# Caterpillar Tractors: An UI Design Embedded with Remote Controller

#### Team 2

Ge Gao, Rithish Koneru, Srinivas Nethra Padala, Yudong Rao, Shreya Tangri, Hongyi Fan

## **Problem Statement**





- Need for the remote task machine operations
- Caterpillar need their own remote controllers

## Our Goal

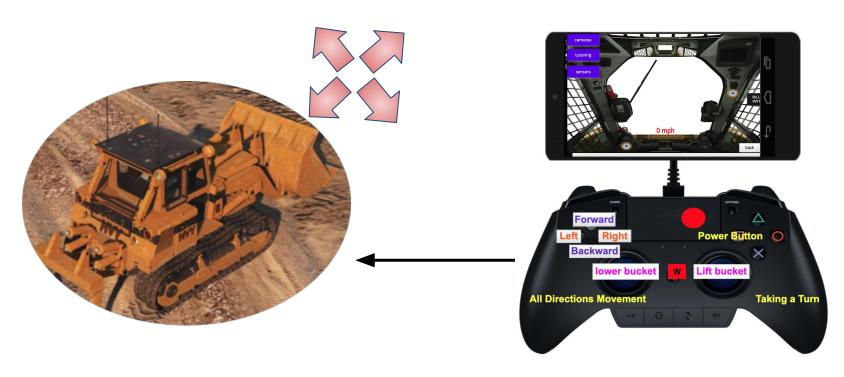
- Develop a nice UI for the remote controller for the CAT machines
- Integrate it with the new features like sensor, mobile app
- Operate it remotely efficiently and effortlessly

# **Proof-of-Concept Prototype**

Cell phone APP embedded with the Remote Controller to fulfill the needs of both the experienced and novice operators.

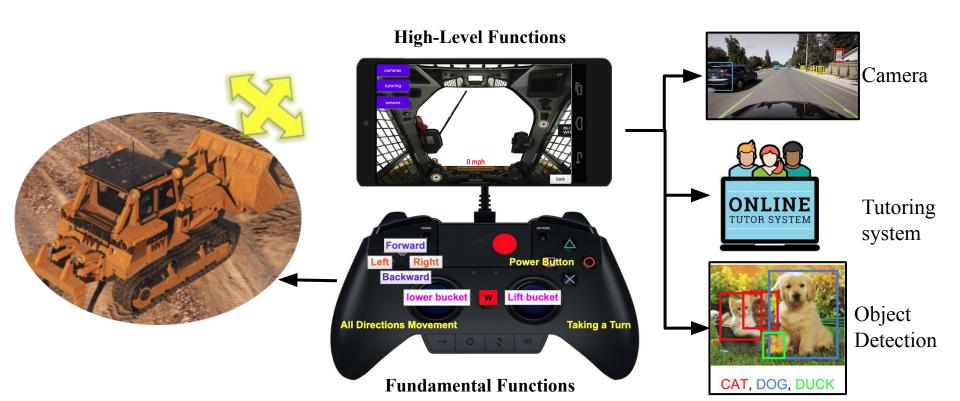


# **Proof-of-Concept Prototype**



**Fundamental Functions** 

# **Proof-of-Concept Prototype**



## **Phase 1: Research**

## **Challenges to deal with:**

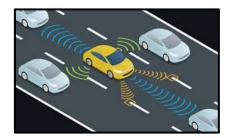
- Safety
- Cost
- Visibility
- Communication with new operators
- Test

## **Problems/Opportunities**

- Ensuring Robustness
- Scalability
- Authorized login

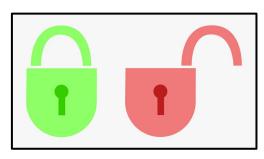












## **Phase 2: Generate**



Mobile Application



VR control system



Remote Joystick Control



Remote Drive Setup



**Tutoring System** 



360° - view



Sensor feedback

## **Phase 3: Choose**









### We decided to combine the following ideas:

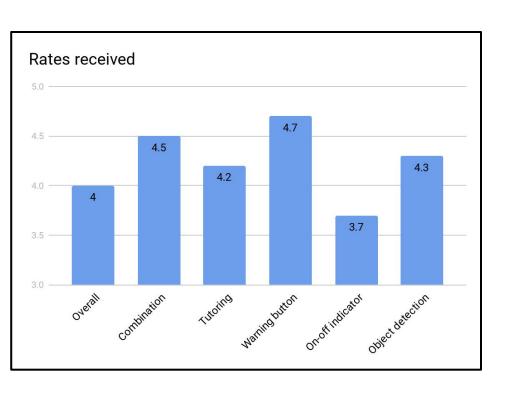
- Mobile application: Visibility, Secure Authorization and Connectivity
- Remote control joystick: Ease of control, Preserving haptic feedback
- Tutoring system: Module oriented learning for the new and existing operators
- Sensor feedback: Operator is responsive during the potential hazards

# **Phase 4: Prototype**



Online prototype: <a href="https://feelbergood.github.io/RemoteControlTractors/prototype">https://feelbergood.github.io/RemoteControlTractors/prototype</a>
Walkthrough video: <a href="https://www.youtube.com/watch?v=6sFXXeZlncw&feature=emb\_title">https://www.youtube.com/watch?v=6sFXXeZlncw&feature=emb\_title</a>

## **Phase 5: Evaluation**



#### **Patterns**

- Prototype received positive feedbacks
- Ideas of mobile-RC combination, tutoring system, physical warning button and object detection are successful
- Power on-off indicator is redundant

#### Follow-ups

- Use joysticks on remote controller for steering
- Make tutoring system more interactive and add details
- Add mechanism to prevent misclicking warning button
- Remove power on-off indicator
- Prevent object detection system to avoid mixing real hazards with the ordinary objects at job sites

## **NC STATE UNIVERSITY**



Thank You