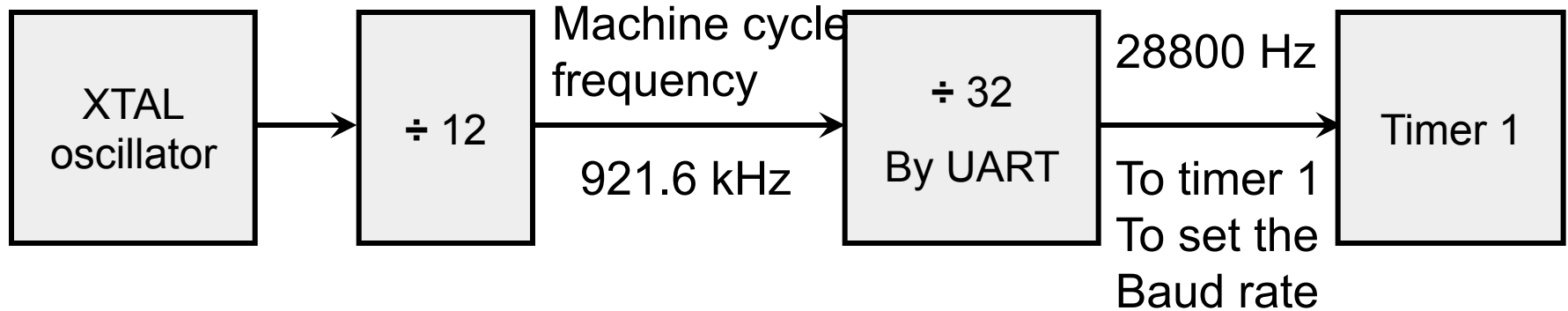
*Note:* Baud rates supported by 486/Pentium IBM PC BIOS.



# Baud Rates in 8051

- The 8051 transfers and receives data serially at many different baud rates by using UART.
- UART divides the machine cycle frequency by 32 and sends it to Timer 1 to set the baud rate.
- Signal change for each roll over of timer 1

11.0592 MHz



# Baud Rates in 8051

- Timer 1, mode 2 (8-bit, auto-reload)
- Define TH1 to set the baud rate.
  - XTAL = 11.0592 MHz
  - The system frequency =  $11.0592 \text{ MHz} / 12 = 921.6 \text{ kHz}$
  - Timer 1 has  $921.6 \text{ kHz} / 32 = 28,800 \text{ Hz}$  as source.
  - TH1=FDH means that UART sends a bit every 3 timer source.
  - Baud rate =  $28,800/3 = 9,600 \text{ Hz}$



# Example

With XTAL = 11.0592 MHz, find the TH1 value needed to have the following baud rates. (a) 9600 (b) 2400 (c) 1200

With XTAL = 11.0592 MHz, we have:

The frequency of system clock =  $11.0592 \text{ MHz} / 12 = 921.6 \text{ kHz}$

The frequency sent to timer 1 =  $921.6 \text{ kHz} / 32 = 28,800 \text{ Hz}$

(a)  $28,800 / 3 = 9600$  where -3 = FD (hex) is loaded into TH1

(b)  $28,800 / 12 = 2400$  where -12 = F4 (hex) is loaded into TH1

(c)  $28,800 / 24 = 1200$  where -24 = E8 (hex) is loaded into TH1

Notice that dividing 1/12th of the crystal frequency by 32 is the default value upon activation of the 8051 RESET pin.



# Timer 1 TH1 Register Values for Various Baud Rates

Baud Rate	TH1 (Decimal)	TH1 (Hex)
9600	-3	FD
4800	-6	FA
2400	-12	F4
1200	-24	E8

*Note:* XTAL = 11.0592 MHz.





# Registers Used in Serial Transfer Circuit

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- SUBF (Serial data buffer)
- SCON (Serial control register)
- PCON (Power control register)



# SBUF Register

- Serial data register: **SBUF**
  - MOV SBUF, #'A'** ;put char 'A' to transmit
  - MOV SBUF, A** ;send data from A
  - MOV A, SBUF** ;copy received data to A
- An 8-bit register
- Set the usage mode for two timers
  - For a byte of data to be transferred via the TxD line, it must be placed in the SBUF.
  - SBUF holds the byte of data when it is received by the 8051's RxD line.
- Not bit-addressable



# SCON Register

- Serial control register: **SCON**

**SM0, SM1** Serial port mode specifier

**REN** (Receive enable) set/cleared by software to enable/disable reception.

**TI** Transmit interrupt flag.

**RI** Receive interrupt flag.

**SM2 = TB8 = RB8 = 0** (not widely used)

(MSB)

(LSB)



\* SCON is bit-addressable.



# SCON Mode bits

- SM1 and SM0 determine the framing of data.
  - SCON.6 (SM1) and SCON.7 (SM0)

.

SM1	SM0	Mode	Operating Mode	Baud Rate
0	0	<b>0</b>	Shift register	Fosc./12
0	1	<b>1</b>	<b>8-bit UART</b>	<b>Variable by timer1</b>
1	0	<b>2</b>	9-bit UART	Fosc./64 or Fosc./32
1	1	<b>3</b>	9-bit UART	Variable



# SM2

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- SM2 enables the multiprocessor communication for mode 2 & 3.
- We make it 0 since we are not using the 8051 in a multiprocessor environment.
  - SM2=0 : Single processor environment
  - SM2=1 : multiprocessor environment



# REN (Receive Enable)

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- Set/cleared by software to enable/disable reception.
  - REN=1
    - It enable the 8051 to receive data on the RxD pin of the 8051.
    - If we want the 8051 to both transfer and receive data, REN must be set to 1.
    - **SETB SCON.4**
  - REN=0
    - The receiver is **disabled**.
    - The 8051 can not receive data.
    - **CLR SCON.4**



# TB8 (Transfer Bit 8)

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- SCON.3
- TB8 is used for serial modes 2 and 3.
- The 9<sup>th</sup> bit that will be transmitted in mode 2 & 3.
- Set/Cleared by software.



# RB8 (Receive Bit 8)

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- SCON.2
- In serial mode 1, RB8 gets a copy of the stop bit when an 8-bit data is received.





# TI (Transmit Interrupt Flag)

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- When the 8051 finishes the transfer of the 8-bit character, it raises the TI flag.
- TI is raised by hardware at the beginning of the stop bit in mode 1.
- Must be cleared by software.



# RI (Receive Interrupt)

---

- Receive interrupt flag. Set by hardware in mode 1. Must be cleared by software.
- When the 8051 receives data serially via RxD, it gets rid of the start and stop bits and place the byte in the SBUF register.
- Then 8051 raises RI to indicate that a byte is received
- RI is raised at the beginning of the stop bit.



# SCON Serial Port Control Register (Bit Addressable)

SM0	SM1	SM2	REN	TB8	RB8	TI	RI
-----	-----	-----	-----	-----	-----	----	----

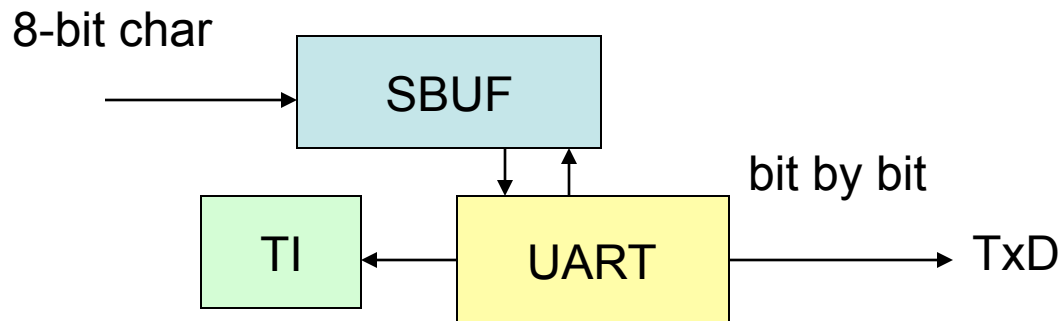
<b>SM0</b>	SCON.7	Serial port mode specifier
<b>SM1</b>	SCON.6	Serial port mode specifier
<b>SM2</b>	SCON.5	Used for multiprocessor communication. (Make it 0)
<b>REN</b>	SCON.4	Set/cleared by software to enable/disable reception.
<b>TB8</b>	SCON.3	Not widely used.
<b>RB8</b>	SCON.2	Not widely used.
<b>TI</b>	SCON.1	Transmit interrupt flag. Set by hardware at the beginning of the stop bit in mode 1. Must be cleared by software.
<b>RI</b>	SCON.0	Receive interrupt flag. Set by hardware halfway through the stop bit time in mode 1. Must be cleared by software.

*Note:* Make SM2, TB8, and RB8 = 0.



# Transfer Data with TI Flag

- The following sequence is the steps that the 8051 goes through in transmitting a character via TxD:
  1. The byte character to be transmitted is written into the SBUF register.
  2. It transfers the **start bit**.
  3. The **8-bit character** is transferred one bit at a time.
  4. The **stop bit** is transferred.



# Transfer Data with the TI flag

5. During the transfer of the stop bit, the 8051 raises the TI flag, indicating that the last character was transmitted and it is ready to transfer the next character.
6. By monitoring the **TI** flag, we know whether or not the 8051 is ready to transfer another byte.
  - We will not **overloading** the SBUF register.
  - If we write another byte into the SBUF before TI is raised, **the untransmitted portion of the previous byte will be lost.**
  - We can use interrupt to transfer data
7. After SBUF is loaded with a new byte, the TI flag bit must be cleared by the **programmer.**



# Transferring Data Serially in 8051

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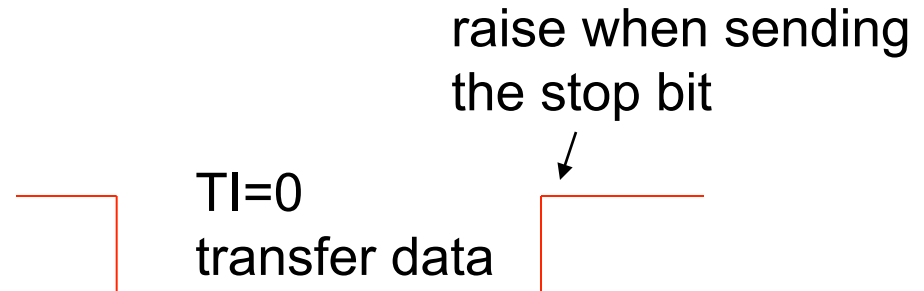
1. Use the timer 1 in mode 2
  - `MOV TMOD,#20H`
2. Set the value TH1 to chose baud rate.
  - `MOV TH1,#FDH` ;Baud rate = 9600bps
3. Set SCON register in mode 1.
  - `MOV SCON,#50H`
4. Start the timer.
  - `SETB TR1`



# Transferring Data Serially in 8051

5. Clear TI flag.

– **CLR TI**



6. The character byte to be transferred serially is written into the SBUF register.

– **MOV SBUF, #'A'**

7. Keep monitoring the Transmit Interrupt (TI) to see if it is raised.

– **HERE: JNB TI, HERE**

8. To transfer the next character, go to Step 5.



# Example: Serial Transmission

Write a program for the 8051 to transfer letter “A” serially at 4800 baud, continuously.

```
MOV    TMOD , #20H    ;timer 1, mode 2
MOV    TH1 , #-6      ;4800 baud rate
MOV    SCON , #50H    ;8-bit,1 stop,REN enabled
SETB   TR1            ;start timer 1
AGAIN: MOV    SBUF , #"A" ;letter "A" to be transferred
HERE:   JNB    TI , HERE ;wait for the last bit
        CLR    TI      ;clear TI for next char
        SJMP   AGAIN    ;keep sending A
```





# Thank You

