# **MOMA Optimization**

Team Optimistic

Group 40

Mechanical Engineering Department Indian Institute of Technology Bombay

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# What is Muti Objective Optimization?

In general we are interested in the following mathematical problem type:

$$\begin{split} \text{minimize/maximize} & \quad f_m(x), m = 1, 2, ..., M \\ \text{subject to} & \quad g_j(x) \geq 0, j = 1, 2, ..., J \\ & \quad h_k(x) = 0, k = 1, 2, ..., K \\ & \quad x_i^{(L)} \leq x_i \leq x_i^{(U)}, i = 1, 2, ..., n \end{split}$$

A solution is a vector of n decision variables:

$$x = (x_1, x_2, ..., x_n)^T$$



#### **Feasible Solution**

A solution that satisfies all constraints and variable bounds. The set of all feasible solutions is called the feasible region, or S

#### **Domination**

- 1.  $\mathbf{x}^{(1)}$  is strictly better than  $\mathbf{x}^{(2)}$  in at least one objective
- 2.  $\mathbf{x}^{(1)}$  is no worse than  $\mathbf{x}^{(2)}$  for all objectives

#### Non-dominated set

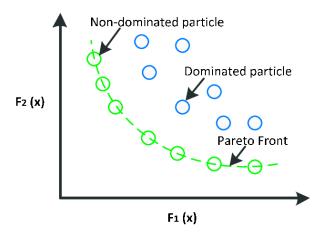
Solutions that are not dominated by any member of given set P

#### **Globally Pareto-optimal set**

The non-dominated set of the entire feasible search space S is the globally Pareto-optimal set



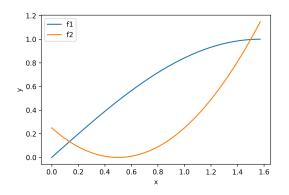
### **Pareto Optimal Solutions**





# **Synthetic Experiments**







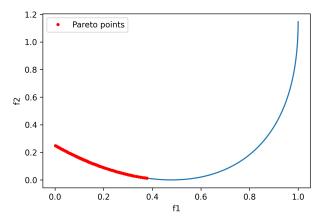
### **Synthetic Experiments**

#### Algorithm 1: Naive Gradient-Based Algorithm

```
\begin{split} & \text{Input: } f_1, f_2, \, \eta, \, \text{epochs} \\ & x \sim U(a,b) \\ & P \leftarrow \phi \\ & \text{for } i = 0 \text{ to epochs do} \\ & & | x_i = x_{i-1} - \eta \nabla_x f_1(x_{i-1}) \\ & | \text{if } f_2(x_i) > f_2(x_{i-1}) \text{ and } x_i \notin P \text{ and } x_i \in [a,b] \text{ then} \\ & | P \leftarrow P \cup \{x_i\} \\ & \text{else} \\ & | x_i \sim U(a,b) \\ & \text{return } P \end{split}
```

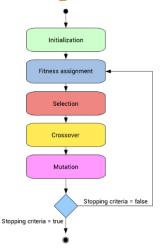


# **Synthetic Experiments**





# What are Genetic Algorithms?





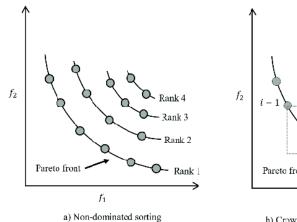
#### NSGA - II

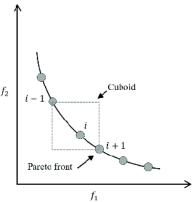
#### Nondominated Sorting Genetic Algorithm II

- Emphasis the non-dominated solutions
- Explicit diversity preserving mechanism (Crowding distance )
- Elitist principle



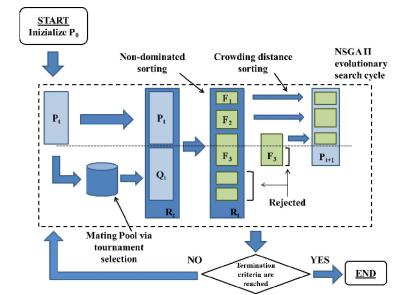
#### **NSGA-II**





b) Crowding distance calculation







# Choosing solutions from a Pareto set

#### **TOPSIS**

- Let decision matrix after normalization be denoted as  $r_{ij}$ , i=1,2,3...n, j=1,2,3...m.
- The weighted matrix is calculated as :  $v_{ij} = w_i r_{ij}$ .
- Best solution  $A^+ = (v_1^+, v_2^+, ..., v_m^+) = \max_i(v_{ij}), i = 1, 2, 3...n$
- Worst solution  $A^- = (v_1^-, v_2^-, ..., v_m^-) = \min_i(v_{ii}), i = 1, 2, 3...n$
- Euclidean distance between weighted matrix and the best and worst

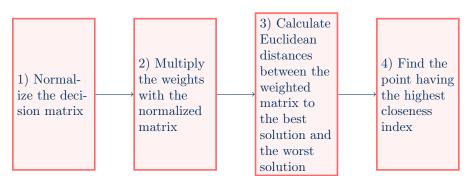
solutions are 
$$S_i^+ = \sqrt{\sum_{j=1}^m (v_{ij} - v_j^+)^2}$$
 and  $S_i^- = \sqrt{\sum_{j=1}^m (v_{ij} - v_j^-)^2}$ 

respectively.

• Closeness index is calculated as  $\frac{S_i^-}{S_i^- + S_i^+}$ .



### **Steps of TOPSIS**





# **Multi-Agent extension**

$$\begin{array}{c} \text{Agent 1: } x_1^1, x_1^2, ... x_1^n \\ \\ f_1^1(x_1^1, x_1^2, ..., x_2^1, ..) \\ f_1^2(x_1^1, x_1^2, ... x_2^1, ..), ... \\ f_1^m(x_1^1, x_1^2, ... x_2^1, ..) \end{array}$$

$$\begin{array}{lll} \text{Agent 2: } x_2^1, x_2^2, ... x_2^n \\ f_2^1(x_1^1, ... x_2^1, x_2^2, ..., x_3^1, ..) \\ f_2^2(x_1^1, ... x_2^1, x_2^2, ... x_3^1, ..), ... & \ldots & \text{k agents} \\ f_2^m(x_1^1, ... x_2^1, x_2^2, ... x_3^1, ..) & & \end{array}$$

$$\begin{split} \text{Single Agent: } x_1^1, x_1^2, .., x_k^n \\ f_1^1(x_1^1, x_1^2, ..., x_2^1, ..), ... \\ f_2^1(x_1^1, ..x_2^1, x_2^2, ..., x_3^1, ..), ... \\ f_k^m(x_1^1, ..x_2^1, x_2^2, ...x_3^1, ..) \end{split}$$

#### Single agent

- kn Decision variables
- km Objective functions



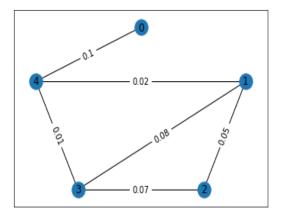
#### **Problem Definition**

- I Group of k undergrad students, each with m<sub>i</sub> objective functions
- II Each student has n decision variables representing the time given to certain activities
- III Further, each student in the group is influenced by some other student(s) in the group.

Here we analyse a group of 5 students with a total of 6 objective functions



# Graph





# **Objective Functions**

Table 1: List of objective functions of different students

Student ID	Objective Functions
1	job
2	gradstudy
3	health
4	social
5	explore, social



#### **Decision Variables**

We have the following decision variables with the unit of hours per week

- Academic Activities (ac)
- Sports (sp)
- Research Work (rw)
- PoRs (pr)
- Tech Teams (tt)

- Tech Clubs (tc)
- Non-Core Clubs (nc)
- Culturals (cu)
- Leisure (le)
- Sleep (sl)



#### **Constraints**

- 1. ac + sp + rw + pr + tt + tc + nc + cu + le + sl  $\leq 168$
- 2. ac + sp + rw + pr + tt + tc + nc + cu + le + sl  $\geq 120$
- 3. 18  $\leq$  ac  $\leq$  54
- 4. pr + tt + tc + nc  $\leq 50$
- $5. \text{ sl } \geq 35$
- 6.  $le \ge 10$



### **Influence Methods**

$$\lambda_{i} \leftarrow \lambda_{i} + \sigma_{ji}\lambda_{j}$$

(2) 
$$\lambda_{i} \leftarrow \lambda_{i} + \sigma_{ji}(\lambda_{j} - \lambda_{i})$$

(3) 
$$\lambda_{i} \leftarrow \frac{\lambda_{i} + \sigma_{ji}\lambda_{j}}{1 + \sigma_{ji}}$$

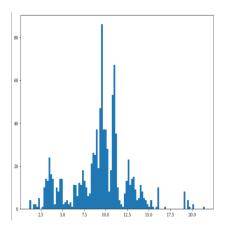
- Here,  $\sigma_{ji} \in [0, 1]$  is the influence of agent i on j, and  $\lambda_i$  is the i<sup>th</sup> decision variable
- Drawbacks when using Method (1)
- Comparative study between methods (2) and (3)



# MaxHist: New Method for Choosing Solutions

Given a pareto set, For each decision variable,

• Choose its most occurring value that decision variable in the pareto set





# Sample Solution

One of the obtained solution is shown below to understand

{1: [job], 2: [gradstudy], 3: [health], 4: [social], 5: [explore, social]}

wtsu 1500 500

İ	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
i	1	36	2	10	2	0	6	0	1	10	48
i	2	59	0	57	1	0	0	0	0	10	48
İ	3	18	21	0	2	0	0	0	9	11	49
	4	17	0	14	1	0	0	5	1	13	42
ĺ	5	21	0	0	1	0	3	1	21	14	37
_		L									

Figure 1: Sample Solution



# **Experiments Conducted**

- 1. Experimental Analysis for Different Influence Methods
- 2. Analysis of varying number of generations on the result
- 3. Choosing Effective Selection Method from Pareto
- 4. Extending number of objectives to 15
- 5. Effect of Influence on Optimal Solutions



### 1. Different Influence Methods

į	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
į	1	36 59	2	10 57	2	0	6	9	1 0	10 10	48     48
i	3	18	21	0	2	ø	0	ø	9	11	49
- 1	4	17	0	14	1	0	0	5	1	13	42
- !	5	21	0	0	1	0	3	1	21	14	37

Figure 2: Method 2 - Influence

Student	ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
1	i	32	2	10	1	11	1	8	4	17	45
2		58	0	57	0	0	0	0	0	10	46
3		18	12	1	4	3	1	7	0	10	49
4		19	24	0	13	0	1	4	10	11	46
5	- 1	23	2	3	0	0	4	1	22	15	47
+	+-		+	+	+	·	+	+	+	·	++

Figure 3: Method 3 - Influence



### 2. Effect Of Number of Generations

abswtsf 1500 150

į	Student ID							Non-Core Clubs	Cult	Leisure	Sleep
i	1	38	10	8	0	3	5	0	12	10	38
i	2	53	8	7	8	7	1	4	0	11	47
	3	21	59	2	5	7	0	2	6	9	48
	4	19	15	1	1	9	3	11	22	10	53
	5	22	0	5	6	6	9	1	7	10	47
	-				-				. 1		

Figure 4: Ngen = 150

bswtsf_1500_		<b>+</b>	<b>.</b>	<b>4</b>	<b>.</b>	+	<b>+</b>	+		L
	-	•			-	•	Non-Core Clubs			Sleep
1	+   29	+   1	   2	+   1	+   0	+   2	+   17	+   26	10	47
2	59	0	59	0	0	0	j 0	j ø j	10	45
3	23	18	2	0	2	0	2	7	12	51
4	15	1	33	3	0	0	1	5	10	51
5	19	0	0	1	0	1	0	19	14	47
5	19	j ø	0	1	0	1 +	j ø	19	1	4 j

Figure 5: Ngen = 1000



# 3. Topsis vs MaxHist

V	rtsu_1500_300	_IMP	<b>.</b>	L	L	<b></b>	<b></b>	<b>.</b>	L	<b></b>	<b></b>
į	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
i	1	53	0	37	1	0	11	1	0	10	48
	2	57	0	6	1	3	0	0	4	10	43
	3	18	30	2	0	0	6	5	5	11	45
ı	4	17	2	2	3	0	14	6	1	10	42
Ì	5	53	0	3	0	2	0	1	10	11	47
4		+	+	·	·	·	·	+	+	+	++
+		+	+	·		·	+	·		+	++
	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
4		+	+	·		·	<b></b>	h		+	++
	1	56	0	0	0	0	4	0	0	10	49
İ	2	59	0	47	1	0	0	0	0	10	45
ı	3	18	59	0	0	0	0	0	5	11	49
i	4	18	0	2	0	0	0	1	59	10	49
ı	5	16	0	0	0	0	0	0	59	10	48
4		+	+	·		·	<b></b>	<b></b>	·	+	++

Figure 6: Topsis vs MaxHist



# 4. More number of Objectives

Student ID	Objective Functions
1	job, health, social
2	gradstudy, explore, social
3	job, health, social
4	social, explore, job, health
5	explore, gradstudy

#### largeobj\_3000\_100

1	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
j	1	31	9	8	9	3	9	17	11	10	45
	2	21	9	7	4	9	9	14	6	11	36
	3	27	10	6	10	10	8	11	0	16	46
	4	17	18	1	9	2	3	9	9	11	34
	5	19	11	15	14	9	10	10	9	16	39
4			+	+	+	+	+	<b> </b>	+		++

Figure 7: 15 Objective functions



# 5. Effect Of influence On Optimal Solution

#### largeobj 3000 100

1	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
i	1	31	9	8	9	3	9	17	11	10	45
	2	21	9	7	4	9	9	14	6	11	36
- 1	3	27	10	6	10	10	8	11	0	16	46
- 1	4	17	18	1	9	2	3	9	9	11	34
Ì	5	19	11	15	14	9	10	10	9	16	39

Figure 8: Effect Of Influence in Students 1 and 3



# Stochasticity

We identify sources of uncertainty in our proposed framework:

- Naive Algo:
  - Random restarts
- NSGA-II:
  - Random mutations in the NSGA-II algorithm
  - Cross-over occurs with probability 0.9



### Sensitivity Analysis

Here we analyse sensitivity of our framework with respect to the influence weights.

#### abswtsinfluence 1000 500

								+			
į	Student ID	Acads	Sports	Research	PORs	Tech Teams	Tech Clubs	Non-Core Clubs	Cult	Leisure	Sleep
i	1	43	:	:	:	2			0	9	48
j	2	59		57	0	1	0	0	0	10	47
	3	18	13	1	6	1	2	2	1	13	45
	4	18	0	9	7	1	0	3	10	11	46
ı	5	17	4	3	0	0	0	5	21	11	47

Figure 9: Results with  $\sigma_{25} = 0.02$ 

#### abswtsinfluence\_1000\_500

			•			•	Non-Core Clubs			
1	31	0	2	4	13	13	6	9	16	38
2	49	0	59	1	0	1	0	1	10	47
3	21	22	1 1	7	0	0	4	4	16	49
4	31   18	Z   a	13   a	4	0   7	/   1	]	טן 1 35	13	46
					, 				13	J1

Figure 10: Results with  $\sigma_{25} = 0.022$ 



#### Limitations

- Competitive nature of some objective functions not considered
- The algorithm depends on the number of generations in two ways :
  - If the number of generations is low, then the preferred gene may not appear by mutation and sub optimal solutions may be obtained
  - If the number of generations is high, the the population will be saturated with preferred decision variables



### Conclusion

- Pareto Solutions
- Synthetic Experiments, Naive Algorithm
- Genetic algorithms
- Selection from Pareto
- Multi-agent extension
- Insti-Life Problem

- We can take up any queries now
- The following slides contain(for reference):
  - Appendix A : Some Code Snippets
  - Appendix B : More on Genetic Algorithms



```
## objective functions
def iob(s):
   job = (9*(s.acads)**2 + 4*(s.research)**2 + 3*(s.pors)**2 + 5*(s.tech team)**2
          + 5*(s.tech club)**2)*np.exp(-((s.sleep-49)**2 / (2.0 * 14**2 ))) # mu = 49, sigma = 14
   return job
def gradstudy(s):
   gradstudy = (np.exp(-( (s.sleep-49)**2 / ( 2.0 * 14**2 ) ) ))*(8*(s.acads)**2
                     +10*(s.research)**2+5*(s.tech team)**2+5*(s.tech club)**2)
   return gradstudy
def health(s):
   health = (np.exp(-((s.sleep-49)**2 / (2.0 * 7**2))))*
             (1 + s.sports**2/5 + (1 - np.exp(-s.leisure/15)))
   return health
def social(s):
   social = (np.exp(-( (s.sleep-49)**2 / ( 2.0 * 14**2 ) ) ))*((s.sports**2)
                   +7*(s.pors**2)+3*(s.tech team)**2+3*(s.tech club)**2+7*(s.nc club**2)+7*(s.cult**2))
   return social
def explore(s):
   explore = (np.exp(-(s.sleep-49)**2 / (2.0 * 14**2))))*((5*(s.sports**2)+5*(s.pors**2))
   +5*(s.tech team)**2+5*(s.tech club)**2 +5*(s.nc club**2)+5*(s.cult**2)+5*(s.acads**2)+5*(s.research**2)))
   return explore
```





```
from pymoo.algorithms.moo.nsga2 import NSGA2
from pymoo.optimize import minimize
from pymoo.visualization.scatter import Scatter
import matplotlib.pyplot as plt
import time
problem = CollegeLife(student list, g)
n var = 50
X = 10*np.ones((1000, n var))
algorithm = NSGA2(pop size=1000, sampling=X)
# algorithm = NSGA2(pop size=2000)
t1 = time.time()
res = minimize(problem,
               algorithm,
               ('n gen', 150), ## was 200 ## 120 giving good results
               seed=1,
               verbose=True)
```

Figure 12: PYMOO's NSGA2



```
def TOPSIS(pareto matrix, weights):
    normalized mx = normalize(pareto matrix)
   weighted mx = normalized mx*weights
    best sol = np.max(weighted mx, axis=0)
   worst sol = np.min(weighted mx, axis=0)
   diff best = weighted mx - best sol
    diff worst = weighted mx - worst sol
    sq diff best = np.square(diff best)
    sq diff worst = np.square(diff worst)
    dist best = np.sqrt(np.sum(sq diff best, axis=1))
    dist worst = np.sqrt(np.sum(sq diff worst, axis=1))
    final cost = dist worst/(dist best + dist worst)
    ##print(final cost)
    return np.argmax(final cost)
```

Figure 13: TOPSIS



```
# This is using max Distribution
ans=np.linspace(1,1,50)
for i in range(0,50):
   n, bins, patches = ax.hist(res.X[:,i], bins = 100)
   max_occ = bins[np.argmax(n)]
   ans[i]=max_occ
ans
```

Figure 14: MAXHist



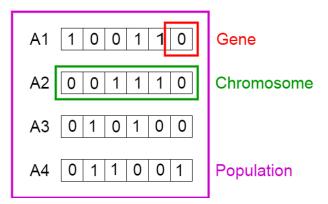
# Appendix B: Genetic Algortihms

**Example: Knapsack Problem** 

ITEM	WEIGHT	SURVIVAL POINTS
SLEEPING BAG	15	15
ROPE	3	7
POCKET KNIFE	2	10
TORCH	5	5
BOTTLE	9	8
GLUCOSE	20	17



#### 1. Initialization





#### 2. Fitness Function

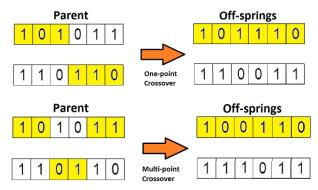
ITEMS	WEIGHT	SURVIVAL POINTS
Sleeping bag	15	15
Torch	5	5
Bottle	9	8
TOTAL	29	<mark>28</mark>

ITEMS	WEIGHT	SURVIVAL POINTS
Pocket Knife	2	10
Torch	5	5
Bottle	9	8
TOTAL	16	<mark>23</mark>

#### 3. Selection



#### 4. Crossover



#### 5. Mutation



